

Modelling the impact of treatment uncertainties in radiotherapy

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A thesis submitted for the degree of

Doctor of Philosophy

in the Department of Physics and Mathematical Physics

University of Adelaide

~ March 2002 ~

Table of Contents

TABLE OF CONTENTS	III
ABBREVIATIONS AND ACRONYMS	VIII
SYMBOLS	X
LIST OF FIGURES	XIV
LIST OF TABLES	XVIII
ABSTRACT	XIX
THESIS STATEMENT	XXI
ACKNOWLEDGEMENTS	XXII
CHAPTER 1 GENERAL INTRODUCTION	1
1.1. EXTERNAL BEAM RADIOTHERAPY PLANNING	1
1.2. AIMS OF CURRENT INVESTIGATION	4
1.3. THESIS OUTLINE	5
1.4. PUBLICATIONS	6
CHAPTER 2 A REVIEW OF PATIENT POSITIONING UNCERTAINTY AND ORGAN MOTION AT VARIOUS ANATOMICAL SITES	9
2.1. INTRODUCTION	9
2.2. REVIEW OF ICRU REPORTS 50 AND 62	10
2.3. COMPARISON ACROSS STUDIES	12
2.4. PATIENT POSITIONING (SETUP) ERRORS	14
2.4.1. Defining Patient Positioning Errors	14
2.4.2. Magnitudes of positioning errors at various sites	16
2.4.3. Patient Immobilisation	18
2.4.4. Pelvis	18
2.4.5. Brain	20
2.4.6. Abdomen	20
2.4.7. Head and Neck	20
2.4.8. Breast	21
2.5. ORGAN MOTION	21
2.5.1. Defining organ motion	21

2.5.2.	Magnitudes of organ motion	22
2.5.3.	Prostate Motion	23
2.5.3.1.	<i>Supine versus prone treatment positions</i>	25
2.5.3.2.	<i>Bladder/rectum filling influence on prostate motion (MODprostate)</i>	25
2.5.3.3.	<i>Strategies to account for prostate motion</i>	27
2.5.4.	Abdominal Motion	28
2.5.4.1.	<i>Generalities</i>	28
2.5.4.2.	<i>Kidney Motion</i>	30
2.5.4.3.	<i>Diaphragm Motion</i>	30
2.5.4.4.	<i>Pancreas Motion</i>	31
2.5.4.5.	<i>Breath Holding Techniques</i>	31
2.5.4.6.	<i>Advanced Techniques</i>	31
2.5.4.7.	<i>Patient Orientation during treatment</i>	32
2.6.	PATIENT REPOSITIONING STRATEGIES	32
2.7.	CONTEMPORARY SUGGESTIONS FOR TREATMENT PLANNING	35
2.7.1.	Statistics based treatment margins	35
2.7.2.	Adaptive radiation therapy	39
2.7.3.	Monte Carlo techniques	40
2.7.4.	Convolution techniques	41
2.8.	SUMMARY	42
CHAPTER 3 REVIEW OF RADIOBIOLOGICAL MODELS		43
3.1.	INTRODUCTION	43
3.2.	BIOLOGICAL MODELS	44
3.2.1.	Empirical (Logit and Probit) Models	44
3.2.2.	Theoretical (Poisson/Linear Quadratic) Model	45
3.2.3.	Hyper sensitivity of tumour/normal tissue at low doses	48
3.2.4.	Biological Effective Dose	49
3.2.5.	Standard Effective Dose	50
3.2.6.	Equivalent Uniform Dose	50
3.3.	TUMOUR CONTROL PROBABILITY	51
3.3.1.	Accounting for interpatient radiosensitivity variation in a population of patients	52
3.3.2.	Clonogen density and optimisation	52
3.3.3.	Prostate Carcinoma	54
3.4.	NORMAL TISSUE COMPLICATION PROBABILITY	55
3.4.1.	Dose-Volume effects	55
3.4.2.	Lyman-Kutcher-Burman (LKB) model	56
3.4.3.	Källman k- and s-models	59
3.4.4.	Yaes-Kalend/Fenwick model	60
3.4.5.	Clinical application of NTCP	61
3.4.6.	Rectal complications	62
3.4.6.1.	<i>Grading rectal complications</i>	62
3.4.6.2.	<i>Rectum architecture</i>	62
3.4.6.3.	<i>Dose volume characterisation</i>	64
3.5.	UNCOMPLICATED TUMOUR CONTROL AND OBJECTIVE FUNCTIONS	67
3.6.	SUMMARY	69
CHAPTER 4 MODELLING THE DOSIMETRIC EFFECT OF TREATMENT UNCERTAINTY		71

4.1.	INTRODUCTION	71
4.2.	DOSE UNCERTAINTY	72
4.2.1.	Modelling dose uncertainty	73
4.2.2.	Probability density functions for position and dose	73
4.3.	MONTE CARLO TECHNIQUE	76
4.3.1.	Methods	76
4.3.1.1.	<i>Sampling from distributions, and the dose grid</i>	77
4.3.1.2.	<i>Dose accumulation</i>	78
4.3.1.3.	<i>Clinical example</i>	79
4.3.2.	Results	80
4.3.2.1.	<i>Mean and variance in fractionated dose for single incident beam</i>	80
4.3.2.2.	<i>Impact of margin size</i>	83
4.3.2.3.	<i>Impact of magnitude of patient positioning and organ variations</i>	83
4.3.2.4.	<i>Number of fields and dose gradients.</i>	83
4.3.3.	Discussion	85
4.3.3.1.	<i>Possible margin reductions with multiple pretreatment CT scans</i>	85
4.3.3.2.	<i>Relative importance of systematic and random components</i>	85
4.3.3.3.	<i>Comparison of spatially uniform dose error and positioning errors</i>	86
4.3.3.4.	<i>Dose reporting</i>	87
4.4.	CONVOLUTION TECHNIQUE	87
4.4.1.	Derivation of spatial PDF including systematic organ motion error	88
4.4.2.	Benchmarking against Monte Carlo results	89
4.4.3.	Margin recipe including systematic error	89
4.5.	MULTIPLE CT SCANS	90
4.5.1.	Timing regimes for multiple intra-treatment image acquisition	90
4.5.2.	Results	92
4.6.	MONTE CARLO MODELLING OF 3D DOSIMETRIC IMPACT	92
4.6.1.	Methods	92
4.6.2.	Results	95
4.6.3.	Discussion	97
4.7.	SUMMARY AND CONCLUSION	99

CHAPTER 5	MODELLING DOSE DEPOSITION TO THE DEFORMING RECTUM	101
5.1.	INTRODUCTION	101
5.2.	BACKGROUND	102
5.3.	METHODS	104
5.3.1.	‘Original’ and ‘Initial’ rectum geometries	104
5.3.1.1.	<i>Original geometry</i>	104
5.3.1.2.	<i>Initial Geometry</i>	106
5.3.2.	Modelling rectum deformations	107
5.3.3.	Modelling planning CT image acquisition	109
5.3.4.	Modelling treatment delivery	112
5.3.5.	The input data	113
5.3.5.1.	<i>Geometry</i>	113
5.3.5.2.	<i>Uncertainty parameters</i>	114
5.3.6.	Calculations	114
5.4.	RESULTS	115
5.4.1.	Planned rectum dose distributions	115
5.4.2.	Interfraction variations	117
5.4.2.1.	<i>Systematic error: empty rectum at planning</i>	117
5.4.2.2.	<i>Systematic error: full rectum at planning</i>	120

5.4.3.	Interpatient variations	121
5.5.	DISCUSSION	128
5.6.	CONCLUSIONS	130

CHAPTER 6 MODELLING THE RADIOBIOLOGICAL EFFECT OF TREATMENT UNCERTAINTY IN RADIOTHERAPY **133**

6.1.	INTRODUCTION	133
6.2.	TUMOUR CONTROL PROBABILITY	133
6.2.1.	Background	134
6.2.2.	Method	134
6.2.2.1.	<i>Input data for 1D case</i>	136
6.2.2.2.	<i>Input data for 3D case</i>	138
6.2.2.3.	<i>Calculations</i>	138
6.2.3.	Results	139
6.2.3.1.	<i>Impact of margin size</i>	139
6.2.3.2.	<i>Impact of penumbra steepness</i>	141
6.2.3.3.	<i>Impact of uniform dose uncertainty and interpatient heterogeneity</i>	143
6.2.3.4.	<i>Results using 3D input data</i>	149
6.2.4.	Discussion	151
6.3.	NORMAL TISSUE COMPLICATION PROBABILITY	154
6.3.1.	Background: Incorporating treatment uncertainty into NTCP calculation	154
6.3.2.	Methods	155
6.3.2.1.	<i>Fitting Linear-Quadratic parameters to late rectum complications</i>	155
6.3.2.2.	<i>Modelling individual treatments and patient populations</i>	156
6.3.3.	Results	156
6.3.3.1.	<i>Individual patients</i>	156
6.3.3.2.	<i>Population based results</i>	158
6.3.3.3.	<i>Impact of fluctuations in fractional dose</i>	158
6.3.3.4.	<i>Comparison with mean treatment dose</i>	160
6.3.4.	Discussion	162
6.4.	UNCOMPLICATED TUMOUR CONTROL PROBABILITY (UTCP)	165
6.4.1.	Methods	165
6.4.2.	Results	166
6.4.2.1.	<i>UTCP calculated for an individual patient</i>	166
6.4.2.2.	<i>Population based results</i>	167
6.4.3.	Discussion	171
6.5.	CONCLUSIONS	173

CHAPTER 7 TREATMENT PLANNING ALGORITHM CORRECTIONS TO ACCOUNT FOR AND DISPLAY DOSE UNCERTAINTY IN RADIOTHERAPY **175**

7.1.	INTRODUCTION	175
7.1.1.	Possibilities for future radiotherapy treatment planning	175
7.1.2.	Purpose	176
7.2.	MODIFICATIONS TO DOSE CALCULATION ALGORITHMS FOR PHOTONS	177
7.1.3.	Correction based techniques	177
7.2.1.1.	<i>Input data</i>	177
7.2.1.2.	<i>Dose calculation</i>	178
7.2.1.3.	<i>Including estimations of error</i>	180
7.1.4.	Superposition technique	180

7.2.1.4.	<i>Input data</i>	180
7.2.1.5.	<i>Dose calculation</i>	180
7.2.1.6.	<i>Including estimations of error</i>	181
7.1.5.	Monte Carlo technique	183
7.2.1.7.	<i>Input data</i>	183
7.2.1.8.	<i>Dose calculation</i>	183
7.2.1.9.	<i>Including estimations of error</i>	184
7.3.	REQUIREMENTS FOR DISPLAY INPUT DATA	185
7.1.6.	Standard deviations	185
7.1.7.	Non standard deviations	186
7.4.	TREATMENT PLANNING DISPLAYS	187
7.1.8.	Mean dose and/or standard deviation	187
7.1.9.	Modified dose volume histogram	190
7.1.10.	Mean with estimated standard deviation display	190
7.1.11.	Difference maps	192
7.5.	CRITICAL EVALUATION OF UNCERTAINTY DISPLAY TOOLS	193
7.6.	CONCLUSIONS	196
CHAPTER 8 CONCLUSIONS AND FURTHER RESEARCH		197
8.1.	MAJOR CONCLUSIONS	198
8.2.	FURTHER RESEARCH	201
Appendix A		203
References		223

Abbreviations and Acronyms

AP	Anterior-Posterior direction
BED	Biological Effective Dose
CL-DVH	Confidence Limited Dose Volume Histogram
CT	Computed Tomography
CTV	Clinical Tumour Volume
DNA	Deoxyribose Nucleic Acid
DSAR	Differential Scatter Air Ratio
DVH	Dose Volume Histogram
DWH	Dose Wall Histogram
EGS4	Electron Gamma Shower version 4
EPID	Electronic Portal Imaging Device
ETAR	Equivalent Tissue Air Ratio
EUBED	Equivalent Uniform Biologically Effective Dose
EUD	Equivalent Uniform Dose
FFT	Fast Fourier Transform
FML	Full Maximum Likelihood
FS	Field Size
FSU	Functional Sub-Unit
FWHM	Full Width at Half Maximum
GTV	Gross Tumour Volume
HDSA	High Dose Surface Area
I-125	Iodine-125
ICRU	International Commission on Radiation Units
IM	Internal Margin
IMRT	Intensity Modulated Radiation Therapy
IPTV	Internal Planning Target Volume
IR	Induced Repair
LET	Linear Energy Transfer
LQ	Linear Quadratic
LR	Left-Right direction
MC	Monte Carlo
ML	Medio Lateral (same plane as left right)

MOD	Mean Organ Displacement
MRI	(nuclear) Magnetic Resonance Imaging
MTPD	Mean Treatment Position Deviation
NAL	No Action Level
NTCP	Normal Tissue Complication Probability
OAR	Organ At Risk
PDF	Probability Density Function
PDV	Prescribed Dose Volume
PTV	Planning Target Volume
RTOG	Radiation Therapy Oncology Group grading system
RTP	Radiation Therapy Planning
SAL	Shrinking Action Level
SD	Standard Deviation
SEAS	Setup Error (averaged) Across Studies
SED	Standard effective dose
SI	Superior-Inferior direction
SM	Setup Margin
SSD	Surface-Skin Distance
TCP	Tumour Control Probability
TERMA	Total Energy Released in the Medium
TPD	Treatment Position Deviation
TPS	Treatment Planning System
UTCP	Uncomplicated Tumour Control Probability

Symbols

\bar{x}	mean organ position
\bar{x}	mean patient position based on all measurements for a group of patients
\bar{r}	mean rectal wall radius across N_z CT slices
\bar{r}_{pop}	mean rectal wall radius across patient population
\bar{D}	mean treatment dose
$d_s^*(r)$	perturbed sample fraction dose in spatial element Δr located $\Delta r + r$ units from the isocentre
$\Delta \bar{x}_j$	systematic patient positioning error for j th patient
τ	initial action level for possible patient repositioning
ϕ	proportion of patients with injury uncorrelated to benefit
ϕ_j	random deviate from Gaussian distribution describing patient position at the j th fraction dose
$\sigma_{m,organ}$	standard deviation in mean organ position
$\sigma_{R,j}$	standard deviation of random error for j th patient
Σ_T	standard deviation of systematic setup error across a group of patients
$\Delta x_{i,j}$	measured shift in patient position in i th portal image from position at simulation for j th patient
a	variable
A_0	(original) area of rectal wall segment
b	variable
c_a	partial score (for treatment plan)
C_i	score
CT_∞	infinite CT images used to calculate true mean organ position
d	fraction dose
D	treatment dose including, for example, 30 fraction doses
D_0	planned treatment dose
D_{50}	dose that produces a given endpoint in 50% of the population after 5 years
d_c	dose limit for induced repair
d_{eff}	effective depth
D_m	Maximum treatment dose
d_{max}	depth of maximum dose

d_s	fraction dose sampled from known distribution
$D_s(r)$	sum of N_{fx} sample fraction doses
d_s^*	perturbed fraction dose
d_{st}	standard dose per fraction (Gy)
$d\Theta$	angle increment
E	rotation vector
$erf()$	error function
F	objective function
g	Gaussian function
GC	(absolute) position of geometric centre of rectum
H	CTV→PTV margin
H_p	primary kernel
H_s	scatter kernel
k	parameter from Kallman k-model
m	parameter from Lyman model
M	the total number of voxels
N	a number (general)
n	parameter from Lyman model
N_0	initial number of cells in tumour/organ
N_{cell}	number of consecutive cells
N_{CT}	the number in CT image acquisitions
N_F	number of FSU's in organ
N_{FSU}	number of cells per FSU
N_{fx}	the number of fraction doses
n_j	number of portal images
N_{pat}	number of patients in a particular study
N_S	number of surviving cells following irradiation
N_{SD}	number of standard deviations
N_z	number of slices in CT image set
P	probability (general)
$P(D,1)$	dose-response function, giving the probability of a given endpoint following irradiation of whole organ volume
$P(D,v)$	dose-response function, giving the probability of a given endpoint following irradiation of partial volume
P_+	probability of uncomplicated tumour control

P_B	probability of benefit from the treatment
P_{BI}	conditional probability for benefit without injury
P_I	probability of treatment induced injury
r	radius (general)
r_0	initial rectal radius
ξ	random deviate from Gaussian distribution describing organ position
r_{def}	radius of deformed rectal wall
r_{in}	inner rectal wall radius
s	parameter from Kallman s-model
S	surviving fraction
T	TERMA (see abbreviations)
T	total time of treatment (days)
$T_{1/2}$	half-life for sub lethal damage
T_k	kick-off time (days)
T_{pot}	potential doubling time of tumour (days)
U	Utility of treatment
u_t	vector displacement at time, t.
v	partial volume (cm^3)
V_{eff}	effective volume (considering tissue architecture) (cm^3)
V_t	tumour volume (cm^3)
w	rectal wall thickness (mm).
w'	weighted change in rectal wall thickness
x	position along LR axis (mm).
$x_0(v)$	position (absolute) of v at planning (mm).
$x_t(v)$	position (absolute) of v at time, t (mm).
y	position along AP axis (mm).
z	position along SI axis (mm).
γ	gradient of dose response function
Δ	deviation or shift (of dose distribution) (mm).
Δr	change in rectum radius (mm).
Δv	sub-volume (normally volume of a voxel)
Δw	change in rectal wall thickness (mm).
ζ	random deviate sampled from Gaussian distribution

η	co-efficient
Θ	angle
μ	on-going number of measurement
ξ	organ position (mm).
ω	a weighting factor
Δ_j	total shift from mean organ position for j_{th} fraction (mm).
$\Delta r'$	weighted change in radius
Σ	standard deviation between patient variables (systematic error)
Σ_{delin}	standard deviation in interpatient (systematic) mean delineation error
Σ_{OM}	standard deviation in interpatient (systematic) mean organ motion error
Σ_{SE}	standard deviation in interpatient (systematic) mean setup error
α	parameter of the Linear Quadratic model for cell killing (Gy^{-1})
α_s	hyper sensitive cell sensitive at low dose (Gy^{-1})
β	parameter of the Linear Quadratic model for cell killing (Gy^{-2})
ρ	clonogen density (cm^{-3})
σ	standard deviation in random parameter (general)
σ_{OM}	standard deviation in interfraction (random) organ motion
σ_p	standard deviation describing the production of penumbra
σ_{SE}	standard deviation in interfraction (random) setup error
σ_{TD}	standard deviation of treatment delivery (random) errors (i.e. interfraction setup errors plus interfraction organ motion error)
σ_α	standard deviation in interpatient (systematic) cell sensitivity

List of Figures

Figure 2.1 Definitions of treatment volumes as defined by ICRU-62 (Fig. 2.16) showing their relation by scenarios A, B and C discussed in the text.

