



NUMERICAL METHODS FOR TOEPLITZ MATRICES

VOLUME II

APPENDIX - PROGRAMS AND RESULTS

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Note on machine used

The programs listed in this volume were run on an IBM 370/3033, and all floating-point variables were in IBM double-precision ("REAL*8") format. In this format, one bit is used for the sign, 7 bits represent the hexadecimal exponent in excess-64 form, and the remaining 56 bits (about 16.8 decimal digits) are used for the mantissa.



```
C TEST PROGRAM FOR PBA1 (PIVOTED BAREISS ALG, STRATEGY 1:
C SIMPLE 2-CHOICE STRATEGY)
```

```
C 1. MAKES UP N X N TOEP.MX. 'A' WITH A(N,1),...,A(1,1),...,
C ...,A(1,N) EQUAL TO TO(1),...,TO(2*N-1) RESPECTIVELY.
C 2. MAKES SPECIFIED SUB-MATRIX OF ORDER NSIZE ILL-COND.
C BY ADJUST RELEVANT TOEP.DIAG.
C 3. CALCS. RHS. CORRESP. TO SOL. (1,1,...,1)
C 4. SOLVES SYSTEM USING BNA AND PBA1, AND PRINTS OUT ERRORS
```

```
REAL*8 T(11),A(20,20),B(20),X(20),XERR(20),XERRSZ,EPS
REAL*8 DELTA(2)
DATA T/3.,2.,6.,1.,8.,4.,6.,5.,5.,3.,1./,DELTA/0.,1D-3/
```

```
C MATRIX DIMENSIONS
```

```
  ID1=20
  N=6
  N2M1=2*N-1
  NMI=N-1
```

```
C GEN. 'A' FROM ITS 1ST ROW AND COL, GET SPECS. FOR ILL-COND
C SUBMATRIX, AND ADJUST TOEP.DIAG. ACCORDINGLY
```

```
  CALL TOEPMX(T,A,N,N2M1,ID1)
  WRITE(6,3)
  3 FORMAT('/' SIZE OF ILL-COND BLOCK, DIST FROM SINGULARITY')
  READ(5,*) NSIZE,EPS
  CALL ADJSMX(T,A,N,N2M1,ID1,NSIZE,1,1,EPS)
```

```
  9 WRITE(6,10)
 10 FORMAT('///' INPUT TOEPLITZ MATRIX T')
  CALL PRNTMX(A,N,N,ID1)
  WRITE(6,15)
 15 FORMAT('///// EXACT SOL OF T*X = B IS (1,1,...,1)')
```

```
C GENERATE RHS FOR SOL=(1,1,...,1)
```

```
  DO 20 I=1,N
  B(I)=0.
  DO 20 J=1,N
 20 B(I)=B(I)+A(I,J)
```

```
C SOLVE SYSTEM AND PRINT DIFFERENCE VECTOR FOR BNA (WHEN
C DELTA=0) AND PBA-1
```

```
  DO 50 IDEL=1,2
  CALL PBA1(A,B,X,DELTA(IDEAL),N,ID1)
  XERRSZ=0.
  DO 30 I=1,N
  XERR(I)=X(I)-1.
  IF(DABS(XERR(I)).GT.XERRSZ) XERRSZ=DABS(XERR(I))
 30 CONTINUE
  IF(IDEAL.EQ.1) WRITE (6,35)
 35 FORMAT('/// BAREISS ALG (BNA):')
  IF(IDEAL.EQ.2) WRITE (6,38)
 38 FORMAT('/// PIVOTED BAREISS ALG (PBA1):')
  WRITE(6,40) XERRSZ,(XERR(I),I=1,N)
 40 FORMAT('/' ERROR NORM = ',D12.4/' ERROR VECTOR',
 1 / (1X,10D12.4))
 50 CONTINUE
```

STOP
END

SUBROUTINE PBA1(TO,B,X,DELTA,N,LRO)

C
C PIVOTED BAREISS ALG, STRATEGY 1 (SIMPLE 2-CHOICE STRATEGY)
C
C TO - I/P TOEP.MX.; B - RHS; X - SOL(O/P); DELTA - PIVOT THRESHOLD;
C N,LRO - ORDER,ROW-DIM OF TO
C
C OUTLINE OF ALG.:
C 1. CARRY OUT BNA UNTIL AT STEP (-K) TM-PIVOT/TMAX.LT.DELTA,
C OR STEP N-1 IS FINISHED, AT WHICH CASE, EXIT. IF
C TM-PIVOT/TMAX.LT.DELTA, GO TO 2 IF THE ALTERNATE PIVOT
C (THE ELEMENT BELOW THE ZERO-BAND) IS GREATER THAN THE
C THE BNA PIVOT, ELSE GO BACK TO THE BEGINNING OF THIS STEP
C
C 2. WITH TM(-K-1) AS PIVOT (NOTE. A(J) DENOTES J-TH DIAG. OF
C TOEPLITZ PART OF A) ELIMINATE TP(0).
C
C 3. WITH TP(K) AS PIVOT, ELIMINATE TM(0)
C
C 4. RESTORE TO BAREISS FORM BY USING TM(1) TO ELIMINATE TP(K)
C
C 5. REPLACE K WITH K+1
C (RBF)
C
C 6. GO TO 1.
C
C TEMPORARIES:
C T - COPY OF TO
C TM,TP - NEGATIVE-INDEX (N.I.) AND POSITIVE-INDEX (P.I.) BAREISS
C ITERATES.
C BM,BP - RHS'S FOR TM,TP
C U,BU - UPR.TRIANGLE AND CORRESP RHS FOR BACK-SUBST
C TX - TM-MAX
C IMT,IMB - TOP,BOTTOM ROW OF TOEP.PART OF TM
C IPT,IPB - TP
C MM,MP - MULTIPLIERS FOR BAREISS OPERATIONS

REAL*8 TO(LRO,N),B(N),X(N),T(20,20),TM(20,20),TP(20,20),
1 BM(20),BP(20),U(20,20),BU(20),MM,MP
REAL*8 TX,DELTA

LR=20
NM1=N-1

C INITIALIZATION
DO 2 I=1,N
DO 2 J=1,N
2 T(I,J)=TO(I,J)

CALL MOVMTX(T,TP,N,N,LR)
CALL MOVMTX(T,TM,N,N,LR)
CALL MOVMTX(B,BP,N,1,LR)

```

CALL MOVMTX(B,BM,N,1,LR)

CALL UTROW(TM,BM,U,BU,0,1,0,N,LR)

IPT=1
IMB=N

C MAIN LOOP. K IS CYCLE NO.
  K=0
10 K=K+1
  IF(K.EQ.N) GO TO 500

C STEP (-K) OF BNA-CYCLE
  IMT=K+IMB-N
  IPB=N-K+IPT
  CALL BAROP(TP,BP,IPT,IPB-1,IPT,1,TM,BM,IMT+1,MM,N,LR)
  IMT=IMT+1
  CALL UTROW(TM,BM,U,BU,K,IMT,0,N,LR)

C PIVOT IF REQUIRED
  TX=TMAX(TM,IMT,IMB,N,LR)
  IF(DABS(TM(IMT,K+1))/TX.LT.DELTA .AND.
1  DABS(TM(IMT+1,1)).GT.DABS(TM(IMT,K+1))) GO TO 100

C STEP (K) OF BNA-CYCLE
  CALL BAROP(TM,BM,IMT,IMB,IMT,K+1,TP,BP,IPT,MP,N,LR)
  GO TO 10

C PIVOTING PROCEDURE, STRATEGY 1

C USE TM(-K-1) TO ELIM TP(0). (NOTE: A(J) DENOTES JTH
C DIAGONAL OF TOEPLITZ PART OF A)
100 CALL BAROP(TM,BM,IMT+1,IMB,IMT+1,1,TP,BP,IPT,MP,N,LR)
  CALL MOVMTX(TP(IPT,1),U(K+1,1),1,N,LR)
  BU(K+1)=BP(IPT)

C USE TP(K) TO ELIM. TM(0)
  CALL BAROP(TP,BP,IPT,IPB-2,IPT,K+1,TM,BM,IMT,MM,N,LR)
  IMB=IMB-1
  CALL UTROW(TM,BM,U,BU,K+1,IMT,0,N,LR)

C FINALLY, RESTORE TO BAREISS FORM BY USING TM(1) TO
C ELIM. TP(K)
  CALL BAROP(TM,BM,IMT,IMB-1,IMT,K+2,TP,BP,IPT+1,MP,N,LR)
  IPT=IPT+1
  K=K+1
  GO TO 10

500 CALL BCKSUB(U,BU,X,N,LR)
  RETURN
  END

SUBROUTINE BAROP(TS,BS,IS1,IS2,IP,JP,TD,BD,ID1,M,N,LR)

```

```

C
C PERFORMS A BAREISS-OPERATION (REAL*8)

C TS,BS .... SOURCE MATRIX AND RHS
C IS1,IS2 .. 1ST AND LAST ROWS OF SOURCE BLOCK
C IP,JP .... INDICES OF PIVOT
C TD,BD .... DESTINATION MATRIX AND RHS
C ID1 ..... 1ST ROW OF DESTINATION BLOCK
C M (O/P) .. MULTIPLIER (REAL*8)
C N ..... ORDER OF MATRICES
C LR ..... ROW-DIMENSION OF MATRICES

      REAL*8 M,TS(LR,N),TD(LR,N),BS(N),BD(N)

      M=TD(IP+ID1-IS1,JP)/TS(IP,JP)

      ID=ID1
      DO 20 IS=IS1,IS2
      DO 10 J=1,N
10    TD(ID,J)=TD(ID,J) - M*TS(IS,J)
      BD(ID)=BD(ID) - M*BS(IS)
20    ID=ID+1
C     CALL DUMP(TS,TD,N,LR)
      RETURN
      END

      DOUBLE PRECISION FUNCTION TMAX(TI,IT,IB,N,LR)
C
C FUNC. TO FIND LGST.MAGN.OF ELEMENTS IN TOEP.PART OF TI
C
C IT,IB - TOP,BOTTOM ROWS OF TOEP.PART OF TI
C N,LR - ORDER,ROW DIM.OF TI

      REAL*8 TI(LR,N),TMAG

      TMAX=0.
      DO 10 J=2,N
      TMAG=DABS(TI(IT,J))
      IF(TMAG.GT.TMAX) TMAX=TMAG
10    CONTINUE

      DO 20 I=IT,IB
      TMAG=DABS(TI(I,1))
      IF(TMAG.GT.TMAX) TMAX=TMAG
20    CONTINUE
      RETURN
      END

      SUBROUTINE BCKSUB(U,B,X,N,LR)
C
C S/R TO BACKSUBST THE TRIANGULAR SYSTEM U*X=B.
C
C N,LR - ORDER, ROW-DIM OF U

```

```
REAL*8 U(LR,N),B(N),X(N)
```

```

I=N
DO 20 II=1,N
X(I)=B(I)
IF(I.EQ.N) GO TO 15
IP1=I+1
DO 10 J=IP1,N
10 X(I)=X(I)-U(I,J)*X(J)
15 X(I)=X(I)/U(I,I)
20 I=I-1
RETURN
END
```

```
SUBROUTINE DUMP(TS,TD,N,LR)
```

```

C
C DIAGNOSTIC DUMP OF TS AND TD. (N,LR ARE THE ORDER
C AND ROW-DIMENSION OF TS AND TD)
```

```
REAL*8 TS(LR,N),TD(LR,N)
```

```

WRITE(6,10)
10 FORMAT('/' TS')
DO 20 I=1,N
20 WRITE(6,30) (TS(I,J),J=1,N)
30 FORMAT(1X,13F9.3)
```

```

WRITE(6,40)
40 FORMAT('/' TD')
DO 50 I=1,N
50 WRITE(6,30) (TD(I,J),J=1,N)
RETURN
END
```

```
SUBROUTINE UTROW(TM,BM,U,BU,K,IMT,ZD,N,LR)
```

```

C S/R TO GET NEXT ROW OF U-MATRIX (AND RHS) FOR BACK-SUBST
C
C TM - BAREISS ITERATE(-K)
C BM - CORRESP RHS
C U - (O/P) U.T. MATRIX FOR BACK-SUBST
C B - CORRESP RHS
C K - CYCLE NO.
C IMT- TOP OF TOEP.PT.OF TM
C ZD - (INTEGER) ZERO-BAND DISPL. - MUST BE LE.1
C N,LR-ORDER,ROW DIM OF MATRICES
```

```
REAL*8 TM(LR,N),BM(N),U(LR,N),BU(N)
INTEGER ZD
```

```

IF(ZD.GE.0) GO TO 20
WRITE(6,10) ZD,K,IMT
10 FORMAT(' ABORT - ZD.LT.0'/' ZD =',I3,' K =',I2,' IMT =',I2)
STOP
```

```

20 CALL MOVMTX(TM(IMT+ZD,1),U(K+1,1),1,N,LR)
   BU(K+1)=BM(IMT+ZD)
   RETURN
   END

```

```

SUBROUTINE ADJSMX(T,A,N,N2M1,LR,NSIZE,NCOL,NROW,EPS)

```

```

C S/R TO MAKE SOME ORDER-NSIZE SUBMATRICES OF AN N X N
C TOEP.MX. ILL-COND. BY ADJUSTING TOEP.DIAGS.
C
C T - INITIAL VALUE OF A(N,1)...A(1,1)...A(1,N)
C A - I/P TOEP.MX.
C N - ORDER OF A
C N2M1 - 2*N-1
C LR - ROW-DIM OF A
C NSIZE- SIZE OF ILL-COND S/MATRICES
C NCOL - NO.OF ILL-COND S/MATRICES ALONG COL, STARTING AT TOP
C NROW - NO.OF ILL-COND S/MATRICES ALONG ROW, STARTING AT LEFT
C EPS - QTY TO BE ADDED TO DIAG AFTER EACH BLOCK HAS BEEN
C MADE SINGULAR

```

```

REAL*8 T(N2M1),A(LR,N),EPS
REAL*8 WKA(860)

```

```

IF(NSIZE.EQ.0.OR.NCOL.EQ.0.OR.NROW.EQ.0) RETURN
N2P3=2*N+3
DO 4 I=1,NCOL
CALL SINGSM(A,N,N,LR,I+NSIZE-1,1,NSIZE,-1,1,WKA,N2P3,IER)
T(N+NSIZE+I-2)=A(I+NSIZE-1,1)+EPS
4 CALL TOEPMX(T,A,N,N2M1,LR)

IF(NROW.EQ.1) RETURN
DO 6 J=2,NROW
CALL SINGSM(A,N,N,LR,1,J+NSIZE-1,NSIZE,1,-1,WKA,N2P3,IER)
IF(IER.NE.0) WRITE(6,5) IER
5 FORMAT(' SINGSM ERROR CODE = ',I3)
T(N-NSIZE-J+2)=A(1,J+NSIZE-1)+EPS
6 CALL TOEPMX(T,A,N,N2M1,LR)
RETURN
END

```

```

SUBROUTINE MOVMTX(A,B,M,N,LR)

```

```

C
C MOVES D.P. MATRIX A(M X N) TO B. LR IS THE ROW-DIMENSION
C OF A AND B.

```

```

REAL*8 A(LR,N),B(LR,N)

```

```

DO 10 I=1,M
DO 10 J=1,N
10 B(I,J)=A(I,J)
RETURN

```


SIZE OF ILL-COND BLOCK, DIST FROM SINGULARITY

?
3,5d-8

INPUT TOEPLITZ MATRIX T

4.000	2.000	1.000	6.000	2.000	3.000
6.000	4.000	8.000	1.000	6.000	2.000
4.733	6.000	4.000	8.000	1.000	6.000
5.000	4.733	6.000	4.000	8.000	1.000
3.000	5.000	4.733	6.000	4.000	8.000
1.000	3.000	5.000	4.733	6.000	4.000

EXACT SOL OF $TX = B$ IS (1,1,...,1)

BAREISS ALG (BNA):

ERROR NORM = 0.6910D-01

ERROR VECTOR

0.6910D-01 -0.3516D-01 -0.5120D-01 -0.6696D-02 0.1674D-01 0.2091D-01

PIVOTED BAREISS ALG (PBA1):

ERROR NORM = 0.1110D-14

ERROR VECTOR

-0.8327D-15 0.1110D-14 0.8882D-15 -0.6661D-15 -0.7772D-15 -0.2637D-15

READY

```

C TEST PROGRAM FOR PBA2 (PIVOTED BAREISS ALG, STRATEGY 2)

C 1. MAKES UP N X N TOEP.MX. 'A' WITH A(N,1),...,A(1,1),...,
C ... ,A(1,N) EQUAL TO T0(1),...,T0(2*N-1) RESPECTIVELY.
C 2. MAKES SPECIFIES SUB-MATRICES OF ORDER NSIZE ILL-COND.
C BY ADJUST RELEVANT TOEP.DIAGS.
C 3. CALCS. RHS. CORRESP. TO SOL. (1,1,...,1)
C 4. SOLVES SYSTEM USING BNA AND PBA2, AND PRINTS OUT ERRORS

REAL*8 T(25),T0(25),A(20,20),B(20),X(20),XERR(20),XERRSZ,EPS
REAL*8 DELTA(2),K1
DATA T0/-1.5,10.,1.,-7.,-2.,-5.,3.,7.,9.,2.,6.,-1.,5.,
1 1.,-3.,0.,0.,-4.,-7.,-1.,2.,1.,-6.,1.,-0.5/,DELTA/0.,1D-3/,
2 K1/100./

C MATRIX DIMENSIONS
  ID1=20
  N=13
  N2M1=2*N-1
  NM1=N-1

C GEN. 'A' FROM ITS 1ST ROW AND COL, GET SPECS. FOR ILL-COND
C SUBMATRICES, AND ADJUST TOEP.DIAGS. ACCORDINGLY
  1 DO 2 I=1,N2M1
  2 T(I)=T0(I)
  CALL TOEPMX(T,A,N,N2M1,ID1)
  WRITE(6,3)
  3 FORMAT(/' SIZE OF ILL-COND BLOCK, NO.ALONG COL,ROW, DIST ',
  1 'FROM SINGULARITY')
  READ(5,*) NSIZE,NCOL,NROW,EPS
  CALL ADJSMX(T,A,N,N2M1,ID1,NSIZE,NCOL,NROW,EPS)

  9 WRITE(6,10)
  10 FORMAT(///' INPUT TOEPLITZ MATRIX T')
  CALL PRNTMX(A,N,N,ID1)
  WRITE(6,15)
  15 FORMAT(/////' EXACT SOL OF T*X = B IS (1,1,...,1)')

C GENERATE RHS FOR SOL=(1,1,...,1)
  DO 20 I=1,N
  B(I)=0.
  DO 20 J=1,N
  20 B(I)=B(I)+A(I,J)

C SOLVE SYSTEM AND PRINT DIFFERENCE VECTOR FOR BNA (WHEN
C DELTA=0) AND PBA-1
  DO 50 IDEL=1,2
  CALL PBA2(A,B,X,DELTA(IDEL),K1,N,ID1)
  XERRSZ=0.
  DO 30 I=1,N
  XERR(I)=X(I)-1.
  IF(DABS(XERR(I)).GT.XERRSZ) XERRSZ=DABS(XERR(I))
  30 CONTINUE
  IF(IDEL.EQ.1) WRITE (6,35)
  35 FORMAT(///' BAREISS ALG (BNA):')
  IF(IDEL.EQ.2) WRITE (6,38)
  38 FORMAT(///' PIVOTED BAREISS ALG (PBA2):')

```

```

WRITE(6,40) XERRSZ,(XERR(I),I=1,N)
40 FORMAT(/' ERROR NORM = ',D12.4/' ERROR VECTOR',
1 / (1X,10D12.4))
50 CONTINUE
STOP
END

```

```

SUBROUTINE PBA2(TO,B,X,DELTA,K1,N,LRO)

```

```

C
C PIVOTED BAREISS ALG, STRATEGY 2 (SIMPLIFIED VERSION)
C
C TO - I/P TOEP.MX.; B - RHS; X - SOL(O/P); DELTA - PIVOT THRESHOLD;
C K1 - (REAL*8) PIVOT PARAMETER (SEE BELOW); N - ORDER OF TO;
C LRO - ROW DIM. OF TO
C
C N.B.: THIS IS A SLIGHTLY SIMPLIFIED VERSION OF THE PBA-2
C DESCRIBED IN CH.5, IN THAT WE ONLY SEARCH BELOW THE ZERO-BAND
C FOR A PIVOT (INSTEAD OF BOTH ABOVE AND BELOW). THIS PROGRAM
C CAN EASILY BE EXTENDED TO USE PIVOTS ABOVE THE ZERO-BAND AS
C WELL, BUT THE BACK-SUBST PROCEDURE MUST BE GENERALIZED IN
C ACCORDANCE WITH THE REMARKS IN CH.5.
C
C OUTLINE OF ALG.:
C 1. CARRY OUT BNA UNTIL AT STEP (-K) TM-PIVOT/TMAX.LT.DELTA,
C OR STEP N-1 IS FINISHED, AT WHICH CASE, EXIT. IF
C T-PIVOT/TMAX.LT.DELTA, DO:
C
C 2. FIND TM(P) P PLACES ABOVE THE ZERO-BAND (Z.B.) AND TM(-K-1-Q)
C Q PLACES BELOW THE Z.B. SATISFYING :
C (A) TM(.)/TMAX.GE.DELTA
C (B) TM(.).GE.K1*(SUM OF ELEMENTS BETW. TM(.) AND Z.B.)
C
C 3. RECOVER ITERATES +,-(K-Q-1) AND DO Q+1 C-CYCLES TO MOVE Z.B.
C DOWN
C
C 4. DO P+Q B-CYCLES (BNA-CYCLES) TO GO ALONG BOTTOM OF BLOCK
C OF ILL-COND SUBMATRICES
C
C 5. DO Q+1 A-CYCLES TO MOVE THE Z.B. AND RESTORE TO BAREISS FORM
C (RBF)
C
C 6. GO TO 1.
C
C TEMPORARIES:
C T - COPY OF TO
C TM,TP - NEGATIVE-INDEX (N.I.) AND POSITIVE-INDEX (P.I.) BAREISS
C ITERATES.
C TMSV,TPSV - MATRICES TO SAVE P.I. AND N.I. ITERATES
C BM,BP - RHS'S FOR TM,TP
C BMSV,BPSV - MATRICES TO SAVE TM'S AND TP'S
C U,BU - UPR.TRIANGLE AND CORRESP RHS FOR BACK-SUBST
C TX - TM-MAX
C IMT,IMB - TOP,BOTTOM ROW OF TOEP.PART OF TM
C IPT,IPB - .. .. . TP
C ZD(INTEGER) - Z.B. DISPLACEMENT

```

C P,Q - POSITIONS OF ACCEPTABLE PIVOTS ABOVE AND BELOW Z.B.

```

INTEGER ZD,P,Q,PP1,QP1
REAL*8 T0(LR0,N),B(N),X(N),T(20,20),TM(20,20),TP(20,20),
1  BM(20),BP(20),TMSV(20,20),TPSV(20,20),BMSV(20,20),
2  BPSV(20,20),U(20,20),BU(20)
REAL*8 TX,DELTA,K1

```

```

LR=20
NM1=N-1

```

C INITIALIZATION

```

DO 2 I=1,N
DO 2 J=1,N
2 T(I,J)=T0(I,J)

```

```

CALL MOVMTX(T,TP,N,N,LR)
CALL MOVMTX(T,TM,N,N,LR)
CALL MOVMTX(B,BP,N,1,LR)
CALL MOVMTX(B,BM,N,1,LR)

```

```

CALL UTROW(TM,BM,U,BU,0,1,0,N,LR)
CALL SAVE(TM,TP,BM,BP,TMSV,TPSV,BMSV,BPSV,0,N,1,N,LR)

```

```

IPT=1
IMB=N
ZD=0

```

C MAIN LOOP. K IS CYCLE NO.

```

K=0
10 K=K+1
IF(K.EQ.N) GO TO 500

```

C BNA-CYCLE

```

CALL BCYC(TM,BM,IMB,TP,BP,IPT,K,ZD,N,LR)
CALL SAVE(TM,TP,BM,BP,TMSV,TPSV,BMSV,BPSV,K,IMB,IPT,N,LR)
IMT=IMB+K-N+1
CALL UTROW(TM,BM,U,BU,K,IMT,ZD,N,LR)

```

C PIVOT IF REQUIRED

```

TX=TMAX(TM,IMT,IMB,N,LR)
IF (DABS(TM(IMT+ZD,K+1))/TX.LT.DELTA) GO TO 100
GO TO 10

```

C PIVOTING PROCEDURE, STRATEGY 2

C FIND ACCEPTABLE PIVOTS ABOVE AND BELOW Z.B.

```

100 CALL FINDPV(TM(IMT,K+1),LR*(N-K),LR,N-K,TX,DELTA,K1,PP1,IERR)
P=PP1-1
CALL FINDPV(TM(IMT+1,1),N-K-1,1,N-K-1,TX,DELTA,K1,QP1,IERR)
Q=QP1-1

```

C MAKE TM(-K-1-Q) AVAILABLE FOR PIVOTING BY GETTING ITERATES

```

C +, -(-K-Q-1) AND PERFORMING Q+1 C-CYCLES
NCCYC=Q+1
K=K-NCCYC

```

```

CALL RECOV(TMSV,TPSV,BMSV,BPSV, TM, TP, BM, BP, K, IMB, IPT, N, LR)
  DO 140 I=1,NCCYC
    K=K+1
    CALL CCYC(TM,BM,IMB,TP,BP,IPT,K,ZD,N,LR)
140  CALL UTROW(TM,BM,U,BU,K,IMB-N+K+1,ZD,N,LR)

C . NEXT DO P+Q BNA-CYCLES (B-CYCLES)
  NBCYC=P+Q
  DO 150 I=1,NBCYC
    K=K+1
    CALL BCYC(TM,BM,IMB,TP,BP,IPT,K,ZD,N,LR)
150  CALL UTROW(TM,BM,U,BU,K,IMB-N+K+1,ZD,N,LR)

C FINALLY DO Q+1 (=NCCYC) A-CYCLES TO RESTORE TO BAREISS FORM
  DO 160 I=1,NCCYC
    K=K+1
    CALL ACYC(TM,BM,IMB,TP,BP,IPT,K,ZD,N,LR)
160  CALL UTROW(TM,BM,U,BU,K,IMB-N+K+1,ZD,N,LR)
      GO TO 10

500 CALL BCKSUB(U,BU,X,N,LR)
      RETURN
      END

```

```

SUBROUTINE MOVMTX(A,B,M,N,LR)
C
C MOVES D.P. MATRIX A(M X N) TO B. LC IS THE ROW-DIMENSION
C OF A AND B.

```

```

REAL*8 A(LR,N),B(LR,N)

DO 10 I=1,M
DO 10 J=1,N
10 B(I,J)=A(I,J)
RETURN
END

```

```

SUBROUTINE BAROP(TS,BS,IS1,IS2,IP,JP,TD,BD,ID1,M,N,LR)
C
C PERFORMS A BAREISS-OPERATION (REAL*8)

C TS,BS .... SOURCE MATRIX AND RHS
C IS1,IS2 .. 1ST AND LAST ROWS OF SOURCE BLOCK
C IP,JP .... INDICES OF PIVOT
C TD,BD .... DESTINATION MATRIX AND RHS
C ID1 ..... 1ST ROW OF DESTINATION BLOCK
C M (O/P) .. MULTIPLIER (REAL*8)
C N ..... ORDER OF MATRICES
C LR ..... ROW-DIMENSION OF MATRICES

```

```

REAL*8 M,TS(LR,N),TD(LR,N),BS(N),BD(N)

```

```
M=TD(IP+ID1-IS1,JP)/TS(IP,JP)
```

```

ID=ID1
DO 20 IS=IS1,IS2
DO 10 J=1,N
10 TD(ID,J)=TD(ID,J) - M*TS(IS,J)
   BD(ID)=BD(ID) - M*BS(IS)
20 ID=ID+1
C CALL DUMP(TS,TD,N,LR)
  RETURN
  END

```

```
DOUBLE PRECISION FUNCTION TMAX(TI,IT,IB,N,LR)
```

```

C
C FUNC. TO FIND LGST.MAGN.OF ELEMENTS IN TOEP.PART OF TI
C
C IT,IB - TOP,BOTTOM ROWS OF TOEP.PART OF TI
C N,LR - ORDER,ROW DIM.OF TI

```

```
REAL*8 TI(LR,N),TMAG
```

```

TMAG=0.
DO 10 J=2,N
  TMAG=DABS(TI(IT,J))
  IF(TMAG.GT.TMAX) TMAX=TMAG
10 CONTINUE

```

```

DO 20 I=IT,IB
  TMAG=DABS(TI(I,1))
  IF(TMAG.GT.TMAX) TMAX=TMAG
20 CONTINUE
RETURN
END

```

```
SUBROUTINE BCKSUB(U,B,X,N,LR)
```

```

C
C S/R TO BACKSUBST THE TRIANGULAR SYSTEM U*X=B.
C
C N,LR - ORDER, ROW-DIM OF U

```

```
REAL*8 U(LR,N),B(N),X(N)
```

```

I=N
DO 20 II=1,N
  X(I)=B(I)
  IF(I.EQ.N) GO TO 15
  IP1=I+1
  DO 10 J=IP1,N
10 X(I)=X(I)-U(I,J)*X(J)
15 X(I)=X(I)/U(I,I)
20 I=I-1
RETURN
END

```

SUBROUTINE DUMP(TS,TD,N,LR)

C
C DIAGNOSTIC DUMP OF TS AND TD. (N,LR ARE THE ORDER
C AND ROW-DIMENSION OF TS AND TD)

REAL*8 TS(LR,N),TD(LR,N)

WRITE(6,10)
10 FORMAT(/' TS')
DO 20 I=1,N
20 WRITE(6,30) (TS(I,J),J=1,N)
30 FORMAT(1X,13F9.3)

WRITE(6,40)
40 FORMAT(/' TD')
DO 50 I=1,N
50 WRITE(6,30) (TD(I,J),J=1,N)
RETURN
END

SUBROUTINE BCYC(TM,BM,IMB,TP,BP,IPT,K,ZD,N,LR)

C
C S/R TO DO A BAREISS CYCLE (B-CYCLE)

C TM,BM - NEG.INDEX ITERATE AND RHS
C IMB - INDEX OF LAST ROW IN TOEP.PART OF TM
C TP,TP - POS.INDEX ITERATE AND RHS
C IPT - INDEX OF 1ST ROW IN TOEP.PART OF TP
C K - CYCLE TO BE COMPUTED
C ZD - (INTEGER) I/P ZERO-BAND DISPLACEMENT
C N,LR - ORDER, ROW DIM OF MATRICES

C
C PROCEDURE:
C 1. ELIM BELOW ZERO-BAND OF NEG.INDEX ITERATE
C 2. ELIM ABOVE ZERO-BAND OF POS.INDEX ITERATE

INTEGER ZD
REAL*8 MM,MP
REAL*8 TM(LR,N),BM(N),TP(LR,N),BP(N)

IMT=K+IMB-N
IPB=N-K+IPT
CALL BAROP(TP,BP,IPT,IPB-1,IPT+ZD,1,TM,BM,IMT+1,MM,N,LR)
CALL BAROP(TM,BM,IMT+1,IMB,IMT+1,K+1-ZD,TP,BP,IPT,MP,N,LR)
RETURN
END

SUBROUTINE CCYC(TM,BM,IMB,TP,BP,IPT,K,ZD,N,LR)

C S/R TO MOVE ZERO-BAND DOWN (C-CYCLE)
C
C PARAMETERS - AS FOR S/R 'BCYC'

```

C
C PROCEDURE:
C 1. ELIM BELOW ZERO-BAND OF POS. INDEX ITERATE
C 2. ELIM BELOW ZERO-BAND OF NEG. INDEX ITERATE

```

```

INTEGER ZD
REAL*8 MM,MP
REAL*8 TM(LR,N),BM(N),TP(LR,N),BP(N)

```

```

IMT=K+IMB-N
IPB=N-K+IPT
CALL BAROP(TM,BM,IMT+1,IMB,IMT+ZD+1,1,TP,BP,IPT,MP,N,LR)
CALL BAROP(TP,BP,IPT,IPB-1,IPT+ZD+1,1,TM,BM,IMT,MM,N,LR)

```

```

ZD=ZD+1
IMB=IMB-1
RETURN
END

```

```

SUBROUTINE ACYC(TM,BM,IMB,TP,BP,IPT,K,ZD,N,LR)

```

```

C
C S/R TO MOVE ZERO-BAND UP (A-CYCLE)
C
C PARAMETERS - AS FOR S/R 'BCYC'
C
C PROCEDURE:
C 1. ELIM ABOVE ZERO-BAND OF NEG. INDEX ITERATE
C 2. ELIM ABOVE ZERO-BAND OF POS. INDEX ITERATE

```

```

INTEGER ZD
REAL*8 MM,MP
REAL*8 TM(LR,N),BM(N),TP(LR,N),BP(N)

```

```

IMT=K+IMB-N
IPB=N-K+IPT

```

```

CALL BAROP(TP,BP,IPT,IPB-1,IPT,K+1-ZD,TM,BM,IMT+1,MM,N,LR)
CALL BAROP(TM,BM,IMT+1,IMB,IMT+1,K+2-ZD,TP,BP,IPT+1,MP,N,LR)

```

```

ZD=ZD-1
IPT=IPT+1
RETURN
END

```

```

SUBROUTINE SAVE(TM,TP,BM,BP,TMSV,TPSV,BMSV,BPSV,K,IMB,IPT,N,LR)

```

```

C S/R TO SAVE TOEP.PART OF BAREISS ITERATES
C
C 1ST TOW OF TOEP PT.OF TM(ITER.-K) GOES TO TMSV(K+1,K+1)...TMSV(K+1,N)
C 1ST COL .. .. .. .. .. TMSV(K+2,K+1)...TMSV(N,K+1)
C CORRESP ENTRIES IN BM(ITER.-K) GO TO BMSV(K+1,K+1)...BMSV(N,K+1)
C LAST ROW OF TOEP PT.OF TP(ITER.K) GOES TO TPSV(N-K,1)...TPSV(N-K,N-K)
C LAST COL.. .. .. .. .. TPSV(1,N-K)..TPSV(N-K-1,N-K)

```


C CORRESP ENTRIES IN BP(ITER K) GO TO BPSV(1,K+1)...BPSV(N-K,K+1)

C IMB - BOTTOM OF TOEP.PT OF TM

C IPT - TOP OF TOEP.PT OF TP

C N,LR- ORDER,ROW-DIM OF MATRICES

REAL*8 TM(LR,N),TP(LR,N),TMSV(LR,N),TPSV(LR,N),BM(N),BP(N),
1 BMSV(LR,N),BPSV(LR,N)

IMT=IMB+K-N+1

CALL MOVMTX(TM(IMT,K+1),TMSV(K+1,K+1),1,N-K,LR)

CALL MOVMTX(TM(IMT+1,1),TMSV(K+2,K+1),N-K-1,1,LR)

CALL MOVMTX(BM(IMT),BMSV(K+1,K+1),N-K,1,LR)

IPB=IPT+N-K-1

CALL MOVMTX(TP(IPB,1),TPSV(N-K,1),1,N-K,LR)

CALL MOVMTX(TP(IPT,N),TPSV(1,N-K),N-K-1,1,LR)

CALL MOVMTX(BP(IPT),BPSV(1,K+1),N-K,1,LR)

RETURN

END

SUBROUTINE RECOV(TMSV,TPSV,BMSV,BPSV,TM,TP,BM,BP,K,IMB,IPT,N,LR)

C

C S/R TO RECOVER TOEP.PT. OF BAREISS ITERATES AS STORED IN TMSV,TPSV,
C BMSV AND BPSV (SEE S/R 'SAVE')

C

C TMSV,TPSV,BMSV,BPSV - 'HISTORY' OF TM,TP,BM,BP STORED AS IN S/R
C 'SAVE'

C

C TM,TP,BM,BP - BAREISS ITERATES (POS AND NEG INDICES) AND
C RESPECTIVE RHS'S

C

C K - CYCLE NO.