Figure 2.2 Cumulative probability distributions as a function of the normalised radius of expansion for three different CTV-PTV margin strategies. From Antolak and Rosen (1999).

Figure 3.1 Plots of Probability of effect following single fraction irradiation to dose, as calculated with the Probit model (solid curve) and Logit model (dashed).

Figure 3.2 Surviving fraction versus dose for early responding tumour tissue and late responding normal tissue. Tumour is characterised by $\alpha = 0.35 \text{ Gy}^{-1}$ and $\alpha/b = 10$, while normal tissue is characterised by $\alpha = 0.15 \text{ Gy}^{-1}$ and $\alpha/b = 3$ (from Metcalfe et al. 1997).

Figure 3.3 Survival fraction versus dose for T98G human glioma cells. The dots with error bars are the experimental data points, the dashed curve is the LQ model prediction, and the solid curve is the IR model prediction. From Joiner et al. (2001).

Figure 3.4 Characteristic sigmoidal TCP versus dose curve derived theoretically and experimentally. (Taken from Webb and Nahum 1994)

Figure 3.5 The dose-volume relationship for a) the (mostly serial) esophagus, b) for (mostly parallel) lung, and c) for the rectum. Taken from Burman et al. (1991) using data from Emami et al. (1991).

Figure 3.6 a) The distribution of rectal surface area irradiated across patients can be separated by the grade of prostate cancer. Taken from Lu et al. (1995) b) The correlation between NTCP and volume is strongest at low partial volumes (less than 0.5) and for full volume delineation. Taken from Dale et al. (1999).

Figure 3.7 A transverse section of the rectum showing different methods of organ delineation for generating histograms. Adapted from Dale and Olsen (1998).

Figure 3.8 Characterisation of the Dose Surface Histogram. From Fenwick et al. (2001).

Figure 4.1 Demonstration of the direct derivation of dose PDF from spatial PDF with static dose distribution. (Adapted from Leong 1987). The spatial PDF (below the half dose profile) is used to allocate probability values (a dose PDF located right of the half dose profile) for a particular element of radius positioned originally at 50% dose. This procedure is repeated for other elements yielding dose PDFs as shown in figure 4-2 below.

Figure 4.2 Dose PDFs within voxels that are positioned at five distances from the central axis, labelled from Figure 4.1. Only odd numbered curves are shown for brevity. Dose PDF curves for distances 3 and 5 cm (corresponding to radii r_3 and r_5 respectively) predict mainly high and low doses respectively because these voxels are centred at the upper and lower position of the dose profile. The dose PDF curve for the voxel centred at 4 cm from the central axis (radius r_4) is smeared over a large dose range because its mean location is the midpoint of the penumbra. The value of the positional PDF standard deviation is 0.6 cm.

Figure 4.3 Rayleigh distribution with $b=2$.

Figure 4.4 Maxwell probability density function with $b=2$.

Figure 4.5 (a) Mean organ position is represented by the x,y co-ordinate system. In routine treatment, due to CT uncertainty, the planning image represents the organ in an off-set co-ordinate system (the x',y' co-ordinate system). This co-ordinate system is then used to plan and deliver the dose. The 1D approach in this study uses only the x -component of these 2D shifts. (b) Organ positions during the treatment delivery (such as ϕ_1 , ϕ_2 and ϕ_3 for 3 fractions) are measured in the off-set (x',y') co-ordinate system.

Figure 4.6 (a) Mean dose incorporating uncertainty at both planning and treatment. The dose profile represented by the broken line is the original dose profile and that represented by a solid line includes only the treatment delivery errors. The spatially uniform dose uncertainty follows the original dose profile. (b) Magnified view of penumbra.

Figure 4.7 Dose variation (1 standard deviation of mean treatment dose) scored in voxels ($\Delta x = 0.1$ cm), using multiple CT scans to estimate mean organ position. The solid line shows dose variation due only to treatment delivery uncertainty. Vertical lines represent position of 95% isodose contour and the dash-dot line represents the spatially uniform dose uncertainty.

Figure 4.8 a) One dimensional profiles of prescribed dose distributions with three margin sizes (0.5, 1.0, 1.5 cm) and b) the associated standard deviations in treatment dose.

Figure 4.9 Standard deviation in treatment dose using the standard deviation in position to be 0.6, 0.8 and 1.0 cm. The value given as 'tumour position' is the standard deviation equal to the quadratic sum of random inter-fraction organ motion and random setup errors.

Figure 4.10 Possible reductions in margin size evident from improving knowledge of mean organ position.

Figure 4.11 Mean treatment dose predicted for 1 and 5 CT scans using the convolution method as compared with MC results. The original dose profile is also shown.

Figure 4.12 Flow chart of regimes for timing multiple imaging

Figure 4.13 Mean dose (A→C) and variance in mean dose (D→F) resulting from incorporating regimes A,B, C into Monte Carlo modelling of the treatment process.

Figure 4.14 Illustration of the prostate gland (GTV), rectum and three dose distributions characterised by margins of a) 0.5 cm b) 1.0 cm and c) 1.5 cm. In each case the 95% isodose indicates the PTV, the green volume is the prostate (GTV & CTV) and the brown volume is the rectal wall.

Figure 4.15 Two views of the mean treatment dose calculated with three original dose distributions (for margins of 0.5, 1.0, 1.5 cm) for three cases. The three cases are an original dose distribution (black solid line), a mean treatment dose calculated based on 1 planning CT scan (blue solid) and a mean treatment dose based on infinite planning CT scans (red dashed line).

Figure 4.16 Iso-standard deviation plots in the transverse plane with a) 0.5 cm and b) 1.5 cm margin.

Figure 4.17 Profiles of one standard deviation in mean treatment dose along the lateral (X) and anterior-posterior (Y) direction for the a) 0.5 cm margin, b) 1.0 cm margin and c) 1.5 cm margin.

Figure 5.1 Schematic of the characterisation of the rectum geometry A rectal wall segment will area, A_0 , subtended by $d\theta$ of distance $r_{in}(\theta)$ from the geometric centre, and of thickness, $w(\theta)$.

Figure 5.2 Plot of inner rectum wall radius, and wall thickness versus angle for a characteristic slice.

Figure 5.3 Calculated wall thickness (Eq.5.7) with changes of rectal wall radius..

Figure 5.4 Rectum segment has constant area. Dashed segment is original segment.

Figure 5.5 Modelling shifts of the rectum GC is done by shifting the entire organ within a fixed dose grid. A) The rectum GC position in the original CT planning image is compared to b) the position (shifted posteriorly) in a later fraction, or CT image acquisition.

Figure 5.6 Dose surface histograms of the planned dose distributions with CTV-PTV margins of 5, 10, or 15 mm.

Figure 5.7 Dose Surface maps of the planned dose distributions with CTV-PTV margins of a) 5 mm, b) 10 mm, or c) 15 mm. Orientation: Left=0°; Anterior=90°.

Figure 5.8 DSH showing the mean and planned dose distributions modelling an empty rectum at planning with three CTV-PTV margins.

Figure 5.9 Dose Surface Maps showing the difference between rectal dose distributions with empty rectum at planning for a) 5 mm margin, b) 10 mm margin, c) 15 mm margin. Orientation: Left=0°; Anterior=90°.

Figure 5.10 DSH for planned and mean (calculated) dose distributions with 5, 10, and 15 mm margins, including a full rectum at planning.

Figure 5.11 DSM showing where the difference dose occurs for margins of a) 5 mm, b) 10 mm, and c) 15 mm with full rectum at planning. Orientation: Left=0°; Anterior=90°.

Figure 5.12 Dose surface histograms of the rectal wall for dose distributions with a) 5 mm b) 10 mm, and c) 15 mm margin. The three planned dose distributions are solid lines and the 20 DSHs including random and systematic errors are dashed lines. The individual patient DSHs are symmetrical about the planned DSH across the population

Figure 5.13 The standard deviation in rectal wall dose calculated with 5 mm margin and a) one pre-treatment CT scan with, b) two pre-treatment CT scans, and c) infinite pre-treatment CT scans. Orientation: Left=0°; Anterior=90°.

Figure 5.14 The standard deviation in rectal wall dose calculated with 10 mm margin and a) one pre-treatment CT scan with, b) two pre-treatment CT scans, and c) infinite pre-treatment CT scans. Orientation: Left=0°; Anterior=90°.

Figure 5.15 The standard deviation in dose presented as a DSM. A margin of 15 mm is used with a) one, b) two, and c) an infinite number of pretreatment CT scan information. Orientation: Left=0°; Anterior=90°.

Figure 6.1 Isodose contours for typical prostate treatment. The CTV (solid and filled), PTV (dotted), and rectum (brown) are shown, with the oblique and horizontal lines indicating the position of dose profiles used.

Figure 6.2 The dose distribution for 1D TCP calculations.

Figure 6.3 TCP calculated with planned dose distribution versus mean calculated with CTV-PTV margins of 0.5 cm, 1.0 cm and 1.5 cm (incorporating treatment uncertainty). The magnitude of treatment uncertainty is fixed for all cases.

Figure 6.4 TCP calculated with planned dose distribution versus mode calculated with CTV-PTV margins of 0.5 cm, 1.0 cm and 1.5 cm (incorporating treatment uncertainty). The magnitude of treatment uncertainty is fixed for all cases.

Figure 6.5 Mean TCP calculated using dose distribution with steep penumbra compared with the standard dose distribution.

Figure 6.6 Mean tumour control probability for treatments incorporating non-uniform dose uncertainty, uniform dose uncertainty and varying cell sensitivity inter-patient.

Figure 6.7 Standard deviation in mean tumour control probability incorporating spatially non-uniform dose uncertainty, spatially uniform dose uncertainty and varying cell sensitivity inter-patient.

Figure 6.8 Distributions of TCP for three dose levels a) 48 Gy, b) 52 Gy, and c) 56 Gy incorporating dose uncertainty (uniform or non-uniform) and inter-patient cell sensitivity variation. The exact calculated TCP at these dose levels (shown as vertical dashed line) are 0.05, 0.58 and 0.90, respectively.

Figure 6.9 Mode of TCP over a patient population.

Figure 6.10 TCP calculated for an individual patient with (F)ull or (E)mpty rectum in planning CT scan with margins of 0.5 cm, 1.0 cm, or 1.5 cm.

Figure 6.11 Plot of TCP versus cell sensitivity. Two values of cell sensitivity ($\alpha_1=0.29 \text{ Gy}^{-1}$, $\alpha_2=0.35 \text{ Gy}^{-1}$) and the range covered by one and two standard deviations in cell sensitivity are illustrated. See text for further description.

Figure 6.11 Schematics of voxel-based dose allocation from the deformed rectal wall (dashed) to the original wall (solid) following a sampled change of radius. Three cases are shown, where a) the wall thickness does not change, b) the wall thickness is reduced, and c) where the wall thickness increases. See text for further explanation.

Figure 6.13 Mean NTCP calculated for individual patients with either full (F) or empty (E) rectums in the planning CT scan and with margins of 0.5 cm, 1.0 cm, or 1.5 cm. Table 6.4 NTCP across a patient population (N=1000) with D=64 Gy

Figure 6.14 NTCP calculated with planned dose or with a 5% spatially uniform dose error at each fraction of treatment.

Figure 6.15 Comparison between NTCP calculated with the planned dose distribution against NTCP calculated assuming that the planned surface dose (from DSM) is deposited uniformly in each angular rectal wall segment.

Figure 6.16 Comparison of mean NTCP calculated with mean dose against the calculated rectal wall dose. Both sets were calculated for a population of patients, with each patient being planned from a single CT image set.

Figure 6.17 Comparison of mean NTCP calculated with the mean dose against the MC calculated rectal wall dose. Both sets were calculated for a population of patients, with each patient being planned using the mean organ position.

Figure 6.18 NTCP calculated using the mean dose with $n=0.24$, $m=0.15$ for an individual patient with systematic error.

Figure 6.19 NTCP calculated using the mean dose with $n=0.12$, $m=0.15$ for an individual patient with systematic error.

Figure 6.20 Mean UTCP calculated for a population of identical patients with fixed systematic error.

Figure 6.21 Mean UTCP (1CT) versus dose for margin sizes 0.5, 1.0, and 1.5 cm.

Figure 6.22 Mean UTCP against margin size at a) 64 Gy and b) 70 Gy..

Figure 7.1 Correction factors for various inhomogeneity correction techniques versus depth in different density media. Taken from Wong and Purdy (1990).

Figure 7.2 The superposition dose calculation technique models primary fluence interactions at r' and the probability of dose deposition in surrounding voxels, including that voxel centred at r . Adapted from Metcalfe et al. (1997).

Figure 7.3 The superposition dose calculation overestimates dose in lower density media and underestimates after lower density media. Taken from Metcalfe et al. (1997).

Figure 7.4 Dose PDF at the medial edge of the penumbra.

Figure 7.5 Standard deviation isodoses for a) a liver treatment including random patient positioning errors (Taken from Lujan et al. 1999) and b) a 4-field prostate treatment (reproduced from Chapter 4).

Figure 7.6 a) Mean isodose contours, and b) Confidence limit plot showing the minimum dose received by 90% of the population.

Figure 7.8 The CL-DVH from Mageras et al. (1999) a) for prostate and b) rectum, and b) the DVH accuracy increases with the number of fractions (from Lujan et al. 1999)

Figure 7.9 Schematic of the a) 95% modal isodose, and b) 30% modal isodose with error bars indicating a 95% chance of depositing given dose.

Figure 7.10 Single axial slice showing lateral and AP beam orientation, b) dose difference display: $\bar{D} - D_0$. Taken from Lujan et al. (1999).

List of Tables

Table 2.1 Variation in parameters used for measurement of $MOD_{prostate}$. Key: full (F) bladder/rectum, empty (E) bladder/rectum, rectum status Not Considered (NC), insufficient information provided (-). The numbers of images taken per patient refers to the number of images (CT, simulation and portals) used to derive their final measurement. Patients were treated in the supine (S) or prone (P) position, whether patient repositioning was done (yes, Y) or was not done (no, N), and the method used for the measurement (M1 or M2) from the text. In two studies the bladder/rectum content was increased with time (*), while in another study two time periods for voiding before treatment were examined (**).

Table 2.2 The mean patient displacement averaged across studies (SEAS) and standard deviation δ (mm), with the systematic standard deviation δ_s (mm) and the random standard deviation δ_R (mm).

Table 2.3 Prostate position uncertainty due to the motion not directly attributed to bladder/rectum filling in the anterior-posterior, medio-lateral and superior-inferior directions. References will be bracketed.

Table 2.4 Summary of respiration-induced abdominal motion. The movement of the organ is the positional difference of the organ from inhalation to exhalation, unless otherwise stated. The details of the measurement may include a direction, breathing rate, alternate endpoint, or the condition of the organ at the time of measurement i.e. disease title.

Table 3.1 Magnitudes of parameters m, n, D_{50}, s and k used to model normal tissue complications following full volume irradiation for a range of organs. From Burman et al. (1991) and Kallman et al. (1992).

Table 4.1 Summary of typical error magnitudes concerning supine treatment of prostate carcinoma used for modelling. Delineation error ranges are due to uncertainty in apex and seminal vesicles localisation. Systematic set-up errors quoted do not include the use of a correction protocol.

Table 5.1 The parameters defining systematic and random changes in rectum geometry

Table 6.1 The effect of margin size on TCP incorporating treatment uncertainty. The difference between planned TCP and mean TCP with 1 CT, as well as the difference in TCP between the planned and calculated mean TCP are shown.

Table 6.2 The effect of margin size on TCP incorporating treatment uncertainty and steep dose gradient to mimic IMRT. The difference between planned TCP and mean TCP at a 60 Gy dose level, as well as the difference in dose between the planned and calculated mean TCP at two levels of TCP are shown.

Table 6.3 Mean TCP across a patient population for three margin sizes, with error given as one standard deviation in mean TCP.

Table 6.4 NTCP across a patient population (N=1000) with D=64 Gy

Table 6.5 Maximum value of mean UTCP across a population with 1 SD uncertainty. The dose required for maximum UTCP is given in brackets.

Abstract

Uncertainties are inevitably part of the radiotherapy process. Uncertainty in the dose deposited in the tumour exists due to organ motion, patient positioning errors, fluctuations in machine output, delineation of regions of interest, the modality of imaging used, and treatment planning algorithm assumptions among others; there is uncertainty in the dose required to eradicate a tumour due to interpatient variations in patient-specific variables such as their sensitivity to radiation; and there is uncertainty in the dose-volume restraints that limit dose to normal tissue.

This thesis involves three major streams of research including investigation of the actual dose delivered to target and normal tissue, the effect of dose uncertainty on radiobiological indices, and techniques to display the dose uncertainty in a treatment planning system. All of the analyses are performed with the dose distribution from a four-field box treatment using 6 MV photons. The treatment fields include uniform margins between the clinical target volume and planning target volume of 0.5 cm, 1.0 cm, and 1.5 cm. The major work is preceded by a thorough literature review on the size of setup and organ motion errors for various organs and setup techniques used in radiotherapy.

A Monte Carlo (MC) code was written to simulate both the treatment planning and delivery phases of the radiotherapy treatment. Using MC, the mean and the variation in treatment dose are calculated for both an individual patient and across a population of patients. In particular, the possible discrepancy in tumour position located from a single CT scan and the magnitude of reduction in dose variation following multiple CT scans is investigated. A novel convolution kernel to include multiple pretreatment CT scans in the calculation of mean treatment dose is derived. Variations in dose deposited to prostate and rectal wall are assessed for each of the margins and for various magnitudes of systematic and random error, and penumbra gradients.

The linear quadratic model is used to calculate prostate Tumour Control Probability (TCP) incorporating an actual (modelled) delivered prostate dose. The Kallman s-model is used to calculate the normal tissue complication probability (NTCP), incorporating actual

(modelled) fraction dose in the deforming rectal wall. The impact of each treatment uncertainty on the variation in the radiobiological index is calculated for the margin sizes.

Thesis Statement

This work contains no material which has been accepted for the award of any other degree or diploma in any University or other tertiary institution and, to the best of my knowledge and belief, contains no material previously published or written by another person, except where due reference has been made in the text.

I give consent to this copy of my thesis, when deposited in the University Library, being available for loan and photocopying.

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Acknowledgements

I am indebted to Dr. Sergei Zavgorodni for his scientific expertise, dedication, guidance and friendship through out the last four years. It was very satisfying (on many levels) to work with Sergei and an honour to be the first PhD student he has supervised. I would also like to thank the other senior members of our research group Dr. John Patterson, Assoc. Prof. Tim van Doorn, and Dr. Eva Bezak. John was particularly generous during the first months of my move to Adelaide and gave me a good start. Tim and Eva both contributed many helpful discussions, and provided guidance in approaching problems holistically.

I have had the pleasure of working in the same office as some other fine physicists including Dr. Peter Greer, Dr. Guilin Lui, Setayesh Behin-ain, and David (Emami) Taylor. At various stages through my 3.5 years each of these people grew to become very good friends. Thank you to Kurt Byas for countenance.

I am grateful for the unconditional love of Angelique, and my family Warwick, Linda, Luke, Chad and Jye.

This thesis is dedicated to my great grandmother, Ethel Jaye 1899-2001

Chapter 1

General Introduction

1.1. External Beam Radiotherapy Planning

Prostate cancer was the most commonly diagnosed cancer in South Australia during 2000. The Department of Human Services* reported that 27% of all male cancers were prostate, and it is the 2nd most lethal (after lung cancer) of all cancers in males. One of the treatment modalities for men with prostate cancer is external beam radiation therapy (EBRT). EBRT is the targeting of cancer cells with an external source of radiation, usually electrons or photons, generated by a linear accelerator.

The EBRT process includes a number of links (or sub-processes). The two major sub-processes are treatment planning and treatment delivery, and these may be further subdivided into tasks. The tasks within the treatment planning process include simulation of the treatment, CT image acquisition, delineation of the tumour volume on the CT images, arranging a suitable configuration of incident beams, beam energies and number of fractions to deposit the prescribed dose to the tumour volume. The tasks within the treatment delivery process include positioning the patient (using the cardinal positioning laser system, and a positioning device) and irradiating with each treatment

* Website: <http://www.dhs.sa.gov.au/pehs/cancer-report2001.html>

field. At each step in these processes, small errors may occur that combine to form large errors. The errors that occur during treatment preparation will impact on the entire treatment and are called *systematic* errors. Those that occur during treatment delivery will be *random* errors.

The systematic errors include (but are not limited to);

- o mistakes in the positioning of a patient during simulation causing the intended positioning during treatment delivery to be incorrect
- o organ motion will cause the treatment target to be displaced from its mean position in the CT image used to delineate the tumour and plan the orientation of the treatment fields,
- o delineation error may be present due to low contrast or image modality
- o the calculated dose may be incorrect due to fluctuating linear accelerator output
- o treatment planning software with incorrect homogeneity correction
- o mechanical inaccuracy of the linear accelerator, including field size, gantry angles, multi-leaf collimator calibration etc.

The random errors will affect the treatment by different amounts at each fraction of treatment delivery. They include (but are not limited to);

- o patient positioning errors
- o organ motion
- o mechanical inaccuracy of the linear accelerator
- o linear accelerator output variability

Considering these uncertainties, the International Commission on Radiation Units (ICRU) recommends that the delineated tumour volume be enlarged by a margin to a planning target volume (PTV). The margin ensures that the tumour receives the

intended target dose. Thus through the 5-6 week fractionated treatment the tumour should be always contained within the PTV.

Portal images may be acquired to test the positioning of actual radiation fields used in treatment delivery. These can be used to detect systematic and random positioning errors. However, ensuring that the planned and actual organ positions (within the patient) coincide is a little more difficult. This is because most organs are of low contrast in current portal images, and physically positioning the organ would be impractical and invasive.

For the treatment of prostate carcinoma, the decision to use fixation devices is taken differently at each radiotherapy centre. Most centres will treat prostate cancer patients with some sort of positioning device, but generally the patient will not be rigidly fixed. This is despite studies demonstrating the benefits of improved targeting with improved patient response (Epstein *et al* 1992, Corn *et al* 1995). A margin around the prostate will normally be in the range 0.6 cm to 1.5 cm and will depend on the confidence the clinician has with the staff, positioning device, technique, and the tolerance of adjacent normal tissues such as the rectum, bladder and femoral heads. The prostate will move inside the patient due to variations in rectum and bladder volume. Some portion of the rectum will be included in the high dose (PTV) volume.

There has been a substantial amount of research studying the positioning accuracy of prostate treatment techniques, the magnitude of prostate movements between the treatment fractions, and methods to calculate the size of the treatment margin. Among other findings, these studies have illustrated that:

- o the prostate can move up to 2 cm between fractions (Ten Haken *et al* 1991)
- o a substantial movement is possible between the original planning CT scan and the mean prostate position during treatment
- o the prostate is invisible in mega voltage portal images
- o statistical (dose based) methods have been derived for sizing the treatment margin

Therefore, despite the technological advances in depositing dose with high accuracy, uncertainty still exists in the actual radiation dose received by the tumour, and with increasing interest, the dose deposited to the rectal wall.

1.2. Aims and Summary of Current Investigation

The aims of this research are:

- o to estimate the differences between the planned and deposited doses in the prostate gland and rectal wall
- o to calculate the biological effect of the differences between the planned and deposited dose
- o to investigate tools to visualise the uncertainty in dose delivery.

The estimating of dose actually deposited is based on a novel computer simulation of the planning and treatment delivery processes, incorporating uncertainties at each stage. These calculations use Monte Carlo (MC) and convolution techniques. Both techniques are used to investigate the dosimetric importance of accurately defining the volume to be treated at the planning stage. This is done through the simulation of multiple pretreatment CT images that can be used to average the centre of mass location of the prostate. For the convolution, a variation kernel including systematic error is suggested and benchmarked. Some institutions are currently utilising serial CT scans to monitor the prostate position during the course of treatment. Other investigators have suggested acquiring images during treatment with kilovoltage x-rays or ultrasound. A calculation of the dosimetric effect of improved localisation using such techniques is presented and discussed.

The biological impact of treatment uncertainty on tumour control of prostate carcinoma and the associated rectal complication is calculated. These calculations are based on MC modelling of the planning and treatment delivery processes, incorporating uncertainties at each stage. For prostate carcinoma, the importance of margin size is assessed using calculations of mean Tumour Control Probability (TCP) and one standard deviation in

mean TCP, the variation in these parameters are investigated with various configurations of treatment error (systematic organ motion error, random organ motion and random patient positioning errors), and margin size. Normal Tissue Complication Probability (NTCP) is calculated for the case of rectum bleeding complications following the prostate treatment. The MC model incorporates rectal wall deformation, and patient positioning errors in the calculation of rectal NTCP with various arrangements of treatment parameters. It is important to understand potential ramifications of each component of uncertainty.

The clinical usefulness of the convolution technique with commercial software is investigated. Current treatment planning systems allow no visualisation of potential outcomes of beam arrangements with respect to uncertainty. Despite the mathematical techniques in the literature there are no tools for visualising what could happen and indicating the probability of certain outcomes occurring.

Thus, through careful evaluation of current techniques for treating prostate carcinoma with external beam radiation therapy, two novel models of the process have been developed and used to investigate the dosimetric impact of separate components of error, a detailed spatial model of the process has been developed to investigate the radiobiological impact of the errors, and tools for displaying potential outcomes and their probability have been addressed.

1.3. Thesis outline

Chapter 1 introduces external beam radiotherapy and the uncertainty present in the planning and treatment delivery processes. The aims and importance of the research are outlined.

Chapter 2 reviews potential sources of radiotherapy uncertainties, the magnitudes and characteristics of these errors, as well as current techniques to reduce and/or manage the uncertainty.

The mathematical models used to simulate radiobiological interaction are introduced in Chapter 3. Particular emphasis is made on the models for calculating Tumour Control Probability (TCP), Normal Tissue Complication Probability (NTCP) and

Uncomplicated Tumour Control Probability (UTCP). The feasibility of each model and the values currently used for their parameters in the literature are discussed.

Chapter 4 presents two models of the planning and treatment delivery processes. These models are used to estimate the dosimetric impact of the treatment uncertainties, particularly systematic organ motion error. The models presented in this chapter are particularly relevant to the treatment of prostate carcinoma because they assume no deformation of the organ.

Deformation of the rectum will lead to considerable uncertainty in the dose delivered to this organ. The uncertainty in rectal wall dose is investigated through another simple model in Chapter 5.

In Chapter 6 a MC model is developed to incorporate prostate motion and patient position errors into the calculation of TCP, NTCP and UTCP.

The importance of presenting the potential quantities of error, their impact and probability of occurrence is investigated in Chapter 7. The convolution method is a simple and accurate method for including systematic organ motion discrepancies into the treatment plan.

Chapter 8 discusses the final conclusions made in the thesis and future research stemming from the project.

1.4. Publications

Publications in refereed journals

Booth JT, Zavgorodni SF. The effects of radiotherapy treatment uncertainties on the delivered dose distribution and tumour control probability. *Australas. Phys. Eng. Sci. Med.* **24**(2):71-79, 2001.

Booth JT, Zavgorodni SF. Modelling the dosimetric consequences of organ motion at CT imaging on radiotherapy treatment planning. *Phys.Med.Biol.* **46**(5):1369-1377, 2001.

Booth JT, Zavgorodni SF. Set-up Error & Organ Motion: A Review. *Australas. Phys. Eng. Sci. Med.*, **22**(2):29-47, 1999.

Keall PJ, Beckham WA, **Booth JT**, Zavgorodni SF, Oppelaar M. A Method to predict the Effect of Organ Motion and Set-up Variation on Treatment Plans. *Australas. Phys. Eng. Sci. Med.*, **22**(2):48-52, 1999.

Conference presentations (abstracts)

Booth JT, Zavgorodni ZF. The influence of PTV margin size and organ deformation on rectal complications. EPSM2001, Perth, October 2001, p92.

Zavgorodni ZF, **Booth JT**, Rosenfeld AR. Investigation of the impact of dose fluctuations on BED and tumour control. EPSM2001, Perth, October 2001, p120.

Booth JT, Zavgorodni ZF. The importance of PTV margin size in the presence of dose uncertainty. ESTRO Physics for Clinical Radiotherapy Meeting, Sevilla September 2001, pS61.

Booth JT, Zavgorodni ZF. The effect of variable fractional doses on rectum complications. AIP2000, Adelaide, December 2000, p41.

Booth JT, Zavgorodni ZF. Incorporating organ motion at imaging into a convolution method for predicting mean treatment dose. EPSM2000, Newcastle, Nov 2000, p148.

> Awarded Curie Prize for best postgraduate presentation.

Booth JT, Zavgorodni ZF. Repetitive pre-treatment CT scans to improve target localisation for planning. WC2000, Chicago, July 2000, Med.Phys. 27(6):1449.

Booth JT, Zavgorodni ZF. Can multiple pre-treatment CT scans reduce the planning margin? WC2000, Chicago, July 2000, Med.Phys. 27(6):1412.

Booth JT, Zavgorodni SF. A convolution method for predicting mean treatment dose including organ motion at imaging. Medical Staff Prize, RAH, June 2000.

Booth JT, Zavgorodni ZF. Considerations of the dose uncertainty in the calculation of tumour control probability. EPSM1999, Surfers Paradise, October, 1999, p93.

Booth JT, Zavgorodni ZF. Tumour position considerations in a model for fractionated radiotherapy. EPSM1999, Surfers Paradise, October, 1999, p148.

Booth JT, Zavgorodni ZF. Setup and Organ Motion Uncertainty: A Summary. EPSM98, Hobart, November, 1998, p29.

Chapter 2

A review of patient positioning uncertainty and organ motion at various anatomical sites

2.1. Introduction

Accounting for treatment errors, including patient setup errors and organ motion, is an increasingly important part of the clinical radiotherapy process. Linear accelerator and multileaf collimator technology has evolved such that radiation dose can be delivered with high accuracy to volumes in regular objects. Unfortunately, the accuracy of dose delivery to dynamic cancer targets is limited by uncertainty in many of the treatment parameters, including the motion of organs and patient positioning. Therefore, knowledge of the treatment errors, their characteristics and causes, and techniques to control or reduce them are very important for comprehensive health care. A thorough understanding of the treatment uncertainties is also required if the radiotherapy process is to be modelled, which is the major task of this thesis.

This chapter defines the components of patient positioning (setup) error and describes the magnitude of setup errors from the literature for various sites including the pelvis, head and neck, brain, abdomen and breast. Organ motion is defined and magnitudes of organ motion are reviewed from the literature for sites including pelvis, kidney, diaphragm, and pancreas. A review of current approaches to compensate and account for the treatment uncertainties in the planning process is also included. General guidelines to accommodate

these and other uncertainties in planning of external beam radiotherapy treatments are provided by the International Commission on Radiation Units (ICRU) report 50 (1993) and supplement report 62 (1999). These reports are reviewed. Other suggested approaches for reducing and/or accommodating uncertainty in the process are reviewed. These include patient repositioning for reducing systematic patient positioning error, breathe holding and gated techniques for controlling respiration-induced abdominal organ motion and contemporary (statistical dose-based) techniques for calculating the size of the treatment margin to account for residual error.

2.2. Review of ICRU reports 50 and 62

The International Commission on Radiation Units (ICRU) have released two reports (Report number 50 (1993) and supplement report number 62 (1999)) offering suggested considerations and a technique to account for uncertainties in the planning of external beam radiotherapy treatments. The ICRU-50/62 documents also suggest requirements for accurate documentation of prescription dose.

Among the specifications, ICRU Report 50 defines a number of organ and tissue volumes relating to the tumour and normal tissues. The number and description of the volumes is improved in ICRU 62 to include the Gross Tumour Volume (GTV), Clinical Tumour Volume (CTV), Internal Planning Target Volume (IPTV) with Internal Margin (IM), Planning Target Volume (PTV) with Setup Margin (SM), and Organs at Risk (OAR). These volumes are shown in figure 2.1 (adapted from ICRU-62 figure 2.16) illustrating three of the possible clinical scenarios (labelled A→C). The scenarios are explained in the following text.

Scenario A describes the basic interaction between the volumes. The GTV is the gross, palpable tumour volume defined usually from CT images by the clinician and in the reference frame of the bony anatomy. The CTV is the GTV plus any suspected sub clinical growth. An internal margin is added to compensate for potential changes in position and/or size and shape of the CTV relative to bony anatomy. A Setup Margin is added to compensate for potential variations/uncertainties in the patient position. The PTV equals $CTV + IM + SM$ and should assure that the complete CTV always receives the prescription dose. Thus the PTV is defined in the room coordinate system, and the CTV will lie within

this volume at all times during treatment.

Scenario B describes a slightly more complex situation than scenario A. In this case the internal margin varies with time, for example due to patient respiration, and sensitive normal tissue abutting (organ at risk illustrated as an inward-facing arrow). The presence of an organ at risk (e.g. spinal cord or rectal tissue) means that the conservative and linearly combined margins (IM & SM) in scenario A may not be sufficient and smaller margins must be sought. In this case, the clinician would typically define a margin based on clinical experience.