C IMB - (O/P) BOTTOM OF TOEP.PT.OF TM - SET TO N

C IPT - (O/P) TOP OF TOEP.PT.OF TP - SET TO 1

C N,LR- ORDER,ROW DIM OF MATRICES

REAL*8 TM(LR,N),TP(LR,N),BM(N),BP(N),TMSV(LR,N),TPSV(LR,N),
1 BMSV(LR,N),BPSV(LR,N)

IMT=K+1

IMB=N

CALL MOVMTX(TMSV(K+1,K+1),TM(IMT,K+1),1,N-K,LR)

CALL MOVMTX(TMSV(K+2,K+1),TM(IMT+1,1),N-K-1,1,LR)

CALL MOVMTX(BMSV(K+1,K+1),BM(IMT),N-K,1,LR)

IPT=1

IPB=N-K

CALL MOVMTX(TPSV(N-K,1),TP(IPB,1),1,N-K,LR)

CALL MOVMTX(TPSV(1,N-K),TP(IPT,N),N-K-1,1,LR)

CALL MOVMTX(BPSV(1,K+1),BP(IPT),N-K,1,LR)

C FILL IN ZERO-BANDS AND TOEP.PTS.OF TM AND TP

IF(K.EQ.0) GO TO 15

DO 10 J=1,K

10 TM(IMT,J)=0.

15 IMTP1=IMT+1

```

DO 20 I=IMTP1,IMB
DO 20 J=2,N
20 TM(I,J)=TM(I-1,J-1)

```

```

NMKP1=N-K+1
IF(K.EQ.0) GO TO 35
DO 30 J=NMKP1,N
30 TP(IPB,J)=0.
35 IPBM1=IPB-1
NM1=N-1
I=IPBM1
DO 50 II=IPT,IPBM1
DO 40 J=1,NM1
40 TP(I,J)=TP(I+1,J+1)
50 I=I-1
RETURN
END

```

SUBROUTINE UTROW(TM,BM,U,BU,K,IMT,ZD,N,LR)

```

C S/R TO GET NEXT ROW OF U-MATRIX (AND RHS) FOR BACK-SUBST
C
C TM - BAREISS ITERATE(-K)
C BM - CORRESP RHS
C U - (O/P) U.T. MATRIX FOR BACK-SUBST
C B - CORRESP RHS
C K - CYCLE NO.
C IMT- TOP OF TOEP.PT.OF TM
C ZD - (INTEGER) ZERO-BAND DISPL. - MUST BE LE.1
C N,LR-ORDER,ROW DIM OF MATRICES

```

```

REAL*8 TM(LR,N),BM(N),U(LR,N),BU(N)
INTEGER ZD

```

```

IF(ZD.GE.0) GO TO 20
WRITE(6,10) ZD,K,IMT
10 FORMAT(' ABORT - ZD.LT.0'/' ZD =',I3,' K =',I2,' IMT =',I2)
STOP

20 CALL MOVMTX(TM(IMT+ZD,1),U(K+1,1),1,N,LR)
BU(K+1)=BM(IMT+ZD)
RETURN
END

```

SUBROUTINE FINDPV(TI,L,ISEP,NENTS,TX,DELTA,K1,P,IERR)

```

C S/R TO FIND A PIVOT ACCORDING TO STRATEGY 2
C
C TI - VECTOR CONTAINING ELEMENTS TO BE SEARCHED
C L - LENGTH OF TI
C ISEP - SEPARATION BETW. ELEMENTS TO BE SEARCHED
C NENTS- NO.OF ELEMENTS TO BE SEARCHED
C TX - MAX ELT. OF TOEP.BLOCK BEING SEARCHED

```

```

C DELTA- THRESHOLD: PIVOT MUST BE GE.DELTA*TX
C K1 - (REAL*8) PIVOT PARAMETER : PIVOT MUST BE GE.K1*PREVIOUS
C                                     ELTS. SEARCHED
C P - (O/P) POSITION OF PIVOT (IF FOUND)
C IERR - 0 : PIVOT FOUND; 1 : PIVOT NOT FOUND

```

```

INTEGER P
REAL*8 TI(L),DELTA,K1,SUM,TX

```

```

IERR=0
SUM=0.
I=1

```

```

DO 20 P=1,NENTS
IF(DABS(TI(I))/TX.LT.DELTA) GO TO 10
IF(DABS(TI(I)).GE.K1*SUM) RETURN
10 SUM=SUM+DABS(TI(I))
20 I=I+ISEP

```

```

IERR=1
RETURN
END

```

```

SUBROUTINE ADJSMX(T,A,N,N2M1,LR,NSIZE,NCOL,NROW,EPS)

```

```

C S/R TO MAKE SOME ORDER-NSIZE SUBMATRICES OF AN N X N
C TOEP.MX. ILL-COND. BY ADJUSTING TOEP.DIAGS.
C
C T - INITIAL VALUE OF A(N,1)...A(1,1)...A(1,N)
C A - I/P TOEP.MX.
C N - ORDER OF A
C N2M1 - 2*N-1
C LR - ROW-DIM OF A
C NSIZE- SIZE OF ILL-COND S/MATRICES
C NCOL - NO.OF ILL-COND S/MATRICES ALONG COL, STARTING AT TOP
C NROW - NO.OF ILL-COND S/MATRICES ALONG ROW, STARTING AT LEFT
C EPS - QTY TO BE ADDED TO DIAG AFTER EACH BLOCK HAS BEEN
C MADE SINGULAR

```

```

REAL*8 T(N2M1),A(LR,N),EPS
REAL*8 WKA(860)

```

```

IF(NSIZE.EQ.0.OR.NCOL.EQ.0.OR.NROW.EQ.0) RETURN
N2P3=2*N+3
DO 4 I=1,NCOL
CALL SINGSM(A,N,N,LR,I+NSIZE-1,1,NSIZE,-1,1,WKA,N2P3,IERR)
T(N+NSIZE+I-2)=A(I+NSIZE-1,1)+EPS
4 CALL TOEPMX(T,A,N,N2M1,LR)

IF(NROW.EQ.1) RETURN
DO 6 J=2,NROW
CALL SINGSM(A,N,N,LR,1,J+NSIZE-1,NSIZE,1,-1,WKA,N2P3,IERR)
IF(IERR.NE.0) WRITE(6,5) IERR
5 FORMAT(' SINGSM ERROR CODE = ',I3)
T(N-NSIZE-J+2)=A(1,J+NSIZE-1)+EPS

```

```
6 CALL TOEPMX(T,A,N,N2M1,LR)
  RETURN
  END
```

SIZE OF ILL-COND BLOCK, NO.ALONG COL,ROW, DIST FROM SINGULARITY

4,3,2,2d-3

INPUT TOEPLITZ MATRIX T

5.000	-1.000	6.000	2.000	5.699	7.000	3.000	-5.000	-2.000	-7.000	1.000	10.000	-1.500
1.000	5.000	-1.000	6.000	2.000	5.699	7.000	3.000	-5.000	-2.000	-7.000	1.000	10.000
-3.000	1.000	5.000	-1.000	6.000	2.000	5.699	7.000	3.000	-5.000	-2.000	-7.000	1.000
12.757	-3.000	1.000	5.000	-1.000	6.000	2.000	5.699	7.000	3.000	-5.000	-2.000	-7.000
-19.661	12.757	-3.000	1.000	5.000	-1.000	6.000	2.000	5.699	7.000	3.000	-5.000	-2.000
28.373	-19.661	12.757	-3.000	1.000	5.000	-1.000	6.000	2.000	5.699	7.000	3.000	-5.000
-7.000	28.373	-19.661	12.757	-3.000	1.000	5.000	-1.000	6.000	2.000	5.699	7.000	3.000
-1.000	-7.000	28.373	-19.661	12.757	-3.000	1.000	5.000	-1.000	6.000	2.000	5.699	7.000
2.000	-1.000	-7.000	28.373	-19.661	12.757	-3.000	1.000	5.000	-1.000	6.000	2.000	5.699
1.000	2.000	-1.000	-7.000	28.373	-19.661	12.757	-3.000	1.000	5.000	-1.000	6.000	2.000
-6.000	1.000	2.000	-1.000	-7.000	28.373	-19.661	12.757	-3.000	1.000	5.000	-1.000	6.000
1.000	-6.000	1.000	2.000	-1.000	-7.000	28.373	-19.661	12.757	-3.000	1.000	5.000	-1.000
-0.500	1.000	-6.000	1.000	2.000	-1.000	-7.000	28.373	-19.661	12.757	-3.000	1.000	5.000

EXACT SOL OF $T^*X = B$ IS (1,1,...,1)

BAREISS ALG (BNA):

ERROR NORM = 0.2661D-01

ERROR VECTOR

0.9628D-02 0.6009D-02 -0.6716D-02 -0.7315D-04 0.2661D-01 0.1394D-01 -0.2368D-01 -0.2004D-01 0.4591D-02 0.5767D-02
0.1351D-02 -0.2150D-01 0.1127D-01

PIVOTED BAREISS ALG (PBA2):

ERROR NORM = 0.4330D-13

ERROR VECTOR

-0.3327D-13 -0.3478D-13 -0.5551D-14 0.4663D-14 -0.2981D-13 -0.6536D-14 0.2642D-13 0.4197D-13 0.3553D-14 -0.8243D-14
0.5107D-14 0.4330D-13 -0.5676D-14

READY

SIZE OF ILL-COND BLOCK, NO.ALONG COL,ROW, DIST FROM SINGULARITY
 ?
 4,3,3,2d-6

INPUT TOEPLITZ MATRIX T

5.000	-1.000	6.000	2.000	5.697	5.850	3.000	-5.000	-2.000	-7.000	1.000	10.000	-1.500
1.000	5.000	-1.000	6.000	2.000	5.697	5.850	3.000	-5.000	-2.000	-7.000	1.000	10.000
-3.000	1.000	5.000	-1.000	6.000	2.000	5.697	5.850	3.000	-5.000	-2.000	-7.000	1.000
12.755	-3.000	1.000	5.000	-1.000	6.000	2.000	5.697	5.850	3.000	-5.000	-2.000	-7.000
-19.656	12.755	-3.000	1.000	5.000	-1.000	6.000	2.000	5.697	5.850	3.000	-5.000	-2.000
28.361	-19.656	12.755	-3.000	1.000	5.000	-1.000	6.000	2.000	5.697	5.850	3.000	-5.000
-7.000	28.361	-19.656	12.755	-3.000	1.000	5.000	-1.000	6.000	2.000	5.697	5.850	3.000
-1.000	-7.000	28.361	-19.656	12.755	-3.000	1.000	5.000	-1.000	6.000	2.000	5.697	5.850
2.000	-1.000	-7.000	28.361	-19.656	12.755	-3.000	1.000	5.000	-1.000	6.000	2.000	5.697
1.000	2.000	-1.000	-7.000	28.361	-19.656	12.755	-3.000	1.000	5.000	-1.000	6.000	2.000
-6.000	1.000	2.000	-1.000	-7.000	28.361	-19.656	12.755	-3.000	1.000	5.000	-1.000	6.000
1.000	-6.000	1.000	2.000	-1.000	-7.000	28.361	-19.656	12.755	-3.000	1.000	5.000	-1.000
-0.500	1.000	-6.000	1.000	2.000	-1.000	-7.000	28.361	-19.656	12.755	-3.000	1.000	5.000

EXACT SOL OF T*X = B IS (1,1,...,1)

BAREISS ALG (BNA):

ERROR NORM = 0.1898D+00

ERROR VECTOR

0.3581D-01	0.9108D-02	0.4447D-02	0.1255D+00	0.4220D-01	-0.1530D+00	0.8745D-01	0.9942D-02	-0.1898D+00	-0.4101D-02
0.3750D-01	-0.6338D-01	-0.1216D+00							

PIVOTED BAREISS ALG (PBA2):

ERROR NORM = 0.6040D-13

ERROR VECTOR

0.8882D-14	-0.3536D-13	-0.3163D-13	-0.2642D-13	-0.6453D-14	-0.1586D-13	0.1443D-13	0.5884D-13	0.3020D-13	-0.4372D-14
-0.1994D-13	0.6040D-13	0.1021D-13							

READY

C TEST PROGRAM FOR PBA3 IS THE SAME AS THAT FOR PBA2, EXCEPT THAT
 C PBA3 IS CALLED INSTEAD OF PBA2
 C

SUBROUTINE PBA3(TO,B,X,DELTA,K1,N,LRO)

C
 C PIVOTED BAREISS ALG, STRATEGY 3 (SIMPLIFIED VERSION)
 C
 C TO - I/P TOEP.MX.; B - RHS; X - SOL(O/P); DELTA - PIVOT THRESHOLD;
 C K1 - (REAL*8) PIVOT PARAMETER (SEE BELOW); N - ORDER OF TO;
 C LRO - ROW DIM. OF TO
 C
 C N.B.: THIS IS A SLIGHTLY SIMPLIFIED VERSION OF THE PBA-3
 C DESCRIBED IN CH.5, IN THAT WE ONLY SEARCH BELOW THE ZERO-BAND
 C FOR A PIVOT (INSTEAD OF BOTH ABOVE AND BELOW). THIS PROGRAM
 C CAN EASILY BE EXTENDED TO USE PIVOTS ABOVE THE ZERO-BAND AS
 C WELL, BUT THE BACK-SUBST PROCEDURE MUST BE GENERALIZED IN
 C ACCORDANCE WITH THE REMARKS IN CH.5.
 C
 C OUTLINE OF ALG.:
 C 1. CARRY OUT BNA UNTIL AT STEP (-K) TM-PIVOT/TMAX.LT.DELTA,
 C OR STEP N-1 IS FINISHED, AT WHICH CASE, EXIT. IF
 C T-PIVOT/TMAX.LT.DELTA, DO:
 C
 C 2. FIND TM(P) P PLACES ABOVE THE ZERO-BAND (Z.B.) AND TM(-K-1-Q)
 C Q PLACES BELOW THE Z.B. SATISFYING :
 C (A) TM(.)/TMAX.GE.DELTA
 C (B) TM(.).GE.K1*(SUM OF ELEMENTS BETW. TM(.) AND Z.B.)
 C
 C 3. MOVE Z.B. DOWN Q+1 PLACES USING BACKTRACK PROC C (BPC).
 C
 C 4. DO P+Q B-CYCLES (BNA-CYCLES) TO GO ALONG BOTTOM OF BLOCK
 C OF ILL-COND SUBMATRICES
 C
 C 5. MOVE Z.B. UP Q+1 PLACES USING BPC TO RESTORE TO BAREISS
 C FORM (RBF).
 C
 C 6. GO TO 1.
 C
 C TEMPORARIES:
 C T - COPY OF TO
 C TM,TP - NEGATIVE-INDEX (N.I.) AND POSITIVE-INDEX (P.I.) BAREISS
 C ITERATES.
 C TMSV,TPSV - MATRICES TO SAVE P.I. AND N.I. ITERATES
 C BM,BP - RHS'S FOR TM,TP
 C BMSV,BPSV - MATRICES TO SAVE TM'S AND TP'S
 C U,BU - UPR.TRIANGLE AND CORRESP RHS FOR BACK-SUBST
 C TX - TM-MAX
 C IMT,IMB - TOP,BOTTOM ROW OF TOEP.PART OF TM
 C IPT,IPB - TP
 C ZD(INTEGER) - Z.B. DISPLACEMENT
 C P,Q - POSITIONS OF ACCEPTABLE PIVOTS ABOVE AND BELOW Z.B.

C MM,MP - 1ST ROWS OF TOEP PTS OF MPYR MATRICES
 C MMSV,MPSV - VECTORS TO SAVE PREVIOUS MM,MP

```

    INTEGER ZD,P,Q,PP1,QP1,QM1
    REAL*8 T0(LR0,N),B(N),X(N),T(20,20),TM(20,20),TP(20,20),
  1  BM(20),BP(20),TMSV(20,20),TPSV(20,20),BMSV(20,20),
  2  BPSV(20,20),U(20,20),BU(20)
    REAL*8 MM(20),MP(20),MPSV(20),MMSV(20)
    REAL*8 TX,DELTA,K1
  
```

```

    LR=20
    NM1=N-1
  
```

C INITIALIZATION

```

    DO 2 I=1,N
    DO 2 J=1,N
  2 T(I,J)=T0(I,J)
  
```

```

    CALL MOVMTX(T,TP,N,N,LR)
    CALL MOVMTX(T,TM,N,N,LR)
    CALL MOVMTX(B,BP,N,1,LR)
    CALL MOVMTX(B,BM,N,1,LR)
  
```

```

    CALL UTROW(TM,BM,U,BU,0,1,0,N,LR)
    CALL SAVE(TM,TP,BM,BP,TMSV,TPSV,BMSV,BPSV,0,N,1,N,LR)
  
```

```

    MP(1)=1.
    MM(1)=1.
    DO 5 I=2,N
    MP(I)=0.
  5 MM(I)=0.
  
```

```

    IPT=1
    IMB=N
    ZD=0
  
```

C MAIN LOOP. K IS CYCLE NO.

```

    K=0
  10 K=K+1
    IF(K.EQ.N) GO TO 500
  
```

C BNA-CYCLE

```

    CALL MOVMTX(MP,MPSV,N,1,LR)
    CALL MOVMTX(MM,MMSV,N,1,LR)
    CALL BCYCM(TM,BM,IMB,TP,BP,IPT,MM,MP,K,ZD,N,LR)
    CALL SAVE(TM,TP,BM,BP,TMSV,TPSV,BMSV,BPSV,K,IMB,IPT,N,LR)
    IMT=IMB+K-N+1
    CALL UTROW(TM,BM,U,BU,K,IMT,ZD,N,LR)
  
```

C PIVOT IF REQUIRED

```

    TX=TMAX(TM,IMT,IMB,N,LR)
    IF (DABS(TM(IMT+ZD,K+1)))/TX.LT.DELTA) GO TO 100
    GO TO 10
  
```

C PIVOTING PROCEDURE, STRATEGY 3


```

C FIND ACCEPTABLE PIVOTS ABOVE AND BELOW Z.B.
100 CALL FINDPV(TM(IMT,K+1),LR*(N-K),LR,N-K,TX,DELTA,K1,PP1,IERR)
    P=PP1-1
    CALL FINDPV(TM(IMT+1,1),N-K-1,1,N-K-1,TX,DELTA,K1,QP1,IERR)
    Q=QP1-1

C MAKE TM(-K-1-Q) AVAILABLE FOR PIVOTING BY USING BPC : GET
C ITERATES +,-(K-1), DO (R,C-CYCLE) Q TIMES, THEN ANOTHER
C C-CYCLE.
    K=K-1
    CALL RECOV(TMSV,TPSV,BMSV,BPSV,TM,TP,BM,BP,K,IMB,IPT,N,LR)
    CALL MOVMTX(MPSV,MP,N,1,LR)
    CALL MOVMTX(MMSV,MM,N,1,LR)
    DO 140 I=1,Q
        CALL RCYCM(T,B,TM,BM,IMB,TP,BP,IPT,MM,MP,K,ZD,N,LR)
140    CALL CCYCM(TM,BM,IMB,TP,BP,IPT,MM,MP,K,ZD,N,LR)
    K=K+1
    CALL CCYCM(TM,BM,IMB,TP,BP,IPT,MM,MP,K,ZD,N,LR)
    CALL UTROW(TM,BM,U,BU,K,IMB-N+K+1,ZD,N,LR)

C NEXT DO P+Q BNA-CYCLES (B-CYCLES)
    NBCYC=P+Q
    DO 150 I=1,NBCYC
        K=K+1
        CALL BCYCM(TM,BM,IMB,TP,BP,IPT,MM,MP,K,ZD,N,LR)
150    CALL UTROW(TM,BM,U,BU,K,IMB-N+K+1,ZD,N,LR)

C FINALLY, RESTORE TO BAREISS FORM USING BPC : DO AN A-CYCLE,
C (AN A,R-CYCLE) Q-1 TIMES, THEN ANOTHER A-CYCLE
    K=K+1
    CALL ACYCM(TM,BM,IMB,TP,BP,IPT,MM,MP,K,ZD,N,LR)
    CALL UTROW(TM,BM,U,BU,K,IMB-N+K+1,ZD,N,LR)

    K=K+1
    QM1=Q-1
    DO 160 I=1,QM1
        CALL ACYCM(TM,BM,IMB,TP,BP,IPT,MM,MP,K,ZD,N,LR)
160    CALL RCYCM(T,B,TM,BM,IMB,TP,BP,IPT,MM,MP,K,ZD,N,LR)
    CALL ACYCM(TM,BM,IMB,TP,BP,IPT,MM,MP,K,ZD,N,LR)
    CALL UTROW(TM,BM,U,BU,K,IMB-N+K+1,ZD,N,LR)
    GO TO 10

500 CALL BCKSUB(U,BU,X,N,LR)
    RETURN
    END

    SUBROUTINE BCYCM(TM,BM,IMB,TP,BP,IPT,MM,MP,K,ZD,N,LR)
C
C S/R TO DO A BAREISS CYCLE (B-CYCLE) & ACCUM MPYR MCS.

C TM,BM - NEG.INDEX ITERATE AND RHS
C IMB - INDEX OF LAST ROW IN TOEP.PART OF TM
C TP,TP - POS.INDEX ITERATE AND RHS
C IPT - INDEX OF 1ST ROW IN TOEP.PART OF TP

```

```

C MM,MP - (REAL*8) 1ST ROW OF TOEP.PT. OF POS. AND NEG.
C INDEX MPYR.MATRICES
C K - CYCLE TO BE COMPUTED
C ZD - (INTEGER) I/P ZERO-BAND DISPLACEMENT
C N,LR - ORDER, ROW DIM OF MATRICES

```

```

C
C PROCEDURE:
C 1. ELIM BELOW ZERO-BAND OF NEG.INDEX ITERATE
C 2. ELIM ABOVE ZERO-BAND OF POS.INDEX ITERATE

```

```

INTEGER ZD
REAL*8 M
REAL*8 TM(LR,N),BM(N),TP(LR,N),BP(N),MM(N),MP(N)

```

```

IMT=K+IMB-N
IPB=N-K+IPT
CALL BAROP(TP,BP,IPT,IPB-1,IPT+ZD,1, TM,BM,IMT+1,M,N,LR)
CALL MCALC(MP,0,MM,1,M,K+1)
CALL BAROP(TM,BM,IMT+1,IMB,IMT+1,K+1-ZD,TP,BP,IPT,M,N,LR)
CALL MCALC(MM,0,MP,0,M,K+1)
RETURN
END

```

```

SUBROUTINE CCYCM(TM,BM,IMB,TP,BP,IPT,MM,MP,K,ZD,N,LR)

```

```

C S/R TO MOVE ZERO-BAND DOWN (C-CYCLE) & ACCUM.MPYR.MCS.
C
C PARAMETERS - AS FOR S/R 'BCYCM'
C
C PROCEDURE:
C 1. ELIM BELOW ZERO-BAND OF POS.INDEX ITERATE
C 2. ELIM ABOVE ZERO-BAND OF NEG.INDEX ITERATE

```

```

INTEGER ZD
REAL*8 M
REAL*8 TM(LR,N),BM(N),TP(LR,N),BP(N),MM(N),MP(N)

```

```

IMT=K+IMB-N
IPB=N-K+IPT
CALL BAROP(TM,BM,IMT+1,IMB,IMT+ZD+1,1,TP,BP,IPT,M,N,LR)
CALL MCALC(MM,1,MP,0,M,K+1)
CALL BAROP(TP,BP,IPT,IPB-1,IPT+ZD+1,1, TM,BM,IMT,M,N,LR)
CALL MCALC(MP,0,MM,0,M,K+1)

```

```

ZD=ZD+1
IMB=IMB-1
RETURN
END

```

```

SUBROUTINE ACYCM(TM,BM,IMB,TP,BP,IPT,MM,MP,K,ZD,N,LR)

```

```

C
C S/R TO MOVE ZERO-BAND UP (A-CYCLE) & ACCUM.MPYR.MCS.
C

```

C PARAMETERS - AS FOR S/R 'BCYCM'
C

C PROCEDURE:

- C 1. ELIM ABOVE ZERO-BAND OF NEG. INDEX ITERATE
C 2. ELIM ABOVE ZERO-BAND OF POS. INDEX ITERATE

INTEGER ZD

REAL*8 M

REAL*8 TM(LR,N), BM(N), TP(LR,N), BP(N), MM(N), MP(N)

IMT=K+IMB-N

IPB=N-K+IPT

CALL BAROP(TP, BP, IPT, IPB-1, IPT, K+1-ZD, TM, BM, IMT+1, M, N, LR)

CALL MCALC(MP, 0, MM, 1, M, K+1)

CALL BAROP(TM, BM, IMT+1, IMB, IMT+1, K+2-ZD, TP, BP, IPT+1, M, N, LR)

CALL MCALC(MM, 0, MP, 1, M, K+1)

ZD=ZD-1

IPT=IPT+1

RETURN

END

SUBROUTINE RCYCM(T, B, TM, BM, IMB, TP, BP, IPT, MM, MP, K, ZD, N, LR)

C S/R TO PERFORM A REVERSE BAREISS-CYCLE

C

C PARAMETERS - T, B : I/P TOEP.MX. AND RHS. OTHERS: AS FOR S/R
C 'BCYCM' EXCEPT THAT K IS THE I/P CYCLE (K-1) IS THE CYCLE
C TO BE COMPUTED.

C

C PROCEDURE:

- C 1. GET PREVIOUS POS. INDEX MPYR & MPYR.MX. (1ST ROW OF
C TOEP.PT.)
C 2. EXECUTE STEP K IN REVERSE TO GET STEP (K-1).
C 3. GET PREVIOUS NEG. INDEX MPYR & MPYR.MX. (1ST ROW OF
C TOEP.PT.)
C 4. EXECUTE STEP (-K) IN REVERSE TO GET STEP (1-K).

INTEGER ZD

REAL*8 M

REAL*8 TM(LR,N), BM(N), TP(LR,N), BP(N), MM(N), MP(N)

REAL*8 T(LR,N), B(N)

IMT=IMB+K+1-N

IPB=IPT+N-K-1

CALL MPREV(MM, MP, M, K+1)

CALL BARREV(TM, BM, IMT, IMB, TP, BP, IPT, M, N, LR)

C RESTORE ROW IPB+1 OF ITERATE (K-1) USING TOEPLICITY AND
C THE MULTIPLIER IDENTITY

DO 10 J=2,N

10 TP(IPB+1, J)=TP(IPB, J-1)

TP(IPB+1, 1)=0.

```

BP(IPB+1)=0.
DO 20 I=1,K
TP(IPB+1,1)=TP(IPB+1,1) + MP(I)*T(N-K+I,1)
20 BP(IPB+1)=BP(IPB+1) + MP(I)*B(N-K+I)

```

```

CALL MMREV(MM,MP,M,K+1)
CALL BARREV(TP,BP,IPT,IPB,TM,BM,IMT,M,N,LR)

```

```

C RESTORE ROW IMT-1 OF ITERATE (1-K) USING TOEPLICITY AND
C THE MULTIPLIER IDENTITY

```

```

DO 30 J=2,N
30 TM(IMT-1,J-1)=TM(IMT,J)
TM(IMT-1,N)=0.
BM(IMT-1)=0.
DO 40 I=1,K
TM(IMT-1,N)=TM(IMT-1,N) + MM(I)*T(I,N)
40 BM(IMT-1)=BM(IMT-1) + MM(I)*B(I)

```

```

RETURN
END

```

```

SUBROUTINE BARREV(TS,BS,IS1,IS2,TD,BD,ID1,M,N,LR)

```

```

C
C PERFORMS A BAREISS-OPERATION IN REVERSE (REAL*8)

```

```

C TS,BS .... SOURCE MATRIX AND RHS
C IS1,IS2 .. 1ST AND LAST ROWS OF SOURCE-BLOCK
C TD,BD .... DESTINATION BLOCK AND RHS
C ID1 ..... 1ST ROW OF DESTINATION BLOCK
C M ..... MULTIPLIER (REAL*8)
C N ..... ORDER OF MATRICES
C LR ..... ROW-DIMENSION OF MATRICES

```

```

REAL*8 M,TS(LR,N),BS(N),TD(LR,N),BD(N)

```

```

ID=ID1
DO 20 IS=IS1,IS2
DO 10 J=1,N
10 TD(ID,J)=TD(ID,J) + M*TS(IS,J)
BD(ID)=BD(ID) + M*BS(IS)
20 ID=ID+1
C CALL DUMP(TS,TD,N,LR)
RETURN
END

```

```

SUBROUTINE MCALC(MS,SS,MD,SD,M,L)

```

```

C
C UPDATES MULTIPLIER VECTOR(REAL*8)
C
C MS IS THE SOURCE VECTOR, SS IS THE NO. OF R/SHIFTS
C FOR MS, MD IS THE DESTINATION VECTOR, SD IS THE NO.
C OF PRELIMINARY R/SHIFTS FOR MD, M IS THE MULTIPLIER,
C AND L IS THE LENGTH OF THE VECTORS.