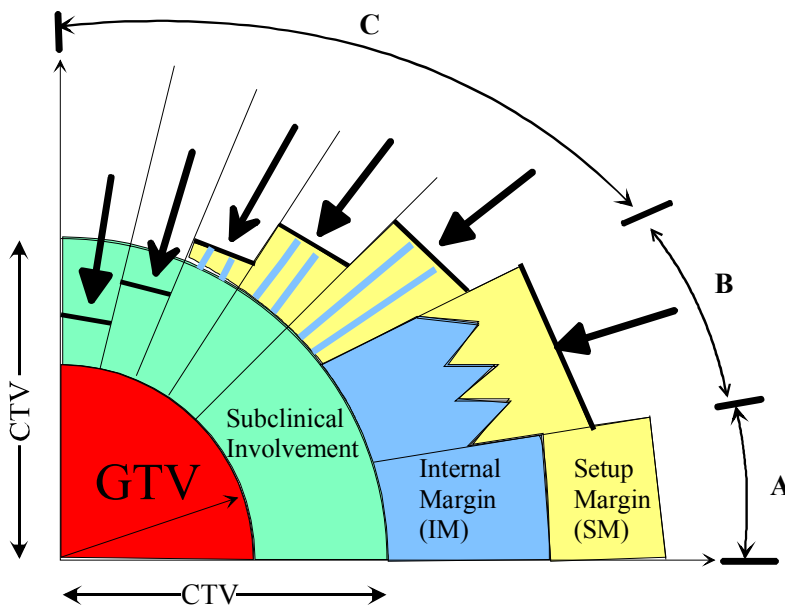


Figure 2.1 Definitions of treatment volumes as defined by ICRU-62 (Fig. 2.16) showing their relation by scenarios A, B and C discussed in the text.

Scenario C describes the situation where the Organ At Risk (OAR) impinges to varying degrees on the PTV and CTV. Also, scenario C describes a circumstance where the internal and setup margins may be prescribed as a single 'global' margin. In this case, techniques (such as the $\sqrt{\sum \sigma^2}$ formalism, if the variances, σ^2 , are independent) for defining the size of margin can be used. The presence of OAR may strictly control the size of the margins.

The magnitude of the treatment margin has, historically, been sized by the clinician using a 'rule of thumb' that is based on clinical experience for each particular site and situation. For example, external beam prostate treatments typically receive a 0.6 cm to 1.5 cm

margin that may vary along each coordinate axis. The magnitude 0.6 cm to 1.5 cm was, in some cases, used prior to measurements of the reproducibility of patient position and organ mobility, but does coincide with current measurements from the literature. Statistically oriented techniques utilizing in-house measurements of setup reproducibility and organ mobility for sizing the margin have been proposed in the literature and are addressed below (see §2.7.1).

Setup errors and organ motion aren't the only factors causing uncertainty in the position of the CTV, for example approximations of algorithms used in the treatment planning software or simply inaccuracy in machine calibrations do exist. However, the predominant (non-setup or organ motion) error is *tumour delineation*. That is, the volume of the tumour delineated on the planning image may differ considerably depending on the clinicians, and the methods and imaging modality used (Gademann 1996, Ketting *et al* 1997, Logue *et al* 1998, Rasch *et al* 1999, Valicenti *et al* 1999, Yamamoto *et al* 1999). Tumour boundaries are not well defined. In particular, prostate GTVs defined using Magnetic Resonance Imaging (MRI) have been found to be 30% smaller than those same tumours defined by means of conventional Computed Tomography (CT) scans (Rasch *et al* 1999). Also comparisons among clinicians show a factor of 1.8 variation in the CTV definitions for the same tumour from the same set of images (Ketting *et al* 1997). Tumour delineation is discussed in the ICRU-62 document, and should be considered in the definition of a PTV, but is not explicitly described as belonging to either the IM or SM.

2.3. Comparison across studies

An attempt has been made in this section to average the mean and standard deviations quoted in the literature across studies. In this case it is important to provide strict definitions, as has been done below. However, the number of measurements adhering to these definitions is greatly reduced from the total number of values quoted in the literature.

For example, consider the existing literature regarding the inter fraction movement of the prostate (see table 2.1). Variables such as whether or not the rectum and/or bladder are full, if an immobilisation device was used, the number of images (CT, simulation and portal) per patient, the number of fields used, whether or not repositioning has been applied and how, whether the patient was treated supine or prone, and even the stage (A, B, or C) of the

prostate cancer, can all affect the measurement.

Table 2.1 shows that for the case of inter fraction prostate motion, none of the reviewed articles contain the same combination of parameters. Two broad methods of measuring the position of the prostate were used in the reviewed studies. One method (M1) measured the relative position of centre of mass of the prostate from bony anatomy. The other method

Table 2.1 Variation in parameters used for measurement of $MOD_{prostate}$. Key: full (F) bladder/rectum, empty (E) bladder/rectum, rectum status Not Considered (NC), insufficient information provided (-). The numbers of images taken per patient refers to the number of images (CT, simulation and portals) used to derive their final measurement. Patients were treated in the supine (S) or prone (P) position, whether patient repositioning was done (yes, Y) or was not done (no, N), and the method used for the measurement (M1 or M2) from the text. In two studies the bladder/rectum content was increased with time (), while in another study two time periods for voiding before treatment were examined (**).*

Author	Year	Rectum Status	Bladder Status	Patient Immobilisation	images/patient	Treated position	Repositioning	Method
Ten Haken <i>et al</i>	1991	F*	F*	Y	-	S	N	M1,M2
Beard <i>et al</i>	1993	-	-	Y	-	S	-	M1
Schild <i>et al</i>	1993	F*	F*	N	3	S	N	M2
Balter <i>et al</i>	1995	-	F	N	4-8	-	N	M1
Crook <i>et al</i>	1995	-	F	N	6.5-7.0	S	N	M1,M2
Althof <i>et al</i>	1996	NC	NC	N	6	S	-	M2
Rudat <i>et al</i>	1996	NC	NC	N	4.5	S	N	M1
Melian <i>et al</i>	1997	F	E**	Y	4	P	Y	M1
Vigneault <i>et al</i>	1997	-	-	N	N/A	-	N	M2
Lattanzi <i>et al</i>	1998	F	E	Y	6-8	S	Y	M1
Roeske <i>et al</i>	1998	F	-	Y	5-8	S	N	M1

(M2) measured the relative position of markers (fiducial, radio opaque, or Foley catheter) or prostate border (using CT images) relative to bony anatomy. Measurements of mean prostate movement were all made relative to a ‘gold standard’ image that was taken either during simulation or during the first fraction of treatment. Ten Haken *et al* (1991) and Schild *et al* (1993) both describe the movement of the prostate as the rectum and bladder were filled. Others describe the motion of the prostate during treatment not directly due to bladder/rectum filling. (Beard *et al* 1993, Balter *et al* 1995, Crook *et al* 1995, Roeske *et al* 1995, Althof *et al* 1996, Rudat *et al* 1996, Melian *et al* 1997, Vigneault *et al* 1997, Lattanzi *et al* 1998).

Variability in the reported parameters for other sites is also common - the prostate motion is just one example. In this situation the most realistic approach is to represent the published data in a uniform manner as outlined in the next section. The variability, however, does highlight the conclusion that each institution should measure personalised data for use with their clinical decision making.

2.4. Patient positioning (setup) errors

Fractionated external beam radiotherapy requires patients to be positioned for about 30 fractions of treatment, based on initial measurements done at planning. Thus, *systematic* differences between the initial measurements and the desired positioning for a particular patient may exist due to many factors including inaccurate alignment of positioning devices and differences in cushioning capacity of couch material between CT and treatment. Also *random* error will exist between the daily patient positions and the desired patient position, due to factors such as the width of positioning laser beams and human error. The patient positioning (or setup) errors then can be defined as consisting of systematic and random components.

2.4.1. Defining Patient Positioning Errors

The *treatment position deviation* (TPD), $\Delta x_{i,j}$, is defined as the difference between the set-up position described by the i_{th} portal or CT image, from the setup position described at the physical or digital simulation for the j_{th} patient. These 'setup positions' are usually

measured using landmarks clearly visible on the Electronic Portal Imaging Device (EPID) or portal film. The measurement includes components of both random and systematic error. The j^{th} patient may be described as having *systematic error*, $\Delta\bar{x}_j$, defined as the average TPD of that patient.

$$\Delta\bar{x}_j = \frac{\sum_{i=1}^{n_j} \Delta x_i}{n_j}. \quad (2.1)$$

Equation 2.1 provides a calculation of systematic error in the x-direction only. Similar measurements are made in the y- and z- directions and used with the calculations. Generally the coordinate system that is adopted is based on the patient coordinate system and defines x in the lateral direction, y is defined in the anterior-posterior direction and z is defined in the superior-inferior direction. The positive and negative directions do differ in the literature. In practise, the orientation and direction of x, y, z is based on the linear accelerators software specifications and may differ between corporations. The distribution of Δx_i about the systematic error is defined as the random error, $\sigma_{R,j}$, for the j^{th} patient with a variance defined as:

$$\sigma_{R,j}^2 = \frac{\sum_{i=1}^{n_j} (\Delta x_i - \Delta\bar{x}_j)^2}{n_j - 1}. \quad (2.2)$$

It is useful to define the *mean treatment position deviation* (MTPD), \bar{x} , as the average of TPD measurements over all N patients' n_j images within the study. Mathematically, the MTPD is defined as:

$$\bar{x} = \frac{\sum_{j=1}^N \sum_{i=1}^{n_j} \Delta x_{i,j}}{\sum_{j=1}^N n_j}. \quad (2.3)$$

If \bar{x} is shown to be small, then the mean setup position over all patients is near the position defined at simulation. It is important to represent the variation in the TPD using the standard deviation, σ_T , of the data set because one set of data may vary more than other sets. The variation in setup position will impact directly on the setup margin. The

magnitude of systematic error is important, but particularly if the systematic error is small, the magnitude of the largest random shifts is important for setting a safe, conservative setup margin. The setup error is generally written as $\bar{x} \pm \sigma_T$ for a given group of patients.

For a population of patients the *mean systematic error*, $\Delta\bar{x}_S$, is defined as the average of the systematic errors for each patient. The value of the mean systematic error will always be close to that of the MTPD and identical to it if the number of portal images n_j is equal for all patients. Both the MTPD and the mean systematic error are important determinants in locating setup technique errors at an institution. The *systematic setup variation*, Σ_{SE} , is defined from the standard deviation of the $\Delta\bar{x}_j$ data set over the j patients. The systematic component then could be presented in a similar form to the setup error as $\Delta\bar{x}_S \pm \Sigma_{SE}$. The mean random error for a population of patients is necessarily zero. The *random setup variation*, σ_R , is calculated as the standard deviation of the set of data including all $(\Delta x_{i,j} - \Delta\bar{x}_j)$ values. That is, the set of data including all patients' TPDs subtracted from that patient's systematic setup error.

2.4.2. Magnitudes of positioning errors at various sites

Data for the typical magnitude of Setup Errors Averaged across Studies (SEAS) at a variety of sites are presented in Table 2.2. The interested reader is directed to other review articles on the topic, see Kutcher *et al* (1995).

Table 2.2 shows typical magnitudes of setup errors. The number of references attached to each value indicates the number of studies that the corresponding value has been averaged across, with the one exception. Bel *et al* (1996) provide results for prostate setup errors from three institutions in the Netherlands. The statistics of the non-immobilised prostate patient data is superior to those results with immobilised patients. A large number of vacant cells appear indicating that no data was found for that entry or due to incongruent presentation. Furthermore, it is noted that the prostate and pelvic regions are the most extensively studied.

Generally, results for SEAS range from 0 mm to 3 mm (for both immobilised and non-immobilised patients) across all sites. Immobilising the patient is shown to reduce SEAS, but it has been noted in *some* studies that it is not beneficial. Results for σ_T across all sites

Table 2.2 The mean patient displacement averaged across studies (SEAS) and standard deviation σ_T (mm), with the systematic standard deviation Σ_{SE} (mm) and the random standard deviation σ (mm).

Site	Uncert ion	SEAS(mm)		σ_T (mm)		Σ_{SE} (mm)		σ (mm)	
		Immob	No Immob.	Immob	No Immob.	Immob	No Immob.	Immob	No Immob.
Prostate	AP	-	1.2 _{11,40,60,61}	2.3 ₆₃	3.3 _{3,40,60,61,149}	1.3 ₆₃	2.7 _{11,42,60,61}	1.9 ₆₃	1.9 _{11,42,60,61}
	ML	-	0.4 _{11,42,60}	2.7 ₆₃	3.0 _{3,40,60,149}	1.9 ₆₃	2.4 _{11,40,60}	2.0 ₆₃	2.0 _{11,60,61}
	SI	-	0.9 _{11,42,60}	2.2 ₆₃	3.0 _{3,40,61,149}	1.4 ₆₃	1.9 _{11,40,60}	1.7 ₆₃	1.7 _{11,60,61}
Pelvis	AP	1.2 _{71,155}	0.5 ₅₇	5.3 _{74,156}	3.6 _{57,156}	-	8.1 ₁₇₁	0.7 ₁₅₅	2.5 ₁₇₃
	ML	0.6 _{71,155}	2.7 _{57,156}	5.0 _{74,156}	1.9 _{57,156}	-	5.0 ₁₇₁	1.5 ₁₅₅	2.2 _{72,192}
	SI	-	2.4 _{57,156}	-	2.4 _{57,156}	-	6.7 ₁₇₁	-	2.9 _{72,192}
Brain	AP	0.66 ₅₇	N/A	2.24 ₅₇	N/A	-	N/A	-	N/A
	ML	2.17 ₅₇	N/A	2.25 ₅₇	N/A	-	N/A	-	N/A
	SI	0.67 ₅₇	N/A	2.58 ₅₇	N/A	-	N/A	-	N/A
Abdomen	AP	0.7 ₁₅₅	-	4.9 ₁₅₅	-	-	-	1.8 ₁₅₅	-
	ML	0.8 ₁₅₅	-	7.4 ₁₅₅	-	-	-	1.7 ₁₅₅	-
	SI	-	-	-	-	-	-	-	N/A
H&N	AP	1.1 _{11,70,193}	N/A	2.3 _{70,193}	N/A	1.6 ₁₁	N/A	1.7 _{11,193}	N/A
	ML	0.8 ₁₁	N/A		N/A	1.5 ₁₁	N/A	1.8 ₁₁	N/A
	SI	0.9 _{11,70,193}	N/A	2.3 _{70,193}	N/A	1.7 ₁₁	N/A	1.6 _{11,193}	N/A
Chest	AP	3.3 ₁₅₅	-	6.7 ₁₅₅	-	-	-	0.8 ₁₅₅	-
	ML	1.3 ₁₅₅	-	7.1 ₁₅₅	-	-	-	2.1 ₁₅₅	-
	SI	-	-	-	-	-	-	-	-
Lung	AP	-	-	-	-	-	-	-	-
	ML	2.3 ₁₉₃	-	0.8 ₁₉₃	-	-	-	2.5 ₁₉₃	-
	SI	2.7 ₁₉₃	-	0.8 ₁₉₃	-	-	-	3.5 ₁₉₃	
Rectum	AP	-	1.4 ₄₀	-	3.9 ₄₀	-	2.8 ₄₀	-	2.6 ₄₀
	ML	-	1.0 ₄₀	-	3.0 ₄₀	-	1.8 ₄₀	-	2.4 ₄₀
	SI	-	0.5 ₄₀	-	3.0 ₄₀	-	1.7 ₄₀	-	2.5 ₄₀

range from 1 mm to 7 mm, with results for the abdomen and chest providing the upper range of 5 mm to 7 mm. Typical values for Σ_{SE} and σ_R are in the same range as σ_T . Note that the quoted values are one standard deviation, so for 90% confidence they should be

doubled.

It is important to note that the published results tend to be from advanced institutions and may not indicate the variation applicable to the average busy department.

2.4.3. Patient Immobilisation

It is evident from table 2.2 that head and neck, brain, abdomen and lung treatments are typically performed with immobilisation devices, while treatment at the pelvis is still in debate. Verhey (1995) has published a review of patient immobilisation techniques by site. Prostate immobilisation devices have yielded results that have been described as beneficial (Soffen *et al* 1991, Rosenthal *et al* 1993) and not beneficial (Song *et al* 1996) for improving the reproducibility of prostate treatment. Soffen *et al* (1991) reported a reduction in the greatest Δx measured during treatment by over 50% in each direction. The value of \bar{x} reduced from 8.0 mm to 3.3 mm. An increase in the percentage of exact agreements with simulator increased from 22 % to 43 % because of the use of an alpha cradle cast (extending from mid thigh to low thoracic area). This study used 20 port films per patient. Bentel *et al* (1995) discovered that the number of isocentre shifts required to achieve treatment position decreased by 20% for patients using custom made hemibody foam cradles (formed around the supine patients back and down to their feet) compared to non-immobilised patients, over a 7 week treatment course. Catton *et al* (1997) used a treatment couch stiffened with polycarbonate inserts and a soft immobilisation device. Values of \bar{x} were decreased from 3.9 mm to 2.6 mm using this device and the percentage of Δx values greater than 5 mm was decreased from 17 % of setups to 8 % of setups.

Washington *et al* (1994) measured insignificant improvement in σ_T using immobilisation devices against results without any immobilisation device (three tested). Among the devices tested were the alpha cradle as used by Soffen *et al* (1991) and a styrofoam immobiliser below the knees.

2.4.4. Pelvis

Table 2.2 lists ‘pelvic’ and ‘prostate’ as separate entries. This is because the literature provides some studies that isolate measurements of the prostate, while others combine a number of tumour sites in the pelvic region. The pelvic sites include genitourinary,

gynaecological, prostate, bladder, and rectal tumours.