```

C (SEE BELOW FOR DATA TYPES)

```
INTEGER SS,SD
REAL*8 M,MS(L),MD(L),WK(20)
```

```
CALL RSHIFT(MS,WK,SS,L)
CALL RSHIFT(MD,MD,SD,L)
DO 10 I=1,L
10 MD(I)=MD(I) - M*WK(I)
RETURN
END
```

SUBROUTINE RSHIFT(A,B,NS,L)

C
C RIGHT-SHIFTS ROW-VECTOR A BY NS PLACES, PUTTING THE RESULT
C IN B. L IS THE LENGTH OF THE VECTORS
C
C A AND B ARE DOUBLE-PRECISION

```
REAL*8 A(L),B(L)
```

```
I=L
10 IF(I.EQ.NS) GO TO 20
B(I)=A(I-NS)
I=I-1
GO TO 10
```

```
20 IF(NS.EQ.0) RETURN
DO 30 I=1,NS
30 B(I)=0.
RETURN
END
```

SUBROUTINE MPREV(MM,MP,M,KP1)

C
C S/R TO FIND MPYR & MPYR MX. (TOP OF TOEP.PT.) FOR STEP
C K-1.
C
C MM,MP - MPYR.MCS.(1ST ROW OF TOEP.PTS) FOR ITER.(-K),K.
C MPYR.MX.FOR STEP (K-1) IS OVERWRITTEN ON MP.
C M - MPYR(O/P) FOR STEP K-1
C KP1 - K+1

```
REAL*8 MM(KP1),MP(KP1),M
```

```
K=KP1-1
M= -MP(KP1)/MM(KP1)
DO 10 I=1,K
10 MP(I)=MP(I) + M*MM(I)
MP(KP1)=0.
RETURN
END
```

```
      SUBROUTINE MMREV(MM,MP,M,KP1)
C
C S/R TO FIND MPYR & MPYR MX. (TOP OF TOEP.PT) FOR STEP
C 1-K.
C
C MM,MP - MPYR.MCS.(1ST ROW OF TOEP.PTS) FOR ITER.(-K),K-1.
C       MPYR.MX.FOR STEP (1-K) IS OVERWRITTEN ON MM.
C M      - MPYR(O/P) FOR STEP (1-K)
C KP1    - K+1

      REAL*8 MM(KP1),MP(KP1),M

      K=KP1-1
      M= -MM(1)/MP(1)
      DO 10 I=1,K
10 MM(I)=MM(I+1) + M*MP(I+1)
      MM(KP1)=0.
      RETURN
      END

C SUBROUTINES UTROW, SAVE, RECOV, ADJSMX, BAROP, TMAX, MOVMTX AND
C BCKSUB ARE THE SAME AS IN PBA-2.
C
C
C
```

SIZE OF ILL-COND BLOCK, NO.ALONG COL,ROW, DIST FROM SINGULARITY

4,3,2,2d-3

INPUT TOEPLITZ MATRIX T

5.000	-1.000	6.000	2.000	5.699	7.000	3.000	-5.000	-2.000	-7.000	1.000	10.000	-1.500
1.000	5.000	-1.000	6.000	2.000	5.699	7.000	3.000	-5.000	-2.000	-7.000	1.000	10.000
-3.000	1.000	5.000	-1.000	6.000	2.000	5.699	7.000	3.000	-5.000	-2.000	-7.000	1.000
12.757	-3.000	1.000	5.000	-1.000	6.000	2.000	5.699	7.000	3.000	-5.000	-2.000	-7.000
-19.661	12.757	-3.000	1.000	5.000	-1.000	6.000	2.000	5.699	7.000	3.000	-5.000	-2.000
28.373	-19.661	12.757	-3.000	1.000	5.000	-1.000	6.000	2.000	5.699	7.000	3.000	-5.000
-7.000	28.373	-19.661	12.757	-3.000	1.000	5.000	-1.000	6.000	2.000	5.699	7.000	3.000
-1.000	-7.000	28.373	-19.661	12.757	-3.000	1.000	5.000	-1.000	6.000	2.000	5.699	7.000
2.000	-1.000	-7.000	28.373	-19.661	12.757	-3.000	1.000	5.000	-1.000	6.000	2.000	5.699
1.000	2.000	-1.000	-7.000	28.373	-19.661	12.757	-3.000	1.000	5.000	-1.000	6.000	2.000
-6.000	1.000	2.000	-1.000	-7.000	28.373	-19.661	12.757	-3.000	1.000	5.000	-1.000	6.000
1.000	-6.000	1.000	2.000	-1.000	-7.000	28.373	-19.661	12.757	-3.000	1.000	5.000	-1.000
-0.500	1.000	-6.000	1.000	2.000	-1.000	-7.000	28.373	-19.661	12.757	-3.000	1.000	5.000

EXACT SOL OF $TX = B$ IS (1,1,...,1)

BAREISS ALG (BNA):

ERROR NORM = 0.2661D-01

ERROR VECTOR

0.9628D-02	0.6009D-02	-0.6716D-02	-0.7315D-04	0.2661D-01	0.1394D-01	-0.2368D-01	-0.2004D-01	0.4591D-02	0.5767D-02
0.1351D-02	-0.2150D-01	0.1127D-01							

PIVOTED BAREISS ALG (PBA3):

ERROR NORM = 0.1377D-12

ERROR VECTOR

0.1377D-12	0.1443D-13	0.1310D-13	-0.3582D-13	-0.1216D-13	-0.2537D-13	-0.2380D-13	0.4774D-13	0.7305D-13	-0.1943D-15
-0.4677D-14	0.9770D-14	0.5218D-13							

READY

SIZE OF ILL-COMD BLOCK, NO.ALONG COL,ROW, DIST FROM SINGULARITY

?
4,3,3,24-6

INPUT TOEPLITZ MATRIX T

5.000	-1.000	6.000	2.000	5.697	5.850	3.000	-5.000	-2.000	-7.000	1.000	10.000	-1.500
1.000	5.000	-1.000	6.000	2.000	5.697	5.850	3.000	-5.000	-2.000	-7.000	1.000	10.000
-3.000	1.000	5.000	-1.000	6.000	2.000	5.697	5.850	3.000	-5.000	-2.000	-7.000	1.000
12.755	-3.000	1.000	5.000	-1.000	6.000	2.000	5.697	5.850	3.000	-5.000	-2.000	-7.000
-19.656	12.755	-3.000	1.000	5.000	-1.000	6.000	2.000	5.697	5.850	3.000	-5.000	-2.000
28.361	-19.656	12.755	-3.000	1.000	5.000	-1.000	6.000	2.000	5.697	5.850	3.000	-5.000
-7.000	28.361	-19.656	12.755	-3.000	1.000	5.000	-1.000	6.000	2.000	5.697	5.850	3.000
-1.000	-7.000	28.361	-19.656	12.755	-3.000	1.000	5.000	-1.000	6.000	2.000	5.697	5.850
2.000	-1.000	-7.000	28.361	-19.656	12.755	-3.000	1.000	5.000	-1.000	6.000	2.000	5.697
1.000	2.000	-1.000	-7.000	28.361	-19.656	12.755	-3.000	1.000	5.000	-1.000	6.000	2.000
-6.000	1.000	2.000	-1.000	-7.000	28.361	-19.656	12.755	-3.000	1.000	5.000	-1.000	6.000
1.000	-6.000	1.000	2.000	-1.000	-7.000	28.361	-19.656	12.755	-3.000	1.000	5.000	-1.000
-0.500	1.000	-6.000	1.000	2.000	-1.000	-7.000	28.361	-19.656	12.755	-3.000	1.000	5.000

EXACT SOL OF TXX = B IS (1,1,...,1)

BAREISS ALG (BNA):

ERROR NORM = 0.1898D+00

ERROR VECTOR

0.3581D-01	0.9108D-02	0.4447D-02	0.1255D+00	0.4220D-01	-0.1530D+00	0.8745D-01	0.9942D-02	-0.1898D+00	-0.4101D-02
0.3750D-01	-0.6338D-01	-0.1216D+00							

PIVOTED BAREISS ALG (PBA3):

ERROR NORM = 0.1195D-12

ERROR VECTOR

0.1195D-12	-0.1708D-13	0.5285D-13	-0.3805D-13	-0.4725D-13	-0.2838D-13	0.7105D-14	0.6395D-13	0.2753D-13	0.1599D-13
-0.1231D-13	0.1021D-13	0.3331D-13							

READY


```

C TEST PROGRAM FOR PIVOTED TOEPLITZ FACTORIZATION
C (PBAFAC)

C 1. MAKES UP N X N TOEP.MX. 'A' WITH A(N,1),...,A(1,1);...,
C ...,A(1,N) EQUAL TO T0(1),...,T0(2*N-1) RESPECTIVELY.
C 2. MAKES SPECIFIES SUB-MATRICES OF ORDER NSIZE ILL-COND.
C BY ADJUST RELEVANT TOEP.DIAGS.
C 3. CALCS. FACTORS L,U USING ADAPTED BAREISS ALG (ABA) AND
C EVALUATES L*U.
C 4. CALCS. L,U USING THE PIVOTING SEQ.RESULTING FROM PBA-2,
C AND EVALUATES L*U.

      INTEGER ABASEQ(13),PBASEQ(13)
      REAL*8 T(25),T0(25),A(20,20),L(20,20),U(20,20),LU(20,20)
      REAL*8 EPS
      DATA T0/-1.5,10.,1.,-7.,-2.,-5.,3.,7.,9.,2.,6.,-1.,5.,
1  1.,-3.,0.,0.,-4.,-7.,-1.,2.,1.,-6.,1.,-0.5/,
2  ABASEQ/2,2,2,2,2,2,2,2,2,2,2,2,0/,
3  PBASEQ/3,3,3,2,2,2,2,1,1,1,2,2,0/

C MATRIX DIMENSIONS
      ID1=20
      N=13
      N2M1=2*N-1
      NM1=N-1

C GEN. 'A' FROM ITS 1ST ROW AND COL, GET SPECS. FOR ILL-COND
C SUBMATRICES, AND ADJUST TOEP.DIAGS. ACCORDINGLY
      1 DO 2 I=1,N2M1
      2 T(I)=T0(I)
      CALL TOEPMX(T,A,N,N2M1,ID1)
      WRITE(6,3)
      3 FORMAT(/' SIZE OF ILL-COND BLOCK, NO.ALONG COL,ROW, DIST ',
1  'FROM SINGULARITY')
      READ(5,*) NSIZE,NCOL,NROW,EPS
      CALL ADJSMX(T,A,N,N2M1,ID1,NSIZE,NCOL,NROW,EPS)

      9 WRITE(6,10)
      10 FORMAT(/' INPUT TOEPLITZ MATRIX T')
      CALL PRNTMX(A,N,N,ID1)

C FACTOR T USING ABA AND PRINT OUT L,U AND L*U
      CALL PBAFAC(A,ABASEQ,L,U,N,ID1)
      WRITE (6,30)
      30 FORMAT(/' L-FACTOR USING ABA')
      CALL PRNTMX(L,N,N,ID1)
      WRITE (6,40)
      40 FORMAT(/' U-FACTOR USING ABA')
      CALL PRNTMX(U,N,N,ID1)
      CALL MULTMX(L,U,LU,N,N,N,ID1,ID1,ID1)
      WRITE (6,45)
      45 FORMAT(/' L*U (L,U FROM ABA). SHOULD BE T')
      CALL PRNTMX(LU,N,N,ID1)

C FACTOR T USING THE PIVOTING SEQ.FROM PBA-2 AND PRINT OUT
C L,U AND L*U
      CALL PBAFAC(A,PBASEQ,L,U,N,ID1)

```

```

WRITE(6,50)
50 FORMAT(///// ' L-FACTOR USING PBA-2')
CALL PRNTMX(L,N,N,ID1)
WRITE(6,60)
60 FORMAT(// ' U-FACTOR USING PBA-2')
CALL PRNTMX(U,N,N,ID1)
CALL MULTMX(L,U,LU,N,N,N,ID1,ID1,ID1)
WRITE (6,70)
70 FORMAT(// ' L*U (L,U FROM PBA-2). SHOULD BE T')
CALL PRNTMX(LU,N,N,ID1)

STOP
END

```

```

SUBROUTINE PBAFAC(TO,PSEQ,LO,UO,N,LR0)
C
C PIVOTED BAREISS-FACTORIZATION. IMPLEMENTS ALG.6.4.1 FOR
C A GIVEN SEQ. OF A,B OR C-CYCLES.
C
C TO - I/P TOEP.MX.
C PSEQ- (INTEGER) PIVOTING SEQ. (1:A-CYCLE,2:B-CYCLE
C                                     3:C-CYCLE)
C LO - O/P L-FACTOR
C UO - O/P U-FACTOR
C N,LR0-ORDER,ROW DIMS.OF MATRICES

C TEMPORARIES HAVE SAME NOTATION AS IN ALG.6.4.1
C
C INTEGER ZD,S(20),V(20),G,H,PSEQ(N)
C REAL*8 TO(LR0,N),T(20,20),TM(20,20),TP(20,20),
1 LO(LR0,N),UO(LR0,N),L(20,20),U(20,20),SM,SP
C REAL*8 TX,DELTA

LR=20
NM1=N-1

DO 2 I=1,N
DO 2 J=1,N
2 T(I,J)=TO(I,J)

C INITIALIZATION
CALL MOVMTX(T,TP,N,N,LR)
CALL MOVMTX(T,TM,N,N,LR)

C TOEPLITZ ROW-POINTERS AND MPYR MX SCALE FACTORS
IPT=1
IMB=N
SP=1.
SM=1.

C INITIALIZE S(1),V(1),G,H FOR THE GIVEN PIVOTING SEQUENCE
C PSEQ (SEE ALG.6.4.1)

NA=0

```

```

NC=0
DO 5 I=1,NM1
IF(PSEQ(I).EQ.1) NA=NA+1
IF(PSEQ(I).EQ.3) NC=NC+1
5 CONTINUE
S(1)=NA+1
V(1)=NC+1
G=NA
H=NC

C GET 1ST COL AND ROW OF L AND U RESPECTIVELY
CALL MOVMTX(TM(1+NA,1),U,1,N,LR)
DO 8 I=1,N
8 L(I,1)=TP(N-NC,N+1-I)/TP(N-NC,N+1-S(1))

ZD=0

C MAIN LOOP
DO 40 K=1,NM1
ICYC=PSEQ(K)
GO TO (10,20,30),ICYC
10 CALL BFA(TM,IMB,TP,IPT,L,U,K,ZD,SM,SP,S,V,G,H,N,LR)
GO TO 40
20 CALL BFB(TM,IMB,TP,IPT,L,U,K,ZD,SM,SP,S,V,G,H,N,LR)
GO TO 40
30 CALL BFC(TM,IMB,TP,IPT,L,U,K,ZD,SM,SP,S,V,G,H,N,LR)
40 CONTINUE

C COPY L,U INTO L0,U0 TO PASS TO CALLING PROG.
DO 50 I=1,N
DO 50 J=1,N
L0(I,J)=L(I,J)
50 U0(I,J)=U(I,J)

RETURN
END

SUBROUTINE BFB(TM,IMB,TP,IPT,L,U,K,ZD,SM,SP,S,V,
1 G,H,N,LR)

C
C S/R TO DO A B-CYCLE AND GET COL OF L AND ROW OF U
C ACCORDING TO ALG.6.4.1
C
C TM - NEG.INDEX BAREISS ITERATE
C IMB - BOTTOM OF TOEP.PT.OF TM
C TP - POS.INDEX BAREISS ITERATE
C IPT - TOP OF TOEP.PT.OF TP
C L,U - (O/P,REAL*8) L,U FACTORS
C K,ZD- BAREISS CYCLE, ZERO-BAND DISPLACEMENT
C SM,SP-SCALE FACTORS FOR NEG.,POS.INDEX MPYR MCS.
C S,V - PERMUTATION VECTORS (SEE ALG.6.4.1)
C G,H - NO.OF NON-ZEROS TO RIGHT,LEFT OF ZERO-BAND OF DESIRED
C ROW FOR USE IN FACTORS (SEE ALG.6.4.1)
C N,LR- ORDER,ROW DIM. OF MATRICES

```

C TEMPORARIES : LAMBDA,RHO - AS IN ALG.6.4.1 ; BZB,EZB -
 C BZB,EZB - BEGINNING, END OF ZERO-BAND; IMT,IPB - TOP,
 C BOTTOM OF TM,TP RESPEC.; SU - SCALE FACTOR FOR ROWS OF U.

INTEGER ZD,S(N),V(N),G,H,RHO,BZB,EZB
 REAL*8 MM,MP,SM,SP,SU
 REAL*8 TM(LR,N),BM(20),TP(LR,N),BP(20),L(LR,N),U(LR,N)

C DO B-CYCLE, UPDATE SCALE FACTORS AND PERM.VECTORS
 IMT=K+IMB-N
 IPB=N-K+IPT
 CALL BAROP(TP,BP,IPT,IPB-1,IPT+ZD,1,TM,BM,IMT+1,MM,N,LR)
 CALL BAROP(TM,BM,IMT+1,IMB,IMT+1,K+1-ZD,TP,BP,IPT,MP,N,LR)
 SU=SM
 SP=TP(IPT+ZD,1)*SM/TM(IMT+1,K+1-ZD)
 S(K+1)=IMAX(S,K)+1
 V(K+1)=IMAX(V,K)+1

C GET COL,ROW OF L,U ACCORDING TO ALG.6.4.1
 LAMBDA=IMT+1+ZD+H
 DO 10 J=1,N
 10 U(K+1,J)=TM(LAMBDA,J)/SU
 RHO=IPB-1+ZD-G
 DO 20 I=1,N
 20 L(I,K+1)=TP(RHO,N+1-I)/TP(RHO,N+1-S(K+1))

C CLEAR ELEMENTS THAT SHOULD BE ZERO IN L AND U
 BZB=H+1
 EZB=H+K
 DO 30 J=BZB,EZB
 30 U(K+1,J)=0.
 BZB=G+1
 EZB=G+K
 DO 40 I=BZB,EZB
 40 L(I,K+1)=0.
 RETURN
 END

SUBROUTINE BFC(TM,IMB,TP,IPT,L,U,K,ZD,SM,SP,S,V,G,H,
 1 N,LR)

C S/R TO DO A C-CYCLE AND GET COL OF L AND ROW OF U
 C ACCORDING TO ALG.6.4.1
 C
 C PARAMETERS AND TEMPORARIES - AS FOR BFB

INTEGER ZD,S(N),V(N),G,H,RHO,BZB,EZB
 REAL*8 MM,MP,SM,SP,SU
 REAL*8 TM(LR,N),BM(20),TP(LR,N),BP(20),L(LR,N),U(LR,N)

C DO C-CYCLE, UPDATE SCALE FACTORS AND PERM.VECTORS
 IMT=K+IMB-N
 IPB=N-K+IPT
 CALL BAROP(TM,BM,IMT+1,IMB,IMT+ZD+1,1,TP,BP,IPT,MP,N,LR)
 SU=-MP*SM

```

CALL BAROP(TP,BP,IPT,IPB-1,IPT+ZD+1,1, TM, BM, IMT, MM, N, LR)
SM=TM(IMT,K-ZD)*SP/TP(IPT+ZD+1,1)
ZD=ZD+1
IMB=IMB-1
S(K+1)=IMAX(S,K)+1
V(K+1)=IMIN(V,K)-1

C GET COL,ROW OF L,U ACCORDING TO ALG.6.4.1
  LAMBDA=IPT+ZD-1+H
  DO 10 J=1,N
10 U(K+1,J)=TP(LAMBDA,J)/SU
  RHO=IPB-1+ZD-G
  DO 20 I=1,N
20 L(I,K+1)=TP(RHO,N+1-I)/TP(RHO,N+1-S(K+1))

C CLEAR ELEMENTS THAT SHOULD BE ZERO IN L AND U
  BZB=H+1
  EZB=H+K
  DO 30 J=BZB,EZB
30 U(K+1,J)=0.
  BZB=G+1
  EZB=G+K
  DO 40 I=BZB,EZB
40 L(I,K+1)=0.

C UPDATE H
  H=H-1
  RETURN
  END

```

```

SUBROUTINE BFA(TM,IMB,TP,IPT,L,U,K,ZD,SM,SP,S,V,G,H,
1 N,LR)

```

```

C
C S/R TO DO AN A-CYCLE AND GET COL OF L AND ROW OF U
C ACCORDING TO ALG.6.4.1.
C
C PARAMETERS AND TEMPORARIES - AS IN BFB.

```

```

INTEGER ZD,S(N),V(N),G,H,RHO,BZB,EZB
REAL*8 MM,MP,SM,SP,SU
REAL*8 TM(LR,N),BM(20),TP(LR,N),BP(20),L(LR,N),U(LR,N)

```

```

C DO A-CYCLE, UPDATE SCALE FACTORS AND PERM.VECTORS
  IMT=K+IMB-N
  IPB=N-K+IPT
  CALL BAROP(TP,BP,IPT,IPB-1,IPT,K+1-ZD, TM, BM, IMT+1, MM, N, LR)
  SU=-MM*SP
  CALL BAROP(TM, BM, IMT+1, IMB, IMT+1, K+2-ZD, TP, BP, IPT+1, MP, N, LR)
  SP=TP(IPT+ZD,1)*SM/TM(IMT+1,K+2-ZD)
  ZD=ZD-1
  IPT=IPT+1
  S(K+1)=IMIN(S,K)-1
  V(K+1)=IMAX(V,K)+1

C GET COL,ROW OF L,U ACCORDING TO ALG.6.4.1

```

```

    LAMBDA=IMT+1+ZD+H
    DO 10 J=1,N
10  U(K+1,J)=TM(LAMBDA,J)/SU
    RHO=IMB+ZD-G+1
    DO 20 I=1,N
20  L(I,K+1)=TM(RHO,N+1-I)/TM(RHO,N+1-S(K+1))

C  CLEAR ELEMENTS THAT SHOULD BE ZERO IN L AND U
    BZB=H+1
    EZB=H+K
    DO 30 J=BZB,EZB
30  U(K+1,J)=0.
    BZB=G+1
    EZB=G+K
    DO 40 I=BZB,EZB
40  L(I,K+1)=0.

C  UPDATE G
    G=G-1
    RETURN
    END

```

```

    FUNCTION IMAX(KK,N)

```

```

C  FUNCTION TO FIND MAX INTEGER IN KK(N)
    DIMENSION KK(N)

    IMAX=KK(1)
    DO 10 I=1,N
    IF(KK(I).GT.IMAX) IMAX=KK(I)
10  CONTINUE
    RETURN
    END

```

```

    FUNCTION IMIN(KK,N)

```

```

C  FUNCTION OF FIND MIN INTEGER INKK(N)
    DIMENSION KK(N)

    IMIN=KK(1)
    DO 10 I=1,N
    IF(KK(I).LT.IMIN) IMIN=KK(I)
10  CONTINUE
    RETURN
    END

```

```

C  SUBROUTINES ADJSMX, BAROP AND MOVMTX ARE THE SAME AS IN
C  PBA2.

```

SIZE OF ILL-COMD BLOCK, NO.ALONG COL,ROW, DIST FROM SINGULARITY

7
4,3,2,5d-3

INPUT TOEPLITZ MATRIX T

5.000	-1.000	6.000	2.000	5.702	7.000	3.000	-5.000	-2.000	-7.000	1.000	10.000	-1.500
1.000	5.000	-1.000	6.000	2.000	5.702	7.000	3.000	-5.000	-7.000	-2.000	1.000	10.000
-3.000	1.000	5.000	-1.000	6.000	2.000	5.702	7.000	3.000	-5.000	-2.000	-7.000	1.000
12.760	-3.000	1.000	5.000	-1.000	6.000	2.000	5.702	7.000	3.000	-5.000	-2.000	-7.000
-19.668	12.760	-3.000	1.000	5.000	-1.000	6.000	2.000	5.702	7.000	3.000	-5.000	-2.000
28.391	-19.668	12.760	-3.000	1.000	5.000	-1.000	6.000	2.000	5.702	7.000	3.000	-5.000
-7.000	28.391	-19.668	12.760	-3.000	1.000	5.000	-1.000	6.000	2.000	5.702	7.000	3.000
-1.000	-7.000	28.391	-19.668	12.760	-3.000	1.000	5.000	-1.000	6.000	2.000	5.702	7.000
2.000	-1.000	-7.000	28.391	-19.668	12.760	-3.000	1.000	5.000	-1.000	6.000	2.000	5.702
1.000	2.000	-1.000	-7.000	28.391	-19.668	12.760	-3.000	1.000	5.000	-1.000	6.000	2.000
-6.000	1.000	2.000	-1.000	-7.000	28.391	-19.668	12.760	-3.000	1.000	5.000	-1.000	6.000
1.000	-6.000	1.000	2.000	-1.000	-7.000	28.391	-19.668	12.760	-3.000	1.000	5.000	-1.000
-6.500	1.000	-6.000	1.000	2.000	-1.000	-7.000	28.391	-19.668	12.760	-3.000	1.000	5.000

L-FACTOR USING ABA

1.	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.
0.	1.	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.
-1.	0.	1.	0.	0.	0.	0.	0.	0.	0.	0.	0.	0.
3.	-0.	-2.	1.	0.	0.	0.	0.	0.	0.	0.	0.	0.
-4.	2.	3.	-1.	1.	0.	0.	0.	0.	0.	0.	0.	0.
6.	-3.	-3.	2.	-1.	1.	0.	0.	0.	0.	0.	0.	0.
-1.	5.	0.	4189.	7172.	-1292786.	1.	0.	0.	0.	0.	0.	0.
-0.	-1.	3.	3355.	2762.	265213.	-0.	1.	0.	0.	0.	0.	0.
0.	-0.	-1.	-8680.	-17248.	3717772.	-3.	1.	1.	0.	0.	0.	0.
0.	0.	-0.	3041.	11381.	-3636350.	3.	-2.	1.	1.	0.	0.	0.
-1.	-0.	1.	-576.	-3148.	1128518.	-1.	1.	-2.	1.	0.	0.	0.
0.	-1.	-0.	-2412.	-3721.	563577.	-0.	-0.	0.	-15.	-2.	1.	0.
-0.	0.	-1.	-31.	1664.	-739137.	1.	-1.	-0.	10.	1.	0.	1.

U-FACTOR USING ABA

0.50D+01	-0.10D+01	0.60D+01	0.20D+01	0.57D+01	0.70D+01	0.30D+01	-0.50D+01	-0.20D+01	-0.70D+01	0.10D+01	0.10D+02	-0.15D+01
0.0	0.52D+01	-0.22D+01	0.56D+01	0.86D+00	0.43D+01	0.64D+01	0.40D+01	-0.46D+01	-0.60D+00	-0.72D+01	-0.10D+01	0.10D+02
0.0	0.0	0.88D+01	-0.23D+00	0.94D+01	0.59D+01	0.70D+01	0.37D+01	0.22D+01	-0.92D+01	-0.85D+00	-0.92D+00	-0.69D+00
0.0	0.0	0.0	-0.32D-02	-0.77D-02	-0.18D+01	0.65D+01	0.25D+02	0.15D+02	0.57D+01	-0.96D+01	-0.29D+02	-0.34D+01
0.0	0.0	0.0	0.0	0.45D-02	0.18D+01	-0.83D+01	-0.18D+02	0.96D+01	0.96D+01	0.15D+02	0.20D+02	-0.26D+02
0.0	0.0	0.0	0.0	0.0	0.41D-02	0.18D+01	-0.83D+01	-0.18D+02	0.96D+01	0.96D+01	0.15D+02	0.20D+02
0.0	0.0	0.0	0.0	0.0	0.0	0.23D+07	-0.11D+08	-0.24D+08	0.12D+08	0.12D+08	0.20D+08	0.25D+08
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.81D+04	-0.26D+05	-0.11D+06	-0.65D+05	-0.25D+05	0.39D+05
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-0.20D+04	-0.53D+04	-0.29D+04	-0.63D+03	0.27D+04
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.31D+02	-0.22D+03	-0.21D+02	-0.16D+02
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.24D+04	0.30D+03	0.18D+03	0.0
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.10D+02	0.49D+02
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-0.76D+02

LXU (L,U FROM ABA), SHOULD BE T

5.000	-1.000	6.000	2.000	5.702	7.000	3.000	-5.000	-2.000	-7.000	1.000	10.000	-1.500
1.000	5.000	-1.000	6.000	2.000	5.702	7.000	3.000	-5.000	-7.000	-2.000	1.000	10.000
-3.000	1.000	5.000	-1.000	6.000	2.000	5.702	7.000	3.000	-5.000	-2.000	-7.000	1.000
12.760	-3.000	1.000	5.000	-1.000	6.000	2.000	5.702	7.000	3.000	-5.000	-2.000	-7.000
-19.668	12.760	-3.000	1.000	5.000	-1.000	6.000	2.000	5.702	7.000	3.000	-5.000	-2.000
28.391	-19.668	12.760	-3.000	1.000	5.000	-1.000	6.000	2.000	5.702	7.000	3.000	-5.000
-7.000	28.391	-19.668	12.760	-3.000	1.000	5.000	-1.000	6.000	2.000	5.702	7.000	3.000
-1.000	-7.000	28.391	-19.668	12.760	-3.000	1.000	4.999	-1.007	6.001	5.701	5.700	7.004
2.000	-1.000	-7.000	28.391	-19.668	12.760	-3.000	1.000	5.001	-1.007	6.001	2.000	5.700
1.000	2.000	-1.000	-7.000	28.391	-19.668	12.761	-3.004	1.000	5.003	-1.003	5.992	2.001
-6.000	1.000	2.000	-1.000	-7.000	28.391	-19.668	12.761	-3.021	1.011	5.004	-0.986	5.990
1.000	-6.000	1.000	2.000	-1.000	-7.000	28.391	-19.669	12.764	-3.020	1.012	5.000	-0.986
-6.500	1.000	-6.000	1.000	2.000	-1.000	-7.000	28.391	-19.666	12.764	-3.020	1.000	4.990

L-FACTOR USING PBA-2

0.400	-1.750	0.687	-0.000	-0.001	-0.085	0.310	1.175	-4.716	2.738	1.000	0.0	0.0
1.200	0.688	-0.017	-0.000	-0.000	-0.000	-0.085	0.305	0.039	1.000	0.0	0.0	0.0
-0.200	-1.625	0.644	-0.000	-0.000	-0.000	-0.000	-0.084	1.000	0.0	0.0	0.0	0.0
1.000	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.200	1.000	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
-0.600	-4.175	1.000	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
2.552	6.944	-1.653	1.000	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
-3.934	-10.101	3.385	0.800	1.000	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
5.678	3.962	-1.075	-2.072	0.802	1.000	0.0	0.0	0.0	0.0	0.0	0.0	0.0
-1.400	-0.125	-0.015	0.726	-2.074	0.799	1.000	0.0	0.0	0.0	0.0	0.0	0.0
-0.200	-0.688	0.279	-0.137	0.726	-2.070	0.805	1.000	0.0	0.0	0.0	0.0	0.0
0.400	-0.188	-0.067	-0.576	-0.137	0.725	-2.077	0.775	-9.745	5.226	2.043	1.000	0.0
0.200	1.938	-0.708	-0.007	-0.576	-0.137	0.727	-2.040	15.324	-6.225	-3.141	0.490	1.000

U-FACTOR USING PBA-2

12.760	-3.000	1.000	5.000	-1.000	6.000	2.000	5.702	7.000	3.000	-5.000	-2.000	-7.000
-22.220	13.360	-3.200	0.0	5.200	-2.200	5.600	0.860	4.302	6.400	4.000	-4.600	-0.600
-55.722	34.311	0.0	0.0	22.110	-0.585	23.580	13.010	24.163	34.223	20.700	-17.405	-11.705
20.953	0.0	0.0	0.0	-0.003	-0.003	-0.007	-0.013	-1.794	6.480	24.909	15.271	5.680
0.0	0.0	0.0	0.0	-13.494	0.362	-14.387	-7.920	-10.368	-38.591	-67.271	-1.928	8.485
0.0	0.0	0.0	0.0	0.0	-13.518	0.338	-14.469	-21.210	37.787	146.365	46.055	40.204
0.0	0.0	0.0	0.0	0.0	0.0	-13.477	0.437	8.456	-104.393	-281.696	-49.521	-25.702
0.0	0.0	0.0	0.0	0.0	0.0	0.0	-13.691	-48.816	187.654	583.077	139.004	106.792
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-8.282	-0.326	39.058	8.010	15.138
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-75.611	-205.992	-40.707	-16.858
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	161.240	19.857	12.044
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	18.525	48.959
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-76.132

L&U (L,U FROM PBA-2). SHOULD BE T

5.000	-1.000	6.000	2.000	5.702	7.000	3.000	-5.000	-2.000	-7.000	1.000	10.000	-1.500
1.000	5.000	-1.000	6.000	2.000	5.702	7.000	3.000	-5.000	-2.000	-7.000	1.000	10.000
-3.000	1.000	5.000	-1.000	6.000	2.000	5.702	7.000	3.000	-5.000	-2.000	-7.000	1.000
12.760	-3.000	1.000	5.000	-1.000	6.000	2.000	5.702	7.000	3.000	-5.000	-2.000	-7.000
-19.668	12.760	-3.000	1.000	5.000	-1.000	6.000	2.000	5.702	7.000	3.000	-5.000	-2.000
28.391	-19.668	12.760	-3.000	1.000	5.000	-1.000	6.000	2.000	5.702	7.000	3.000	-5.000
-7.000	28.391	-19.668	12.760	-3.000	1.000	5.000	-1.000	6.000	2.000	5.702	7.000	3.000
-1.000	-7.000	28.391	-19.668	12.760	-3.000	1.000	5.000	-1.000	6.000	2.000	5.702	7.000
2.000	-1.000	-7.000	28.391	-19.668	12.760	-3.000	1.000	5.000	-1.000	6.000	2.000	5.702
1.000	2.000	-1.000	-7.000	28.391	-19.668	12.760	-3.000	1.000	5.000	-1.000	6.000	2.000
-6.000	1.000	2.000	-1.000	-7.000	28.391	-19.668	12.760	-3.000	1.000	5.000	-1.000	6.000
1.000	-6.000	1.000	2.000	-1.000	-7.000	28.391	-19.668	12.760	-3.000	1.000	5.000	-1.000
-0.500	1.000	-6.000	1.000	2.000	-1.000	-7.000	28.391	-19.668	12.760	-3.000	1.000	5.000

READY

SIZE OF ILL-COMD BLOCK, NO.ALONG COL,ROW, DIST FROM SINGULARITY

4,3,2,4d-4

INPUT TOEPLITZ MATRIX T

5.000	-1.000	6.000	2.000	5.698	7.000	3.000	-5.000	-2.000	-7.000	1.000	10.000	-1.500
1.000	5.000	-1.000	6.000	2.000	5.698	7.000	3.000	-5.000	-2.000	-7.000	1.000	10.000
-3.000	1.000	5.000	-1.000	6.000	2.000	5.698	7.000	3.000	-5.000	-2.000	-7.000	1.000
12.756	-3.000	1.000	5.000	-1.000	6.000	2.000	5.698	7.000	3.000	-5.000	-2.000	-7.000
-19.657	12.756	-3.000	1.000	5.000	-1.000	6.000	2.000	5.698	7.000	3.000	-5.000	-2.000
28.363	-19.657	12.756	-3.000	1.000	5.000	-1.000	6.000	2.000	5.698	7.000	3.000	-5.000
-7.000	28.363	-19.657	12.756	-3.000	1.000	5.000	-1.000	6.000	2.000	5.698	7.000	3.000
-1.000	-7.000	28.363	-19.657	12.756	-3.000	1.000	5.000	-1.000	6.000	2.000	5.698	7.000
2.000	-1.000	-7.000	28.363	-19.657	12.756	-3.000	1.000	5.000	-1.000	6.000	2.000	5.698
1.000	2.000	-1.000	-7.000	28.363	-19.657	12.756	-3.000	1.000	5.000	-1.000	6.000	2.000
-8.000	1.000	2.000	-1.000	-7.000	28.363	-19.657	12.756	-3.000	1.000	5.000	-1.000	6.000
1.000	-6.000	1.000	2.000	-1.000	-7.000	28.363	-19.657	12.756	-3.000	1.000	5.000	-1.000
-0.500	1.000	-6.000	1.000	2.000	-1.000	-7.000	28.363	-19.657	12.756	-3.000	1.000	5.000

L-FACTOR USING ABA

0.10D+01	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.20D+00	0.10D+01	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
-0.60D+00	0.77D+01	0.10D+01	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.26D+01	-0.86D+01	-0.17D+01	0.10D+01	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
-0.39D+01	0.17D+01	0.28D+01	-0.65D+00	0.10D+01	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.57D+01	-0.27D+01	-0.31D+01	0.21D+01	-0.65D+00	0.10D+01	0.0	0.0	0.0	0.0	0.0	0.0	0.0
-0.14D+01	0.52D+01	0.17D+01	0.52D+00	0.89D+00	-0.20D+00	0.10D+01	0.0	0.0	0.0	0.0	0.0	0.0
-0.20D+00	-0.14D+01	0.30D+01	0.42D+00	0.35D+00	0.40D+00	-0.20D+00	0.10D+01	0.0	0.0	0.0	0.0	0.0
0.40D+00	-0.12D+00	-0.11D+01	-0.11D+00	-0.22D+00	0.59D+00	-0.29D+01	0.80D+00	0.10D+01	0.0	0.0	0.0	0.0
0.20D+00	0.42D+00	-0.14D+00	0.38D+00	0.14D+00	-0.57D+00	0.28D+01	-0.21D+01	0.96D+00	0.10D+01	0.0	0.0	0.0
-0.12D+01	-0.38D+01	0.10D+01	-0.72D+04	-0.39D+00	0.18D+00	-0.87D+00	0.74D+00	-0.18D+01	-0.38D+01	0.10D+01	0.0	0.0
0.20D+00	-0.11D+01	-0.30D+00	-0.30D+00	-0.46D+00	0.89D+00	-0.44D+00	-0.14D+00	0.40D+00	0.38D+01	-0.16D+01	0.10D+01	0.0
-0.10D+00	0.17D+00	-0.57D+00	-0.38D+03	0.21D+00	-0.12D+00	0.57D+00	-0.58D+00	-0.63D+01	-0.16D+01	0.91D+00	-0.59D+00	0.10D+01