Hanley *et al* (1995, 1997) have two separate sets of results listed in table 2.2. The former is a retrospective study into the magnitude of setup errors for treatment of the prostate while the latter is a study into the use of multiple projection port films. Results at that institution have shown a reduction in systematic setup error because of the introduction of patient repositioning when Δx is measured to be greater than 2 mm. Greer *et al* (1998a) reported that systematic setup errors in the AP direction were reduced for prostate from 3.7 mm to 1.2 mm, by adjusting the technique from setups with tattoos to using a table height method. Bel *et al* (1995) also report highly accurate set-up results using a table height method, although not for the pelvis.

Interestingly, Althof *et al* (1996) measured σ_T for both the bony anatomy and the prostate (with I^{125} seeds). Measurements of the prostate set up error (included in table 2.2) showed similar values as those for the bony anatomy with the largest difference being 0.2 mm. The setup error for individual measurements (i.e. Δx) ranged up to 9 mm (with no significant differences between bony anatomy and prostate setup error).

Hanley *et al* (1995) measured an inherent uncertainty in the registration algorithm in portal imaging software* (while imaging the prostate) of 0.6 ± 0.5 mm in translation and $0.7 \pm 0.8^\circ$ in rotation within the 2D image plane. This uncertainty was increased to 2.3 ± 1.0 mm and $1.2 \pm 1.1^\circ$, by applying a 2° out of plane rotation to the treatment planning computers 3D dose matrix. Crook *et al* (1995) and Balter *et al* (1996) measured rotation around the AP and ML axes using implanted radio opaque markers (3 per prostate). Crook *et al* (1995) reported rotation of $1.63 \pm 1.55^\circ$ around AP and $2.09 \pm 1.81^\circ$ around ML. This rotation is greater than that measured by Balter *et al* (1995) who quoted rotations of 0.2° , and 0.7° about the AP and ML axes respectively.

Weber *et al* (2000) investigated the prone versus supine orientations for prostate treatment. The random variations appeared similar for each patient orientation, but the prone orientation provided larger systematic errors. Also, the prone position is associated with higher dose to the rectum and/or bladder in over 30% of the patients.

* Varian PortalVision, software v.3.1.e., palo Alto, CA.

2.4.5. Brain

Gildersleve *et al* (1995) have published measurements of setup error (av. > 20 setups per patient) involving stereotactic radiotherapy of the brain. In this study each of the 12 patients were immobilised using plastic (individually moulded) fixation shells for simulation and treatment. Patients were positioned using marks on the cast with alignment lasers for isocentric treatments. Values of \bar{x} are about three times greater for the ML direction, than for the AP and SI directions. Values of σ in each direction are similar at between 2 mm and 3 mm. This suggests that the distribution was skewed because of a systematic error (at this institution) in the ML direction. 13% of patients showed \bar{x} to be greater than 5 mm with none greater than 1 cm. A beam margin of 5 mm is suggested by Gildersleve *et al* (1995). Rabinowitz *et al* (1985) measured σ_R equal to 3 mm for treatment of the brain, with a positioning device.

2.4.6. Abdomen

Schewe *et al* (1996) measured set-up errors for a number of sites including the treatment of abdominal cancers. Mean setup errors were measured as similar with standard deviations greater in the ML direction than in the AP direction (see table 2.2). Rabinowitz *et al* (1985) measured σ_R to equal 2.3 mm, for patients with abdominal cancer. These measurements are similar in magnitude to those measuring abdominal motion (see table 2.4) suggesting that much of the setup error may be due to abdominal movement. Interestingly, the setup errors in the abdomen have been measured to be comparable to those at other sites within the body, including the head and neck region.

2.4.7. Head and Neck

Magnitudes of SEAS for head and neck region (see table 2.2) show two predominant trends including: 1) use of immobilisation devices eventuated in all presented cases, and 2) highly accurate patient positioning across studies. Values of SEAS are typically around 1 mm with a value of σ_T equal to approximately 2 mm. The components of σ and Σ_S appear to be typically similar with values of each ranging from 1.5- 1.8 mm. Rabinowitz *et al*. (1985) measured σ from a single head and neck patient to be 0.1 mm with an immobilisation device. McParland *et al* (1993) measured field placement errors of the head

and neck region of immobilised patients to be 1.5 ± 4.6 mm. Meertens *et al* (1990) measured \bar{x} between simulator and portal images with σ_T equal to 1.5 mm using an online EPID system.

2.4.8. Breast

Westbrook *et al* (1991) measured setup errors for breast treatments. They measured the movement of tattoos with a megavoltage imaging device and found that most (84%) of the measurements fall within ± 2 mm of the initial position. A large variety of patient and breast sizes were evaluated with no substantial differences between patients based on physical size. Other studies (Creutzberg *et al* 1993, van Thienoven *et al* 1991, Lirette *et al* 1995) generally measured larger positioning errors, with mean values of systematic standard deviations ranging up to 4 mm, and maximum individual deviations ranging up to around 15 mm for particular patients. A systematic error between the simulation patient position and the reproduced patient position during the treatments was measured to be less than 4 mm in each direction (Pradier *et al* 1999). Pradier *et al* (1999) suggest that for breast treatments an immobilising device would improve the set-up reproducibility.

2.5. Organ motion

2.5.1. Defining organ motion

The motion of organs within the body can be broadly classified as moving randomly and/or cyclically. For example, most organs in the pelvis are described as moving randomly between fractions and organs in the abdomen are described as moving cyclically due to breathing. These two types of organ motion need to be defined separately. The interested reader is referred to a review article by Langen and Jones (2001).

Temporal prostate displacement is defined similarly to MTPD. The position of the organ from bony landmarks is described at simulation, and then inter fraction deviation from this position is measured during the treatment giving organ displacements. Alternatively, intra fraction variations can be measured using movie clips obtained with imaging equipment. All organ displacements from each patient are combined to form a data set from which a *mean organ displacement* (MOD_{organ}) is calculated with corresponding standard deviation

($\sigma_{m,organ}$). The standard deviation of MOD is discussed more extensively in the literature than the MOD. This is because the range of movement has been generally considered of higher importance than the mean organ position. However, in recent years knowledge of systematic error between planning CT images and the mean organ position during the fractionated treatment has sparked increased interest in systematic organ motion error (van Herk *et al* 1995). A novel investigation of the effect of (random inter patient) systematic organ motion error on delivered dose is done below (refer to Chapter 4).

For those organs moving predominantly due to respiratory forces, for example abdominal organs, most authors measure a total organ movement. The total organ movement is defined as the total positional change of the organ from inspiration to exhalation. Alternatively, for gated techniques that may include breathe holding, the reproducibility of the organ position at breathe hold or at a particular part of the cycle (say, inspiration) is required.

2.5.2. Magnitudes of organ motion

The Internal Planning Target Volume (IPTV) describes a volume to contain all movements of the CTV relative to the bony anatomy. The CTV may be displaced between fractions (inter fraction variation) or during the fraction (intra fraction variation). *Inter fraction* variations occur due to various factors including, for example with prostate treatments, the patient may void before some fractions, or the patient might not sit or lie on the treatment couch in the same way for each fraction. *Intra fraction* variations may occur due to factors including breathing, digestive processes or the pulsing of the heart or arteries. Obviously the location of the tumour, the structure/function of nearby organs and the setup procedure all have important influences on the motions, their magnitudes and the size of the IPTV to include uncertainty. The literature suggests that many institutions are starting to utilise values of the mean and standard deviations for inter fraction organ position and setup uncertainty to prescribe a ‘global’ margin, and not two separate internal and setup margins (as suggested by ICRU-62).

In the literature, organs in the pelvis (particularly the prostate) and abdomen are the most thoroughly studied. Published movements of the prostate, abdominal organs and others are summarised below. Techniques to reduce the organ movements are also explored. One of the challenges in comparing the published literature is the variety in measurement

techniques between institutions. Therefore, further detail in some cases is provided regarding the measurement techniques.

2.5.3. Prostate Motion

Measurements of prostate position have demonstrated movement of the organ due to factors including partial rectum and bladder filling (inter fraction variations) and also due to breathing (intra fraction variations). Studies have measured the prostate movements specifically due to each of these factors and also neglecting these factors. Inter fraction variations can be large in some circumstances. Therefore, an understanding of why the prostate moves and how factors such as constant rectal volume affect prostate position can be of great importance to accurate treatment field positioning.

Inter fraction variation is caused predominately by differences in rectal and bladder volumes at each fraction (Melian *et al* 1997, Beard *et al* 1993). Recently, respiratory induced prostate motion for patients who were positioned prone has been suggested as a cause of non trivial movements (Malone *et al* 2000).

The measurement of prostate motion, neglecting the rectal and bladder volume provides similar values of MOD_{prostate} and Σ_{OM} (the standard deviation in MOD_{prostate}) in the literature to those studies directly measuring the effects of these motions. Detailed investigation of rectal and bladder effects is given in §2.5.3.2.

The MOD_{prostate} values presented in the literature range up to 6 mm, with σ_{OM} varying in the range 1.3 mm to 4.5 mm. Typical values ($MODAS_{\text{prostate}}$) derived from measurements of MOD_{prostate} , using prostate centre of mass or individual markers have been tabulated below (table 2.3) with and without the patient being immobilised[†] during treatment. The vacant column indicates no prostate motion information found (of suitable format) for non immobilised patients in the literature. Movements tend to be greater in the AP direction

[†] Patient immobilisation devices refer to those devices that rigidly hold the patient in position for treatment. They might be personalised. Other patient positioning devices such as neck or knee rolls, bars held by the patient, or positioning lasers are not generally included in this description of patient immobilisation devices.

due to rectal filling, which might be intuitive from the geometry/position of the rectum.

Crook *et al* (1995) measured $MOD_{prostate}$ with patient immobilisation using two methods. Only the results from one of the methods (measuring positional change of the centre of mass of three gold seeds) were consistent with our definitions and therefore included in table 2.3. Results from the other study demonstrated that the prostate changes shape between measurements.

Standard deviations in $MODAS_{prostate}$, $\Sigma_{OM,prostate}$, for those patients treated with an immobilisation device are typically reported to be similar to those measured without the use of an immobilisation device. Several institutions have published improved results using immobilisation devices. Standard deviations of $MODAS_{prostate}$ with and without patient immobilisation devices were presented in table 2.3. These values were comparable to those directly measuring the effect of bladder/rectal filling on prostate positional change. For example, Melian *et al* (1997) reported $\sigma_{OM,prostate}$ values of 4.0 mm, 1.2 mm and 3.1mm, in the anterior-posterior (AP), medio-lateral (ML) and superior-inferior (SI) directions, respectively. Ten Haken *et al* (1991), measured σ_{OM} values of about 5 mm over the 31 patients in their Foley catheter study, and 2 mm for their CT study over 5 post implant patients.

Table 2.3 Prostate position uncertainty due to the motion not directly attributed to bladder/rectum filling in the ant-post, medio-lateral and sup-inf directions. References are bracketed.

Site	Uncertainty Direction	MODAS _{prostate} (mm)		$\delta_{prostate}$ (mm)	
		Immobilised	Not Immobilised	Immobilised	Not Immobilised
Prostate	AP	2.4 [31,93,147]	-	3.2 [31,93,147]	3.2 [3,8,150]
	ML	2.0 [31,93,147]	-	1.0 [31,93,147]	1.5 [3,8,150]
	SI	3.1 [31,147]	-	4.1 [31,93,147]	2.7 [3,8,150]

$MODAS_{prostate}$ and $\Sigma_{OM,prostate}$ in the ML direction is shown to be typically less than the movement in the AP and SI directions, for both patients with and without immobilisation. The superior portion of the prostate and the seminal vesicles tend to move more freely in

the anterior-posterior direction than the rest of the prostate (from a study with immobilised patients, Melian *et al* 1997). Methods of measuring the position of the prostate from its centre of mass assume that the prostate does not change shape, but the prostate has been measured to deform (with dosimetric consequences) due to physiological effects (Forman *et al* 1993) such as rectal and bladder filling. Therefore methods using markers or measuring positional changes of the prostate borders may give a more representative measurement of MOD_{prostate} .

2.5.3.1. Supine versus prone treatment positions

There may be advantages to treating patients in a prone rather than a supine position on the treatment couch. The prostates of men positioned prone tends to shift anteriorly, due to gravity, away from the rectum. Rectal filling has been correlated with prostate movements, and thus less prostate motion is evidenced in the prone position. However, those prostates of prone patients immobilised in thermoplastic shells can move substantially due to respiration (Malone *et al* 2000). One study showed that twenty three percent (23%) of patients treated prone and immobilised experienced intra fraction motions of greater than 4 mm. Calculations of rectal wall dose show reduced doses compared to patients treated supine (Schild *et al* 1993, Zelefsky *et al* 1997). The average rectal dose (as a percentage of the prescribed dose) was calculated as 64 ± 1.3 % in the prone position and 72 ± 1.1 % in the supine position, despite the PTV's being the same in both cases (Zelefsky *et al* 1997). No significant difference in bladder wall dose was found. Melian *et al* (1997) noted that treating patients in the prone position might increase bladder effects compared to the supine position. It is also suggested that the prone position may not be suitable for those patients who are obese or suffer significant orthopaedic/arthritis disease. In these cases the supine position may be more practical and tolerable for the patient.

2.5.3.2. Bladder/rectum filling influence on prostate motion (MOD_{prostate})

MOD_{prostate} values of 1 to 8 mm, due to rectal and bladder distension, were measured by Ten Haken *et al* (1991) using the centre of mass of the prostate derived from CT images. Greater movements of a Foley catheter balloon (i.e. 0 to 20 mm) due to rectal and bladder distension were also measured. The effects of rectal wall and bladder movement have been separately measured using CT images (Schild *et al* 1993). In this study, each border was measured to move by different amounts. Filling of the bladder was found to cause posterior

movement of the prostate and seminal vesicles with maximum range of 0 to 8 mm and maximum mean 2 mm (for posterior prostate margin). Rectal filling was found to cause compression of the prostate and seminal vesicles in the anterior direction of maximum range 0 to 17 mm and maximum mean 3 mm (for anterior seminal vesicles).

The effect of bladder filling can be inferred by comparing the MOD_{prostate} measured due to bladder and rectum filling (Melian *et al* 1997), with the MOD_{prostate} calculated for patients with full bladders (Crook *et al* 1995). Those MOD_{prostate} values derived separately for rectal and bladder filling showed substantially smaller magnitudes than those reported with only fixed bladder volumes. Despite this, the variation about the mean treatment positions (i.e. σ_{OM}) were similar for both cases. The small values of MOD_{prostate} (less than 0.1 mm in each direction) indicate that the distribution of prostate positions was centred at the position of the prostate described at simulation. A systematic difference between the treatment fractions and the single simulation image was present in the study using patients with full bladders (Crook *et al* 1995). Constant volume of the rectum before and during treatment appears to be a more important indicator than the bladder volume for prostate position precision.

Indeed a time trend has been shown with movements of the prostate. The prostate tends to move in a superior-posterior direction as the treatment proceeds. The position of the prostate seems to be more constant near the end of the treatment (Lattanzi *et al* 1998). This is thought to be due to incontinence induced by the irradiation of rectal tissue (Yeoh *et al* 1999). Forman *et al* (1993) suggest the presence of a systematic difference between the mean position of the prostate measured during treatment and the mean position during treatment plus the prostate position in the planning CT scan. Using CT scan images Forman *et al* (1993) reported $MOD_{\text{prostate/seminal vesicles}}$ measurements as 12 mm with Δx measurements ranging up to 37 mm during the treatment alone (i.e. disregarding the treatment planning CT). Interestingly, when the treatment planning CT was included in the calculations the mean shifted to 17 mm with Δx values ranging up to 35 mm. This suggests that the position of the prostate in the initial planning CT scan (typically used as the ‘gold standard’ prostate position) was significantly different to the mean prostate position during the treatment.

Chemotherapy combined with radiotherapy may affect the prostate volume and hence the amount of movement possible within the pelvic chamber. The prostate volume has been

measured to decrease by 37% following radiotherapy and three monthly injections of Lupron (Forman *et al* 1993, 1995). Radiation alone has been shown to decrease the volume by an average of 14% after two weeks of fractionated radiotherapy (Roach *et al* 1997).

The stage of the tumour has been linked with the amount of inter fraction variation measured (Ten Haken *et al* 1991). Patients treated with earlier stage disease appear to exhibit larger movements (Ten Haken *et al* 1991, Crook *et al* 1995). Another study however found no correlation between tumour stage and the inter fraction variation (Melian *et al* 1997). Radical treatment of prostate cancer is usually only performed on earlier stage tumours. Perhaps it may be inferred that the tumour stage (and correspondingly increased size) causes the pelvis to restrict prostate movement for those at later stages of the disease.

2.5.3.3. Strategies to account for prostate motion

A number of authors have made suggestions from the results of their measurements of prostate motion. In particular Webb (1997) summarises four strategies. These may be classified into those that accept organ motion and aim to account for the uncertainty with the application of safety margins (Pickett *et al* 1993), and those that aim to monitor or control motion (Balter *et al* 1993, Liebel *et al* 1994). Some strategies include;

Using a Foley catheter with rectal stent to keep the rectal volume constant (Ten Haken *et al* 1991).

Treat patients prone with full rectums and bladders (Schild *et al* 1993). The prostate position then is not only more reproducible, but the inferred shift of the prostate is advantageous to rectal sparing.