U-FACTOR USING ABA

0.50D+01	-0.10D+01	0.60D+01	0.20D+01	0.57D+01	0.70D+01	0.30D+01	-0.50D+01	-0.20D+01	-0.70D+01	0.10D+01	0.10D+02	-0.15D+01
0.0	0.52D+01	-0.22D+01	0.56D+01	0.86D+00	0.43D+01	0.64D+01	0.40D+01	-0.46D+01	-0.60D+00	-0.72D+01	-0.10D+01	0.10D+02
0.0	0.0	0.88D+01	-0.23D+00	0.94D+01	0.59D+01	0.70D+01	0.37D+01	0.22D+01	-0.92D+01	-0.85D+00	-0.92D+00	-0.69D+00
0.0	0.0	0.0	-0.26D+03	-0.61D+03	-0.18D+01	0.65D+01	0.25D+02	0.15D+02	0.57D+01	-0.96D+01	-0.29D+02	-0.34D+01
0.0	0.0	0.0	0.0	0.36D+03	0.18D+01	-0.83D+01	-0.18D+02	0.96D+01	0.96D+01	0.15D+02	0.20D+02	-0.26D+02
0.0	0.0	0.0	0.0	0.0	0.33D+03	0.18D+01	-0.83D+01	-0.18D+02	0.96D+01	0.96D+01	0.15D+02	0.20D+02
0.0	0.0	0.0	0.0	0.0	0.0	0.36D+03	-0.17D+10	-0.38D+10	0.20D+10	0.20D+10	0.31D+10	0.40D+10
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.94D+05	-0.34D+06	-0.13D+07	-0.80D+06	-0.30D+06	0.50D+06
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-0.24D+04	-0.61D+04	-0.34D+04	-0.66D+03	0.32D+04
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-0.90D+02	-0.34D+03	-0.68D+02	0.39D+02
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-0.63D+03	-0.53D+02	0.25D+03
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.22D+03	0.21D+03
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.77D+02

L&U (L,U FROM ABA). SHOULD BE T

5.000	-1.000	6.000	2.000	5.698	7.000	3.000	-5.000	-2.000	-7.000	1.000	10.000	-1.500
1.000	5.000	-1.000	6.000	2.000	5.698	7.000	3.000	-5.000	-2.000	-7.000	1.000	10.000
-3.000	1.000	5.000	-1.000	6.000	2.000	5.698	7.000	3.000	-5.000	-2.000	-7.000	1.000
12.756	-3.000	1.000	5.000	-1.000	6.000	2.000	5.698	7.000	3.000	-5.000	-2.000	-7.000
-19.657	12.756	-3.000	1.000	5.000	-1.000	6.000	2.000	5.698	7.000	3.000	-5.000	-2.000
28.363	-19.657	12.756	-3.000	1.000	5.000	-1.000	6.000	2.000	5.698	7.000	3.000	-5.000
-7.000	28.363	-19.657	12.756	-3.000	1.000	5.000	-1.000	6.000	2.000	5.698	7.000	3.000
-1.000	-7.000	28.363	-19.657	12.756	-3.000	1.000	5.000	-1.000	6.000	2.000	5.698	7.000
2.000	-1.000	-7.000	28.363	-19.657	12.756	-3.000	1.000	5.000	-1.000	6.000	2.000	5.698
1.000	2.000	-1.000	-7.000	28.363	-19.657	-0.020	-71.102	-154.282	16.236	-26.186	141.396	217.704
-6.000	1.000	2.000	-1.000	-7.000	28.363	9.574	-12.370	-85.376	-93.672	114.662	11.193	161.581
1.000	-6.000	1.000	2.000	-1.000	-7.000	18.773	15.983	-2.174	-107.122	-127.085	98.330	-1.185
-0.500	1.000	-6.000	1.000	2.000	-1.000	-9.306	10.183	-5.259	0.598	-110.330	-113.523	120.090

L-FACTOR USING PBA-2

0.400	-1.750	0.688	-0.000	-0.000	-0.085	0.310	1.190	-4.776	2.729	1.000	0.0	0.0
1.200	0.688	-0.017	-0.000	-0.000	-0.000	-0.085	0.310	0.010	1.000	0.0	0.0	0.0
-0.200	-1.625	0.645	-0.000	-0.000	-0.000	-0.000	-0.085	1.000	0.0	0.0	0.0	0.0
1.000	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
0.200	1.000	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
-0.600	-4.174	1.000	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
2.561	6.949	-1.653	1.000	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
-3.031	-10.032	3.333	0.802	1.000	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
5.673	3.990	-1.076	-2.074	0.802	1.000	0.0	0.0	0.0	0.0	0.0	0.0	0.0
-1.400	-0.125	-0.015	0.727	-2.074	0.802	1.000	0.0	0.0	0.0	0.0	0.0	0.0
-0.200	-0.688	0.279	-0.138	0.727	-2.074	0.802	1.000	0.0	0.0	0.0	0.0	0.0
0.400	-0.188	-0.067	-0.577	-0.138	0.727	-2.075	0.800	-9.843	5.199	2.040	1.000	0.0
0.200	1.938	-0.708	-0.007	-0.577	-0.138	0.727	-2.072	15.420	-6.187	-3.137	0.487	1.000

U-FACTOR USING PBA-2

12.756	-3.000	1.000	5.000	-1.000	6.000	2.000	5.698	7.000	3.000	-5.000	-2.000	-7.000
-22.208	13.356	-3.200	0.0	5.200	-2.200	5.600	0.860	4.298	6.400	4.000	-4.600	-0.600
-56.672	34.283	0.0	0.0	22.103	-0.582	23.572	13.010	24.137	34.209	20.694	-17.399	-11.704
20.905	0.0	0.0	0.0	-0.000	-0.000	-0.001	-0.001	-1.784	6.479	24.902	15.266	5.674
0.0	0.0	0.0	0.0	-13.477	0.355	-14.373	-7.931	-10.339	-38.549	-67.258	-1.962	8.475
0.0	0.0	0.0	0.0	0.0	-13.479	0.353	-14.379	-21.179	37.778	146.367	46.087	40.168
0.0	0.0	0.0	0.0	0.0	0.0	-13.476	0.361	8.539	-104.427	-282.146	-49.759	-26.801
0.0	0.0	0.0	0.0	0.0	0.0	0.0	-13.493	-48.890	187.421	583.187	139.322	100.879
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-8.345	-0.079	39.854	8.215	15.280
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-76.378	-208.421	-41.193	-16.910
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	160.776	19.912	11.960
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	18.563	48.981
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-75.936

L*U (L,U FROM PBA-2). SHOULD BE T

5.000	-1.000	6.000	2.000	5.698	7.000	3.000	-5.000	-2.000	-7.000	1.000	10.000	-1.500
1.000	5.000	-1.000	6.000	2.000	5.698	7.000	3.000	-5.000	-2.000	-7.000	1.000	10.000
-3.000	1.000	5.000	-1.000	6.000	2.000	5.698	7.000	3.000	-5.000	-2.000	-7.000	1.000
12.756	-3.000	1.000	5.000	-1.000	6.000	2.000	5.698	7.000	3.000	-5.000	-2.000	-7.000
-19.657	12.756	-3.000	1.000	5.000	-1.000	6.000	2.000	5.698	7.000	3.000	-5.000	-2.000
28.363	-19.657	12.756	-3.000	1.000	5.000	-1.000	6.000	2.000	5.698	7.000	3.000	-5.000
-7.000	28.363	-19.657	12.756	-3.000	1.000	5.000	-1.000	6.000	2.000	5.698	7.000	3.000
-1.000	-7.000	28.363	-19.657	12.756	-3.000	1.000	5.000	-1.000	6.000	2.000	5.698	7.000
2.000	-1.000	-7.000	28.363	-19.657	12.756	-3.000	1.000	5.000	-1.000	6.000	2.000	5.698
1.000	2.000	-1.000	-7.000	28.363	-19.657	12.756	-3.000	1.000	5.000	-1.000	6.000	2.000
-6.000	1.000	2.000	-1.000	-7.000	28.363	-19.657	12.756	-3.000	1.000	5.000	-1.000	6.000
1.000	-6.000	1.000	2.000	-1.000	-7.000	28.363	-19.657	12.756	-3.000	1.000	5.000	-1.000
-0.500	1.000	-6.000	1.000	2.000	-1.000	-7.000	28.363	-19.657	12.756	-3.000	1.000	5.000

READY

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C TEST PROGRAM FOR PTZA1 (PIVOTED BAREISS ALG, STRATEGY 1:
C SIMPLE 2-CHOICE STRATEGY)

C 1. MAKES UP N X N TOEP.MX. 'A' WITH A(N,1),...,A(1,1),...,
C ...,A(1,N) EQUAL TO T0(1),...,T0(2*N-1) RESPECTIVELY.
C 2. MAKES SPECIFIED SUB-MATRIX OF ORDER NSIZE ILL-COND.
C BY ADJUST RELEVANT TOEP.DIAG.
C 3. INVERTS 'A' USING TRENCH-ZOHAR ALG (TZA) AND PIVOTED TZA,
C STRATEGY 1 (PTZA1), AND CALCULATES ERROR MATRIX =
C ('A'*INVERSE-'A')-IDENTITY.

REAL*8 T(11),A(20,20),AI(20,20),ERR(20,20),ERRSZ,EPS,
1 RSUM,MMA(2)
DATA T/3.,2.,6.,1.,4.,8.,4.,0.,5.,3.,1./,MMA/1D70,1D3/

C MATRIX DIMENSIONS
ID1=20
N=6
N2M1=2*N-1
NM1=N-1

C GEN. 'A' FROM ITS 1ST ROW AND COL, GET SPECS. FOR ILL-COND
C SUBMATRIX, AND ADJUST TOEP.DIAG. ACCORDINGLY
CALL TOEPMX(T,A,N,N2M1,ID1)
WRITE(6,3)
3 FORMAT('/' SIZE OF ILL-COND BLOCK, DIST FROM SINGULARITY')
READ(5,*) NSIZE,EPS
CALL ADJSMX(T,A,N,N2M1,ID1,NSIZE,1,1,EPS)

9 WRITE(6,10)
10 FORMAT('///' INPUT TOEPLITZ MATRIX T')
CALL PRNTMX(A,N,N,ID1)

C INVERT A AND PRINT ERROR MATRIX (A*A.INV - IDENTITY) FOR
C TZA (WHEN MMA=1D70) AND PTZA-1
DO 50 IMX=1,2
CALL PTZA1(A,AI,MMA(IMX),N,ID1)
IF(IMX.EQ.1) WRITE(6,22)
22 FORMAT('///' *** RESULTS FOR TRENCH-ZOHAR ALG.***')
IF(IMX.EQ.2) WRITE(6,23)
23 FORMAT('///' *** RESULTS FOR PIVOTED TRENCH-ZOHAR ALG., ',
1 'STRATEGY 1 ***')
WRITE(6,24)
24 FORMAT('///' INVERSE OF T')
CALL PRNTMX(AI,N,N,ID1)

CALL MULTMX(A,AI,ERR,N,N,N,ID1,ID1,ID1)
DO 25 I=1,N
25 ERR(I,I)=ERR(I,I)-1.
WRITE(6,27)
27 FORMAT('///' ERROR MATRIX = T*T.INVERSE - IDENTITY')
DO 28 I=1,N
28 WRITE(6,29) (ERR(I,J),J=1,N)
29 FORMAT(1X,6D12.3)

ERRSZ=0.
DO 32 I=1,N

```

```

      RSUM=0.
      DO 30 J=1,N
30      RSUM=RSUM+DABS(ERR(I,J))
      IF(RSUM.GT.ERRSZ) ERRSZ=RSUM
32      CONTINUE
      WRITE(6,35) ERRSZ
35  FORMAT(/' INFINITY-NORM OF ERROR MATRIX = ',D12.3)
50  CONTINUE
      STOP
      END

```

SUBROUTINE PTZA1(T, TI, MMAX, N, LR)

```

C
C S/R TO INVERT A TOEPLITZ MATRIX USING THE PIVOTED TRENCH-ZOHAR
C ALGORITHM, STRATEGY 1.
C
C T - I/P TOEPLITZ MATRIX; TI - (O/P) INVERSE OF T;
C MMAX - PIVOTING THRESHOLD FOR MULTIPLIER ;
C N,LR - ORDER, ROW-DIMENSION OF T AND TI
C
C BRIEF DESCRIPTION OF PTZA1.
C FOLLOWS ALG.6.9.1, WITH THE SAME NOTATION. EXECUTES
C TRENCH-ZOHAR ALG (ACTUALLY, ALTERNATIVE BAREISS SYMMETRIC
C ALGORITHM) UNTIL MULTIPLIER EXCEEDS MMAX. IF THE OTHER
C MULTIPLIER IS SMALLER, DO THE SIMPLE PIVOTING PROCEDURE.
C THIS IS EXACTLY ANALOGOUS TO THE SIMPLE PIVOTING
C PROCEDURE IN PBA1, WITH THE FIRST ROWS OF THE TOEPLITZ
C PART OF THE MUTIPLIER MATRICES BEING ACCUMULATED, AND ONLY
C THOSE DIAGS OF THE BAREISS ITERATES ABOVE (TMA, NEG.INDEX,
C TPA, POS.INDEX) AND BELOW (TMB, NEG.INDEX, TPB,
C POS.INDEX) THE ZERO-BANDS BEING CALCULATED, USING EITHER
C THE BAREISS RECURSION OR THE MULTIPLIER MATRICES.
C
C OTHER TEMPORARIES:
C K - BAREISS CYCLE NO.
C MM,MP- 1ST ROWS OF TOEP.PTS.OF NEG., POS.INDEX MULTIPLIER
C MATRICES
C MMSV,ETC: TEMPORARY AREA FOR SAVING MM, ETC.
C
      REAL*8 T(LR,N), TI(LR,N)
      REAL*8 MMAX, TMA, TMB, TPA, TPB, MM(20), MP(20), M
      REAL*8 MMSV(20), TMASV, TMBSV, MPSV(20), TPASV, TPBSV
      REAL*8 INPROD

      NM1=N-1
      NM2=N-2

C TZA INITIALIZATION : K,MM,MP, TM, TP
      K=0
      MP(1)=1.
      MM(1)=1.
      DO 2 I=2,N
      MP(I)=0.
2      MM(I)=0.
      TMA=T(1,1)

```

```

TMB=T(2,1)
TPA=T(1,2)
TPB=T(1,1)

```

C NORMAL TZA LOOP, WITH PIVOT SELECTION TEST. K IS CYCLE NO.

C

C STEP (-K)

```

5 K=K+1
TMA SV=TMA
TMBSV=TMB
CALL MOVMTX(MM,MMSV,N,1,N)
M=TMB/TPB
CALL MCALC(MP,0,MM,1,M,N)
TMA=TMA-M*TPA
IF(K.NE.NM1) TMB=INPROD(MM,1,T,1,N,LR)

```

C STEP (K)

```

TPASV=TPA
TPBSV=TPB
CALL MOVMTX(MP,MPSV,N,1,N)
M=TPA/TMASV
CALL MCALC(MMSV,1,MP,0,M,N)
TPB=TPB-M*TMBSV
IF(K.EQ.NM1) GO TO 200
TPA=INPROD(MP,0,T,K+2,N,LR)

```

C

C PIVOT IF MULTIPLIER INVOLVING TPA IS TOO LARGE AND IF

C ALTERNATE MULTIPLIER IS SMALLER, ELSE CONTINUE WITH

C TZA

```

IF(DABS(TPA/TMA).LE.MMAX.OR.DABS(TPA/TMA).LE.DABS(TPB/TMB))
1 GO TO 5

```

C *** END OF TZA LOOP ***

C *** SIMPLE PIVOTING PROCEDURE ***

C 1. RE-DO STEP K: WITH TMB AS PIVOT, ELIMINATE TPB

```

TPA=TPASV
TPB=TPBSV
CALL MOVMTX(MPSV,MP,N,1,LR)
M=TPB/TMB
CALL MCALC(MM,1,MP,0,M,N)
TPB=INPROD(MP,1,T,1,N,LR)

```

C

C 2. WITH TPA AS PIVOT, ELIMINATE TMA

```

M=TMA/TPA
CALL MCALC(MP,0,MM,0,M,N)
TMB=TMB-M*TPB
TMA=INPROD(MM,0,T,K+2,N,LR)

```

C 3. RESTORE TO BAREISS FORM BY USING TMA TO ELIM. TPA

```

M=TPA/TMA
CALL MCALC(MM,0,MP,1,M,N)
TPA=INPROD(MP,0,T,K+3,N,LR)
K=K+1

```

```

      GO TO 5
C
C *** END OF PIVOTING PROCEDURE ***
C
C CALC 1ST ROW AND COL OF TI.
200 DO 210 I=1,N
      TI(N-I+1,1)=MM(I)/TMA
210 TI(1,I)=MP(I)/TPB
C
C USE ZOHAR'S RECURSION TO FILL TI TO SECONDARY DIAG
      DO 215 I=1,NM2
      NMIM1=N-I-1
      DO 215 J=1,NMIM1
215 TI(I+1,J+1)=TI(I,J) +
      1 (TI(I+1,1)*TI(1,J+1)-TI(1,N-I+1)*TI(N-J+1,1))/TI(1,1)
C
C FILL IN REST OF TI USING PERSYMMETRY
      DO 220 I=2,N
      NMIP2=N-I+2
      DO 220 J=NMIP2,N
220 TI(I,J)=TI(N-J+1,N-I+1)
      RETURN
      END

```

```

      DOUBLE PRECISION FUNCTION INPROD(V,NS,A,IC,N,LR)
C
C FUNCTION TO FIND THE INNER PRODUCT OF V(N), DOWNSHIFTED
C NS PLACES, WITH COLUMN IC OF MATRIX A.
C N AND LR ARE THE ORDER AND ROW-DIMENSION OF A
C
      REAL*8 V(N),A(LR,N)

      NMNS=N-NS
      INPROD=0.
      DO 10 I=1,NMNS
      INPROD=INPROD + V(I)*A(I+NS,IC)
10 CONTINUE
      RETURN
      END

```

```

C SUBROUTINES ADJSMX AND MOVMTX ARE AS IN PBA2, AND
C SUBROUTINES MCALC AND RSHIFT ARE AS IN PBA3
C
C
C

```

SIZE OF ILL-COND BLOCK, DIST FROM SINGULARITY

?
3,5d-13

INPUT TOEPLITZ MATRIX T

8.000	4.000	1.000	6.000	2.000	3.000
4.000	8.000	4.000	1.000	6.000	2.000
-34.000	4.000	8.000	4.000	1.000	6.000
5.000	-34.000	4.000	8.000	4.000	1.000
3.000	5.000	-34.000	4.000	8.000	4.000
1.000	3.000	5.000	-34.000	4.000	8.000

*** RESULTS FOR TRENCH-ZOHAR ALG.***

INVERSE OF T

0.042	-0.010	-0.022	-0.001	-0.004	0.004
0.011	0.018	-0.002	-0.025	-0.002	-0.004
0.002	0.030	0.005	0.002	-0.025	-0.001
0.034	-0.001	0.010	0.005	-0.002	-0.022
-0.131	0.173	-0.001	0.030	0.018	-0.010
0.214	-0.131	0.034	0.002	0.011	0.042

ERROR MATRIX = T*T.INVERSE - IDENTITY

-0.320D-01	-0.316D-01	-0.135D-01	-0.116D-01	-0.679D-02	-0.330D-02
-0.605D-01	-0.160D-02	-0.110D-01	-0.979D-02	-0.575D-02	-0.122D-01
-0.935D-01	0.224D-01	0.835D-02	0.397D-03	-0.371D-03	-0.123D-01
-0.179D+00	0.956D-02	0.754D-01	0.215D-01	0.178D-01	-0.157D-01
0.416D-01	-0.109D+00	-0.602D-01	0.871D-01	0.185D-01	0.260D-01
0.126D+00	-0.118D+00	-0.929D-01	-0.832D-01	0.739D-01	0.250D-01

INFINITY-NORM OF ERROR MATRIX = 0.520D+00

*** RESULTS FOR PIVOTED TRENCH-ZOHAR ALG., STRATEGY 1 ***

INVERSE OF T

0.041	-0.008	-0.021	0.000	-0.004	0.004
0.008	0.018	0.000	-0.025	-0.001	-0.004
0.006	0.028	0.003	0.004	-0.025	0.000
0.039	-0.003	0.009	0.003	0.000	-0.021
-0.120	0.170	-0.003	0.028	0.018	-0.008
0.213	-0.120	0.039	0.006	0.008	0.041

ERROR MATRIX = T*T.INVERSE - IDENTITY

-0.278D-16	0.222D-15	0.0	0.162D-15	0.651D-16	0.278D-16
0.291D-15	-0.472D-15	0.111D-15	-0.226D-16	0.128D-15	0.971D-16
0.444D-15	-0.208D-15	0.222D-15	0.165D-16	-0.173D-16	0.971D-16
-0.167D-15	-0.555D-15	0.141D-15	0.0	0.295D-16	-0.668D-16
-0.301D-14	0.555D-15	0.860D-15	0.191D-15	0.444D-15	-0.278D-15
0.178D-14	-0.197D-14	-0.888D-15	0.112D-14	0.694D-16	0.666D-15

INFINITY-NORM OF ERROR MATRIX = 0.649D-14

READY

SIZE OF ILL-COND BLOCK, DIST FROM SINGULARITY

?
3,1d-8

INPUT TOEPLITZ MATRIX T

8.000	4.000	1.000	6.000	2.000	3.000
4.000	8.000	4.000	1.000	6.000	2.000
-34.000	4.000	8.000	4.000	1.000	6.000
5.000	-34.000	4.000	8.000	4.000	1.000
3.000	5.000	-34.000	4.000	8.000	4.000
1.000	3.000	5.000	-34.000	4.000	8.000

*** RESULTS FOR TRENCH-ZOHAR ALG.***

INVERSE OF T

0.041	-0.008	-0.021	0.000	-0.004	0.004
0.008	0.018	0.000	-0.025	-0.001	-0.004
0.006	0.028	0.003	0.004	-0.025	0.000
0.039	-0.003	0.009	0.003	0.000	-0.021
-0.120	0.170	-0.003	0.028	0.018	-0.008
0.213	-0.120	0.039	0.006	0.008	0.041

ERROR MATRIX = T*T.INVERSE - IDENTITY

-0.851D-07	-0.159D-05	-0.107D-06	-0.272D-06	-0.228D-06	0.280D-07
-0.198D-05	0.151D-06	-0.502D-06	-0.148D-06	-0.836D-07	-0.435D-06
-0.106D-05	0.475D-06	-0.583D-06	-0.984D-07	0.203D-07	-0.105D-06
-0.408D-05	0.273D-06	0.224D-05	-0.513D-06	0.313D-06	-0.373D-06
-0.135D-04	0.441D-06	0.603D-05	0.250D-05	0.850D-06	-0.981D-06
0.103D-04	-0.104D-04	-0.768D-05	0.704D-05	0.164D-05	0.209D-05

INFINITY-NORM OF ERROR MATRIX = 0.392D-04

*** RESULTS FOR PIVOTED TRENCH-ZOHAR ALG., STRATEGY 1 ***

INVERSE OF T

0.041	-0.008	-0.021	0.000	-0.004	0.004
0.008	0.018	0.000	-0.025	-0.001	-0.004
0.006	0.028	0.003	0.004	-0.025	0.000
0.039	-0.003	0.009	0.003	0.000	-0.021
-0.120	0.170	-0.003	0.028	0.018	-0.008
0.213	-0.120	0.039	0.006	0.008	0.041

ERROR MATRIX = T*T.INVERSE - IDENTITY

-0.167D-15	-0.971D-16	-0.416D-16	0.486D-16	-0.147D-16	-0.139D-16
-0.278D-15	-0.444D-15	0.139D-16	-0.416D-16	0.538D-16	-0.278D-16
0.222D-15	-0.153D-15	0.0	0.278D-16	-0.460D-16	0.555D-16
0.416D-15	-0.472D-15	-0.989D-16	-0.278D-16	-0.425D-16	-0.199D-16
-0.622D-14	0.148D-14	0.273D-14	-0.153D-15	0.444D-15	-0.652D-15
0.200D-14	-0.334D-14	-0.126D-14	0.334D-14	-0.264D-15	0.888D-15

INFINITY-NORM OF ERROR MATRIX = 0.117D-13

READY

SIZE OF ILL-COND BLOCK, DIST FROM SINGULARITY
?
3,1d-15

INPUT TOEPLITZ MATRIX T

8.000	4.000	1.000	6.000	2.000	3.000
4.000	8.000	4.000	1.000	6.000	2.000
-34.000	4.000	8.000	4.000	1.000	6.000
5.000	-34.000	4.000	8.000	4.000	1.000
3.000	5.000	-34.000	4.000	8.000	4.000
1.000	3.000	5.000	-34.000	4.000	8.000

*** RESULTS FOR TRENCH-ZOHAR ALG.***

INVERSE OF T

-0.008	0.004	-0.001	-0.004	0.003	-0.000
0.038	-0.026	0.006	0.010	-0.012	0.003
-0.107	0.086	-0.024	0.012	0.010	-0.004
0.162	-0.181	0.084	-0.024	0.006	-0.001
0.036	0.145	-0.181	0.086	-0.026	0.004
-0.017	0.036	0.162	-0.107	0.038	-0.008

ERROR MATRIX = T*T.INVERSE - IDENTITY

-0.244D-01	-0.672D+00	0.624D+00	-0.271D+00	0.810D-01	-0.159D-01
0.192D+00	-0.866D-01	-0.727D+00	0.391D+00	-0.124D+00	0.132D-01
0.140D+00	0.911D-01	-0.105D-01	-0.381D+00	0.156D+00	-0.514D-01
-0.347D+00	0.432D+00	-0.185D+00	-0.126D+01	0.457D+00	-0.116D+00
0.468D+01	-0.247D+01	0.372D+00	-0.202D+00	-0.142D+01	0.146D+00
-0.593D+01	0.737D+01	-0.240D+01	0.379D+00	0.155D-01	-0.103D+01

INFINITY-NORM OF ERROR MATRIX = 0.171D+02

*** RESULTS FOR PIVOTED TRENCH-ZOHAR ALG., STRATEGY 1 ***

INVERSE OF T

0.041	-0.008	-0.021	0.000	-0.004	0.004
0.008	0.018	0.000	-0.025	-0.001	-0.004
0.006	0.028	0.003	0.004	-0.025	0.000
0.039	-0.003	0.009	0.003	0.000	-0.021
-0.120	0.170	-0.003	0.028	0.018	-0.008
0.213	-0.120	0.039	0.006	0.008	0.041

ERROR MATRIX = T*T.INVERSE - IDENTITY

-0.583D-15	0.569D-15	-0.139D-16	0.181D-15	0.616D-16	-0.278D-16
0.555D-15	-0.888D-15	0.236D-15	0.226D-16	0.114D-15	0.139D-15
0.0	-0.180D-15	0.0	0.859D-16	0.694D-17	0.833D-16
0.555D-15	-0.680D-15	-0.114D-15	-0.694D-16	0.156D-16	0.408D-16
-0.665D-14	0.119D-14	0.294D-14	-0.191D-15	0.444D-15	-0.666D-15
0.289D-14	-0.390D-14	-0.171D-14	0.359D-14	-0.361D-15	0.888D-15

INFINITY-NORM OF ERROR MATRIX = 0.133D-13

READY

```

C TEST PROGRAM FOR FTO1, WHICH ORTHOGONALLY-TRIANGULARIZES A
C TOEPLITZ MATRIX IN  $O(N^2)$  OPERATIONS. FTO1 USES THE
C GILL-GOLUB-MURRAY-SAUNDERS ORTHOGONAL-UPDATE ALGORITHM
C AND THE SHIFT-INVARIANCE OF THE TOEPLITZ MATRIX.
C
C TEST PROCEDURE: (1) GENERATE TOEP.MX. 'A' WITH 1ST ROW
C AND COL FROM 'T'. (2) REDUCE TOEP.MX. WITH HOUSEHOLDER
C TRANSFORMS (O/P OVERWRITES 'A') TO UPR.TRIANGULAR FORM
C (3) CALL FTO1 TO PRODUCE UPR.TRIANGLE IN 'R'.
C
C OTHER VARIABLES: N=MATRIX ORDER, ID1=ROW DIM.OF MATRICES
C
REAL*8 T(19),A(10,10),R(10,10),W1(10),W2(10),W3(10),
1 W4(10),W5(10),W6(10),W7(10),W8(10),W9(10),W10(10),W11(10),
2 W12(10),W13(10),W14(10),W15(10),W16(10),W17(10)
DATA T/2.2,3.7,-5.9,-1.1,-2.8,6.3,-4.9,8.0,
1 6.2,18.6,-14.7,2.5,2.9,4.2,-8.6,-1.5,2.0,
2 0.2,-1.5/

ID1=10
N=10
N2M1=2*N-1
NM1=N-1

CALL TOEPMX(T,A,N,N2M1,ID1)
WRITE(6,10)
10 FORMAT('//////////' INPUT TOEPLITZ MATRIX T')
CALL PRNTMX(A,N,N,ID1)

C REDUCE TOEPLITZ MATRIX BY HOUSEHOLDER TRANSFORMS
CALL HOUTRI(A,N,ID1)
DO 30 I=2,N
IM1=I-1
DO 30 J=1,IM1
30 A(I,J)=0.

WRITE(6,40)
40 FORMAT(' REDUCED MATRIX USING HOUSEHOLDER TRANSFORMS')
CALL PRNTMX(A,N,N,ID1)

C REDUCE TOEPLITZ MATRIX USING FTO1
CALL FTO1(T,R,W1,W2,W3,W4,W5,W6,W7,W8,W9,W10,W11,W12,
1 W13,W14,W15,W16,W17,N,N2M1,ID1)
DO 15 I=2,N
IM1=I-1
DO 15 J=1,IM1
15 R(I,J)=0.

WRITE(6,20)
20 FORMAT(' REDUCED MATRIX AS CALCULATED BY FTO1')
CALL PRNTMX(R,N,N,ID1)
STOP
END

SUBROUTINE FTO1(T,R,CPhiUP,SPHIUP,CPhiDN,SPHIDN,CTheup,

```

```

1  STHEUP,CTHEDN,STHEDN,RM,RD1,RDJ,RT1,RTJ,QN,SIGD,SIGT,
2  Z,N,N2M1,ID1)
C
C S/R TO TRIANGULARIZE A TOEPLITZ MATRIX USING GILL ET AL'S
C ORTHOGONAL UPDATE ALG. AND SHIFT-INVARIANCE. FOLLOWS ALG.
C 7.3.1, AND THE VARIABLE NOTATION IS THE SAME.
C
C
C PARAMETERS
C T.....VECTOR CONTAINING 1ST ROW AND COL OF TOEPLITZ MATRIX
C         TO BE TRIANGULARIZED. IF N IS THE ORDER OF THE MATRIX,
C         ORDER OF STORAGE IS (1,N),(1,N-1),..., (1,1),(2,1),...
C         ..., (N,1)
C R.....CONTAINS UPPER-TRIANGULAR MATRIX PRODUCED BY THE
C         ORTHOGONALIZATION. NOTE THAT R(I,J), I.GT.J HAVE
C         NOT BEEN ZEROED
C CPHIUP)
C SPHIUP) OUTPUT COSINES AND SINES OF GIVENS ROTATIONS USED
C CPHIDN) IN FTO1. NOTATION FOLLOWS ALG.7.3.1, WITH THE
C SPHIDN)..FOLLOWING CONVENTION
C CTHEUP) 1ST LETTER. C-COSINE, S-SINE
C STHEUP) NEXT 3 LETTERS. PHI-PHI, THE-THETA
C CTHEDN) LAST 2 LETTERS. UP-UP ARROW, DN-DOWN ARROW
C STHEDN)
C RM.....TEMP. VECTOR TO STORE COL. OF R(SUPERSCRPT N-1)
C RD1.....O/P VECTOR CONTAINING 1ST COL OF R-DOT
C RDJ.....TEMP. VECTOR TO STORE COL.J OF R-DOT.
C RT1.....O/P VECTOR CONTAINING 1ST COL OF R-TILDE
C RTJ.....TEMP. VECTOR TO STORE COL.J OF R-TILDE
C QN.....O/P VECTOR CONTAINING LAST ROW OF Q
C SIGD.....O/P VECTOR CONTAINING VALUES OF SIGMA-DOT
C SIGT.....O/P VECTOR CONTAINING VALUES OF SIGMA-TILDE
C Z.....O/P VECTOR (= T-TRANSPOSE * (T(2,1),...,T(N,1))
C                                     TRANSPOSE )
C N.....ORDER OF TOEPLITZ MATRIX AND R, AND LENGTH OF
C         VECTORS CPHIUP,...,Z.
C N2M1.....2*N-1. T MUST BE AT LEAST THIS LENGTH
C ID1.....ROW-DIMENSION OF R
C
C GENERAL REMARKS ON CALLING FTO1. THE ONLY INPUTS REQUIRED
C ARE T,N,N2M1 AND ID1. THE MAIN OUTPUT IS IN R. THE OTHER
C 17 VECTORS ARE BY-PRODUCTS AND TEMPORARIES OF FTO1, AND
C NORMALLY THE USER ONLY ALLOCATES SPACE FOR THESE VECTORS
C WITHOUT DOING ANYTHING MORE WITH THEM. HOWEVER, THE GIVENS
C TRANSFORM VECTORS CPHIUP,...,STHEDN CAN BE USED TO GENERATE
C THE Q-MATRIX EXPLICITLY USING ALG.7.4.1.
C
C QUICK OUTLINE OF FTO1
C -----
C DEFINE
C RM = R(SUPERSCRPT N-1) = ORTHOGONAL TRIANGULAR FACTOR
C         OF LEADING SUBMATRIX OF T.
C QM = Q(SUPERSCRPT N-1) = OTHOGONAL MATRIX SUCH THAT
C         LEADING SUBMATRIX OF T = QM*RM
C R-DOT = MATRIX WITH 1ST ROW = T(1,1..N), REST OF 1ST
C         COLUMN = QM-TRANSPOSE * T(2..N,1),
C         TRAILING SUBMATRIX = LEADING SUBMATRIX OF T.

```

```

C R-TILDE = R + Q(N,1..N)*(T(N,1..N-1),0)
C
C R-DOT MAY BE TRANSFORMED TO R USING GILL ET AL'S RANK-1
C ORTHOGONAL UPDATE, WITH AN UPSWEEP AND A DOWNSWEEP OF
C GIVENS TRANSFORMS (ANGLES PHI-UP AND PHI-DOWN). SIMILARLY,
C R-TILDE MAY BE TRANSFORMED TO AN UPPER-TRIANGULAR MATRIX
C WITH RM AS ITS LEADING SUBMATRIX (GIVENS ANGLES THETA-UP
C AND THETA-DOWN)
C SUPPOSE THAT RM(.J-1), R(.J-1) AND Q(N,1..J-1) ARE KNOWN.
C THEN R-DOT(.J) CAN BE CONSTRUCTED. PERFORM A GILL UPSWEEP
C AND DOWNSWEEP ON R-DOT(.J), YIELDING R(.J). CALCULATE
C Q(N,J) USING THE RELATION Q(N,1..J)*R(1..J,J)=T(N,J),
C AND CALCULATE R-TILDE(.J) FROM THE DEFINITION. PERFORM
C A GILL UPSWEEP AND DOWNSWEEP ON R-TILDE(.J), YIELDING
C RM(.J). THIS COMPLETES THE BASIC RECURSION. NOTE THAT
C THE GILL SWEEPS AND THE CALCULATION OF Q(N,J) REQUIRE
C ONLY O(N) OPERATIONS, SO THE WHOLE ALGORITHM REQUIRES
C ONLY O(N**2) OPERATIONS. DETAILS OF THE CALCULATION
C OF THE GILL ROTATIONS, WHICH PROCEEDS IN TANDEM WITH
C THE BASIC RECURSION ARE GIVEN IN ALG.7.3.1.

      REAL*8 T(N2M1),R(ID1,N),CPHIUP(N),SPHIUP(N),CPHIDN(N),SPHIDN(N)
1      ,CTHEUP(N),STHEUP(N),CTHEDN(N),STHEDN(N),RM(N),RD1(N),RDJ(N),
2      RT1(N),RTJ(N),SIGD(N),SIGT(N),QN(N),Z(N)
      REAL*8 EPS

C INITIALIZATION

      M=N-1
      EPS=10.**(-5)

C CALC R(1,1) AND RM(1,1) USING NORM-INVARIANCE
      RM(1)=0.
      DO 10 I=1,M
10 RM(1)=RM(1)+T(I-1+N)**2
      R(1,1)=RM(1)+T(N2M1)*T(N2M1)
      R(1,1)=DSQRT(R(1,1))
      RM(1)=DSQRT(RM(1))

C GET R-DOT(1,1),(1,2),(2,2) AND SIGMA-DOT(1),(2), WHERE SIGMA-DOT(I)
C IS NORM(R-DOT(I..N,1))
      RD1(1)=T(N)
      RDJ(1)=T(N-1)
      RDJ(2)=RM(1)
      SIGD(1)=R(1,1)
      SIGD(2)=DSQRT(SIGD(1)**2 - RD1(1)**2)

C OTHER INITIALIZATION - PHIDN(1),THEDN(1),Q(N,1),R-TILDE(1,1), AND
C SIGMA-TILDE(1),(2) WHERE SIGMA-TILDE(I)=NORM(R-TILDE(I..N,1))
      CPHIDN(1)=RD1(1)/SIGD(1)
      SPHIDN(1)=SIGD(2)/SIGD(1)
      QN(1)=T(N2M1)/R(1,1)
      RT1(1)=R(1,1)-QN(1)*T(N2M1)
      SIGT(1)=RM(1)
      SIGT(2)=DSQRT(SIGT(1)**2 - RT1(1)**2)
      CTHEDN(1)=RT1(1)/SIGT(1)
      STHEDN(1)=SIGT(2)/SIGT(1)

```



```
C Z=TRANPOSE OF PRINC SUBMX OF T * T(2..N,1)
  DO 28 I=1,M
  Z(I)=0.
  DO 28 J=1,M
  28 Z(I)=Z(I)+T(J-I+N)*T(J+N)

C*****MAIN LOOP - CALC R(.J) AND RM(.J)*****

  J=2
C
C PHASE I - CALC R(.J) FROM R-DOT(.J)
C
  30 RDJ(1)=T(1-J+N)
  DO 40 I=2,J
  40 RDJ(I)=RM(I-1)
C RM CONTAINS RM(.J-1)
C
C BACK-SUBST FOR R-DOT(J,1) IN EQN. RM(TRANS)*R-DOT(.1)=Z
  RD1(J)=Z(J-1)
  IF(J.EQ.2) GO TO 60
  JM2=J-2
  DO 50 I=1,JM2
  50 RD1(J)=RD1(J)-RM(I)*RD1(I+1)
  60 RD1(J)=RD1(J)/RM(J-1)

C IF J=N, CHECK THAT RD1(N) IS POSITIVE. IF NOT, RD(N.) WAS
C REVERSED IN SIGN IN THE PREVIOUS STEP - SO RDJ(N) MUST BE
C REPLACED BY -RDJ(N).
  IF(J.NE.N) GO TO 65
  IF(RD1(N).LT.0) RDJ(N)=-RDJ(N)
  GO TO 70

C NEXT PHIUP
  65 SIGD(J+1)=DSQRT(SIGD(J)**2-RD1(J)**2)
  CPHIUP(J)=RD1(J)/SIGD(J)
  SPHIUP(J)=SIGD(J+1)/SIGD(J)
C SINGULARITY CHECK
  IF(DABS(SPHIUP(J)).GE.EPS) GO TO 68
  WRITE(6,66)
  66 FORMAT(' I/P MATRIX NUMERICALLY SINGULAR - ERROR EXIT')
  RETURN

C UP-SWEEP ON R-DOT(.J)
  68 RDJ(J+1)=0.
  CALL GIVENS(RDJ(J),RDJ(J+1),CPHIUP(J),SPHIUP(J))
  70 IF(J.EQ.2) GO TO 90
  JM1=J-1
  I=JM1
  DO 80 II=2,JM1
  CALL GIVENS(RDJ(I),RDJ(I+1),CPHIUP(I),SPHIUP(I))
  80 I=I-1

C DOWN-SWEEP ON R-DOT(.J), EXCLUDING LAST PHIDN
  90 DO 100 I=1,JM1
  CALL GIVENS(RDJ(I),RDJ(I+1),CPHIDN(I),SPHIDN(I))
  100 R(I,J)=RDJ(I)
```

```

C  CALC AND APPLY LAST PHIDN IN DOWN-SWEEP (N/A IF J=N)
  IF(J.NE.N) GO TO 110
  R(N,N)=RDJ(N)
  RETURN
110 R(J,J)=DSQRT(RDJ(J)**2 + RDJ(J+1)**2)
  CPHIDN(J)=RDJ(J)/R(J,J)
  SPHIDN(J)=RDJ(J+1)/R(J,J)

C  PHASE II - CALC RM(.J) FROM R-TILDE(.J)

C  CALC Q(N,J) USING Q(N,1..J)*R(1..J,J)=T(N,J)
  QN(J)=T(N-J+N)
  DO 120 I=1,JM1
120 QN(J)=QN(J)-QN(I)*R(I,J)
  QN(J)=QN(J)/R(J,J)

C  NEXT THEUP
  RT1(J)= -T(N2M1)*QN(J)
  SIGT(J+1)=DSQRT(SIGT(J)**2 - RT1(J)**2)
  CTHEUP(J)=RT1(J)/SIGT(J)
  STHEUP(J)=SIGT(J+1)/SIGT(J)

C  SINGULARITY CHECK
  IF(DABS(STHEUP(J)).GE.EPS) GO TO 124
  WRITE(6,123)
123 FORMAT(' LDG SUBMX NUMERICALLY SINGULAR - ERROR EXIT',
  1      /' REMEDY - AUGMENT I/P MATRIX AND RERUN')
  RETURN

C  CALC R-TILDE(1..J,J)
124 DO 125 I=1,J
125 RTJ(I)=R(I,J)-QN(I)*T(N-J+N)

C  UP-SWEEP ON R-TILDE(.J)
  RTJ(J+1)=SIGT(J+1)*T(N-J+N)/T(N2M1)
  CALL GIVENS(RTJ(J),RTJ(J+1),CTHEUP(J),STHEUP(J))
  IF(J.EQ.2) GO TO 140
  I=JM1
  DO 130 II=2,JM1
  CALL GIVENS(RTJ(I),RTJ(I+1),CTHEUP(I),STHEUP(I))
130 I=I-1

C
C  DOWN-SWEEP ON R-TILDE(.J), EXCLUDING LAST THEDN
140 DO 150 I=1,JM1
  CALL GIVENS(RTJ(I),RTJ(I+1),CTHEDN(I),STHEDN(I))
150 RM(I)=RTJ(I)

C
C  CALC AND APPLY LAST THEDN
  RM(J)=DSQRT(RTJ(J)**2 + RTJ(J+1)**2)
  CTHEDN(J)=RTJ(J)/RM(J)
  STHEDN(J)=RTJ(J+1)/RM(J)

  J=J+1
  GO TO 30

C
C*****END OF MAIN LOOP*****

```

INPUT TOEPLITZ MATRIX T

18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100	-5.900	3.700	2.200
-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100	-5.900	3.700
2.500	-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100	-5.900
2.900	2.500	-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100
4.200	2.900	2.500	-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800
-8.600	4.200	2.900	2.500	-14.700	18.600	6.200	8.000	-4.900	6.300
-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600	6.200	8.000	-4.900
2.000	-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600	6.200	8.000
0.200	2.000	-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600	6.200
-1.500	0.200	2.000	-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600

REDUCED MATRIX USING HOUSEHOLDER TRANSFORMS

-26.016	7.747	-0.780	8.378	-17.201	9.468	2.254	5.784	-9.204	3.869
0.0	-25.554	5.698	2.817	1.874	-13.458	10.343	5.309	2.054	-7.868
0.0	0.0	-27.275	7.360	-0.716	4.318	-12.849	11.746	2.957	2.031
0.0	0.0	0.0	-25.782	2.909	-0.052	6.139	-10.894	10.403	2.651
0.0	0.0	0.0	0.0	-22.936	2.543	-2.887	4.710	-11.662	10.939
0.0	0.0	0.0	0.0	0.0	-21.736	1.355	-3.165	4.339	-6.728
0.0	0.0	0.0	0.0	0.0	0.0	-20.661	2.342	-1.687	2.130
0.0	0.0	0.0	0.0	0.0	0.0	0.0	-20.551	2.515	-3.749
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-20.393	0.606
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	17.394

REDUCED MATRIX AS CALCULATED BY FT01

26.016	-7.747	0.780	-8.378	17.201	-9.468	-2.254	-5.784	9.204	-3.869
0.0	25.554	-5.698	-2.817	-1.874	13.458	-10.343	-5.309	-2.054	7.868
0.0	0.0	27.275	-7.360	0.716	-4.318	12.849	-11.746	-2.957	-2.031
0.0	0.0	0.0	25.782	-2.909	0.052	-6.139	10.894	-10.403	-2.651
0.0	0.0	0.0	0.0	22.936	-2.543	2.887	-4.710	11.662	-10.939
0.0	0.0	0.0	0.0	0.0	21.736	-1.355	3.165	-4.339	6.728
0.0	0.0	0.0	0.0	0.0	0.0	20.661	-2.342	1.687	-2.130
0.0	0.0	0.0	0.0	0.0	0.0	0.0	20.551	-2.515	3.749
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	20.393	-0.606
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-17.394

READY

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C TEST PROGRAM FOR FTO2, WHICH FINDS THE Q-R DECOMPOSITION
C OF A TOEPLITZ MATRIX IN  $O(N^2)$  OPERATIONS. FTO2 USES THE
C GILL-GOLUB-MURRAY-SAUNDERS ORTHOGONAL UPDATE ALGORITHM
C AND THE SHIFT-INVARIANCE OF THE TOEPLITZ MATRIX TO
C GIVE AN  $O(N)$  COLUMN-RECURSION FOR R AND AN  $O(N)$ 
C ROW-RECURSION FOR QT (Q-TRANPOSE).
C
C
C TEST PROCEDURE: (1) GENERATE TOEP.MX. 'A' WITH 1ST ROW
C AND COL FROM 'T'. (2) FIND Q-R DECOMP. OF 'A' USING
C HOUSEHOLDER TRANSFORMS(R OVERWRITES 'A') (3) CALL FTO2
C TO CALC. Q-R DECOMP.OF 'A'.
C
  REAL*8 T(19),A(10,10),R(10,10),QT(10,10),WKA(230)
  DATA T/2.2,3.7,-5.9,-1.1,-2.8,6.3,-4.9,8.0,
1  6.2,18.6,-14.7,2.5,2.9,4.2,-8.6,-1.5,2.0,
2  0.2,-1.5/

  EPS=10.**(-4)
  ID1=10
  N=10
  N2P3=2*N+3
  N2M1=2*N-1
  NM1=N-1

  CALL TOEPMX(T,A,N,N2M1,ID1)

  WRITE(6,10)
10 FORMAT(///' INPUT TOEPLITZ MATRIX T')
  CALL PRNTMX(A,N,N,ID1)

C REDUCE TOEPLITZ MATRIX BY HOUSEHOLDER TRANSFORMS
  CALL HOUQR(A,QT,N,ID1)
  DO 30 I=2,N
  IM1=I-1
  DO 30 J=1,IM1
30 A(I,J)=0.

35 WRITE(6,40)
40 FORMAT('/' REDUCED MATRIX USING HOUSEHOLDER TRANSFORMS')
  CALL PRNTMX(A,N,N,ID1)
  WRITE(6,50)
50 FORMAT('/' QT = PRODUCT OF HOUSEHOLDER TRANSFORMS')
  CALL PRNTMX(QT,N,N,ID1)

C REDUCE TOEPLITZ MATRIX USING FTO2
  CALL FTO2(T,QT,R,N,N2M1,ID1)
  DO 52 I=2,N
  IM1=I-1
  DO 52 J=1,IM1
52 R(I,J)=0.

56 WRITE(6,58)
58 FORMAT('/' REDUCED MATRIX AS CALCULATED BY FTO2')
  CALL PRNTMX(R,N,N,ID1)
  WRITE(6,60)

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60 FORMAT('/' QT = ORTHOG MATRIX THAT REDUCES T')
   CALL PRNTMX(QT,N,N,ID1)
   STOP
   END

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SUBROUTINE FTO2(T,Y,R,N,N2M1,ID1)

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C
C S/R TO FIND THE Q-R DECOMPOSITION OF A TOEPLITZ MATRIX USING
C GILL ET-AL'S ORTHOGONAL UPDATE ALG., SHIFT-INVARIANCE, AND A
C A RECURSION ON THE ROWS OF Q-TRANSPPOSE. FOLLOWS ALG.7.4.2.,
C WITH THE SAME NOTATION.
C
C PARAMETERS
C T.....VECTOR CONTAINING 1ST ROW AND COL OF TOEPLITZ MATRIX
C         TO BE TRIANGULARIZED. IF N IS THE ORDER OF THE MATRIX,
C         ORDER OF STORAGE IS (1,N),(1,N-1),..., (1,1), (2,1),...
C         ..., (N,1)
C Y.....ORTHOGONAL MATRIX SATISFYING YT=R, R UPPER-TRIANGULAR
C R.....CONTAINS UPPER-TRIANGULAR MATRIX PRODUCED BY THE
C         ORTHOGONALIZATION. NOTE THAT R(I,J), I.GT.J HAVE
C         NOT BEEN ZEROED
C N.....ORDER OF TOEPLITZ MATRIX
C N2M1.....2*N-1. T MUST BE AT LEAST THIS LENGTH
C ID1.....ROW-DIMENSION OF R
C
C QUICK OUTLINE OF FTO2
C -----
C DEFINE
C TM = T(SUPERSCRIPT N-1) = LEADING SUBMATRIX OF T
C RM = R(SUPERSCRIPT N-1) = ORTHOGONAL TRIANGULAR FACTOR OF TM
C YM = Y(SUPERSCRIPT N-1) = ORTHOGONAL MATRIX SUCH THAT YM*TM=RM
C R-DOT = MATRIX WITH 1ST ROW = T(1,1..N), REST OF 1ST
C         COLUMN = YM * T(2..N,1),
C         TRAILING SUBMATRIX = LEADING SUBMATRIX OF T.
C R-TILDE = R + Y(N.)*(T(N,1..N-1),0)
C
C R-DOT MAY BE TRANSFORMED TO R USING GILL ET AL'S RANK-1
C ORTHOGONAL UPDATE, WITH AN UPSWEEP AND A DOWNSWEEP OF
C GIVENS TRANSFORMS (ANGLES PHI-UP AND PHI-DOWN). SIMILARLY,
C R-TILDE MAY BE TRANSFORMED TO AN UPPER-TRIANGULAR MATRIX
C WITH RM AS ITS LEADING SUBMATRIX (GIVENS ANGLES THETA-UP
C AND THETA-DOWN)
C SUPPOSE THAT RM(.J-1), R(.J-1), YM(J-1.) AND Y(J.) ARE
C KNOWN. THEN R-DOT(.J) CAN BE CONSTRUCTED. PERFORM A GILL
C UPSWEEP AND DOWNSWEEP ON R-DOT(.J), YIELDING R(.J).
C Y(J.) MAY BE OBTAINED FROM YM(J-1.) IN A SIMILAR MANNER,
C RE-ARRANGING THE CALCULATIONS TO OPERATE ON ROWS, RATHER
C THAN COLUMNS.
C CALCULATE R-TILDE(.J) FROM THE DEFINITION, AND PERFORM
C A GILL UPSWEEP AND DOWNSWEEP ON R-TILDE(.J), YIELDING
C RM(.J). YM(J.) MAY BE OBTAINED FROM Y(J.) IN A SIMILAR
C MANNER, RE-ARRANGING THE CALCULATIONS TO OPERATE ON ROWS,
C RATHER THAN COLUMNS. THIS COMPLETES THE BASIC RECURSION.
C NOTE THAT THE GILL SWEEPS IN THE RECURSION, WHICH
C ACCOUNT FOR MOST OF THE COMPUTING LOAD, REQUIRE ONLY

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C O(N) OPERATIONS, SO THE WHOLE ALGORITHM REQUIRES
C ONLY O(N**2) OPERATIONS. DETAILS OF THE CALCULATION
C OF THE GILL ROTATIONS, WHICH PROCEEDS IN TANDEM WITH
C THE BASIC RECURSION ARE GIVEN IN ALG.7.4.2.

C NOTATION - WORKING STORAGE
C -----
C CPHIUP)
C SPHIUP) OUTPUT COSINES AND SINES OF GIVENS ROTATIONS USED
C CPHIDN) IN FTO2. NOTATION FOLLOWS ALG.7.4.2, WITH THE
C SPHIDN)..FOLLOWING CONVENTION
C CTHEUP) 1ST LETTER. C-COSINE, S-SINE
C STHEUP) NEXT 3 LETTERS. PHI-PHI, THE-THETA
C CTHEDN) LAST 2 LETTERS. UP-UP ARROW, DN-DOWN ARROW
C STHEDN)
C RM.....TEMP. VECTOR TO STORE COL. OF R(SUPERSCRIP N-1)
C RD1.....O/P VECTOR CONTAINING 1ST COL OF R-DOT
C RDJ.....TEMP. VECTOR TO STORE COL.J OF R-DOT.
C RT1.....O/P VECTOR CONTAINING 1ST COL OF R-TILDE
C RTJ.....TEMP. VECTOR TO STORE COL.J OF R-TILDE
C SIGD.....O/P VECTOR CONTAINING VALUES OF SIGMA-DOT
C SIGT.....O/P VECTOR CONTAINING VALUES OF SIGMA-TILDE
C Z.....O/P VECTOR (= T-TRANPOSE * (T(2,1),...,T(N,1))
C                                     TRANSPOSE )
C YD.....TEMP.VECTOR CONTAINING Y-DOT(J.)
C YD1.....TEMP.VECTOR CONTAINING Y-DOT-1(J.), AND OVERWRITTEN
C                                     BY Y-DOT-1(J+1.)
C YD2.....TEMP.VECTOR CONTAINING Y-DOT-2(J+1.)
C YD3.....TEMP.VECTOR CONTAINING Y-DOT-3(J.), AND OVERWRITTEN
C                                     BY Y-DOT-3(J+1.)
C Y1 TO Y3.SIMILAR TO YD1 TO YD3, BUT REFERRING TO Y.1 TO Y.3
C YM.....TEMP.VECTOR CONTAINING YM(J.)

REAL*8 T(N2M1),R(ID1,N),CPHIUP(100),SPHIUP(100),CPHIDN(100),
1 CTHEUP(100),STHEUP(100),CTHEDN(100),STHEDN(100),RM(100),RD1(100)
2 ,RT1(100),RTJ(100),SIGD(100),SIGT(100),SPHIDN(100),RDJ(100)
REAL*8 Y(ID1,N),YD(100),YD1(100),YD2(100),YD3(100),Y1(100),Y2(100)
1 ,YM(100),Y3(100)
REAL*8 EPS,TEMP

C INITIALIZATION

IF(N.LE.100) GO TO 5
WRITE(6,2)
2 FORMAT(' ** N.GT.100 - NO PROCESSING BY FTO2')
RETURN

5 EPS=10.**(-5)
M=N-1

C CALC R(1,1) AND RM(1,1) USING NORM-INVARIANCE
RM(1)=0.
DO 10 I=1,M
10 RM(1)=RM(1)+T(I-1+N)**2
R(1,1)=RM(1)+T(N2M1)*T(N2M1)
R(1,1)=DSQRT(R(1,1))
RM(1)=DSQRT(RM(1))

```

```

C GET R-DOT(1,1),(1,2),(2,2) AND SIGMA-DOT(1),(2), WHERE SIGMA-DOT(I)
C IS NORM(R-DOT(I..N,1))
  RD1(1)=T(N)
  RDJ(1)=T(N-1)
  RDJ(2)=RM(1)
  SIGD(1)=R(1,1)
  SIGD(2)=DSQRT(SIGD(1)**2 - RD1(1)**2)

C OTHER INITLZN.FOR R-RECURSION - PHIDN(1),THEDN(1),R-TILDE(1,1), AND
C SIGMA-TILDE(1),(2) WHERE SIGMA-TILDE(I)=NORM(R-TILDE(I..N,1))
  CPHIDN(1)=RD1(1)/SIGD(1)
  SPHIDN(1)=SIGD(2)/SIGD(1)
  Y(1,N)=T(N2M1)/R(1,1)
  RT1(1)=R(1,1)-Y(1,N)*T(N2M1)
  SIGT(1)=RM(1)
  SIGT(2)=DSQRT(SIGT(1)**2 - RT1(1)**2)
  CTHEDN(1)=RT1(1)/SIGT(1)
  STHEDN(1)=SIGT(2)/SIGT(1)

C INITLZN.FOR Q-RECURSION - Y-DOT(1.),YM(1.),Y(1.),Y-DOT-1(2.),
C Y-DOT-3(2.),Y.1(2.) AND Y.3(2.)
  YD(1)=1.
  DO 12 I=2,N
12 YD(I)=0.
  DO 14 I=1,M
14 YM(I)=T(I-1+N)/RM(1)
  YM(N)=0.
  DO 16 I=1,N
  Y(1,I)=T(I-1+N)/R(1,1)
  YD1(I)=(Y(1,I)-CPHIDN(1)*YD(I))/SPHIDN(1)
  YD3(I)=-SPHIDN(1)*YD(I) + CPHIDN(1)*YD1(I)
  Y1(I)=(YM(I) - CTHEDN(1)*Y(1,I))/STHEDN(1)
16 Y3(I)=-STHEDN(1)*Y(1,I) + CTHEDN(1)*Y1(I)

*****MAIN LOOP - CALC R(.J),Y(.J),RM(.J) AND YM(.J)*****

  J=2

C
C R-RECURSION PHASE I - CALC R(.J) FROM R-DOT(.J)
C
  30 RDJ(1)=T(1-J+N)
  DO 40 I=2,J
  40 RDJ(I)=RM(I-1)
C RM CONTAINS RM(.J-1)

C CALC R-DOT(J,1) = YM(J-1.)*T(2..N,1)
  48 RD1(J)=0.
  DO 50 I=1,M
  50 RD1(J)=RD1(J) + YM(I)*T(I+N)

C IF J=N, CHECK THAT RD1(N) IS POSITIVE. IF NOT, RD(N.) WAS
C REVERSED IN SIGN IN THE PREVIOUS STEP - SO RDJ(N) MUST BE
C REPLACED BY -RDJ(N).
  IF(J.NE.N) GO TO 65
  IF(RD1(N).LT.0) RDJ(N)=-RDJ(N)
  GO TO 70

```

```

C NEXT PHIUP
65 SIGD(J+1)=DSQRT(SIGD(J)**2-RD1(J)**2)
    CPHIUP(J)=RD1(J)/SIGD(J)
    SPHIUP(J)=SIGD(J+1)/SIGD(J)
C SINGULARITY CHECK
    IF(DABS(SPHIUP(J)).GE.EPS) GO TO 68
    WRITE(6,66)
66 FORMAT(' I/P MATRIX NUMERICALLY SINGULAR - ERROR EXIT')
    RETURN

C APPLY PHIUP(J), THEN PHI(1..J-1) ON RDJ
68 RDJ(J+1)=0.
    CALL GIVENS(RDJ(J),RDJ(J+1),CPHIUP(J),SPHIUP(J))
70 CALL RSWEEP(RDJ,R(1,J),CPHIUP,SPHIUP,CPHIDN,SPHIDN,J-1,J)

C CALC AND APPLY LAST PHIDN IN DOWN-SWEEP (N/A IF J=N)
    IF(J.NE.N) GO TO 110
    DO 105 I=1,N
105 Y(N,I)=YD3(I)
    RETURN
110 R(J,J)=DSQRT(RDJ(J)**2 + RDJ(J+1)**2)
    CPHIDN(J)=RDJ(J)/R(J,J)
    SPHIDN(J)=RDJ(J+1)/R(J,J)

C Q-RECURSION PHASE I - CALC Y-DOT(J.),Y-DOT-1(J+1.),Y-DOT-2(J+1.),
C Y(J.) AND Y-DOT-3(J+1.)
    YD(1)=0.
    DO 112 I=2,N
112 YD(I)=YM(I-1)
    DO 115 I=1,N
        YD1(I)=(YD1(I)-CPHIUP(J)*YD(I))/SPHIUP(J)
        YD2(I)=-SPHIUP(J)*YD(I) + CPHIUP(J)*YD1(I)
        Y(J,I)=CPHIDN(J)*YD3(I) + SPHIDN(J)*YD2(I)
115 YD3(I)=-SPHIDN(J)*YD3(I) + CPHIDN(J)*YD2(I)

C R-RECURSION PHASE II - CALC RM(.J) FROM R-TILDE(.J)

C CALC R-TILDE(1..J,J)
120 DO 125 I=1,J
125 RTJ(I)=R(I,J)-Y(I,N)*T(N-J+N)

C NEXT THEUP
127 RT1(J)= -T(N2M1)*Y(J,N)
    SIGT(J+1)=DSQRT(SIGT(J)**2 - RT1(J)**2)
    CTHEUP(J)=RT1(J)/SIGT(J)
    STHEUP(J)=SIGT(J+1)/SIGT(J)
C SINGULARITY CHECK
    IF(DABS(STHEUP(J)).GE.EPS) GO TO 129
    WRITE(6,128)
128 FORMAT(' LDG SUBMX.NUMERICALLY SINGULAR - ERROR EXIT',
1      /' REMEDY - AUGMENT I/P MATRIX AND RERUN')
    RETURN

C APPLY THEUP(J), THEN THETA(1..J-1) TO R-TILDE(.J)
129 RTJ(J+1)=SIGT(J+1)*T(N-J+N)/T(N2M1)
    CALL GIVENS(RTJ(J),RTJ(J+1),CTHEUP(J),STHEUP(J))

```

```

      CALL RSWEEP(RTJ, RM, CTHEUP, STHEUP, CTHEDN, STHEDN, J-1, J)
C
C  CALC AND APPLY LAST THEDN
1975 RM(J)=DSQRT(RTJ(J)**2 + RTJ(J+1)**2)
      CTHEDN(J)=RTJ(J)/RM(J)
      STHEDN(J)=RTJ(J+1)/RM(J)
C  Q-RECURSION PHASE II - CALC Y.1(J+1.), Y.2(J+1.), YM(J.) AND Y.3(J+1.)
155 DO 160 I=1, N
      Y1(I)=(Y1(I) - CTHEUP(J)*Y(J, I))/STHEUP(J)
      Y2(I)=-STHEUP(J)*Y(J, I) + CTHEUP(J)*Y1(I)
      YM(I)=CTHEDN(J)*Y3(I) + STHEDN(J)*Y2(I)
160 Y3(I)=-STHEDN(J)*Y3(I) + CTHEDN(J)*Y2(I)

170 J=J+1
      GO TO 30
C
C*****END OF MAIN LOOP*****
      END

```

```

      SUBROUTINE RSWEEP(P, R, CUP, SUP, CDN, SDN, NROT, J)
C
C  S/R TO APPLY A GILL-TYPE UP/DOWN SWEEP TO A VECTOR
C
C  P.....I/P VECTOR
C  R.....O/P VECTOR
C  CUP, SUP..COS'S AND SIN'S OF UPSWEEP ANGLES
C  CDN, SDN..COS'S AND SIN'S OF DOWNSWEEP ANGLES
C  NROT.....NO.OF DOWNWARD ROTATIONS TO APPLY. (NO.OF
C           UPWARD ROTATIONS IS ONE LESS THAN NROT)
C  J.....LENGTH OF P AND R. IF J.GT.NROT+1,
C           R(NROT+2..J)=P(NROT+2..J)
C
      REAL*8 P(J), R(J), CUP(J), SUP(J), CDN(J), SDN(J)
C
C  UPSWEEP
      IF(NROT.EQ.1) GO TO 15
      I=NROT
      DO 10 II=2, NROT
      CALL GIVENS(P(I), P(I+1), CUP(I), SUP(I))
10  I=I-1
C
C  DOWNSWEEP
15  DO 20 I=1, NROT
20  CALL GIVENS(P(I), P(I+1), CDN(I), SDN(I))
C
C  OUTPUT
      DO 30 I=1, J
30  R(I)=P(I)
      RETURN
      END

```

INPUT TOEPLITZ MATRIX T

18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100	-5.900	3.700	2.200
-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100	-5.900	3.700
2.500	-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100	-5.900
2.900	2.500	-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100
4.200	2.900	2.500	-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800
-8.600	4.200	2.900	2.500	-14.700	18.600	6.200	8.000	-4.900	6.300
-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600	6.200	8.000	-4.900
2.000	-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600	6.200	8.000
0.200	2.000	-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600	6.200
-1.500	0.200	2.000	-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600

REDUCED MATRIX USING HOUSEHOLDER TRANSFORMS

-26.016	7.747	-0.780	8.378	-17.201	9.468	2.254	5.784	-9.204	3.869
0.0	-25.554	5.698	2.817	1.874	-13.458	10.343	5.309	2.054	-7.868
0.0	0.0	-27.275	7.360	-0.716	4.318	-12.849	11.746	2.957	2.031
0.0	0.0	0.0	-25.782	2.909	-0.052	6.139	-10.894	10.403	2.651
0.0	0.0	0.0	0.0	-22.936	2.543	-2.887	4.710	-11.662	10.939
0.0	0.0	0.0	0.0	0.0	-21.736	1.355	-3.165	4.339	-6.728
0.0	0.0	0.0	0.0	0.0	0.0	-20.661	2.342	-1.687	2.130
0.0	0.0	0.0	0.0	0.0	0.0	0.0	-20.551	2.515	-3.749
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-20.393	0.606
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	17.394

QT = PRODUCT OF HOUSEHOLDER TRANSFORMS

-0.715	0.565	-0.096	-0.111	-0.161	0.331	0.058	-0.077	-0.008	0.058
-0.459	-0.557	0.546	-0.132	-0.162	-0.064	0.354	0.035	-0.081	0.010
-0.369	-0.360	-0.565	0.515	-0.121	-0.129	-0.082	0.325	0.038	-0.073
-0.198	-0.290	-0.373	-0.625	0.465	-0.033	-0.078	-0.091	0.333	0.057
0.210	-0.281	-0.262	-0.293	-0.640	0.388	-0.131	-0.088	-0.143	0.342
0.054	0.197	-0.297	-0.266	-0.355	-0.652	0.451	-0.116	-0.097	-0.149
-0.110	0.108	0.216	-0.323	-0.206	-0.323	-0.641	0.496	-0.073	-0.124
-0.111	-0.065	0.135	0.191	-0.280	-0.216	-0.372	-0.629	0.511	-0.088
-0.173	-0.036	-0.035	0.091	0.241	-0.312	-0.257	-0.358	-0.611	0.487
0.035	0.149	0.106	0.096	-0.033	-0.212	0.151	0.295	0.459	0.767