Image patients before each fraction and shift the linac isocentre accordingly. Daily CT scans can be used to locate the prostate on each treatment day (Lattanzi *et al* 1998). The bony anatomy is matched between the initial planning CT and the daily CT scans (called a CT-CT fusion technique). The daily CT scans, amended planning and setup increased the treatment time by 15 minutes for each patient. Also daily ultrasound has been suggested in the literature to be a simple and reproducible technique (Lattanzi *et al* 1999). If the isocentre is simply adjusted to the daily prostate centre of mass, deformation is obviously being ignored, but can be included in the IM.

Non uniform (isotropic) margins should be used to compensate for prostate deformation and the isotropic nature of the prostate motions (Pickett *et al* 1993).

These considerations are of great importance to IMRT and boost treatments (Deasy and Cornett 1997) where the randomness of prostate motion is becoming a limiting factor to dose escalation.

By accounting for prostate motion in the treatment planning software improvement has been demonstrated in the calculated isodose distribution (Mageras *et al* 1994). Various models of prostate motion exist with some assuming linear motion of the organ (Craig *et al* 1998), while others allow for separate motion in each direction of the entire surface or each individual pixel (i.e. deformation)(Yan *et al* 1994, Fontenla *et al* 1997).

2.5.4. Abdominal Motion

While prostate motion is hypothesised to be caused by patient physiology, abdominal motion is generally caused by respiration and is generally cyclic. During the past 20 years methods to quantify and hence manage patient breathing and the corresponding movement of abdominal organs have progressed forward with technological advances. Organ motion within the abdominal cavity due to respiration has been quantified using computed tomography (CT) (Balter *et al* 1996), magnetic resonance imaging (MRI) (Moerland *et al* 1994, Swartz *et al* 1994) and ultrasonography (US) (Oppelaar 1998, Davies *et al* 1994) techniques.

The data available on radiotherapy aspects of respiratory induced organ motion are scarce and more data is required.

2.5.4.1. Generalities

Measurements of $MOD_{\text{abdominal}}$ under the same clinical conditions (e.g. breathing rate), of the same organ, in a given direction and presented in the same form were not found in the literature. Typical values (in a form similar to table 2.3) of $MOD_{\text{abdominal}}$ could not be derived for this reason. Instead a summary of results from the literature is shown in table 2.4.

Table 2.4 Summary of respiration-induced abdominal motion. The movement of the organ is the positional difference of the organ from inhalation to exhalation, unless otherwise stated. The details of the measurement may include a direction, breathing rate, alternate endpoint, or the condition of the organ at the time of measurement i.e. disease title.

Author	Organ	Movement (mm)	Details
Balter (ref 7)	Kidney (L)	18±6	AP, Normal Breathing (nb)
Balter (ref 7)	Kidney (R)	18±6	AP, Normal Breathing
Swartz (ref 165)	Kidney	< 43	SI, Normal Breathing
Moerland (ref 126)	Kidney (L)	2-24	Normal Breathing
Moerland (ref 126)	Kidney (R)	4-35	Normal Breathing
Suramo (ref 165)	Kidney (L)	19 (10-40)	CC, Normal Breathing
Suramo (ref 165)	Kidney (R)	19 (10-40)	CC, Normal Breathing
Kuhns (ref 87)	Kidney	4.9±8.3	Breath hold @ inspiration
Kuhns (ref 87)	Kidney	7.7±6.6	Breath hold @ expiration
Suramo (ref 165)	Kidney (L)	41 (20-70)	CC, forced respiration
Suramo (ref 165)	Kidney (R)	40 (20-70)	CC, forced respiration
Ahmad (ref 2)	Kidney (L)	1-32	Forced respiration
Ahmad (ref 2)	Kidney (R)	3-21	Forced respiration
Moerland (ref 126)	Kidney (L)	10-86	Forced respiration
Moerland (ref 126)	Kidney (R)	10-66	Forced respiration
Kuhns (ref 87)	Diaphragm	8.0±9.8	Btw exposures, nb
Davies (ref 34)	Diaphragm	12±7 (7-28)	SI, Normal Breathing
Balter (ref 7)	Liver	17±5	AP, Normal Breathing
Suramo (ref 165)	Liver	25 (10-40)	Normal Breathing
Suramo (ref 165)	Liver	55 (30-80)	Forced respiration
Davies (ref 34)	Liver	10±8	Quiet respiration
Suramo (ref 165)	Pancreas	20 (10-30)	Normal pancreas, nb
Suramo (ref 165)	Pancreas	43 (20-80)	Normal pancreas, forced
Kivisaari (ref 84)	Pancreas	30±17 - 41±21	Normal pancreas
Kivisaari (ref 84)	Pancreas	29±16 - 32±23	Pancreatitis
Kivisaari (ref 84)	Pancreas	14±6 - 25±1	Caput carcinoma

Using an ultra fast CT during normal breathing, Ross *et al* (1990) measured total abdominal movement ranges up to 22 mm in the ML direction (with mean 6.1 mm) and up to 15 mm in the AP direction (with mean 1.9 mm). Craniocaudal movements were greatest

near the diaphragm, while lateral movements were greatest near the heart or aorta. Casamassima (1994) measured the kidney and liver to move by up to 3 cm during normal respiration. Davies *et al* (1994) measured abdominal motion to be greatest in the diaphragm, moderate for the kidneys and least for the liver, with motion of the diaphragm and the liver predominantly in the SI direction. Tumours in the upper lobe and those attached to the chest wall showed minimal movement.

The difficulties for comparison of results are the lack of measured directional information for the movement, the different breathing rates requested of patients/volunteers in each study, and the different endpoints of each measurement.

As expected, greater organ movement during forced respiration than during normal or quiet respiration was reported at each site. Movement of organs has been shown to follow complex paths when the patient breathes heavily. However, most studies considering normal breathing show the variation in motion amplitude as being reproducible (with standard deviations ranging from 6 to 8 mm for the kidneys, and up to 30 mm for other abdominal organs).

2.5.4.2. Kidney Motion

Schwartz *et al* (1994) measured total kidney movement ranges up to 43 mm between inhalation and exhalation, with the reproducibility (standard deviation of mean total movement) at inhalation being 1.8 mm to 3.0 mm and 2.8 mm to 3.6 mm for exhalation, using ultra fast MRI. No differences were found between the left and right kidney movements, as measured by Balter *et al* (1996) or Suramo *et al* (1984) during normal breathing. Moerland *et al* (1984) measured the range of displacements of the right kidney to be greater than that of the left kidney during normal breathing. Both Moerland *et al* (1984) and Ahmad *et al* (1997) found greater movements and movement variability of the left kidney to the right kidney during forced respiration. The various borders of the kidney were shown to vary by different amounts, with the internal border varying the least and the inferior border varying the most.

2.5.4.3. Diaphragm Motion

Evaluation of diaphragm motion shown in table 2.4 demonstrates the measurement of diaphragm movements using different endpoints. Kuhns *et al* (1979) measured the

variation in position between exposures, while Davies *et al* (1994) measured movement in the SI direction during normal breathing at inhalation and exhalation. The results, however, show similar values.

2.5.4.4. Pancreas Motion

Kivisaari *et al* (1982) measured total pancreas movement to be dependant on the condition of the pancreas, with those considered normal or suffering pancreatitis being more mobile than those suffering caput carcinoma. Pancreases with the former two conditions tended to be most mobile at the tail and the body being least mobile. Those pancreases with caput carcinoma tended to move most in the body and least in the tail of the pancreas. The measurements of normal pancreas movement by Suramo *et al* (1984) show movements less than those by Kivisaari *et al* (1982).

2.5.4.5. Breath Holding Techniques

Kuhns *et al* (1979) demonstrated the movement of the upper poles of the kidney for breath holds to be 4.9 ± 8.3 mm during inspiration and 7.7 ± 6.6 mm during expiration. Suramo *et al* (1984) devised a method, using a horizontal bar (able to move vertically) placed across the patients' chest, to reduce organ movement. In particular movements of the kidneys, liver, and pancreas were decreased from 4 mm to 1 mm, 9 mm to 2 mm, and 6 mm to 1 mm, respectively. Other attempts to improve reproducibility of lung volume for repeated breath holds (during an imaging session) included providing the patient with an LED display (Jones 1984) or a deflecting pointer (Frolich and Dohring 1985) to indicate chest height.

2.5.4.6. Advanced Techniques

Recent studies (Ohara *et al* 1989, Kubo and Hill 1996) suggest that the radiotherapy beam may be gated by either a mechanical or physiological sensor resulting in "gated radiotherapy". This technique allows the patient to breathe freely during treatment without the risk of compromising the accuracy of the dose delivery. Another two techniques which utilise gated methods are Predictive Respiratory Gating (Richie *et al* 1994) for imaging and Active Breathing Control (Wong *et al* 1997) for radiotherapy. The gating mechanisms are currently standard on some commercial linear accelerators.

Predictive Respiratory Gating uses an algorithm that predicts the time taken to restart inspiration after end of expiration and then aligns the CT acquisition accordingly (without

assuming periodic motion). Whilst Active Breathing Control differs by additionally involving a device that feeds the patient air, and thus controls their breathing cycle. At a predetermined time the apparatus cuts the air supply and holds the lung volume constant while a periodic dose is given. Clinical studies (Wong *et al* 1997) have shown that patients can comfortably hold their breath for around 15 seconds at the end of expiration and from 25 to 50 seconds at the end of inspiration. During this time period the lung volume changes by less than 5%.

2.5.4.7. Patient Orientation during treatment

Willet *et al* (1987) found that Hodgkin's disease patients treated in the standing position had a lower ratio of the mediastinal mass to the inter thoracic diameter than those patients treated supine and prone, during quiet respiration. For heavy breathing no appreciable difference occurred between the patient positions. Harauz and Bronskill (1979) found no appreciable improvement (regarding liver motion) in positioning the patient supine compared to having them stand. The respiratory amplitude decreased from 14 mm to 12 mm.

For a given patient, the movement of abdominal organs deduced during the initial imaging session tends to reflect the movement through the treatment course (Opelaarr 1999). Organs within the abdomen are physically fixed in position and respiration may cause the organs to move substantially. Abdominal motion tends to reflect the distance of the organ from the diaphragm, and might represent the respiratory frequency of the patient. Gated and breathing control techniques match these circumstances.

Abdominal organ position distributions have been shown to be reproducible across patients after the initial sizes and locations have been measured. This has suggested the possibility of modelling organ movement by applying the fixed variation to the personalised initial organ position image (Yan *et al* 1997).

2.6. Patient Repositioning strategies

Patient repositioning using portal images can dramatically reduce systematic set-up errors (Shalev and Glutchev 1994, Yan *et al* 1994). The megavoltage or kilovoltage (Pisani *et al* 2000) portal image is compared to a benchmark simulation image and specialised

computer software is used to detect shifts in the bony anatomy between the two images. If a shift is detected, and it is larger than a prescribed action level, a decision can be made (off line) for the patient to be shifted before the next fraction. Alternatively, the decision can be made in real time and the shift, if any, can be made (on line) for the current treatment fraction. The on line procedure adds 3-10 minutes to each fraction (Stroom *et al* 2000, Pisani *et al* 2000).

Balter *et al* (1993) modelled repositioning patients on-line. They initially measured that 17 out of 27 port films demonstrated shifts (Δx) greater than or equal to 1 cm. Replacing those measured values that were greater than 1 cm with higher accuracy random error data (ranging from 1 mm to 4 mm), the minimum tumour coverage with reduced field margin compared well to that of normal treatment, illustrating that repositioning the patient would be beneficial. Moreover, reducing the systematic error using on-line repositioning is thought to justify the reduction of margins 1 cm to 0.5 cm for gynaecologic tumours (Stroom *et al* 2000).

Many criteria for prescribing a suitable action level have been described in the literature (Yan *et al* 1994). Bel *et al* (1996) suggest a two stage, shrinking action level (SAL) protocol for prostate treatment (known as the Amsterdam method). The first stage involves measuring the Δx over the first few fractions and comparing the measured values against the diminishing action level calculated as τ/μ , where τ is the initial action level and, μ is the measurement number. A minimum of two measurements are taken and if the measured value of Δx is greater than the action level then the isocentre is shifted in the next fraction by the cumulative \bar{x} in each direction and stage 1 is restarted. The initial parameters (τ and μ_{\max} , the number of consecutive treatment sessions featuring portal image acquisition)[‡] are calculated using derived (patient specific) values of σ_T in a computer simulation. When the required accuracy is achieved the second stage begins. The second stage is based on a weekly check of the setup accuracy. This method ignores rotations as they have been measured in the literature and were shown to be small for prostate treatments (van Herk *et al* 1995, Bijhold *et al* 1992). The method also assumes that the σ_R is the same for each patient (Bijhold *et al* 1992). This procedure improved the percentage of Δx measurements

[‡] Typical values for τ , μ_{\max} range from 6 mm to 10 mm, and 2 to 4, respectively.

that were greater than 5 mm from as high as 42.7% to less than 1%, requiring about 12 measurements per patient. Other techniques have been suggested to reduce the average number of measurements per patient using a No Action Level (NAL) protocol (de Boer *et al* 2001). The NAL protocol measures patient positioning over a specified number of fractions before the single repositioning per patient per treatment and is similar to the Newcastle method described below.

Following diagnosis of a discrepancy the Amsterdam method prescribes repositioning of the patient by the whole measured shift despite this measured shift containing components of random and systematic error. Pouliot and Lirette (1996) suggest that only the systematic component of the measured discrepancy should be included in the repositioning of the patient following the diagnosis of an error. They proposed using the full maximum likelihood theory (FML) to derive that the magnitude of the required shift is the measured discrepancy multiplied by the FML factor. The FML factor is calculated from the standard deviations of the systematic error SD_{sys} and random error SD_{rand} , as $FML = SD_{sys}^2 / (SD_{sys}^2 + SD_{rand}^2)$. This procedure is optimal when the component of random error is large, and the method seeks to prevent over corrections.

The flow of operation suggested by Bel *et al* (1996) and by Pouliot and Lirette (1996) assume that the measured discrepancies in each direction are independent and a history of errors associated with that site and procedure are available. See *et al* (2000) test a further method (the Newcastle method) that does not assume the discrepancies are independent and builds case histories for each patient as they are treated. The Newcastle method schedules the patient treatment into two sections, these are; diagnosis during the first week and intervention during the remaining weeks. No corrections are made during the first week, but portal images are acquired and the 3D discrepancies are detected. Hotelling's T^2 statistics are used to prescribe the action level for that patient and to provide useful statistics. The action level is not simply three single direction scalars along each coordinate axis, but plots of the measurements including a multivariate analysis to detail whether the movements in each direction are independent. The method is not based on population statistics and although the derivation of individual patient action levels is advantageous the number of portal images required and the associated workload could limit the clinical usefulness.

2.7. Contemporary suggestions for treatment planning

The provision of a margin between the CTV and the PTV based on a ‘rule of thumb’ is not the optimal technique to account for targeting uncertainty. This is because the rule of thumb may offer no patient specificity, no scientific basis and may not consider the directional dependence of the errors. Statistical dose based methods have been suggested in the literature to size the CTV-PTV margin and also to adaptively conform dose to the tumour while the treatment progresses and individual data are generated (Craig *et al* 2001). It should be noted that many radiotherapy clinics are not yet utilising any of these techniques.

2.7.1. Statistics based treatment margins

The sizing of a margin between the CTV and PTV is a balance between the targeting accuracy and dose constraints on tumour and normal tissue. The margin should be sufficient to account for all geometric errors such that the CTV accumulates no less than, say, 95% of the prescribed dose. Various factors have been included in the statistical techniques for manufacturing a suitable margin.

One of the original suggestions for sizing the margin came from Goitein (1985) who conjectured that the CTV-PTV margin, H , should equal 1.5 multiplied by the standard deviation of combined target/patient motion. At this stage of history, the positioning of dose in space was not as precise as it became during the 1990’s. The basic premise at this stage was, and still is in a large number of centres, the ‘global’ margin identified in §2.1. The global method calculates a margin from the root of the measured variances of patient positioning error plus organ motion assuming that the two uncertainties are independent:

$$H = N_{SD}(\Sigma^2 + \sigma_{\text{random}}^2)^{1/2} \quad (2.4)$$

The technique then uses population statistics, and the margin is based on certain numbers of standard deviations, N_{SD} , providing a certain probability of PTV coverage. For example 2 standard deviations refers to a 90% probability of PTV coverage.

There are other further advanced techniques that account for the geometry of the tumour, the systematic and random components of setup error and the beam geometry. The geometry of the tumour can be incorporated to allow for the areas of tumour near beam

edges with larger volumes (i.e. deeper in the beams eye view) to have larger margins (Fontenla *et al* 1996). Thus weights are calculated using the volumes of tumour in each pixel in the beams eye view. The larger margins indicate the higher importance allocated to the ‘thick’ portions of tumour based on expected tumour response.

The systematic and random components of treatment error have been included in ‘recipes’ for global margins (Antolak *et al* 1999, Stroom *et al* 1999, van Herk *et al* 2000). One of the techniques (Stroom *et al* 1999) uses a coverage probability (CP). The CP is calculated from the convolution of the tumour matrix (zero values outside tumour, values of one inside) and the suitable error distribution (with standard deviations = Σ and σ_{random}). The standard deviation of systematic error, Σ , and random error, σ_{random} , are used for the combination of all error sources. Thus, an iso probability matrix can be derived for each clinical situation to give the patient population a high probability of the CTV receiving a large treatment dose. The generalised margin size will be one that ensures, say, at least 95% dose to 99% of the CTV (on average) to be

$$H = a\Sigma + b\sigma_{\text{random}} \quad (2.5)$$

where a is the co-efficient of the standard deviation in systematic error and b is the co-efficient of the standard deviation in random error. These co-efficients will change according the required field placement accuracy. For example, setting a=2, b=0.7 refers to a 90% probability of depositing at least 95% dose in the target. Delineation error is a systematic error.