REDUCED MATRIX AS CALCULATED BY FT02

26.016	-7.747	0.780	-8.378	17.201	-9.468	-2.254	-5.784	9.204	-3.869
0.0	25.554	-5.698	-2.817	-1.874	13.458	-10.343	-5.309	-2.054	7.868
0.0	0.0	27.275	-7.360	0.716	-4.318	12.849	-11.746	-2.957	-2.031
0.0	0.0	0.0	25.782	-2.909	0.052	-6.139	10.894	-10.403	-2.651
0.0	0.0	0.0	0.0	22.936	-2.543	2.887	-4.710	11.662	-10.939
0.0	0.0	0.0	0.0	0.0	21.736	-1.355	3.165	-4.339	6.728
0.0	0.0	0.0	0.0	0.0	0.0	20.661	-2.342	1.687	-2.130
0.0	0.0	0.0	0.0	0.0	0.0	0.0	20.551	-2.515	3.749
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	20.393	-0.606
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-17.394

QT = ORTHOG MATRIX THAT REDUCES T

0.715	-0.565	0.096	0.111	0.161	-0.331	-0.058	0.077	0.008	-0.058
0.459	0.557	-0.546	-0.132	0.162	-0.064	-0.354	-0.035	0.081	-0.010
0.369	0.360	0.565	-0.515	0.121	0.129	0.082	-0.325	-0.038	0.073
0.198	0.290	0.373	0.625	-0.465	-0.033	0.078	0.091	-0.333	-0.057
-0.210	0.281	0.262	0.293	0.640	-0.388	0.131	0.088	0.143	-0.342
-0.054	-0.197	0.297	0.266	0.355	-0.652	-0.451	0.116	0.097	0.149
0.110	-0.108	-0.216	0.323	0.206	0.323	0.641	-0.496	0.073	0.124
0.111	0.065	-0.135	-0.191	0.280	0.216	0.372	0.629	-0.511	0.088
0.173	0.036	0.035	-0.091	-0.241	0.312	0.257	-0.358	0.611	-0.487
-0.035	-0.149	-0.106	-0.096	0.033	0.212	-0.151	-0.295	-0.459	-0.767

READY

```

C TEST PROGRAM FOR FTO2S, WHICH IS THE SAME AS FTO2 (Q-R DECOMP.
C OF TOEP.MX.IN O(N**2) OPS) BUT HANDLES THE CASE WHERE THE
C I/P MX. AND/OR ITS LDG.S/MATRIX IS SINGULAR. DOES NOT HANDLE
C THE CASE WHERE THE I/P MATRIX HAS RANK.LT.N-1.
C
C TEST SEQUENCE:
C (1) GEN.TEST MATRIX 'A', REQUEST IF 'A' AND/OR ITS LDG.S/MATRIX
C ARE TO BE MADE SINGULAR AND ADJ.ELEMENTS ACCORDINGLY
C (2) FIND Q-R DECOMP.OF 'A' USING HOUSEHOLDER TRANSFORMS
C (3) .. .. .. .. .. FT02.
C
REAL*8 T(19),A(10,10),R(10,10),QT(10,10),WKA(230)
REAL*8 C,S,TEMP,EPS
DATA T/2.2,3.7,-5.9,-1.1,-2.8,6.3,-4.9,8.0,
1 6.2,18.6,-14.7,2.5,2.9,4.2,-8.6,-1.5,2.0,
2 0.2,-1.5/

EPS=10.**(-4)
ID1=10
N=10
N2P3=2*N+3
N2M1=2*N-1
NM1=N-1

1 T(N2M1-1)=0.2
T(N2M1)=-1.5
CALL TOEPMX(T,A,N,N2M1,ID1)
WRITE(6,2)
2 FORMAT(' IS T,T(N-1) SINGULAR?(1=YES,-1=EXIT)')
READ(5,*) NSING,MSING
IF(NSING.EQ.-1.OR.MSING.EQ.-1) STOP
IF(MSING.EQ.1)CALL SINGSM(A,N,N,ID1,N-1,1,N-1,-1,1,WKA,N2P3,IER)
A(N,2)=A(N-1,1)
IF(NSING.EQ.1)CALL SINGSM(A,N,N,ID1,N,1,N,-1,1,WKA,N2P3,IER)
5 T(2*N-2)=A(N-1,1)
T(N2M1)=A(N,1)

WRITE(6,10)
10 FORMAT('/' INPUT TOEPLITZ MATRIX T')
CALL PRNTMX(A,N,N,ID1)

C REDUCE TOEPLITZ MATRIX BY HOUSEHOLDER TRANSFORMS
CALL HOUQR(A,QT,N,ID1)
DO 30 I=2,N
IM1=I-1
DO 30 J=1,IM1
30 A(I,J)=0.
C IF R(N-1,N-1)=0, APPLY ROT. TO ZERO R(N,N)
TEMP=DSQRT(A(NM1,N)**2 + A(N,N)**2)
IF(DABS(A(NM1,N1))/TEMP.GE.EPS) GO TO 35
C=A(NM1,N)/TEMP
S=A(N,N)/TEMP
A(NM1,N)=TEMP
A(N,N)=0.
DO 15 I=1,N
15 CALL GIVENS(QT(NM1,I),QT(N,I),C,S)

```

```

35 WRITE(6,40)
40 FORMAT('/ REDUCED MATRIX USING HOUSEHOLDER TRANSFORMS')
   CALL PRNTMX(A,N,N,ID1)
   WRITE(6,50)
50 FORMAT('/ QT = PRODUCT OF HOUSEHOLDER TRANSFORMS')
   CALL PRNTMX(QT,N,N,ID1)

C  REDUCE TOEPLITZ MATRIX USING FTO2S
   CALL FTO2S(T,QT,R,N,N2M1,ID1)
   DO 52 I=2,N
     IM1=I-1
     DO 52 J=1,IM1
52  R(I,J)=0.
C  IF R(N-1,N-1)=0, APPLY ROT. TO ZERO R(N,N)
   TEMP=DSQRT(R(NM1,N)**2 + R(N,N)**2)
   IF(DABS(R(NM1,NM1))/TEMP.GE.EPS) GO TO 56
   C=R(NM1,N)/TEMP
   S=R(N,N)/TEMP
   R(NM1,N)=TEMP
   R(N,N)=0.
   DO 54 I=1,N
54  CALL GIVENS(QT(NM1,I),QT(N,I),C,S)

56 WRITE(6,58)
58 FORMAT('/ REDUCED MATRIX AS CALCULATED BY FTO2S')
   CALL PRNTMX(R,N,N,ID1)
   WRITE(6,60)
60 FORMAT('/ QT = ORTHOG MATRIX THAT REDUCES T')
   CALL PRNTMX(QT,N,N,ID1)
   GO TO 1
   END

```

SUBROUTINE FTO2S(T,Y,R,N,N2M1,ID1)

```

C
C  S/R TO FIND THE QR FACTORS OF A TOEPLITZ MATRIX USING GILL
C  ET AL'S RANK-1 UPDATE PROC., SHIFT-INVARIANCE AND A ROW-
C  RECURSION FOR Q-TRANSP. HANDLES CASES WHERE I/P MATRIX
C  AND/OR ITS LDG PRINC.S/MATRIX IS SINGULAR, BUT NOT WHERE
C  I/P MATRIX HAS RANK.LT.N-1. PROCEDURE IS AN EXTENSION OF
C  ALG.7.4.2, AND NOTATION IS THE SAME.
C
C  PARAMETERS
C  T.....VECTOR CONTAINING 1ST ROW AND COL OF TOEPLITZ MATRIX
C           TO BE TRIANGULARIZED. IF N IS THE ORDER OF THE MATRIX,
C           ORDER OF STORAGE IS (1,N),(1,N-1),..., (1,1), (2,1),...
C           ..., (N,1)
C  Y.....ORTHOGONAL MATRIX SATISFYING YT=R, R UPPER-TRIANGULAR
C  R.....CONTAINS UPPER-TRIANGULAR MATRIX PRODUCED BY THE
C           ORTHOGONALIZATION. NOTE THAT R(I,J),I.GT.J HAVE
C           NOT BEEN ZEROED
C  N.....ORDER OF TOEPLITZ MATRIX AND R, AND LENGTH OF
C           VECTORS CPHIUP,...,Z.
C  N2M1....2*N-1. T MUST BE AT LEAST THIS LENGTH
C  ID1.....ROW-DIMENSION OF R
C

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```

C QUICK OUTLINE OF FTO2S
C -----
C DEFINE
C TM = T(SUPERSCRIP T N-1) = LEADING SUBMATRIX OF T
C RM = R(SUPERSCRIP T N-1) = ORTHOGONAL TRIANGULAR FACTOR OF TM
C YM = Y(SUPERSCRIP T N-1) = ORTHOGONAL MATRIX SUCH THAT YM*TM=RM
C R-DOT = MATRIX WITH 1ST ROW = T(1,1..N), REST OF 1ST
C         COLUMN = YM * T(2..N,1),
C         TRAILING SUBMATRIX = LEADING SUBMATRIX OF T.
C R-TILDE = R + Y(N.)*(T(N,1..N-1),0)
C
C R-DOT MAY BE TRANSFORMED TO R USING GILL ET AL'S RANK-1
C ORTHOGONAL UPDATE, WITH AN UPSWEEP AND A DOWNSWEEP OF
C GIVENS TRANSFORMS (ANGLES PHI-UP AND PHI-DOWN). SIMILARLY,
C R-TILDE MAY BE TRANSFORMED TO AN UPPER-TRIANGULAR MATRIX
C WITH RM AS ITS LEADING SUBMATRIX (GIVENS ANGLES THETA-UP
C AND THETA-DOWN)
C   SUPPOSE THAT RM(.J-1), R(.J-1), YM(J-1.) AND Y(J.) ARE
C KNOWN. THEN R-DOT(.J) CAN BE CONSTRUCTED. PERFORM A GILL
C UPSWEEP AND DOWNSWEEP ON R-DOT(.J), YIELDING R(.J).
C Y(J.) MAY BE OBTAINED FROM YM(J-1.) IN A SIMILAR MANNER,
C RE-ARRANGING THE CALCULATIONS TO OPERATE ON ROWS, RATHER
C THAN COLUMNS.
C   CALCULATE R-TILDE(.J) FROM THE DEFINITION, AND PERFORM
C A GILL UPSWEEP AND DOWNSWEEP ON R-TILDE(.J), YIELDING
C RM(.J). YM(J.) MAY BE OBTAINED FROM Y(J.) IN A SIMILAR
C MANNER, RE-ARRANGING THE CALCULATIONS TO OPERATE ON ROWS,
C RATHER THAN COLUMNS. THIS COMPLETES THE BASIC RECURSION.
C   NOTE THAT THE GILL SWEEPS IN THE RECURSION, WHICH
C ACCOUNT FOR MOST OF THE COMPUTING LOAD, REQUIRE ONLY
C O(N) OPERATIONS, SO THE WHOLE ALGORITHM REQUIRES
C ONLY O(N**2) OPERATIONS. DETAILS OF THE CALCULATION
C OF THE GILL ROTATIONS, WHICH PROCEEDS IN TANDEM WITH
C THE BASIC RECURSION ARE GIVEN IN ALG.7.4.2.

C NOTATION - WORKING STORAGE
C -----
C CPHIUP)
C SPHIUP) OUTPUT COSINES AND SINES OF GIVENS ROTATIONS USED
C CPHIDN) IN FTO2S. NOTATION FOLLOWS ALG.7.4.2, WITH THE
C SPHIDN)..FOLLOWING CONVENTION
C CTHEUP) 1ST LETTER. C-COSINE, S-SINE
C STHEUP) NEXT 3 LETTERS. PHI-PHI, THE-THETA
C CTHEDN) LAST 2 LETTERS. UP-UP ARROW, DN-DOWN ARROW
C STHEDN)
C RM.....TEMP. VECTOR TO STORE COL. OF R(SUPERSCRIP T N-1)
C RD1.....O/P VECTOR CONTAINING 1ST COL OF R-DOT
C RDJ.....TEMP. VECTOR TO STORE COL.J OF R-DOT.
C RT1.....O/P VECTOR CONTAINING 1ST COL OF R-TILDE
C RTJ.....TEMP. VECTOR TO STORE COL.J OF R-TILDE
C SIGD.....O/P VECTOR CONTAINING VALUES OF SIGMA-DOT
C SIGT.....O/P VECTOR CONTAINING VALUES OF SIGMA-TILDE
C Z.....O/P VECTOR (= T-TRANSPOSE * (T(2,1),...,T(N,1))
C                                     TRANSPOSE )
C
C YD.....TEMP.VECTOR CONTAINING Y-DOT(J.)
C YD1.....TEMP.VECTOR CONTAINING Y-DOT-1(J.), AND OVERWRITTEN
C BY Y-DOT-1(J+1.)

```

```

C YD2.....TEMP.VECTOR CONTAINING Y-DOT-2(J+1.)
C YD3.....TEMP.VECTOR CONTAINING Y-DOT-3(J.), AND OVERWRITTEN
C                               BY Y-DOT-3(J+1.)
C Y1 TO Y3.SIMILAR TO YD1 TO YD3, BUT REFERRING TO Y.1 TO Y.3
C YM.....TEMP.VECTOR CONTAINING YM(J.)

```

```

REAL*8 T(N2M1),R(ID1,N),CPHIUP(100),SPHIUP(100),CPHIDN(100),
1 CTHEUP(100),STHEUP(100),CTHEDN(100),STHEDN(100),RM(100),RD1(100)
2 ,RT1(100),RTJ(100),SIGD(100),SIGT(100),SPHIDN(100),RDJ(100)
REAL*8 Y(ID1,N),YD(100),YD1(100),YD2(100),YD3(100),Y1(100),Y2(100)
1 ,YM(100),Y3(100)
REAL*8 EPS,TEMP
INTEGER PHIFLG,THEFLG

```

C INITIALIZATION

```

IF(N.LE.100) GO TO 5
WRITE(6,2)
2 FORMAT(' ** N.GT.100 - NO PROCESSING BY FTO2S')
RETURN

5 EPS=10.**(-4)
M=N-1
PHIFLG=0
THEFLG=0

```

C CALC R(1,1) AND RM(1,1) USING NORM-INVARIANCE

```

RM(1)=0.
DO 10 I=1,M
10 RM(1)=RM(1)+T(I-1+N)**2
R(1,1)=RM(1)+T(N2M1)*T(N2M1)
R(1,1)=DSQRT(R(1,1))
RM(1)=DSQRT(RM(1))

```

```

C GET R-DOT(1,1),(1,2),(2,2) AND SIGMA-DOT(1),(2), WHERE SIGMA-DOT(I)
C IS NORM(R-DOT(I..N,1))
RD1(1)=T(N)
RDJ(1)=T(N-1)
RDJ(2)=RM(1)
SIGD(1)=R(1,1)
SIGD(2)=DSQRT(SIGD(1)**2 - RD1(1)**2)

```

```

C OTHER INITLZN.FOR R-RECURSION - PHIDN(1),THEDN(1),R-TILDE(1,1), AND
C SIGMA-TILDE(1),(2) WHERE SIGMA-TILDE(I)=NORM(R-TILDE(I..N,1))

```

```

CPHIDN(1)=RD1(1)/SIGD(1)
SPHIDN(1)=SIGD(2)/SIGD(1)
Y(1,N)=T(N2M1)/R(1,1)
RT1(1)=R(1,1)-Y(1,N)*T(N2M1)
SIGT(1)=RM(1)
SIGT(2)=DSQRT(SIGT(1)**2 - RT1(1)**2)
CTHEDN(1)=RT1(1)/SIGT(1)
STHEDN(1)=SIGT(2)/SIGT(1)

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C INITLZN.FOR Q-RECURSION - Y-DOT(1.),YM(1.),Y(1.),Y-DOT-1(2.),
C Y-DOT-3(2.),Y.1(2.) AND Y.3(2.)
YD(1)=1.
DO 12 I=2,N

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```

12 YD(I)=0.
   DO 14 I=1,M
14 YM(I)=T(I-1+N)/RM(1)
   YM(N)=0.
   DO 16 I=1,N
   Y(1,I)=T(I-1+N)/R(1,1)
   YD1(I)=(Y(1,I)-CPHIDN(1)*YD(I))/SPHIDN(1)
   YD3(I)=-SPHIDN(1)*YD(I) + CPHIDN(1)*YD1(I)
   Y1(I)=(YM(I) - CTLEDN(1)*Y(1,I))/STLEDN(1)
16 Y3(I)=-STLEDN(1)*Y(1,I) + CTLEDN(1)*Y1(I)

C*****MAIN LOOP - CALC R(.J),Y(.J),RM(.J) AND YM(.J)*****

      J=2
C
C R-RECURSION PHASE I - CALC R(.J) FROM R-DOT(.J)
C
30 RDJ(1)=T(1-J+N)
   DO 40 I=2,J
40 RDJ(I)=RM(I-1)
C RM CONTAINS RM(.J-1)
C
C DO ONLY A PARTIAL SWEEP IF SOME OF THE PHI'S ARE ZERO
  IF(PHIFLG.EQ.0) GO TO 48
  RDJ(PHIFLG)=DSIGN(RDJ(PHIFLG),CPHIUP(PHIFLG))
  CALL RSWEEP(RDJ,R(1,J),CPHIUP,SPHIUP,CPHIDN,SPHIDN,PHIFLG-1,J)
  Y(J,1)=0.
  DO 45 I=2,N
45 Y(J,I)=YM(I-1)
   IF(J.EQ.N) RETURN
   GO TO 120
C
C CALC R-DOT(J,1) = YM(J-1.)*T(2..N,1)
48 RD1(J)=0.
   DO 50 I=1,M
50 RD1(J)=RD1(J) + YM(I)*T(I+N)

C IF J=N, CHECK THAT RD1(N) IS POSITIVE. IF NOT, RD(N.) WAS
C REVERSED IN SIGN IN THE PREVIOUS STEP - SO RDJ(N) MUST BE
C REPLACED BY -RDJ(N).
   IF(J.NE.N) GO TO 65
   IF(RD1(N).LT.0) RDJ(N)=-RDJ(N)
   GO TO 70

C NEXT PHIUP
65 TEMP=SIGD(J)**2-RD1(J)**2
   IF(TEMP.LT.0.) TEMP=0.
   SIGD(J+1)=DSQRT(TEMP)
   CPHIUP(J)=RD1(J)/SIGD(J)
   SPHIUP(J)=SIGD(J+1)/SIGD(J)
C
C IF PHI(J)=0, USE ONLY PHI(1) TO PHI(J-1) IN THE SWEEP
  IF(DABS(SPHIUP(J)).GE.EPS) GO TO 68
  PHIFLG=J
  RDJ(J)=DSIGN(RDJ(J),CPHIUP(J))
  CALL RSWEEP(RDJ,R(1,J),CPHIUP,SPHIUP,CPHIDN,SPHIDN,PHIFLG-1,J)
  DO 66 I=1,N

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66 Y(J,I)=YD3(I)
   GO TO 120

C  APPLY PHIUP(J), THEN PHI(1..J-1) ON RDJ
68 RDJ(J+1)=0.
   CALL GIVENS(RDJ(J),RDJ(J+1),CPHIUP(J),SPHIUP(J))
70 CALL RSWEAP(RDJ,R(1,J),CPHIUP,SPHIUP,CPHIDN,SPHIDN,J-1,J)

C  CALC AND APPLY LAST PHIDN IN DOWN-SWEEP (N/A IF J=N)
   IF(J.NE.N) GO TO 110
   DO 105 I=1,N
105 Y(N,I)=YD3(I)
   RETURN
110 R(J,J)=DSQRT(RDJ(J)**2 + RDJ(J+1)**2)
   CPHIDN(J)=RDJ(J)/R(J,J)
   SPHIDN(J)=RDJ(J+1)/R(J,J)

C  Q-RECURSION PHASE I - CALC Y-DOT(J.),Y-DOT-1(J+1.),Y-DOT-2(J+1.),
C  Y(J.) AND Y-DOT-3(J+1.)
   YD(1)=0.
   DO 112 I=2,N
112 YD(I)=YM(I-1)
   DO 115 I=1,N
   YD1(I)=(YD1(I)-CPHIUP(J)*YD(I))/SPHIUP(J)
   YD2(I)=-SPHIUP(J)*YD(I) + CPHIUP(J)*YD1(I)
   Y(J,I)=CPHIDN(J)*YD3(I) + SPHIDN(J)*YD2(I)
115 YD3(I)=-SPHIDN(J)*YD3(I) + CPHIDN(J)*YD2(I)

C  R-RECURSION PHASE II - CALC RM(.J) FROM R-TILDE(.J)

C  CALC R-TILDE(1..J,J)
120 DO 125 I=1,J
125 RTJ(I)=R(I,J)-Y(I,N)*T(N-J+N)

C  IF SOME THETA'S ARE ZERO, ONLY APPLY THE NON-ZERO ONES
   IF(THEFLG.EQ.0) GO TO 127
   RTJ(THEFLG)=DSIGN(RTJ(THEFLG),CTHEUP(THEFLG))
   CALL RSWEAP(RTJ,RM,CTHEUP,STHEUP,CTHEDN,STHEDN,THEFLG-1,J)
   DO 126 I=1,N
126 YM(I)=Y(J,I)
   GO TO 170

C  NEXT THEUP
127 RT1(J)= -T(N2M1)*Y(J,N)
   TEMP=SIGT(J)**2 - RT1(J)**2
   IF(TEMP.LT.0.) TEMP=0.
   SIGT(J+1)=DSQRT(TEMP)
   CTHEUP(J)=RT1(J)/SIGT(J)
   STHEUP(J)=SIGT(J+1)/SIGT(J)

C  IF THETA=0, ONLY APPLY THETA(1..J-1) IN SWEEP
   IF(DABS(STHEUP(J)).GE.EPS) GO TO 129
   THEFLG=J
   RTJ(J)=DSIGN(RTJ(J),CTHEUP(J))
   CALL RSWEAP(RTJ,RM,CTHEUP,STHEUP,CTHEDN,STHEDN,THEFLG-1,J)
947 DO 128 I=1,N
128 YM(I)=Y3(I)

```

GO TO 170

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C APPLY THEUP(J), THEN THETA(1..J-1) TO R-TILDE(.J)
129 RTJ(J+1)=SIGT(J+1)*T(N-J+N)/T(N2M1)
    CALL GIVENS(RTJ(J),RTJ(J+1),CTHEUP(J),STHEUP(J))
    CALL RSWEEP(RTJ,RM,CTHEUP,STHEUP,CTHEDN,STHEDN,J-1,J)
C
C CALC AND APPLY LAST THEDN
975 RM(J)=DSQRT(RTJ(J)**2 + RTJ(J+1)**2)
    CTHEDN(J)=RTJ(J)/RM(J)
    STHEDN(J)=RTJ(J+1)/RM(J)

C CHECK THAT YM(J,N) IS 'NUMERICALLY ZERO'. IF NOT, RM HAS RANK
C J-1 OR LESS, AND RM(J,J)=0. THEDN(J) MUST BE RECALCULATED TO
C TO MAKE YM(J,N) ZERO. (RM(J,J) WILL REMAIN ZERO).
    Y2(N)=-STHEUP(J)*Y(J,N) + CTHEUP(J)*
1      (Y1(N)-CTHEUP(J)*Y(J,N))/STHEUP(J)
    YM(N)=CTHEDN(J)*Y3(N) + STHEDN(J)*Y2(N)
    IF(DABS(YM(N)).LE.EPS) GO TO 155
    RM(J)=0.
    TEMP=DSQRT(Y3(N)**2 + Y2(N)**2)
    CTHEDN(J)=Y2(N)/TEMP
    STHEDN(J)=-Y3(N)/TEMP

C Q-RECURSION PHASE II - CALC Y.1(J+1.),Y.2(J+1.),YM(J.) AND Y.3(J+1.)
155 DO 160 I=1,N
    Y1(I)=(Y1(I) - CTHEUP(J)*Y(J,I))/STHEUP(J)
    Y2(I)=-STHEUP(J)*Y(J,I) + CTHEUP(J)*Y1(I)
    YM(I)=CTHEDN(J)*Y3(I) + STHEDN(J)*Y2(I)
160 Y3(I)=-STHEDN(J)*Y3(I) + CTHEDN(J)*Y2(I)

170 J=J+1
    GO TO 30
C
C*****END OF MAIN LOOP*****

```

END

SUBROUTINE RSWEEP(P,R,CUP,SUP,CDN,SDN,NROT,J)

```

C
C S/R TO APPLY A GILL-TYPE UP/DOWN SWEEP TO A VECTOR
C
C P.....I/P VECTOR
C R.....O/P VECTOR
C CUP,SUP..COS'S AND SIN'S OF UPSWEEP ANGLES
C CDN,SDN..COS'S AND SIN'S OF DOWNSWEEP ANGLES
C NROT.....NO.OF DOWNWARD ROTATIONS TO APPLY. (NO.OF
C          UPWARD ROTATIONS IS ONE LESS THAN NROT)
C J.....LENGTH OF P AND R. IF J.GT.NROT+1,
C          R(NROT+2..J)=P(NROT+2..J)
C
C REAL*8 P(J),R(J),CUP(J),SUP(J),CDN(J),SDN(J)
C
C UPSWEEP
    IF(NROT.EQ.1) GO TO 15

```

```
      I=NROT
      DO 10 II=2,NROT
      CALL GIVENS(P(I),P(I+1),CUP(I),SUP(I))
10    I=I-1
C
C  DOWNSWEEP
15    DO 20 I=1,NROT
20    CALL GIVENS(P(I),P(I+1),CDN(I),SDN(I))

C  OUTPUT
      DO 30 I=1,J
30    R(I)=P(I)
      RETURN
      END
```

IS T,T(N-1) SINGULAR?(1=YES,-1=EXIT)

?

0,1

INPUT TOEPLITZ MATRIX T

18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100	-5.900	3.700	2.200
-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100	-5.900	3.700
2.500	-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100	-5.900
2.900	2.500	-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100
4.200	2.900	2.500	-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800
-8.600	4.200	2.900	2.500	-14.700	18.600	6.200	8.000	-4.900	6.300
-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600	6.200	8.000	-4.900
2.000	-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600	6.200	8.000
162.992	2.000	-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600	6.200
-1.500	162.992	2.000	-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600

REDUCED MATRIX USING HOUSEHOLDER TRANSFORMS

-165.055	0.728	1.357	9.803	-6.854	-1.368	-2.111	15.410	-19.796	-5.505
0.0	-165.163	-1.047	1.565	9.543	-6.672	-1.373	-1.846	15.151	-19.756
0.0	0.0	-27.822	7.293	-2.261	7.439	-14.702	11.411	0.684	4.186
0.0	0.0	0.0	-25.402	5.919	-1.737	2.944	-7.847	6.000	-0.441
0.0	0.0	0.0	0.0	-25.617	6.568	-0.854	1.646	-5.604	6.366
0.0	0.0	0.0	0.0	0.0	-24.909	4.111	-0.594	4.431	-4.503
0.0	0.0	0.0	0.0	0.0	0.0	-22.430	-0.382	-2.194	5.312
0.0	0.0	0.0	0.0	0.0	0.0	0.0	-18.505	-7.463	-6.293
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	4.038	2.506
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	1.126

QT = PRODUCT OF HOUSEHOLDER TRANSFORMS

-0.113	0.089	-0.015	-0.018	-0.025	0.052	0.009	-0.012	-0.988	0.009
-0.038	-0.112	0.089	-0.015	-0.018	-0.025	0.052	0.009	-0.016	-0.987
-0.292	-0.214	-0.673	0.528	-0.090	-0.101	-0.152	0.308	0.006	-0.034
0.063	-0.349	-0.438	-0.588	0.542	-0.109	-0.151	-0.081	-0.042	-0.008
-0.190	0.064	-0.317	0.426	-0.593	0.534	-0.102	-0.153	0.084	-0.033
-0.013	-0.251	-0.080	-0.230	-0.464	-0.624	0.514	-0.045	-0.031	0.077
0.266	0.170	-0.096	-0.228	-0.285	0.363	-0.655	0.441	-0.036	-0.033
0.000	0.171	-0.127	0.196	-0.072	-0.327	-0.375	-0.813	0.005	-0.052
0.358	0.723	-0.451	-0.039	0.110	-0.060	0.327	0.085	0.027	-0.119
0.814	-0.405	-0.113	0.221	-0.179	0.238	0.016	-0.102	-0.113	0.000

REDUCED MATRIX AS CALCULATED BY FT02S

165.055	-0.728	-1.357	-9.803	6.854	1.368	2.111	-15.410	19.796	5.505
0.0	165.163	1.047	-1.565	-9.543	6.672	1.373	1.846	-15.151	19.756
0.0	0.0	27.822	-7.293	2.261	-7.439	14.702	-11.411	-0.684	-4.186
0.0	0.0	0.0	25.402	-5.919	1.737	-2.944	7.847	-6.000	0.441
0.0	0.0	0.0	0.0	25.617	-6.568	0.854	-1.646	5.604	-6.366
0.0	0.0	0.0	0.0	0.0	24.909	-4.111	0.594	-4.431	4.503
0.0	0.0	0.0	0.0	0.0	0.0	22.430	0.382	2.194	-5.312
0.0	0.0	0.0	0.0	0.0	0.0	0.0	18.505	7.463	6.293
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	4.038	2.506
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-1.126

QT = ORTHOG MATRIX THAT REDUCES T

0.113	-0.089	0.015	0.018	0.025	-0.052	-0.009	0.012	0.988	-0.009
0.038	0.112	-0.089	0.015	0.018	0.025	-0.052	-0.009	0.016	-0.987
0.292	0.214	0.673	-0.528	0.090	0.101	0.152	-0.308	-0.006	0.034
-0.063	0.349	0.438	-0.588	-0.542	0.109	0.151	0.081	0.042	0.008
0.190	-0.064	0.317	0.426	0.593	-0.534	0.102	0.153	-0.084	0.033
0.013	0.251	-0.080	0.230	0.464	0.624	-0.514	0.045	0.031	-0.077
-0.266	-0.170	-0.096	0.228	0.285	0.363	-0.655	-0.441	0.036	0.033
-0.000	-0.171	0.127	-0.196	0.072	-0.327	0.375	0.813	-0.005	0.052
0.358	0.723	-0.451	-0.039	0.110	-0.060	0.327	0.085	0.027	-0.119
-0.814	0.405	0.113	-0.221	0.179	-0.238	-0.016	0.102	0.113	-0.000

IS T,(N-1) SINGULAR?(1=YES,-1=EXIT)

?

1,0

INPUT TOEPLITZ MATRIX T

18.000	8.200	8.000	-4.900	6.300	-2.800	-1.100	-5.900	3.700	2.200
-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100	-5.900	3.700
2.600	-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100	-5.900
2.900	2.500	-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100
4.200	2.900	2.500	-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800
-8.600	4.200	2.900	2.500	-14.700	18.600	6.200	8.000	-4.900	6.300
-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600	6.200	8.000	-4.900
8.000	-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600	6.200	8.000
0.200	8.000	-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600	6.200
368.581	0.200	2.000	-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600

REDUCED MATRIX USING HOUSEHOLDER TRANSFORMS

-369.495	0.345	-2.058	2.002	7.402	-3.540	-2.746	-2.097	14.075	-18.357
0.0	-26.701	5.653	0.293	6.880	-15.673	9.210	3.376	4.818	-8.890
0.0	0.0	-27.218	6.929	-0.733	4.428	-12.856	11.685	2.205	3.335
0.0	0.0	0.0	-27.286	8.485	-2.047	4.131	-12.943	13.336	0.925
0.0	0.0	0.0	0.0	-25.686	3.698	0.530	4.943	-8.133	5.228
0.0	0.0	0.0	0.0	0.0	-21.741	0.571	-2.959	2.464	-4.079
0.0	0.0	0.0	0.0	0.0	0.0	-21.831	2.301	-3.263	4.449
0.0	0.0	0.0	0.0	0.0	0.0	0.0	-20.493	1.470	-2.284
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-17.224	-8.804
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.000

QT = PRODUCT OF HOUSEHOLDER TRANSFORMS

-0.050	0.040	-0.007	-0.008	-0.011	0.023	0.004	-0.005	-0.001	-0.998
-0.233	0.696	-0.550	-0.094	-0.109	-0.157	0.322	-0.056	-0.075	-0.020
-0.338	-0.375	-0.569	-0.521	-0.114	-0.141	-0.088	0.328	0.040	-0.002
-0.087	-0.393	-0.366	-0.551	-0.508	-0.127	-0.125	-0.070	-0.324	-0.022
-0.284	-0.103	-0.271	-0.466	-0.586	-0.499	-0.049	-0.132	-0.078	-0.035
0.179	0.149	-0.298	-0.220	-0.375	-0.678	0.429	-0.104	-0.115	-0.009
0.172	-0.022	0.196	-0.242	-0.272	-0.300	0.679	0.485	-0.113	-0.018
-0.068	-0.080	0.135	-0.215	-0.281	-0.234	-0.371	-0.629	0.508	-0.003
-0.176	-0.104	-0.084	0.023	0.224	-0.153	-0.298	-0.459	-0.760	0.001
-0.802	0.410	0.119	-0.212	0.175	-0.249	-0.006	0.120	0.141	0.049

REDUCED MATRIX AS CALCULATED BY FT025

369.495	-0.345	2.058	-2.002	-7.402	3.540	2.746	2.097	-14.075	18.357
0.0	26.701	-5.653	-0.293	-6.880	15.673	-9.210	-3.376	-4.818	8.890
0.0	0.0	27.218	-6.929	-0.733	-4.428	12.856	-11.685	-2.205	-3.335
0.0	0.0	0.0	27.286	-8.485	2.047	-4.131	12.943	-13.336	-0.925
0.0	0.0	0.0	0.0	25.686	-3.698	-0.530	-4.943	8.133	-5.228
0.0	0.0	0.0	0.0	0.0	21.741	-0.571	2.959	-2.464	4.079
0.0	0.0	0.0	0.0	0.0	0.0	21.831	-2.301	3.263	-4.449
0.0	0.0	0.0	0.0	0.0	0.0	0.0	20.493	-1.470	2.284
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	17.224	8.804
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-0.000

QT = ORTHOG MATRIX THAT REDUCES T

0.050	-0.040	0.007	0.008	0.011	-0.023	-0.004	0.005	0.001	0.998
0.233	0.696	-0.550	-0.094	0.109	0.157	-0.322	-0.056	0.075	0.020
0.338	0.375	0.569	-0.521	0.114	0.141	0.088	-0.328	-0.040	0.002
-0.087	0.393	0.366	-0.551	-0.508	0.127	0.125	0.070	-0.324	0.022
-0.284	-0.103	0.271	0.466	-0.586	-0.499	0.049	0.132	0.078	-0.035
-0.179	0.149	-0.298	0.220	0.375	-0.678	-0.429	-0.104	0.115	0.009
-0.172	-0.022	0.196	-0.242	0.272	0.300	0.679	-0.485	0.113	0.018
0.068	0.080	-0.135	-0.215	0.281	0.234	-0.371	0.629	-0.508	0.003
0.176	0.104	0.084	-0.023	-0.224	0.153	0.298	-0.459	0.760	-0.001
-0.802	0.410	0.119	-0.212	0.175	-0.249	-0.006	0.120	0.141	0.049

IS T,(N-1) SINGULAR?(1=YES,-1=EXIT)

1,1

INPUT TOEPLITZ MATRIX T

18.600	8.200	8.000	-4.900	6.300	-2.800	-1.100	-5.900	3.700	2.200
-14.700	18.600	8.200	8.000	-4.900	6.300	-2.800	-1.100	-5.900	3.700
2.500	-14.700	18.600	8.200	8.000	-4.900	6.300	-2.800	-1.100	-5.900
2.900	2.500	-14.700	18.600	8.200	8.000	-4.900	6.300	-2.800	-1.100
4.200	2.900	2.500	-14.700	18.600	8.200	8.000	-4.900	6.300	-2.800
-8.600	4.200	2.900	2.500	-14.700	18.600	8.200	8.000	-4.900	6.300
-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600	8.200	8.000	-4.900
2.000	-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600	8.200	8.000
182.992	2.000	-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600	8.200
-246.134	182.992	2.000	-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600

REDUCED MATRIX USING HOUSEHOLDER TRANSFORMS

-296.349	134.954	2.407	4.221	-10.917	2.705	1.218	10.647	-23.160	12.288
0.0	-95.219	1.584	8.622	1.134	-7.728	-0.639	11.769	-6.393	-16.810
0.0	0.0	-27.725	7.757	-2.456	7.073	-14.633	12.223	-0.148	3.830
0.0	0.0	0.0	-25.391	6.449	-2.949	3.583	-7.463	6.448	-0.796
0.0	0.0	0.0	0.0	-25.814	6.778	-1.119	2.194	-6.596	6.129
0.0	0.0	0.0	0.0	0.0	-24.426	3.973	-2.218	6.080	-3.729
0.0	0.0	0.0	0.0	0.0	0.0	-22.495	0.210	-3.028	4.994
0.0	0.0	0.0	0.0	0.0	0.0	0.0	-17.651	-8.788	-6.908
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.000	1.216
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0

QT = PRODUCT OF HOUSEHOLDER TRANSFORMS

-0.063	0.050	-0.008	-0.010	-0.014	0.029	0.005	-0.007	-0.550	0.831
-0.154	-0.125	-0.142	-0.040	-0.051	-0.003	0.007	-0.006	-0.801	-0.535
-0.303	-0.226	-0.663	0.527	-0.094	-0.102	-0.145	0.310	-0.039	-0.031
0.038	-0.418	-0.400	-0.587	0.531	-0.126	-0.125	-0.070	-0.037	0.006
-0.186	0.080	-0.337	-0.435	-0.575	-0.535	0.112	0.156	-0.029	-0.037
0.013	-0.206	-0.083	-0.213	-0.490	-0.623	0.513	-0.050	0.075	0.069
0.264	0.171	0.085	-0.234	-0.267	-0.364	-0.658	0.439	-0.087	-0.034
-0.054	0.067	-0.072	0.194	-0.067	-0.315	-0.417	-0.817	-0.051	-0.035
0.878	-0.106	-0.287	0.192	-0.104	0.184	0.114	-0.104	-0.164	-0.046
0.000	-0.814	0.405	0.113	-0.221	0.179	-0.238	-0.016	0.102	0.113

REDUCED MATRIX AS CALCULATED BY FT025

296.349	-134.954	-2.407	-4.221	10.917	-2.705	-1.218	-10.647	23.160	-12.288
0.0	95.219	-1.584	-8.622	-1.134	7.728	0.639	-11.769	6.393	16.810
0.0	0.0	27.725	-7.757	2.456	-7.073	14.633	-12.223	0.148	-3.830
0.0	0.0	0.0	25.391	-6.449	2.949	-3.583	7.463	-6.448	0.796
0.0	0.0	0.0	0.0	25.814	-6.778	1.119	-2.194	6.596	-6.129
0.0	0.0	0.0	0.0	0.0	24.426	-3.973	2.218	-6.080	3.729
0.0	0.0	0.0	0.0	0.0	0.0	22.495	-0.210	3.028	-4.994
0.0	0.0	0.0	0.0	0.0	0.0	0.0	17.651	8.788	6.908
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-0.000	1.216
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0

QT = ORTHOG MATRIX THAT REDUCES T

0.063	-0.050	0.008	0.010	0.014	-0.029	-0.005	0.007	0.550	-0.831
0.154	0.125	-0.142	-0.040	-0.051	-0.003	-0.007	-0.006	-0.801	-0.535
0.303	0.226	0.663	-0.527	0.094	0.102	0.145	-0.310	0.039	0.031
-0.038	0.418	0.400	0.587	-0.531	0.126	0.125	0.070	0.037	-0.006
0.186	-0.080	0.337	0.435	0.575	-0.535	0.112	0.156	-0.029	0.037
-0.013	0.206	0.083	0.213	0.490	0.623	-0.513	-0.050	-0.075	-0.069
-0.264	-0.171	-0.085	0.234	0.267	-0.364	-0.658	-0.439	0.087	0.034
0.054	-0.067	0.072	-0.194	0.067	0.315	0.417	0.817	-0.051	-0.035
0.878	-0.106	-0.287	0.192	-0.104	0.184	0.114	-0.104	-0.164	-0.046
0.0	0.814	-0.405	-0.113	0.221	-0.179	0.238	0.016	-0.102	-0.113

```

C
C
C
C TEST PROGRAM FOR FTO3 IS THE SAME AS THAT FOR FTO1,
C EXCEPT THAT FTO3 IS CALLED INSTEAD OF FTO1.
C
C
C
C
C SUBROUTINE FTO3(T,R,CPHIUP,SPHIUP,CPHIDN,SPHIDN,SECTHE,
C 1 TANTHE,RM,RD1,RDJ,SIGD,Z,N,N2M1,ID1)
C
C S/R TO TRIANGULARIZE A TOEPLITZ MATRIX USING GILL ET AL'S
C ORTHOG.UPDATE ALG.,INVERSE TRANSFORMS, AND SHIFT-INVARIANCE.
C FOLLOWS ALG.8.2.2, AND THE VARIABLE NOTATION IS THE SAME.
C
C PARAMETERS
C T.....VECTOR CONTAINING 1ST ROW AND COL OF TOEPLITZ MATRIX
C TO BE TRIANGULARIZED. IF N IS THE ORDER OF THE MATRIX,
C ORDER OF STORAGE IS (1,N),(1,N-1),..., (1,1),(2,1),...
C ..., (N,1)
C R.....CONTAINS UPPER-TRIANGULAR MATRIX PRODUCED BY THE
C ORTHOGONALIZATION. NOTE THAT R(I,J),I.GT.J HAVE
C NOT BEEN ZEROED
C CPHIUP) OUTPUT COSINES,SINES (1ST LETTER 'C','S') OF THE
C SPHIUP) GIVENS ROTATIONS('PHIUP':PHI-UPSWEEP; 'PHIDN':
C CPHIDN) PHI-DOWNSWEEP) USED IN PHASE I OF FTO3.
C SPHIDN) NOTATION FOLLOWS ALG.8.2.2.
C
C SECTHE) O/P SEC(THETA),TAN(THETA), WHERE THE THETAS
C TANTHE) ARE THE ANGLES OF THE INVERSE TRANSFORMS USED
C ) IN PHASE II OF FTO3. NOT'N FOLLOWS ALG.8.2.2.
C
C RM.....TEMP. VECTOR TO STORE COL. OF R(SUPERSCRIP N-1)
C RD1.....O/P VECTOR CONTAINING 1ST COL OF R-DOT
C RDJ.....TEMP. VECTOR TO STORE COL.J OF R-DOT.
C SIGD.....O/P VECTOR CONTAINING VALUES OF SIGMA-DOT
C Z.....O/P VECTOR (= T-TRANSPOSE * (T(2,1),...,T(N,1))
C TRANSPOSE )
C N.....ORDER OF TOEPLITZ MATRIX AND R, AND LENGTH OF
C VECTORS CPHIUP,...,Z.
C N2M1.....2*N-1. T MUST BE AT LEAST THIS LENGTH
C ID1.....ROW-DIMENSION OF R
C
C TEMPORARY VARIABLE:
C RTNJ-----CURRENT VALUE OF R-TILDE(N,J)
C
C GENERAL REMARKS ON CALLING FTO3. THE ONLY INPUTS REQUIRED
C ARE T,N,N2M1 AND ID1. THE MAIN OUTPUT IS IN R. THE OTHER
C 11 VECTORS ARE BY-PRODUCTS AND TEMPORARIES OF FTO3, AND
C NORMALLY THE USER ONLY ALLOCATES SPACE FOR THESE VECTORS
C WITHOUT DOING ANYTHING MORE WITH THEM. HOWEVER, THE GIVENS
C TRANSFORM VECTORS CPHIUP,...,TANTHE CAN BE USED TO GENERATE
C THE Q-MATRIX EXPLICITLY USING ALG.8.3.1.
C
C QUICK OUTLINE OF FTO3

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```

C -----
C DEFINE
C RM = R(SUPERSCRIP T N-1) = ORTHOGONAL TRIANGULAR FACTOR
C   OF LEADING SUBMATRIX OF T.
C QM = Q(SUPERSCRIP T N-1) = OTHOGONAL MATRIX SUCH THAT
C   LEADING SUBMATRIX OF T = QM*RM
C R-DOT = MATRIX WITH 1ST ROW = T(1,1..N), REST OF 1ST
C   COLUMN = QM-TRANSP OSE * T(2..N,1),
C   TRAILING SUBMATRIX = LEADING SUBMATRIX OF T.
C
C R-DOT MAY BE TRANSFORMED TO R USING GILL ET AL'S RANK-1
C ORTHOGONAL UPDATE, WITH AN UPSWEEP AND A DOWNSWEEP OF
C GIVENS TRANSFORMS (ANGLES PHI-UP AND PHI-DOWN). THEN,
C (R(1..N-1,.)) = R-TILDE MAY BE TRANSFORMED TO AN
C ( T(N,.))
C UPPER-TRIANGULAR MATRIX WITH RM AS ITS LEADING SUBMATRIX
C USING INVERSE TRANSFORMS.
C   SUPPOSE THAT RM(.J-1) AND R(.J-1) ARE KNOWN.
C THEN R-DOT(.J) CAN BE CONSTRUCTED. PERFORM A GILL UPSWEEP
C AND DOWNSWEEP ON R-DOT(.J), YIELDING R(.J).
C PERFORM J INVERSE TRANSFORMS ON (R(1..N-1,J)) ,YIELDING
C   ( T(N,.))
C RM(.J). THIS COMPLETES THE BASIC RECURSION. NOTE THAT
C THE GILL SWEEPS AND THE INVERSE TRANSFORMS REQUIRE
C ONLY O(N) OPERATIONS, SO THE WHOLE ALGORITHM REQUIRES
C ONLY O(N**2) OPERATIONS. DETAILS OF THE CALCULATION
C OF THE GILL ROTATIONS AND INVERSE TRANSFORM ANGLES,
C WHICH PROCEEDS IN TANDEM WITH THE BASIC RECURSION,
C ARE GIVEN IN ALG.8.2.2.

      REAL*8 T(N2M1),R(ID1,N),CPHIUP(N),SPHIUP(N),CPHIDN(N),
1     SPHIDN(N),SECTHE(N),TANTHE(N),RM(N),RD1(N),RDJ(N),
2     RTNJ,SIGD(N),Z(N)
      REAL*8 EPS

C INITIALIZATION

      M=N-1
      EPS=10.**(-5)

C CALC R(1,1) AND RM(1,1) USING NORM-INVARIANCE
      RM(1)=0.
      DO 10 I=1,M
10     RM(1)=RM(1)+T(I-1+N)**2
      R(1,1)=RM(1)+T(N2M1)*T(N2M1)
      R(1,1)=DSQRT(R(1,1))
      RM(1)=DSQRT(RM(1))

C GET R-DOT(1,1),(1,2),(2,2) AND SIGMA-DOT(1),(2), WHERE SIGMA-DOT(I)
C IS NORM(R-DOT(I..N,1))
      RD1(1)=T(N)
      RDJ(1)=T(N-1)
      RDJ(2)=RM(1)
      SIGD(1)=R(1,1)
      SIGD(2)=DSQRT(SIGD(1)**2 - RD1(1)**2)

C OTHER INITIALIZATION - PHIDN(1),THETA(1)

```

```

CPHIDN(1)=RD1(1)/SIGD(1)
SPHIDN(1)=SIGD(2)/SIGD(1)
SECTHE(1)=R(1,1)/RM(1)
TANTHE(1)=T(N2M1)/RM(1)

C Z=TRANPOSE OF PRINC SUBMX OF T * T(2..N,1)
  DO 28 I=1,M
    Z(I)=0.
    DO 28 J=1,M
      28 Z(I)=Z(I)+T(J-I+N)*T(J+N)

C*****MAIN LOOP - CALC R(.J) AND RM(.J)*****

      J=2

C
C PHASE I - CALC R(.J) FROM R-DOT(.J)
C
  30 RDJ(1)=T(1-J+N)
    DO 40 I=2,J
      40 RDJ(I)=RM(I-1)
C RM CONTAINS RM(.J-1)
C
C BACK-SUBST FOR R-DOT(J,1) IN EQN. RM(TRANS)*R-DOT(.1)=Z
  RD1(J)=Z(J-1)
  IF(J.EQ.2) GO TO 60
  JM2=J-2
  DO 50 I=1,JM2
    50 RD1(J)=RD1(J)-RM(I)*RD1(I+1)
  60 RD1(J)=RD1(J)/RM(J-1)

C IF J=N, CHECK THAT RD1(N) IS POSITIVE. IF NOT, RD(N.) WAS
C REVERSED IN SIGN IN THE PREVIOUS STEP - SO RDJ(N) MUST BE
C REPLACED BY -RDJ(N).
  IF(J.NE.N) GO TO 65
  IF(RD1(N).LT.0) RDJ(N)=-RDJ(N)
  GO TO 70

C NEXT PHIUP
  65 SIGD(J+1)=DSQRT(SIGD(J)**2-RD1(J)**2)
    CPHIUP(J)=RD1(J)/SIGD(J)
    SPHIUP(J)=SIGD(J+1)/SIGD(J)
C SINGULARITY CHECK
  IF(DABS(SPHIUP(J)).GE.EPS) GO TO 68
  WRITE(6,66)
  66 FORMAT(' I/P MATRIX NUMERICALLY SINGULAR - ERROR EXIT')
  RETURN

C UP-SWEEP ON R-DOT(.J)
  68 RDJ(J+1)=0.
    CALL GIVENS(RDJ(J),RDJ(J+1),CPHIUP(J),SPHIUP(J))
  70 IF(J.EQ.2) GO TO 90
    JM1=J-1
    I=JM1
    DO 80 II=2,JM1
      CALL GIVENS(RDJ(I),RDJ(I+1),CPHIUP(I),SPHIUP(I))
  80 I=I-1

```

```

C DOWN-SWEEP ON R-DOT(.J), EXCLUDING LAST PHIDN
  90 DO 100 I=1,JM1
    CALL GIVENS(RDJ(I),RDJ(I+1),CPHIDN(I),SPHIDN(I))
  100 R(I,J)=RDJ(I)

C CALC AND APPLY LAST PHIDN IN DOWN-SWEEP (N/A IF J=N)
  IF(J.NE.N) GO TO 110
  R(N,N)=RDJ(N)
  RETURN
  110 R(J,J)=DSQRT(RDJ(J)**2 + RDJ(J+1)**2)
    CPHIDN(J)=RDJ(J)/R(J,J)
    SPHIDN(J)=RDJ(J+1)/R(J,J)

C PHASE II - CALC RM(.J) FROM R-TILDE(.J)

C INITIALIZE R-TILDE(N,J)
  RTNJ=T(2*N-J)

C FIRST J-1 INVERSE TRANSFORMS
  JM1=J-1
  DO 120 I=1,JM1
    RM(I)=R(I,J)
  120 CALL INVXFM(RM(I),RTNJ,SECTHE(I),TANTHE(I))

C CALC AND APPLY LAST THETA
  RM(J)=DSQRT(R(J,J)**2 - RTNJ**2)
C SINGULARITY CHECK
  IF(RM(J)/R(J,J).GE.EPS) GO TO 140
  WRITE(6,130)
  130 FORMAT(' LDG.SUBMX.NUMERICALLY SINGULAR - ERROR EXIT',
    1 /' REMEDY - AUGMENT I/P MATRIX AND RERUN')
  RETURN

  140 SECTHE(J)=R(J,J)/RM(J)
    TANTHE(J)=RTNJ/RM(J)

  J=J+1
  GO TO 30

C
C*****END OF MAIN LOOP*****

```

END

SUBROUTINE INVXFM(X1,X2,SECA,TANA)

```

C S/R TO APPLY AN INVERSE TRANSFORM
C
C OPERATION:
C
C (X1)      ( SECA  -TANA) (X1)
C ( )      = (          ) ( )
C (X2)      (-TANA  SECA) (X2)
C

```

REAL*8 X1,X2,SECA,TANA,T

```
T=SECA*X1 - TANA*X2
X2= -TANA*X1 + SECA*X2
X1=T
RETURN
END
```

INPUT TOEPLITZ MATRIX T

18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100	-5.900	3.700	2.200
-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100	-5.900	3.700
2.500	-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100	-5.900
2.900	2.500	-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100
4.200	2.900	2.500	-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800
-8.600	4.200	2.900	2.500	-14.700	18.600	6.200	8.000	-4.900	6.300
-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600	6.200	8.000	-4.900
2.000	-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600	6.200	8.000
0.200	2.000	-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600	6.200
-1.500	0.200	2.000	-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600

REDUCED MATRIX USING HOUSEHOLDER TRANSFORMS

-26.016	7.747	-0.780	8.378	-17.201	9.468	2.254	5.784	-9.204	3.869
0.0	-25.554	5.698	2.817	1.874	-13.458	10.343	5.309	2.054	-7.868
0.0	0.0	-27.275	7.360	-0.716	4.318	-12.849	11.746	2.957	2.031
0.0	0.0	0.0	-25.782	2.909	-0.052	6.139	-10.894	10.403	2.651
0.0	0.0	0.0	0.0	-22.936	2.543	-2.887	4.710	-11.662	10.939
0.0	0.0	0.0	0.0	0.0	-21.736	1.355	-3.165	4.339	-6.728
0.0	0.0	0.0	0.0	0.0	0.0	-20.661	2.342	-1.687	2.130
0.0	0.0	0.0	0.0	0.0	0.0	0.0	-20.551	2.515	-3.749
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-20.393	0.606
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	17.394

REDUCED MATRIX AS CALCULATED BY FT03

26.016	-7.747	0.780	-8.378	17.201	-9.468	-2.254	-5.784	9.204	-3.869
0.0	25.554	-5.698	-2.817	-1.874	13.458	-10.343	-5.309	-2.054	7.868
0.0	0.0	27.275	-7.360	0.716	-4.318	12.849	-11.746	-2.957	-2.031
0.0	0.0	0.0	25.782	-2.909	0.052	-6.139	10.894	-10.403	-2.651
0.0	0.0	0.0	0.0	22.936	-2.543	2.887	-4.710	11.662	-10.939
0.0	0.0	0.0	0.0	0.0	21.736	-1.355	3.165	-4.339	6.728
0.0	0.0	0.0	0.0	0.0	0.0	20.661	-2.342	1.687	-2.130
0.0	0.0	0.0	0.0	0.0	0.0	0.0	20.551	-2.515	3.749
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	20.393	-0.606
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-17.394

READY

C
C
C
C
C
C
C
C
C
C
C
C

TEST PROGRAM FOR FTO4 - SAME AS TEST PROGRAM FOR FTO2
EXCEPT THAT FTO4 IS CALLED INSTEAD OF FTO2.

C

SUBROUTINE FTO4(T,Y,R,N,N2M1,ID1)

C

S/R TO FIND THE Q-R DECOMPOSITION OF A TOEPLITZ MATRIX USING
GILL ET-AL'S ORTHOGONAL UPDATE ALG., INVERSE TRANSFORMS, AND
SHIFT-INVARIANCE TO GET AN $O(N)$ RECURSION ON THE COLUMNS
OF R AND ROWS OF Q-TRANSPOSE. TOTAL COMPLEXITY IS THEREFORE
 $O(N^{**2})$. FOLLOWS ALG.8.3.2, WITH THE SAME NOTATION.

C

PARAMETERS

T.....VECTOR CONTAINING 1ST ROW AND COL OF TOEPLITZ MATRIX
TO BE TRIANGULARIZED. IF N IS THE ORDER OF THE MATRIX,
ORDER OF STORAGE IS (1,N),(1,N-1),..., (1,1),(2,1),...
..., (N,1)
Y.....ORTHOGONAL MATRIX SATISFYING $YT=R$, R UPPER-TRIANGULAR
R.....CONTAINS UPPER-TRIANGULAR MATRIX PRODUCED BY THE
ORTHOGONALIZATION. NOTE THAT $R(I,J), I.GT.J$ HAVE
NOT BEEN ZEROED
N.....ORDER OF TOEPLITZ MATRIX
N2M1..... $2*N-1$. T MUST BE AT LEAST THIS LENGTH
ID1.....ROW-DIMENSION OF R

C

QUICK OUTLINE OF FTO4

C

DEFINE

$TM = T(\text{SUPERSCRIPT } N-1) = \text{LEADING SUBMATRIX OF } T$
 $RM = R(\text{SUPERSCRIPT } N-1) = \text{ORTHOGONAL TRIANGULAR FACTOR OF } TM$
 $YM = Y(\text{SUPERSCRIPT } N-1) = \text{ORTHOGONAL MATRIX SUCH THAT } YM*TM=RM$
 $R\text{-DOT} \doteq \text{MATRIX WITH 1ST ROW} = T(1,1..N), \text{ REST OF 1ST}$
 $\text{COLUMN} = YM * T(2..N,1),$
 $\text{TRAILING SUBMATRIX} = \text{LEADING SUBMATRIX OF } T.$
 $R\text{-TILDE} = (R(1..N-1,.))$
 $(T(N,.))$

C

R-DOT MAY BE TRANSFORMED TO R USING GILL ET AL'S RANK-1
ORTHOGONAL UPDATE, WITH AN UPSWEEP AND A DOWNSWEEP OF
GIVENS TRANSFORMS (ANGLES PHI-UP AND PHI-DOWN). THEN,
R-TILDE MAY BE TRANSFORMED TO AN UPPER-TRIANGULAR MATRIX
WITH RM AS ITS LEADING SUBMATRIX BY INVERSE TRANSFORMS.
WE CAN SIMILARLY TRANSFORM A MATRIX WITH YM AS ITS TRAILING
SUBMATRIX TO A MATRIX WITH YM AS ITS LEADING SUBMATRIX.
SUPPOSE THAT $RM(.J-1)$, $R(.J-1)$, $YM(J-1.)$ AND $Y(J.)$ ARE
KNOWN. THEN $R\text{-DOT}(.J)$ CAN BE CONSTRUCTED. PERFORM A GILL
UPSWEEP AND DOWNSWEEP ON $R\text{-DOT}(.J)$, YIELDING $R(.J)$.
 $Y(J.)$ MAY BE OBTAINED FROM $YM(J-1.)$ IN A SIMILAR MANNER,
RE-ARRANGING THE CALCULATIONS TO OPERATE ON ROWS, RATHER
THAN COLUMNS.

C


```

C   CONSTRUCT R-TILDE(.J) FROM THE DEFINITION, AND PERFORM
C   J INVERSE TRANSFORMS ON R-TILDE(.J), YIELDING RM(.J).
C   YM(.J) MAY BE OBTAINING FROM Y(.J) BY AN INVERSE
C   TRANSFORM. THIS COMPLETES THE BASIC RECURSION.
C       NOTE THAT THE GILL SWEEPS AND INVERSE TRANSFORMS,
C   WHICH ACCOUNT FOR MOST OF THE COMPUTING LOAD, REQUIRE
C   ONLY O(N) OPS./RECURSION CYCLE, SO THE WHOLE ALG.
C   REQUIRES ONLY O(N**2) OPS. DETAILS OF THE CALC. OF
C   THE GILL AND INVERSE TRANSFORM ANGLES (THIS CALC.
C   PROCEEDS IN TANDEM WITH THE BASIC RECURSION) ARE GIVEN
C   IN ALG.8.3.2.

C   NOTATION - WORKING STORAGE
C   -----
C   CPHIUP) O/P COSINES,SINES (1ST LETTER 'C','S') OF THE
C   SPHIUP)..GIVENS ROTATIONS('PHIUP':PHI-UPSWEET; 'PHIDN':
C   CPHIDN) PHI-DOWNSWEEP) USED IN PHASE I OF Q AND R
C   SPHIDN) RECURSIONS. NOTATION FOLLOWS ALG.8.3.2.
C
C   SECTHE) O/P SEC(THETA),TAN(THETA), WHERE THE THETAS
C   TANTHE)..ARE THE ANGLES OF THE INVERSE TRANSFORMS USED
C   ) USED IN PHASE II OF THE Q AND R RECURSIONS.
C   ) NOTATION FOLLOWS ALG. 8.3.2.
C
C   RM.....TEMP. VECTOR TO STORE COL. OF R(SUPERSCRIPT N-1)
C   RD1.....O/P VECTOR CONTAINING 1ST COL OF R-DOT
C   RDJ.....TEMP. VECTOR TO STORE COL.J OF R-DOT.
C   SIGD.....O/P VECTOR CONTAINING VALUES OF SIGMA-DOT
C   YD.....TEMP.VECTOR CONTAINING Y-DOT(J.)
C   YD1.....TEMP.VECTOR CONTAINING Y-DOT-1(J.), AND OVERWRITTEN
C   BY Y-DOT-1(J+1.)
C   YD2.....TEMP.VECTOR CONTAINING Y-DOT-2(J+1.)
C   YD3.....TEMP.VECTOR CONTAINING Y-DOT-3(J.), AND OVERWRITTEN
C   BY Y-DOT-3(J+1.)
C   YTN.....TEMP.VECTOR CONTAINING CURRENT VALUE OF Y-TILDE(N.)
C   YM.....TEMP.VECTOR CONTAINING YM(J.)

      REAL*8 T(N2M1),R(ID1,N),CPHIUP(100),SPHIUP(100),CPHIDN(100),
1     SECTHE(100),TANTHE(100),RM(100),RD1(100),SIGD(100),
2     SPHIDN(100),RDJ(100),RTNJ
      REAL*8 Y(ID1,N),YD(100),YD1(100),YD2(100),YD3(100),YM(100),
1     YTN(100)
      REAL*8 EPS

C   INITIALIZATION

      IF(N.LE.100) GO TO 5
      WRITE(6,2)
2     FORMAT(' ** N.GT.100 - NO PROCESSING BY FTO4')
      RETURN

5     EPS=10.**(-5)
      M=N-1

C   CALC R(1,1) AND RM(1,1) USING NORM-INVARIANCE
      RM(1)=0.
      DO 10 I=1,M

```

```

10 RM(1)=RM(1)+T(I-1+N)**2
   R(1,1)=RM(1)+T(N2M1)*T(N2M1)
   R(1,1)=DSQRT(R(1,1))
   RM(1)=DSQRT(RM(1))

C GET R-DOT(1,1),(1,2),(2,2) AND SIGMA-DOT(1),(2), WHERE SIGMA-DOT(I)
C IS NORM(R-DOT(I..N,1))
   RD1(1)=T(N)
   RDJ(1)=T(N-1)
   RDJ(2)=RM(1)
   SIGD(1)=R(1,1)
   SIGD(2)=DSQRT(SIGD(1)**2 - RD1(1)**2)

C OTHER INITIALIZATION FOR R-RECURSION - PHIDN(1),THETA(1)
   CPHIDN(1)=RD1(1)/SIGD(1)
   SPHIDN(1)=SIGD(2)/SIGD(1)
   SECTHE(1)=R(1,1)/RM(1)
   TANTHE(1)=T(N2M1)/RM(1)

C INITLZN.FOR Q-RECURSION - Y-DOT(1.),YM(1.),Y(1.),
C Y-DOT-1(2.),Y-DOT-3(2.),Y-TILDE(N.)
   YD(1)=1.
   DO 12 I=2,N
12 YD(I)=0.
   DO 14 I=1,M
14 YM(I)=T(I-1+N)/RM(1)
   YM(N)=0.
   DO 16 I=1,N
   Y(1,I)=T(I-1+N)/R(1,1)
   YD1(I)=(Y(1,I)-CPHIDN(1)*YD(I))/SPHIDN(1)
   YD3(I)=-SPHIDN(1)*YD(I) + CPHIDN(1)*YD1(I)
16 YTN(I)= -TANTHE(1)*Y(1,I)
   YTN(N)= -TANTHE(1)*Y(1,N) + SECTHE(1)

C*****MAIN LOOP - CALC R(.J),Y(J.),RM(.J) AND YM(J.)*****

   J=2

C
C R-RECURSION PHASE I - CALC R(.J) FROM R-DOT(.J)
C
30 RDJ(1)=T(1-J+N)
   DO 40 I=2,J
40 RDJ(I)=RM(I-1)
C RM CONTAINS RM(.J-1)

C CALC R-DOT(J,1) = YM(J-1.)*T(2..N,1)
48 RD1(J)=0.
   DO 50 I=1,M
50 RD1(J)=RD1(J) + YM(I)*T(I+N)

C IF J=N, CHECK THAT RD1(N) IS POSITIVE. IF NOT, RD(N.) WAS
C REVERSED IN SIGN IN THE PREVIOUS STEP - SO RDJ(N) MUST BE
C REPLACED BY -RDJ(N).
   IF(J.NE.N) GO TO 65
   IF(RD1(N).LT.0) RDJ(N)=-RDJ(N)
   GO TO 70

```

```

C NEXT PHIUP
65 SIGD(J+1)=DSQRT(SIGD(J)**2-RD1(J)**2)
    CPHIUP(J)=RD1(J)/SIGD(J)
    SPHIUP(J)=SIGD(J+1)/SIGD(J)
C SINGULARITY CHECK
    IF(DABS(SPHIUP(J)).GE.EPS) GO TO 68
    WRITE(6,66)
66 FORMAT(' I/P MATRIX NUMERICALLY SINGULAR - ERROR EXIT')
    RETURN

C APPLY PHIUP(J), THEN PHI(1..J-1) ON RDJ
68 RDJ(J+1)=0.
    CALL GIVENS(RDJ(J),RDJ(J+1),CPHIUP(J),SPHIUP(J))
70 CALL RSWEAP(RDJ,R(1,J),CPHIUP,SPHIUP,CPHIDN,SPHIDN,J-1,J)

C CALC AND APPLY LAST PHIDN IN DOWN-SWEEP (N/A IF J=N)
    IF(J.NE.N) GO TO 110
    DO 105 I=1,N
105 Y(N,I)=YD3(I)
    RETURN
110 R(J,J)=DSQRT(RDJ(J)**2 + RDJ(J+1)**2)
    CPHIDN(J)=RDJ(J)/R(J,J)
    SPHIDN(J)=RDJ(J+1)/R(J,J)

C Q-RECURSION PHASE I - CALC Y-DOT(J.),Y-DOT-1(J+1.),Y-DOT-2(J+1.),
C Y(J.) AND Y-DOT-3(J+1.)
    YD(1)=0.
    DO 112 I=2,N
112 YD(I)=YM(I-1)
    DO 115 I=1,N
        YD1(I)=(YD1(I)-CPHIUP(J)*YD(I))/SPHIUP(J)
        YD2(I)=-SPHIUP(J)*YD(I) + CPHIUP(J)*YD1(I)
        Y(J,I)=CPHIDN(J)*YD3(I) + SPHIDN(J)*YD2(I)
115 YD3(I)=-SPHIDN(J)*YD3(I) + CPHIDN(J)*YD2(I)

C R-RECURSION PHASE II - CALC RM(.J) FROM R-TILDE(.J)

C INITIALIZE R-TILDE(N,J)
    RTNJ=T(2*N-J)

C FIRST J-1 INVERSE TRANSFORMS
    JM1=J-1
    DO 120 I=1,JM1
        RM(I)=R(I,J)
120    CALL INVXFM(RM(I),RTNJ,SECTHE(I),TANTHE(I))

C CALC AND APPLY LAST THETA
    RM(J)=DSQRT(R(J,J)**2 - RTNJ**2)
C SINGULARITY CHECK
    IF(RM(J)/R(J,J).GE.EPS) GO TO 140
    WRITE(6,130)
130 FORMAT(' LDG.SUBMX.NUMERICALLY SINGULAR - ERROR EXIT',
1 /' REMEDY - AUGMENT I/P MATRIX AND RERUN')
    RETURN

140 SECTHE(J)=R(J,J)/RM(J)
    TANTHE(J)=RTNJ/RM(J)

```

```
C Q-RECURSION PHASE II - CALC. YM(J.) AND NEW YTN
  DO 160 I=1,N
160 YM(I)=Y(J,I)
  DO 165 I=1,N
165 CALL INVXFM(YM(I),YTN(I),SECTHE(J),TANTHE(J))
```