Another technique to combine systematic and random components of treatment uncertainty is suggested by van Herk *et al* (2000). Their method is derived from first principles. For a single beam in plane geometry the penumbra of a dose profile at depth can be derived as the convolution of a Gaussian distribution (with standard deviation, σ_p) with the *open beam* i.e. a step function. In this case the open beam would be evident if the source was a point and sufficiently distant from the medium for the ray lines of the beam to be considered parallel. The spread of the convolution kernel then describes the impact of the diverging beam and the finite source size. The result of the convolution would be, for example, that dose profile described by a treatment planning computer for a single beam in plane geometry called the *physical beam*.

To investigate the typical magnitude of the σ_p parameter a simple computer program was written. The program reads an input dose profile and then separately calculates the convolution of a Gaussian function with a step function for comparison. The input dose profile is visually compared to the result of the convolution with various σ_p values. Using the input dose profile from a 10x10 cm² beam of 6 MV photons, the value of σ_p was calculated to be 3.2 ± 1.0 mm. Using the oblique and lateral profiles through a four field box technique, the fitted values of σ_p were 6 ± 1 mm (with lower dose cut off 5 Gy) and 5 ± 1 mm (with lower dose cut off 35 Gy), respectively. The literature provides the value 3.4 mm as a typical magnitude (van Herk, 2000).

For a single beam multi fraction treatment the random positioning uncertainty experienced for each fraction of treatment can be characterised by Gaussian σ_{random} , and will lead to a dose profile given as the convolution of the physical beam with the random error. If we wish to use the geometrical beam, then we must perform a convolution with the combined error (given as $\sigma^2 = (\sigma_p^2 + \sigma_{\text{random}}^2)^{1/2}$). Thus, including the random component of error, to cover the CTV with the PTV from the 90% dose point on the penumbra a margin of $1.28(\sigma - \sigma_p)$ should be added. To accommodate systematic error, such as delineation error at the treatment preparation stage, a margin of 2.5Σ is derived to succeed for 90% of patients. Therefore, to include the CTV within the PTV for 90% of patients to 90% of prescription dose the margin required is

$$H = 2.5\Sigma + 1.28(\sigma - \sigma_p). \quad (2.6)$$

For higher confidence that the CTV will be enclosed within the PTV for all fractions, other coefficients can be used. For example, for 95% of prescription dose the coefficient of random error is 1.64 and for 95% of patients the coefficient of systematic error is 2.79.

Another technique using the combined standard deviation of random and systematic error (where Σ_{total} is the root of the systematic and random variances added in quadrature) provides an alternative to the requirement of enclosing a point on the surface of the CTV inside the PTV. Antolak and Rosen (1999) have shown the theoretical probabilities of movement from a point by a certain distance in 1D, 2D, and 3D space. Most relevant is the 3D case, where they use the integral form of the Maxwell equation to express that the probability of finding an object within the sphere of radius R is (Antolak *et al* 1998):

$$P(R) = \sqrt{\frac{2}{\pi}} \int_0^R \exp\left(-\frac{r^2}{2}\right) r^2 dr \quad (2.7)$$

which can be rewritten as

$$P(R) = \operatorname{erf}\left(\frac{R}{\sqrt{2}}\right) - \sqrt{\frac{2}{\pi}} R \cdot \exp\left(-\frac{R^2}{2}\right) \quad (2.8)$$

where $\operatorname{erf}()$ is the standard error function (Press *et al* 1989). Graphically, Antolak and Rosen (1999) express the cumulative probabilities of finding the centre of the CTV inside the normalised radius

$$r^2 = \frac{(x - \bar{x})^2}{\sigma_x^2} + \frac{(y - \bar{y})^2}{\sigma_y^2} + \frac{(z - \bar{z})^2}{\sigma_z^2} \quad (2.9)$$

where only one of the cartesian directions is used for 1D etc. The cumulative probabilities are plotted versus normalised radius in figure 2.2 below.

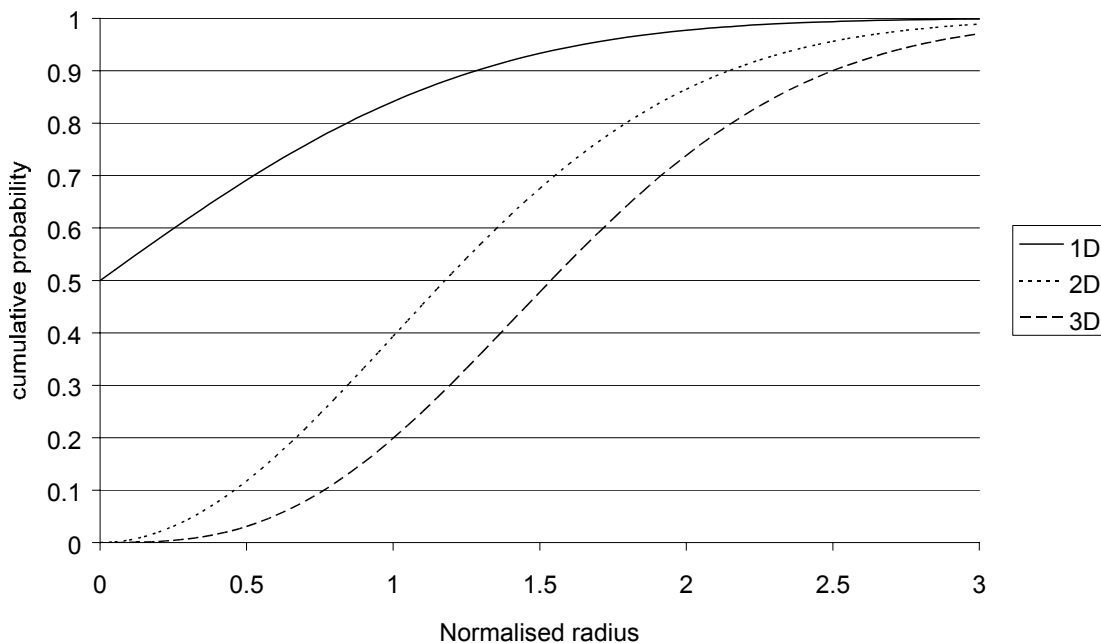


Figure 2.2 Cumulative probability distributions as a function of the normalised radius of expansion for three different CTV-PTV margin strategies. From Antolak and Rosen (1999).

Equation 2.6 is suitable for a single beam in plane geometry or extremely conformal treatments, but with multiple beams a more advanced technique is required. McKenzie *et*

al (2000) derived an alternate co-efficient, η , for the random component of error depending on the number of beams used (up to 6 beams) and whether the beams are parallel and opposed or *not* parallel and opposed. The margin is then

$$H = 2.5\Sigma + \eta(\sigma - \sigma_p), \quad (2.10)$$

where η ranges from 1.64 for a single beam to 0.52 in the transverse plane with 6 beams. Generally, the values of η are greater than one in the transverse and cranio-caudal directions assuming that the patient is treated parallel to the linear accelerator gantry.

The techniques for margin calculation discussed thus far have been predominately theoretical and dose-based. In practise the margin calculated with one of these margin recipes may include a portion of a sensitive normal structure and in that case other factors need to be considered. Other factors may include DVHs, or biological indices such as the normal tissue complication probability. In essence though, these other factors do refer to clinician input directed towards either changing the margin in some way or progress without any changes. Recently, van Herk (2001) has calculated a margin rule that considers the tumour control probability. In that work, decreasing the existing margin by 3 mm was calculated to reduce the probability of tumour control by 1%.

Mageras *et al* (1999) have developed a technique to include population based measurements of patient positioning and organ motion uncertainty into a prescribed dose volume (PDV). The PDV is used to set margins by weighting the importance each region of interest and allocating limits of dose.

In general the margin ‘recipes’ to date have separated uncertainty into systematic and random components. This does not conform to the IM and SM suggested in ICRU-62 (1999). The ICRU-62 document is still relatively new (at the time of writing) and only time will tell if it’s suggestions are put into practice.

2.7.2. Adaptive radiation therapy

Adaptive radiation therapy involves constantly optimising the planning of a treatment as it proceeds according to the accumulating knowledge of each treatment. Thus as portal images are obtained and the distributions of set-up and organ positions become more reliable, the treatment margins can be adjusted accordingly. This broad system of treatment

was proposed by Yan *et al* (1997a) and has been developed further in recent years (Yan *et al* 1999, Yan *et al* 2000, Yan and Lockman 2001). The latest system involves kilovoltage imaging attached to the linear accelerator so that organ motion and setup errors can be reasonably eliminated.

2.7.3. Monte Carlo techniques

Killoran *et al* (1997) suggest a Monte Carlo technique that iteratively samples from population distributions of setup errors and organ motion. The result is a probability of prescription dose curve, which directly relates the margin size with the probability that the CTV will accumulate the prescription dose. This method allows patient specific distributions for each known uncertainty to be included, but computation times are high.

Mageras *et al* (1996) have devised a method to include a population of serial CT images with a planning CT image set to provide information on the potential extent of prostate movement. The region of interest data (reflecting outlined target and non-target organs) from the population of serial images is included on a current patients CT image set. The statistics of the past organ positions are used to calculate a confidence limited dose volume histogram (CL-DVH). The CL-DVH offers the dose deposited to incremental volumes of the specified region of interest tissue, allowing for possible organ movement, within specified confidence limits. Thus, potential organ movements are predicted and included into a DVH. The DVH itself includes no spatial information and therefore the magnitudes of organ motion in each direction may not be easily interpreted. The method also ignores systematic organ shifts from planning to treatment by treating all images with equal weight.

In this thesis, a Monte Carlo code is developed that calculates the standard deviation in deposited dose based on the statistics of the organ motion. With this tool, the regions on the planning CT image that attract the most uncertainty in deposited dose are elucidated. The MC technique presented in §4.3 allows inclusion of single or multiple CT image sets, and details the magnitude of dose advantage from multiple CT scans and the size of the potential regions of regret from the normal practise of single planning CT scans.

2.7.4. Convolution techniques

The convolution integral has been used previously for reducing statistical noise in electrical circuit applications. More recently, in radiotherapy, the convolution integral has been used to model the interaction of high energy photon beams with matter and used for calculating dose in treatment planning systems (Mackie *et al* 1984). However, the application of the convolution integral has also been utilised for calculating the effect of treatment uncertainties (Leong, 1987). The general form of the convolution integral is

$$f'(x) = \int f(x - x') \cdot g(x) dx' \quad (2.11)$$

where f is the planned dose distribution, g is a probability distribution function (PDF) describing the treatment uncertainty and $f'(x)$ is the mean delivered dose distribution. Since the method uses the precalculated dose distribution from the planning system with an existing PDF, and involves one simple calculation, this technique is easily implemented into a treatment planning system. Once the delivered dose distribution has been calculated the associated DVH can be created and compared with both the original plan DVH and rival plan DVHs (Keall *et al* 1999). Moreover, the convolution technique has been extended from calculating only the mean delivered dose to calculating the standard deviation in mean dose (Zavgorodni 1997, Lujan *et al* 1999). Bel *et al* (1996) used deconvolution to calculate CTV→PTV margins.

However, the weakness of the convolution technique is the assumptions that it is based on. These assumptions include (but are not limited to) the organ not deforming during treatment, uncertainty obeying the PDF through out each patients' treatment, and the lack of heterogeneities. Obviously, some disease sites will better conform to these assumptions than others. The prostate, as has been detailed previously, does conform well to the assumptions of the convolution method and is a candidate for accurate use of the technique. The prostate is located in the rather homogeneous bony pelvis, deforms only moderately with physiological function, and shows reasonably small variations from the PDF during a 5 week course of radiotherapy.

There are, however, still areas that need to be improved upon with the convolution technique. In this thesis (§4.4) the technique is extended to predict the effect of single and multiple planning CT images on the precision of dose delivery. As explained previously,

the systematic error of prostate location is a discrepancy between the planning CT image(s) and those taken during treatment are substantial and should be included extrinsically in the planning process. Further detail is given in Chapter 4.

2.8. Summary

This chapter has demonstrated the significance and importance of considering the inevitable uncertainty during the planning and delivery of a radiotherapy treatment. Across all sites, the inclusion of knowledge regarding the magnitudes and characteristics of the errors should be considered. Combined with techniques to control the magnitude of errors, careful efforts need to be employed to account for them as well. The best opportunity to account for uncertainty is in the planning process, using methods that reflect the statistical nature of many of the errors.

The prostate has been illustrated to move up to 2 cm interfraction due to rectal, and to a lesser extent, bowel distension (Ten Haken *et al* 1991). Following the suggestions of the ICRU reports, combined with statistical dose based techniques, suitable CTV→PTV margins can be calculated. But, a large unpredicted movement is always possible, as is a patient-specific trend. Repositioning the patient is not trivial because the prostate is not visible in portal images. Other imaging techniques, such as kilovoltage or CT have been suggested in the literature. However these techniques have not been shown to be efficient or integrated into commercial treatment planning software.

Clearly, the prediction of potential organ movement and patient position is the best option. Accordingly, a number of considerations are explored in this thesis deriving from knowledge of the prostate motion and patient positioning characteristics. One such characteristic is the potential systematic prostate position error between planning and treatment. The ramifications of not considering this error when managing errors during treatment delivery are explored in Chapter 4 using both convolution and MC techniques. The impact of the errors at planning and treatment on the tumour and normal tissue response are calculated with biological models in Chapter 6. Possible techniques for better displaying the potential error are explored in Chapter 7.

Chapter 3

Review of radiobiological models

3.1. Introduction

This chapter introduces the concepts that are important for investigation of the radiobiological impact of the potential errors in the dose delivered to the tumour site and surrounding tissue investigated later in this thesis.

The chapter contains a description of the current radiobiological models used within radiotherapy and discussion of their relative merits. The relevant concepts outlined include the Biologically Effective Dose (BED), Standard Equivalent Dose (SED), Equivalent Uniform Dose (EUD), Tumour Control Probability (TCP), Normal Tissue Complication Probability (NTCP), and Uncomplicated Tumour Control Probability (UTCP).

The calculation of TCP for prostate carcinoma is outlined in detail following the general discussion of TCP. A number of radiobiological aspects such as the currently considered fractionation regime (from the literature) for prostate carcinoma will be reviewed. The feasibility of using the calculated TCP for prostate cancer is discussed. With NTCP, the particular case of late rectal complications is outlined in further detail to highlight the growing knowledge base surrounding the choice of parameter values and their meaning.

3.2. Biological Models

Biological models can be grouped as being either empirically or theoretically based. The empirical models derive from fitting curves to actual clinical data. Strictly, these models are then only valid for situations described by the original clinical data. Alternatively, theoretical models are based on some insight into radiation interaction with cells and DNA and the processes involved. These models require the theory for each process. It is important for the user of such models to take into account the limitations in identifying and theorising about each of the processes.

An important proviso when using the radiobiological tools derived from these models is to remember that they have a limited application, are based on incomplete laboratory data, and that they should be superseded by clinical experience. Box puts this in perspective when he writes “All models are wrong, but some are useful!” (Box, 1984).

3.2.1. Empirical (Probit and Logit) Models

The two most common empirical models are the Probit and Logit models. The Probit model (Lyman, 1985) was derived from tolerance dose data for various percentage volumes irradiated across a variety of organs (and is plotted in figure 3.1). The Probit model can be described by the probability of effect following radiation dose, D using:

$$P(D)_{probit} = \frac{1}{2} \left(1 - \operatorname{erf} \left[\sqrt{\pi} \gamma \left(1 - \frac{D}{D_{50}} \right) \right] \right) \quad (3.1)$$

where $\operatorname{erf}()$ is an error function, γ is the slope of the dose response curve at 50% response, and D_{50} is the dose to cause a given effect (or endpoint) in 50% of the population. For tumours the desired effect is total eradication of all clonogenic cells, while for normal tissue, the effect could be anything from a range of undesired complications, such as skin reddening (erythema).

The error function used in equation 3.1 is a form of the gamma function expressed as:

$$\operatorname{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} dt \quad (3.2)$$

The Logit model was proposed by Schulthiess *et al.* (1983) and is plotted in figure 3.1. The logit model states that for dose D, the probability of effect will be;

$$P(D)_{Logit} = \left[1 + \left(\frac{D_{50}}{D} \right)^{4\gamma} \right]^{-1} \quad (3.3)$$

where γ is (again) the gradient of the dose response function at D_{50} . Both the Logit and Probit models have been fitted to normal tissue dose-volume response data.