```
  J=J+1
  GO TO 30
```

```
C
C*****END OF MAIN LOOP*****
```

```
  END
```

```
C
C
C
C
C
C
C
C
```

```
  SUBROUTINES RSWEAP, INVXFM ARE THE SAME AS IN FTO2.
```

INPUT TOEPLITZ MATRIX T

18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100	-5.900	3.700	2.200
-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100	-5.900	3.700
2.500	-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100	-5.900
2.900	2.500	-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100
4.200	2.900	2.500	-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800
-8.600	4.200	2.500	2.500	-14.700	18.600	6.200	8.000	-4.900	6.300
-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600	6.200	8.000	-4.900
2.000	-1.500	-8.600	4.200	2.900	-14.700	18.600	6.200	8.000	-4.900
0.200	2.000	-1.500	-8.600	4.200	2.900	-14.700	18.600	6.200	8.000
-1.500	0.200	2.000	-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600

REDUCED MATRIX USING HOUSEHOLDER TRANSFORMS

-28.016	7.747	-0.780	8.378	-17.201	9.468	2.254	5.784	-9.204	3.869
0.0	-25.554	5.638	2.817	1.874	-13.458	10.343	5.309	2.054	-7.868
0.0	0.0	-27.275	7.360	-0.716	4.318	-12.849	11.746	2.957	2.031
0.0	0.0	0.0	-25.782	2.909	-0.052	6.139	-10.894	10.403	2.651
0.0	0.0	0.0	0.0	-22.936	2.543	-2.887	4.710	-11.662	10.939
0.0	0.0	0.0	0.0	0.0	-21.736	1.355	-3.165	4.339	-6.728
0.0	0.0	0.0	0.0	0.0	0.0	-20.661	2.342	-1.687	2.130
0.0	0.0	0.0	0.0	0.0	0.0	0.0	-20.551	2.515	-3.749
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-20.393	0.606
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	17.394

QT = PRODUCT OF HOUSEHOLDER TRANSFORMS

-0.715	-0.565	-0.096	-0.111	0.161	0.331	0.058	-0.077	-0.008	0.058
-0.459	-0.557	0.546	-0.132	-0.162	-0.064	0.354	0.035	-0.081	0.010
-0.369	-0.360	-0.565	0.515	-0.121	-0.129	-0.082	-0.325	0.038	-0.073
-0.198	-0.290	-0.373	-0.625	-0.465	-0.033	0.078	-0.091	0.333	0.057
0.210	-0.281	-0.262	-0.293	-0.640	0.388	-0.131	-0.088	-0.143	0.342
0.054	0.197	-0.297	0.266	-0.355	-0.652	-0.451	-0.116	-0.097	-0.149
-0.110	0.108	0.216	-0.323	0.206	-0.323	-0.641	0.496	-0.073	-0.124
-0.111	-0.065	0.135	0.191	-0.280	-0.216	-0.372	-0.629	0.511	-0.088
-0.173	-0.036	-0.035	0.091	-0.241	-0.312	-0.257	-0.358	-0.611	0.487
0.035	0.149	0.106	0.098	-0.033	-0.212	0.151	0.295	0.459	0.767

REDUCED MATRIX AS CALCULATED BY FT04

28.016	-7.747	0.780	-8.378	17.201	-9.468	-2.254	-5.784	9.204	-3.869
0.0	25.554	-5.638	-2.817	-1.874	13.458	-10.343	-5.309	-2.054	7.868
0.0	0.0	27.275	-7.360	0.716	-4.318	12.849	-11.746	-2.957	-2.031
0.0	0.0	0.0	25.782	-2.909	-0.052	-6.139	10.894	-10.403	-2.651
0.0	0.0	0.0	0.0	22.936	-2.543	2.887	-4.710	11.662	-10.939
0.0	0.0	0.0	0.0	0.0	21.736	-1.355	3.165	-4.339	6.728
0.0	0.0	0.0	0.0	0.0	0.0	20.661	-2.342	1.687	-2.130
0.0	0.0	0.0	0.0	0.0	0.0	0.0	20.551	-2.515	3.749
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	20.393	-0.606
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-17.394

QT = ORTHOG MATRIX THAT REDUCES T

0.715	-0.565	0.096	0.111	0.161	-0.331	-0.058	0.077	0.008	-0.058
0.459	0.557	-0.546	0.132	0.162	0.064	-0.354	-0.035	0.081	-0.010
0.369	0.360	0.565	-0.515	0.121	0.129	0.082	-0.325	-0.038	0.073
0.198	0.290	0.373	0.625	-0.465	-0.033	0.078	0.091	-0.333	-0.057
-0.210	0.281	0.262	0.293	0.640	-0.388	0.131	0.088	0.143	-0.342
-0.054	-0.197	0.297	0.266	0.355	-0.652	-0.451	0.116	0.097	0.149
0.110	-0.108	-0.216	0.323	0.206	0.323	0.641	-0.496	0.073	0.124
0.111	0.065	-0.135	-0.191	0.280	0.216	0.372	0.629	-0.511	0.088
0.173	0.036	0.035	-0.091	-0.241	0.312	-0.257	0.358	0.611	-0.487
-0.035	-0.149	-0.106	-0.098	0.033	0.212	-0.151	-0.295	-0.459	-0.767

READY

```

C TEST PROGRAM FOR FT05, WHICH ORTHOGONALLY-TRIANGULARIZES A
C TOEPLITZ MATRIX IN O(N**2) OPERATIONS. FT05 USES THE
C GILL-GOLUB-MURRAY-SAUNDERS ORTHOGONAL-UPDATE ALGORITHM
C WITH FAST GIVENS TRANSFORMS, FAST INVERSE TRANSFORMS,
C AND THE SHIFT-INVARIANCE OF THE TOEPLITZ MATRIX.
C
C TEST PROCEDURE: (1) GENERATE TOEP.MX. 'A' WITH 1ST ROW
C AND COL FROM 'T'. (2) REDUCE TOEP.MX. WITH HOUSEHOLDER
C TRANSFORMS (O/P OVERWRITES 'A') TO UPR.TRIANGULAR FORM
C (3) CALL FT05 TO PRODUCE UPR.TRIANGLE IN 'R'.
C
C OTHER VARIABLES: N=MATRIX ORDER, ID1=ROW DIM.OF MATRICES
C
REAL*8 T(19),A(10,10),R(10,10)
DATA T/2.2,3.7,-5.9,-1.1,-2.8,6.3,-4.9,8.0,
1 6.2,18.6,-14.7,2.5,2.9,4.2,-8.6,-1.5,2.0,
2 0.2,-1.5/

ID1=10
N=10
N2M1=2*N-1
NM1=N-1

CALL TOEPMX(T,A,N,N2M1,ID1)
WRITE(6,10)
10 FORMAT('//////////' INPUT TOEPLITZ MATRIX T')
CALL PRNTMX(A,N,N,ID1)

C REDUCE TOEPLITZ MATRIX BY HOUSEHOLDER TRANSFORMS
CALL HOUTRI(A,N,ID1)
DO 30 I=2,N
IM1=I-1
DO 30 J=1,IM1
30 A(I,J)=0.

WRITE(6,40)
40 FORMAT(' REDUCED MATRIX USING HOUSEHOLDER TRANSFORMS')
CALL PRNTMX(A,N,N,ID1)

C REDUCE TOEPLITZ MATRIX USING FT05
CALL FT05(T,R,N,N2M1,ID1)
DO 15 I=2,N
IM1=I-1
DO 15 J=1,IM1
15 R(I,J)=0.

WRITE(6,20)
20 FORMAT(' REDUCED MATRIX AS CALCULATED BY FT05')
CALL PRNTMX(R,N,N,ID1)
STOP
END

SUBROUTINE FT05(T,R,N,N2M1,ID1)
C
C S/R TO TRIANGULARIZE A TOEPLITZ MATRIX USING GILL ET AL'S

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C ORTHOGONAL UPDATE ALG. WITH FAST GIVENS TRANSFORMS, FAST
C INVERSE TRANSFORMS, AND SHIFT-INVARIANCE. FOLLOWS ALG.
C 8.4.1, AND THE VARIABLE NOTATION IS THE SAME.
C
C
C PARAMETERS:
C T.....VECTOR CONTAINING 1ST ROW AND COL OF TOEPLITZ MATRIX
C         TO BE TRIANGULARIZED. IF N IS THE ORDER OF THE MATRIX,
C         ORDER OF STORAGE IS (1,N),(1,N-1),..., (1,1), (2,1),...
C         ..., (N,1)
C R.....CONTAINS UPPER-TRIANGULAR MATRIX PRODUCED BY THE
C         ORTHOGONALIZATION. NOTE THAT R(I,J), I.GT.J HAVE
C         NOT BEEN ZEROED
C N.....ORDER OF TOEPLITZ MATRIX
C N2M1.....2*N-1
C ID1.....ROW-DIMENSION OF R
C
C TEMPORARIES:
C TPHIUP)
C SPHIUP) TAN'S,COS'S,SINES(1ST LETTER=T,C,S) OF GIVENS
C SPHIDN)..ROTATIONS USED (PHIUP:PHI-UPSWEET,PHIDN:PHI-
C TPHIDN) DOWNSWEEP) IN PHASE I.
C CPHIDN)
C
C FGAUP1) CO-EFFS OF FAST GIVENS TRANSFORM MATRICES USED IN
C FGAUP2)..PHASE I. (LETTERS 4,5 : UP-UPSWEET, DN-DOWNSWEEP;
C FGADN1) LAST LETTER : 1 - (1,2) ELEMENT, 2 - (2,1) ELEMENT)
C FGADN2)
C
C COSTHE)..COS,TAN OF ANGLES THETA USED IN FAST INVERSE
C TANTHE) TRANSFORMS OF PHASE II
C
C FGB1) 1ST AND 2ND CO-EFFICIENTS OF FAST INVERSE TRANSFORMS
C FGB2)....USED IN PHASE II. CORRESPOND TO C1,C2 IN 'FINVT'
C ) CALL.
C
C RM.....USED TO STORE CURRENT(JTH) COL.OF R(SUPERSCRIPT N-1)
C WM.....SCALED VERSION OF RM
C DM.....SCALING FACTORS FOR WM. RM(I)=DM(I)*WM(I).
C W.....SCALED VERSION OF R
C D.....SCALING FACTORS FOR W. R(I,J)=D(I)*W(I,J)
C RD1.....1ST COL OF R-DOT
C RDJ.....USED TO STORE CURRENT (J-TH) COL OF R-DOT
C         (OVERWRITTEN BY RESULTS OF FAST GIVENS TRANSFORMS)
C WDJ.....SCALED VERSION OF RDJ
C DD.....INITIAL SCALING FACTORS OF WDJ. RDJ(I)=DD(I)*WDJ(I)
C DD1.....SCALE FACTOR OF WDJ(I) AFTER 1ST FAST GIVENS TRANSFM
C DD2.....SCALE FACTOR OF WDJ(I) AFTER 2ND FAST GIVENS TRANSFM
C DD3.....SCALE FACTOR OF WDJ(I) AFTER 3RD FAST GIVENS TRANSFM
C RTNJ.....CURRENT VALUE OF R-TILDE(N,J)
C WTNJ.....SCALED VERSION OF RTNJ
C DTN.....SCALE FACTOR OF WTNJ. AFTER I-TH FAST INVERSE
C         TRANSFORM, RTNJ=DTN(I)*WTNJ
C SIGD.....CURRENT VALUE OF SIGMA-DOT (=SIGMA-DOT(J))
C Z..... VECTOR (= T-TRANPOSE * (T(2,1),...,T(N,1))
C                                         TRANSPOSE )
C S.....S(I)=DM(I)*RD1(I+1)

```

C
 C GENERAL REMARKS ON FTO5
 C -----
 C FTO5 IS THE SAME AS FTO3 EXCEPT THAT FAST GIVENS
 C TRANSFORMS AND FAST INVERSE TRANSFORMS ARE USED INSTEAD
 C OF THE STANDARD TRANSFORMS. FOR UNSCALED VARIABLES
 C OF THE TYPE R**, THE SCALED VARIABLES ARE W** AND THE
 C SCALING FACTORS ARE D**, WITH THE EXCEPTION OF DD1 TO
 C DD3, WHICH ARE THE SCALING FACTORS OF THE ROWS OF
 C RDJ AFTER THE 1ST, 2ND AND 3RD FAST GIVENS TRANSFORM
 C AFFECTING THAT PARTICULAR ROW.
 C THE WHOLE ALGORITHM REQUIRES $4.5N^2$ OPS. TO COMPUTE
 C THE SCALED VERSION OF R, THOUGH IT THEN CALCULATES AND
 C AND RETURNS THE ACTUAL R-MATRIX. THIS RE-SCALING IS
 C NOT USUALLY NECESSARY.

```

REAL*8 T(N2M1),R(ID1,N)
REAL*8 W(20,20),WM(20),WDJ(20),RDJ(20),
1 RD1(20),D(20),DD(20),DD1(20),DD2(20),DD3(20),
2 DM(20),Z(20),S(20),RM(20),SIGD(20),RTNJ,WTNJ,
3 DTN(20)
REAL*8 CPHIUP(20),SPHIUP(20),TPHIUP(20),CPHIDN(20),
1 TPHIDN(20),TANTHE(20),COSTHE(20),FGAUP1(20),
2 FGAUP2(20),FGADN1(20),FGADN2(20),
3 FGB1(20),FGB2(20)
REAL*8 EPS

```

C INITIALIZATION

```

M=N-1
EPS=10.**(-5)

```

C CALC R(1,1) AND RM(1,1) USING NORM-INVARIANCE

```

RM(1)=0.
DO 10 I=1,M
10 RM(1)=RM(1)+T(I-1+N)**2
R(1,1)=RM(1)+T(N2M1)*T(N2M1)
R(1,1)=DSQRT(R(1,1))
RM(1)=DSQRT(RM(1))

```

C GET R-DOT(1,1), (1,2), (2,2) AND SIGMA-DOT(1), (2), WHERE SIGMA-DOT(I)
 C IS NORM(R-DOT(I..N,1))

```

RD1(1)=T(N)
RDJ(1)=T(N-1)
RDJ(2)=RM(1)
SIGD(1)=R(1,1)
SIGD(2)=DSQRT(SIGD(1)**2 - RD1(1)**2)

```

C INITIALIZE VARIABLES FOR PHASE I

```

CPHIDN(1)=RD1(1)/SIGD(1)
TPHIDN(1)=SIGD(2)/RD1(1)
D(1)=CPHIDN(1)
DD(1)=1
DD3(1)=DD(1)
W(1,1)=R(1,1)/D(1)

```

C INITIALIZE VARIABLE FOR PHASE II

```

RTNJ=T(N2M1)

```



```

COSTHE(1)=RM(1)/R(1,1)
TANTHE(1)=RTNJ/RM(1)
DM(1)=D(1)/COSTHE(1)
WM(1)=RM(1)/DM(1)
FGB1(1)=TANTHE(1)/DM(1)
FGB2(1)= -TANTHE(1)*DM(1)
DTN(1)=COSTHE(1)

```

```

C Z=TRANPOSE OF PRINC SUBMX OF T * T(2..N,1)
  DO 28 I=1,M
    Z(I)=0.
    DO 28 J=1,M
  28 Z(I)=Z(I)+T(J-I+N)*T(J+N)

```

```

C*****MAIN LOOP - CALC W(.J) AND WM(.J)*****

```

```

  J=2

```

```

C
C PHASE I - CALC W(.J) FROM W-DOT(.J)
C
  30 JM1=J-1
    JM2=J-2
    WDJ(1)=T(1-J+N)
    DO 40 I=2,J
  40 WDJ(I)=WM(I-1)
    DD(J)=DM(J-1)
    DD1(J)=DD(J)
    RDJ(J)=WDJ(J)*DD(J)
C WM CONTAINS WM(.J-1)
C
C BACK-SUBST FOR S(JM1) IN EQN. WM(TRANS)*S=Z. THEN
C RD1(2..N,.)=S
  S(JM1)=Z(JM1)
  IF(J.EQ.2) GO TO 60
  DO 50 I=1,JM2
  50 S(JM1)=S(JM1)-WM(I)*S(I)
  60 S(JM1)=S(JM1)/WM(JM1)
  RD1(J)=S(JM1)/DM(JM1)

C IF J=N, CHECK THAT RD1(N) IS POSITIVE. IF NOT, RD(N.) WAS
C REVERSED IN SIGN IN THE PREVIOUS STEP - SO RDJ(N) MUST BE
C REPLACED BY -RDJ(N).
  IF(J.NE.N) GO TO 65
  IF(RD1(N).LT.0) WDJ(N)=-WDJ(N)
  GO TO 70

C NEXT PHIUP
  65 SIGD(J+1)=DSQRT(SIGD(J)**2-RD1(J)**2)
  CPHIUP(J)=RD1(J)/SIGD(J)
  SPHIUP(J)=SIGD(J+1)/SIGD(J)
  TPHIUP(J)=SIGD(J+1)/RD1(J)
C SINGULARITY CHECK
  IF(DABS(SPHIUP(J)).GE.EPS) GO TO 68
  WRITE(6,66)
  66 FORMAT(' I/P MATRIX NUMERICALLY SINGULAR - ERROR EXIT')
  RETURN

```

```

C FAST GGMS UPSWEEP/DOWNSWEEP ON W-DOT(.J) (PROC 8.4.2)
C (1) UP-SWEEP ON W-DOT(.J)
68 DD1(J)=DD(J)*CPHIUP(J)
   DD2(J)=DD1(J)
   RDJ(J+1)= -RDJ(J)*SPHIUP(J)
70 IF(J.EQ.2) GO TO 105
C CALC FGT MATRIX FOR PHIUP(J-1)
   FGAUP1(JM1)=TPHIUP(JM1)*DD1(J)/DD(JM1)
   FGAUP2(JM1)= -TPHIUP(JM1)*DD(JM1)/DD1(J)
   DD2(J)=DD1(J)*CPHIUP(JM1)

   I=JM1
   DO 80 II=2, JM1
   CALL FGT(WDJ(I),WDJ(I+1),FGAUP1(I),FGAUP2(I))
80 I=I-1

C (2) DOWN-SWEEP ON R-DOT(.J), EXCLUDING LAST TWO PHIDN'S
DO 100 I=1, JM2
   CALL FGT(WDJ(I),WDJ(I+1),FGADN1(I),FGADN2(I))
100 W(I,J)=WDJ(I)

C CALC AND APPLY FGT FOR PHIDN(J-1)
105 FGADN1(JM1)=TPHIDN(JM1)*DD2(J)/DD3(JM1)
   FGADN2(JM1)= -TPHIDN(JM1)*DD3(JM1)/DD2(J)
   DD3(J)=DD2(J)*CPHIDN(JM1)
   CALL FGT(WDJ(JM1),WDJ(J),FGADN1(JM1),FGADN2(JM1))
   W(JM1,J)=WDJ(JM1)

C CALC AND APPLY LAST PHIDN IN DOWN-SWEEP (N/A IF J=N)
IF(J.NE.N) GO TO 110
W(N,N)=WDJ(N)
D(N)=DD3(N)
GO TO 158

110 RDJ(J)=DD3(J)*WDJ(J)
   R(J,J)=DSQRT(RDJ(J)**2 + RDJ(J+1)**2)
   CPHIDN(J)=RDJ(J)/R(J,J)
   TPHIDN(J)=RDJ(J+1)/RDJ(J)
   D(J)=DD3(J)*CPHIDN(J)
   W(J,J)=R(J,J)/D(J)

C PHASE II - CALC WM(.J) FROM W-TILDE(.J)

C INITIALIZE W-TILDE(N,J)
   WTNJ=T(2*N-J)

C 1ST J-1 FAST INVERSE TRANSFORMS
   DO 120 I=1, JM1
   WM(I)=W(I,J)
120 CALL FINVT(WM(I),WTNJ,FGB1(I),FGB2(I))

C
C CALC AND APPLY LAST THETA
   RTNJ=WTNJ*DTN(JM1)
   RM(J)=DSQRT(R(J,J)**2 - RTNJ**2)
C SINGULARITY CHECK
   IF(RM(J)/R(J,J).GE.EPS) GO TO 140
   WRITE(6,123)

```

```

123 FORMAT(' LDG SUBMX NUMERICALLY SINGULAR - ERROR EXIT',
1         /' REMEDY - AUGMENT I/P MATRIX AND RERUN')
RETURN

```

```

140 COSTHE(J)=RM(J)/R(J,J)
TANTHE(J)=RTNJ/RM(J)
DM(J)=D(J)/COSTHE(J)
WM(J)=RM(J)/DM(J)
FGB1(J)=TANTHE(J)*DTN(JM1)/DM(J)
FGB2(J)= -TANTHE(J)*DM(J)/DTN(JM1)
DTN(J)=DTN(JM1)*COSTHE(J)

```

```

J=J+1
GO TO 30

```

```

C
C*****END OF MAIN LOOP*****

```

```

C RE-SCALE R
158 DO 160 I=1,N
DO 160 J=1,N
160 R(I,J)=W(I,J)*D(I)
RETURN
END

```

```

SUBROUTINE FGT(A,B,C1,C2)

```

```

C
C S/R TO APPLY A FAST GIVENS TRANSFORM
C
C OPERATION:
C
C ( A ) ( 1 C1 ) ( A )
C ( ) = ( ) ( )
C ( B ) ( C2 1 ) ( B )

```

```

REAL*8 A,B,C1,C2,T

```

```

T=A+C1*B
B=C2*A+B
A=T
RETURN
END

```

```

SUBROUTINE FINVT(X,Y,C1,C2)

```

```

C
C S/R TO APPLY A FAST INVERSE TRANSFORM
C
C OPERATION:
C SOLVE FOR X AND Y' IN
C
C ( X' ) ( 1 C1 ) ( X )
C ( ) = ( ) ( )
C ( Y' ) ( C2 1 ) ( Y )

```

```
REAL*8 X,Y,C1,C2
```

```
X=X-C1*Y
```

```
Y=C2*X+Y
```

```
RETURN
```

```
END
```

INPUT TOEPLITZ MATRIX T

18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100	-5.900	3.700	2.200
-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100	-5.900	3.700
2.500	-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100	-5.900
2.500	2.500	-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800	-1.100
4.200	2.900	2.500	-14.700	18.600	6.200	8.000	-4.900	6.300	-2.800
-8.600	4.200	2.900	2.500	-14.700	18.600	6.200	8.000	-4.900	6.300
-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600	6.200	8.000	-4.900
2.000	-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600	6.200	8.000
0.200	2.000	-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600	6.200
-1.500	0.200	2.000	-1.500	-8.600	4.200	2.900	2.500	-14.700	18.600

REDUCED MATRIX USING HOUSEHOLDER TRANSFORMS

-26.016	7.747	-0.780	8.378	-17.201	9.468	2.254	5.784	-9.204	3.869
0.0	-25.554	5.698	2.817	1.874	-13.458	10.343	5.309	2.054	-7.868
0.0	0.0	-27.275	7.360	-0.716	4.318	-12.849	11.746	2.957	2.031
0.0	0.0	0.0	-25.782	2.909	-0.052	6.139	-10.894	10.403	2.651
0.0	0.0	0.0	0.0	-22.936	2.543	-2.887	4.710	-11.662	10.939
0.0	0.0	0.0	0.0	0.0	-21.736	1.355	-3.165	4.339	-6.728
0.0	0.0	0.0	0.0	0.0	0.0	-20.661	2.342	-1.687	2.130
0.0	0.0	0.0	0.0	0.0	0.0	0.0	-20.551	2.515	-3.749
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-20.393	0.606
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	17.394

REDUCED MATRIX AS CALCULATED BY FT05

26.016	-7.747	0.780	-8.378	17.201	-9.468	-2.254	-5.784	9.204	-3.869
0.0	25.554	-5.698	-2.817	-1.874	13.458	-10.343	-5.309	-2.054	7.868
0.0	0.0	27.275	-7.360	0.716	-4.318	12.849	-11.746	-2.957	-2.031
0.0	0.0	0.0	25.782	-2.909	0.052	-6.139	10.894	-10.403	-2.651
0.0	0.0	0.0	0.0	22.936	-2.543	2.887	-4.710	11.662	-10.939
0.0	0.0	0.0	0.0	0.0	21.736	-1.355	3.165	-4.339	6.728
0.0	0.0	0.0	0.0	0.0	0.0	20.661	-2.342	1.687	-2.130
0.0	0.0	0.0	0.0	0.0	0.0	0.0	20.551	-2.515	3.749
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	20.393	-0.606
0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	-17.394

READY


```
      SUBROUTINE COPYMX(A,B,M,N,ID1)
C   S/R TO COPY A(M X N) TO B.
C   (ID1 IS THE ROW-DIMENSION OF A AND B)
```

```
      REAL*8 A(ID1,N),B(ID1,N)
```

```
      DO 10 I=1,M
      DO 10 J=1,N
10   B(I,J)=A(I,J)
      RETURN
      END
```

```
SUBROUTINE GIVENS(A,B,COSX,SINX)
REAL*8 A,B,T,COSX,SINX
```

```
C
```

```
C S/R TO PERFORM GIVENS ROTATION OF ANGLE X ON A AND B.
```

```
T=A
A=A*COSX + B*SINX
B=-T*SINX + B*COSX
RETURN
END
```



```
      SUBROUTINE HOUQR(A,QT,N,ID1)
C   S/R TO TRIANGULARIZE A(N X N) USING HOUSEHOLDER'S METHOD,
C   AND ACCUMULATE THE H/H TRANSFMS IN QT.
C   (ID1 IS THE ROW-DIMENSION OF A AND QT).
```

```
      REAL*8 A(ID1,N),QT(ID1,N),UP
      NM1=N-1
      CALL IDMX(QT,N,ID1)
      DO 10 J=1,NM1
      CALL VHS12(1,J,J+1,N,A(1,J),1,UP,A(1,J+1),1,ID1,N-J)
10  CALL VHS12(2,J,J+1,N,A(1,J),1,UP,QT(1,1),1,ID1,N)
      RETURN
      END
```

```
      SUBROUTINE HOUTRI(A,N,ID1)
C
C S/R TO TRIANGULARIZE A(N X N) USING HOUSEHOLDER'S METHOD.
C ID1 IS THE ROW-DIMENSION OF A.
C SEE IMSL WRITE-UP FOR VHS12, WHICH PERFORMS A SINGLE
C HOUSEHOLDER TRANSFORM

      REAL*8 A(ID1,N),UP
      NM1=N-1
      DO 10 J=1,NM1
10 CALL VHS12(1,J,J+1,N,A(1,J),1,UP,A(1,J+1),1,ID1,N-J)
      RETURN
      END
```

```
SUBROUTINE IDMX(A,N,ID1)
```

```
C
```

```
C S/R TO GENERATE THE IDENTITY MATRIX IN A(N X N).
```

```
C (ID1 IS THE ROW-DIMENSION OF A).
```

```
REAL*8 A(ID1,N)
```

```
DO 20 I=1,N
```

```
DO 10 J=1,N
```

```
10 A(I,J)=0.
```

```
20 A(I,I)=1.
```

```
RETURN
```

```
END
```

```
SUBROUTINE MULTMX(A,B,C,L,M,N,ID1,ID2,ID3)
```

```
C S/R TO MULTIPLY A(L X M) BY B(M X N), YIELDING C(L X N).  
C ID1, ID2 AND ID3 ARE THE ROW-DIMENSIONS OF A, B AND C  
C RESPECTIVELY.  
C
```

```
REAL*8 A(ID1,M),B(ID2,N),C(ID3,N)
```

```
DO 10 I=1,L
```

```
DO 10 J=1,N
```

```
C(I,J)=0.
```

```
DO 10 K=1,M
```

```
10 C(I,J)=C(I,J)+A(I,K)*B(K,J)
```

```
RETURN
```

```
END
```

```
      SUBROUTINE PRNTMX(A,M,N,ID1)
C
C S/R TO PRINT A(M X N). (ID1 IS THE ROW-
C DIMENSION OF A). FORMAT IS AS FOLLOWS:
C MAX MAGN .LT. 10000 : 14F9.3
C 10000.LE.MAX MAGN .LT.10**7 : 14F9.0
C MAX MAGN .GE. 10**7 : 14D9.2

      REAL*8 A(ID1,N),MAXMAG

C FIND MAX MAGNITUDE
      MAXMAG=0.
      DO 10 I=1,M
      DO 10 J=1,N
      IF(DABS(A(I,J)).GT.MAXMAG) MAXMAG=DABS(A(I,J))
10 CONTINUE

      IFMT=1
      IF(MAXMAG.GE.10000.) IFMT=2
      IF(MAXMAG.GE.1D7) IFMT=3

      DO 50 I=1,M
      GO TO (20,30,40),IFMT
20 WRITE(6,21) (A(I,J),J=1,N)
21 FORMAT(1X,14F9.3)
      GO TO 50
30 WRITE(6,31) (A(I,J),J=1,N)
31 FORMAT(1X,14F9.0)
      GO TO 50
40 WRITE(6,41) (A(I,J),J=1,N)
41 FORMAT(1X,14D9.2)
50 CONTINUE
      RETURN
      END
```

```

SUBROUTINE SINGSM(A,M,N,ID1,I,J,K,LI,LJ,WKAREA,K2P3,IER)
C
C S/R TO RE-CALCULATE A(I,J) TO MAKE A K X K SUBMATRIX WITH
C A(I,J) ON A CORNER SINGULAR. IF LI IS +1(-1), A(I,J) IS ON A
C TOP(BOTTOM) CORNER. IF LJ IS +1(-1), A(I,J) IS ON A LEFT
C (RIGHT) CORNER.
C OTHER PARAMETERS
C M,N ..... ROW AND COLUMN ORDERS OF A
C ID1 ..... ROW-DIMENSION OF A
C WKAREA ... WORKING AREA OF SIZE AT LEAST K*(2*K+3)
C K2P3 ..... 2*K+3
C                GE.K*(2K*3)
C IER ..... ERROR PARAMETER
C                IER=0 NO ERROR
C                IER=1 TOP OF SUBMATRIX IS ABOVE TOP OF A
C                IER=2 BOTTOM OF SUBMATRIX IS BELOW BOTTOM OF A
C                IER=4 LEFT OF SUBMATRIX IS BEFORE LEFT OF A
C                IER=8 RIGHT OF SUBMATRIX IS AFTER RIGHT OF A
C                IER=16 LI.NE.-1 OR 1
C                IER=32 LJ.NE.-1 OR 1
C                IER CAN ALSO BE A COMBINATION OF THE ABOVE,
C                E.G. IER=10=8+2 MEANS THAT SUBMATRIX EXTENDS
C                BOTH BELOW AND TO THE LEFT OF A
C
C ALGORITHM. LET B BE THE SUBMATRIX THAT IS TO BE MADE SINGULAR,
C LET C BE THE SUBMATRIX OF B FOUND BY DELETING THE ROW AND
C COLUMN OCCUPIED BY A(I,J), AND LET D-TRANSPOSE AND F BE
C THE ROW AND COLUMN OF B LOCATED BY, BUT EXCLUDING A(I,J).
C THEN, FOR B TO BE SINGULAR,
C
C                A(I,J) = D-TRANSPOSE * C-INVERSE * F
C
C REAL*8 A(ID1,N),WKAREA(K,K2P3)
C
C IER=0
C IDGT=0
C KM1=K-1
C
C CHECK FOR ERROR CONDITIONS
C IER=0
C ITOP=I+KM1*((LI-1)/2)
C IF(ITOP.LT.1) IER=IER+1
C IF(ITOP+KM1.GT.M) IER=IER+2
C LEFT=J+KM1*((LJ-1)/2)
C IF(LEFT.LT.1) IER=IER+4
C IF(LEFT+KM1.GT.N) IER=IER+8
C IF(LI.NE.-1.AND.LI.NE.1) IER=IER+16
C IF(LJ.NE.-1.AND.LJ.NE.1) IER=IER+32
C IF(IER.EQ.0) GO TO 5
C WRITE(6,2) IER
C 2 FORMAT(' SINGSM ERROR COND =',I3,' NO OPS PERFORMED')
C RETURN
C
C I1F,J1F ARE THE STARTING INDICES OF F, AND I1C,J1C ARE
C THE STARTING INDICES OF C
C 5 I1F=1
C IF(LI.EQ.-1) I1F=I-KM1

```

```
IF(LI.EQ.1) I1F=I+1
J1F=J
I1C=I1F
J1C=1
IF(LJ.EQ.-1) J1C=J-KM1
IF(LJ.EQ.1) J1C=J+1
C
C MOVE F AND C TO WORKING AREA AND SOLVE C * P = F
DO 10 II=1,KM1
WKAREA(II,K)=A(I1F+II-1,J1F)
DO 10 JJ=1,KM1
10 WKAREA(II,JJ)=A(I1C+II-1,J1C+JJ-1)
CALL LEQT2F(WKAREA,1,KM1,K,WKAREA(1,K),IDGT,WKAREA(1,K+1),IER)
C
C COMPUTE A(I,J) = D-TRANSPOSE * P. (I1D,J1D ARE THE STARTING
C INDICES OF D)
I1D=I
J1D=J1C
A(I,J)=0.
DO 20 II=1,KM1
20 A(I,J)=A(I,J) + A(I1D,J1D+II-1) * WKAREA(II,K)
RETURN
END
```

```
      SUBROUTINE TOEPMX(T,A,N,N2M1,ID1)
C
C  S/R TO MAKE UP A TOEPLITZ MATRIX FROM ITS 1ST ROW AND COL.
C
C  T - ELEMENTS (1,N),(1,N-1),..., (1,1),(2,1),..., (N,1) OF
C      TOEPLITZ MATRIX (INPUT)
C  A - TOEPLITZ MATRIX IN FULL (OUTPUT)
C  N - ORDER OF A
C  N2M1- 2*N-1. T MUST BE AT LEAST THIS LENGTH
C  ID1 - ROW DIMENSION OF A
```

```
      REAL*8 T(N2M1),A(ID1,N)

      DO 10 K=1,N
      A(K,1)=T(N+K-1)
10  A(1,K)=T(N-K+1)

      DO 20 I=2,N
      DO 20 J=2,N
20  A(I,J)=A(I-1,J-1)
      RETURN
      END
```


SUBROUTINE TRANMX(A,N,ID1)

C S/R TO TRANSPOSE A(N X N). ID1 IS THE ROW-DIMENSION OF A.
C

```
REAL*8 A(ID1,N),TEMP
DO 10 I=2,N
  IM1=I-1
  DO 10 J=1,IM1
    TEMP=A(I,J)
    A(I,J)=A(J,I)
10 A(J,I)=TEMP
RETURN
END
```