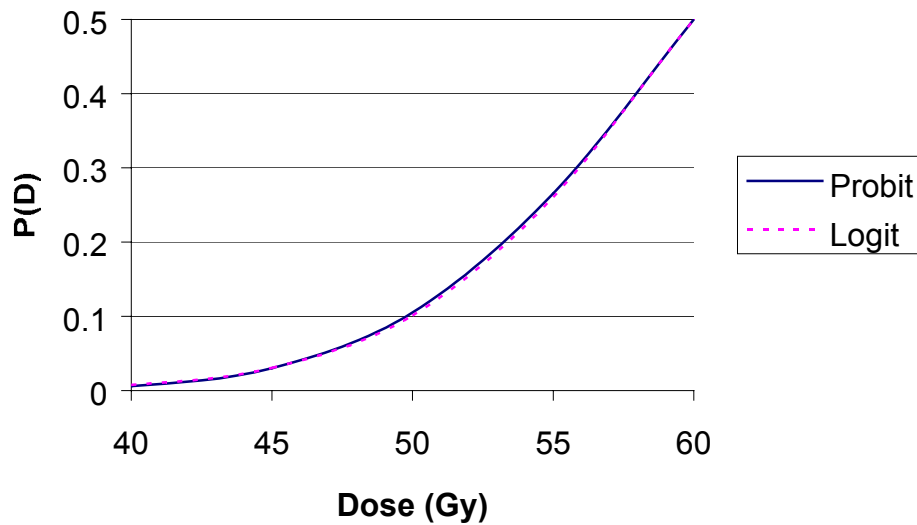


Figure 3.1 Plots of Probability of effect following single fraction irradiation to dose, as calculated with the Probit model (solid curve) and Logit model (dashed).

3.2.2. Theoretical (Poisson/Linear Quadratic) Model

The Poisson model is the most commonly used in radiotherapy, particularly in the linear-quadratic (LQ) form. Using Poisson statistics, the probability of n surviving cells where the expected value is N_s may be written

$$P(n) = \frac{e^{-N_s} N_s^n}{n!} \quad (3.4)$$

For tumour control the number of clonogens remaining will be zero, setting $n=0$, the tumour control probability (TCP) is;

$$TCP = \frac{e^{-N_s} N_s^0}{0!} = e^{-N_s} \quad (3.5)$$

The linear quadratic model provides an expression for the surviving fraction, S , of mammalian cells after low LET irradiation.

The theory behind the shape of the shouldered mammalian cell survival curve relates the linear and quadratic terms in dose to cell kill. The interaction of ionising radiation with the cell DNA causes strand breaks that lead to cell necrosis or apoptosis. Single strand breaks can be easily repaired, while double strand breaks are less likely to be repaired and more likely to cause cell death. The number of hits that are required to kill the cell i.e. single hit or multiple hits can be linked to the probability of single or double strand breaks. The linear coefficient in dose, α , describes the shoulder resulting from cell death dominated by single hit kills, while the quadratic term in dose, β , describes cell death requiring multiple interactions. This allows for cell repair to occur and is the principle allowing fractionation.

For high LET particles like alpha particles the fraction of single hit deaths is higher than for low LET radiation such as gamma radiation so that an alpha particle cell survival curve will show essentially no shoulder.

Considering a tumour originally containing N_0 tumour cells irradiated to total dose, D , then the surviving fraction (N_s/N_0) is given by (Fowler, 1989)

$$S(D) = \frac{N_s}{N_0} = e^{-\alpha D - \beta D^2}. \quad (3.6)$$

The cell sensitivity for a particular tumour or tissue type is indicated by the constants, α and β . These are illustrated in figure 3.2 for two types of tissue; early and late responding tissues. Typically early responding tissues characterise tumour, while the late responding tissues will typically characterise normal tissue (or side effects). The ratio of α/β will also provide valuable information on the tissue response to radiation. With tumours, the α/β ratio generally has the value ~ 10 , while for normal tissue the α/β ratio will have the value ~ 3 . Therefore, the β term is sometimes dropped when relating to tumour control. There is naturally a range of possible α and β values across tissue and tumour types, and these rules will not always hold.

From equation 3.5 we may insert $N_s(=N_0S)$ into equation 3.4, which simplifies to give

$$P(D)_{LQ} = \exp\left[-\rho \cdot V_t \cdot e^{-D(\alpha+\beta d)}\right] \quad (3.7)$$

where the product of the clonogen density, ρ (cm^{-3}) and the tumour volume, V_t (cm^3) calculates the initial number of clonogens, N_0 , and the total dose, $D=nd$, is the number of fractions, n , multiplied by the dose per fraction, d .

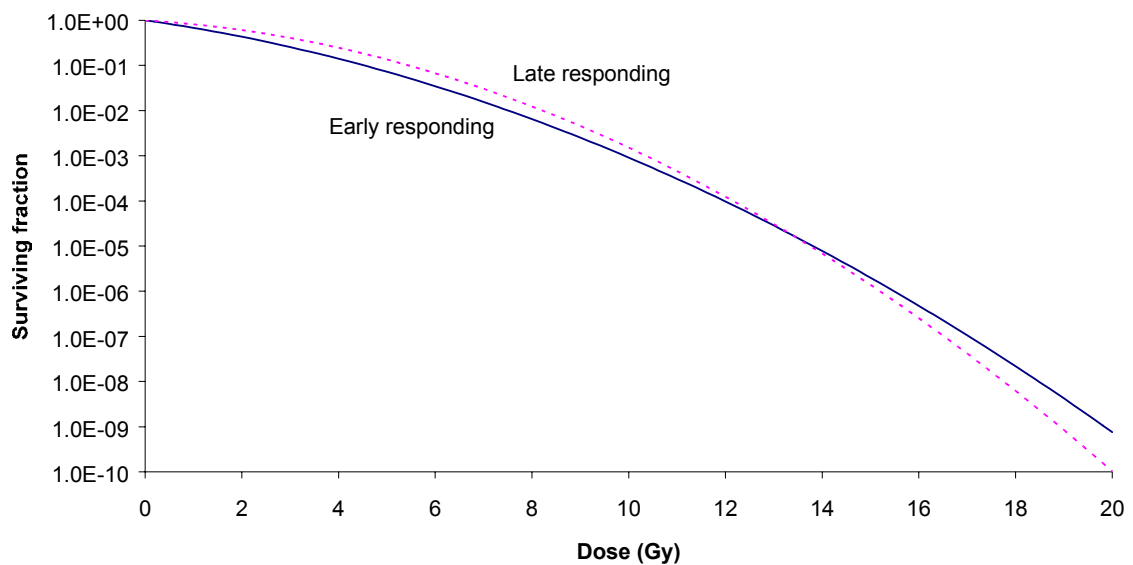


Figure 3.2 Surviving fraction versus dose for early responding tumour tissue and late responding normal tissue. Tumour is characterised by $\alpha = 0.35 \text{ Gy}^{-1}$ and $\alpha/\beta = 10$, while normal tissue is characterised by $\alpha = 0.15 \text{ Gy}^{-1}$ and $\alpha/\beta = 3$ (from Metcalfe et al. 1997).

For rapidly proliferating tumours, such as those of the head and neck, an extension to the conventional LQ model has been proposed (Lee *et al* 1995). The survival fraction will then be calculated as;

$$S = \exp\left(-nd(\alpha + \beta d) + \frac{\ln 2}{T_{pot}}(T - T_k)\right) \quad (3.8)$$

where T_{pot} is the potential doubling time, T is the total time of treatment and T_k is the kick-off time. The potential doubling time is the time taken for the number of clonogens to double, and the kick-off time is the time taken for the irradiation to induce an increased proliferation rate.

3.2.3. Hyper sensitivity of tumour/normal tissue at low doses

Recently, a hypersensitivity to doses lower than ~ 0.5 Gy per fraction has been shown for 26 human cell lines including both tumour and normal tissue (Joiner *et al* 2001). The hypersensitive response occurs maximally at doses around 0.5 Gy as shown in figure 3.3. The LQ model has been shown to significantly underestimate response in the dose range up to 1 Gy. However, two models have been suggested as extensions of the standard LQ model (refer to equation 3.6) to include the low dose hypersensitivity. The two models are the two population model and the induced repair (IR) model.

The two population model states that the increased sensitivity is due to the more radiosensitive cells in the G_0 phase of the cell cycle being predominately killed. However, this model has been subsequently revoked due to the magnitude of the hyper sensitivity being larger than would be predicted from merely cell cycle differences. Additional evidence for rebuttal of this model came from an experiment where cells were repeatedly irradiated in the dark where the cell cycle is arrested (Howard and Cowie, 1978). The cells still showed the hypersensitive response.

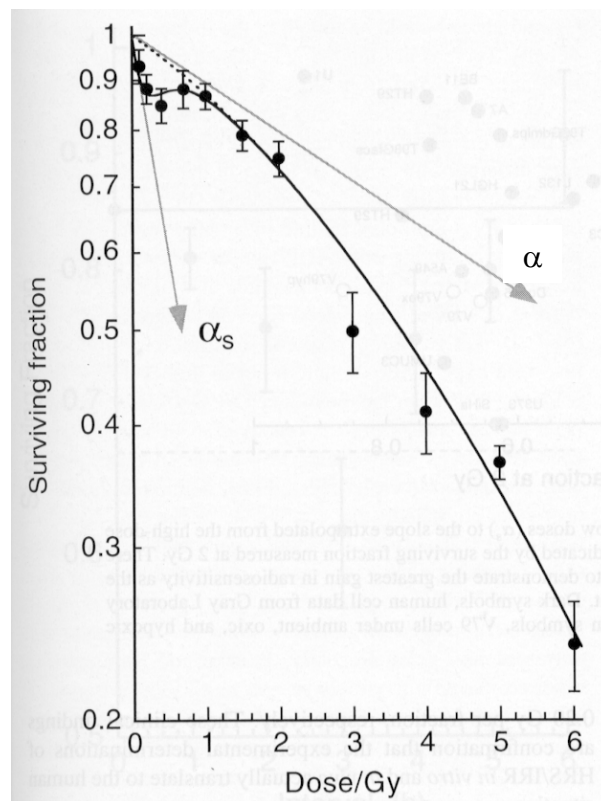


Figure 3.3 Survival fraction versus dose for T98G human glioma cells. The dots with error bars are the experimental data points, the dashed curve is the LQ model prediction, and the solid curve is the IR

model prediction. From Joiner et al. (2001).

The IR model is based on a threshold dose. Prior to this threshold dose (generally following up to ~0.5 Gy) the tissue is hypersensitive, but when the dose has exceeded the threshold repair mechanisms are induced in the tissue and the effective cell sensitivity reduces greatly. The IR model can be expressed in terms of effect on the surviving fraction as (Lambin *et al* 1994):

$$S = \exp\left[-\alpha\left(1 + \left(\frac{\alpha_s}{\alpha} - 1\right)e^{-d/d_c}\right)d - \beta d^2\right], \quad (3.9)$$

where α_s is the larger tissue sensitivity at very low doses; and d_c is a constant which describes the dose range over which induction of repair occurs.

3.2.4. Biological Effective Dose

Until Barendsen introduced the concept of Extrapolated Response Dose (ERD) in 1982 (later renamed Biological Effective Dose (BED) by Fowler) radiobiology was not widely used in radiotherapy. The BED provides a simple method of including the biological response of tissue from fractionation and total dose. The Biological Effective Dose is defined as the dose delivered with a fractionation schedule that delivers 0 Gy fractions;

$$D(\alpha + \beta d) = BED(\alpha + \beta \times 0) \quad (3.10)$$

$$BED = D\left(1 + \frac{d}{\alpha/\beta}\right) \quad (3.11)$$

The BED can then be used to differentiate between fractionation regimes. The α/β ratio is used to differentiate the type of tissue, where broadly an α/β ratio of 10 refers to tumour (early responding) tissue and α/β of 3 refers to normal (late responding) tissues. Commonly, the units of Gy₁₀ and Gy₃ are used to refer to the BED for tumour and normal tissues.

Integral Biological Effective dose has been proposed (Clark *et al* 1998) as the mean BED across an inhomogeneous dose distribution. The Integral Biological Effective Dose is useful where large dose heterogeneities are present because it provided a single value that may be compared to a uniform dose distribution.

3.2.5. Standard Effective Dose

The Standard Effective Dose (SED) provides a BED in terms of a standard fractionation regime (most commonly, $d_{st} = 2$ Gy/fraction). SED is calculated as the ratio of $\alpha \cdot \text{BED}$ for the nonstandard regime to the standard regime

$$SED = \frac{D(\alpha + \beta d)}{\alpha + \beta d_{st}} \quad (3.12)$$

Thus, substituting BED from equation 3.11 we have,

$$SED = \frac{BED}{\left(1 + \frac{d_{st}}{\alpha/\beta}\right)} \quad (3.13)$$

3.2.6. Equivalent Uniform Dose

The Equivalent Uniform Dose (EUD) was proposed by Niemerko (1997) and is defined as the uniform dose distribution giving an equivalent survival fraction to that of a given heterogeneous dose distribution. Using the LQ model of surviving fraction, with only the linear term (for simplicity) the EUD is given as

$$EUD = -\frac{1}{\alpha} \cdot \prod_{i=1}^M v_i e^{-\alpha D_i} \quad (3.14)$$

where D_i is the total dose deposited in the i th voxel and the total number of voxels is M . The EUD concept is advantageous over recording dose to a prescription point because it considers the biological effect of the entire dose distribution.

The Equivalent Uniform Biological Effective Dose (EUBED) was proposed by Jones and Hoban (2000) to allow for variations in the dose per fraction within a dose distribution. The EUBED is then the BED giving an equivalent survival fraction, to a given heterogeneous BED distribution,

$$EUBED = -\frac{1}{\alpha} \ln \left(\sum_{i=1}^M v_i e^{-\alpha \text{BED}_i} \right) \quad (3.15)$$

where BED_i is calculated for voxel, v_i , from the total number of fractions with equation 3.8. The EUBED can also be expressed in terms of EUD for the cases of constant number of fractions or constant fraction size (Jones and Hoban, 2000). This conversion is useful because most clinicians will relate clinical outcomes to dose, or a certain fractionation regime.

3.3. Tumour Control Probability

The probability of killing all tumour cells in the defined tumour volume following irradiation to a certain total dose is named the Tumour Control Probability (TCP). All clonogens need to be eradicated to achieve tumour control since, theoretically, only one tumour cell is required to repopulate the tumour.

For calculation, the tumour volume is considered to be constructed of independent tumour subvolumes (Webb and Nahum, 1993). If each subvolume is considered small enough to receive a uniform dose then the TCP for the tumour is simply the product of the TCP values calculated in each of the M subvolumes:

$$TCP = \prod_i^M TCP_i. \quad (3.16)$$

The probability that all clonogens will be killed by total dose, D , in fractions of dose, d , for the subvolume will be given by the LQ expression for cell killing (from equation 3.6)

$$TCP = \exp\left[-\rho \cdot V_i \cdot e^{-D(\alpha+\beta d)}\right] \quad (3.17)$$

Similarly, an expression for TCP using the Biological Effective Dose is;

$$TCP = \exp\left[-\rho \cdot V_i \cdot e^{-\alpha \cdot BED}\right] \quad (3.18)$$

Following equation 3.17, the expression may be rearranged to calculate the total dose, D , required for a given value of TCP neglecting the β term;

$$D = \frac{-1}{\alpha} \ln\left[\frac{-1}{\rho \cdot V_i} \ln(TCP)\right] \quad (3.19)$$

Equation 3.19 implies that for a constant TCP the dose required will vary in proportion to reciprocal cell sensitivity, $1/\alpha$, the natural logarithm of clonogen density, $\ln(\rho)$, and the natural logarithm of tumour volume, $\ln(V_t)$. Therefore changes in the cell sensitivity or dose can have a large effect on the TCP. For example, for $0.1 < \text{TCP} < 1$ the treatment dose will vary by only about 10 Gy for cell sensitivity of 0.35 Gy^{-1} .

3.3.1. Accounting for interpatient radiosensitivity variation in a population of patients

Clinical measurements of cell cultures have shown variation in surviving fraction across the population of tumour types, across samples of the same type of tumour, and within a single tumour. Clinically, a given type of tumour will then be characterised by a mean and standard deviation of cell sensitivity from measurements made across a patient population. The impact of interpatient variations in cell sensitivity will be a decrease in slope of the population mean tumour control curve from the TCP curve for an individual patient. Population TCP curves are illustrated in figure 3.4 for $\alpha=0.35 \text{ Gy}^{-1}$ with $\sigma_\alpha=0$ or 0.08 Gy^{-1} (Webb and Nahum 1993).

For an individual patient the TCP curve will be steeper than the population average and close to the curve in figure 3.4 with $\sigma_\alpha=0$. Intratumour variation (due to a hypoxic fraction, for example) in cell sensitivity will cause a decrease in the slope of the TCP curve for an individual patient (Niemerko and Goitein, 1991). For an individual patient, the clinician will always prescribe a dose level to terminate the least sensitive cells in the tumour. Importantly, the variation in cell sensitivity for a single patient is hypothesised to be small, and will be closer to the theoretical TCP versus dose curve without variation, than to the less steep population TCP versus dose curve (Zagars *et al* 1989).

3.3.2. Clonogen density and optimisation

A number of studies in the literature have investigated the influence of the spatial distribution of clonogens, as well as inter- and intratumour radiosensitivity variations on the dose distribution required to optimally eradicate the tumour.

Obviously, a uniform dose distribution will yield optimum TCP (Brahme and Ågren 1987, Webb, 1993) if the clonogens are distributed uniformly. However, the spatial distribution

of clonogens is probably not uniform, and a number of workers have investigated the influence of heterogeneous clonogen distributions on TCP. In particular, from equation 3.19, the dose required for constant TCP will decrease with the natural logarithm of clonogen density. Therefore, large decreases in clonogen density, such as across microscopic extensions at the tumour periphery, will still require a significant dose for tumour eradication (Webb and Nahum 1993).

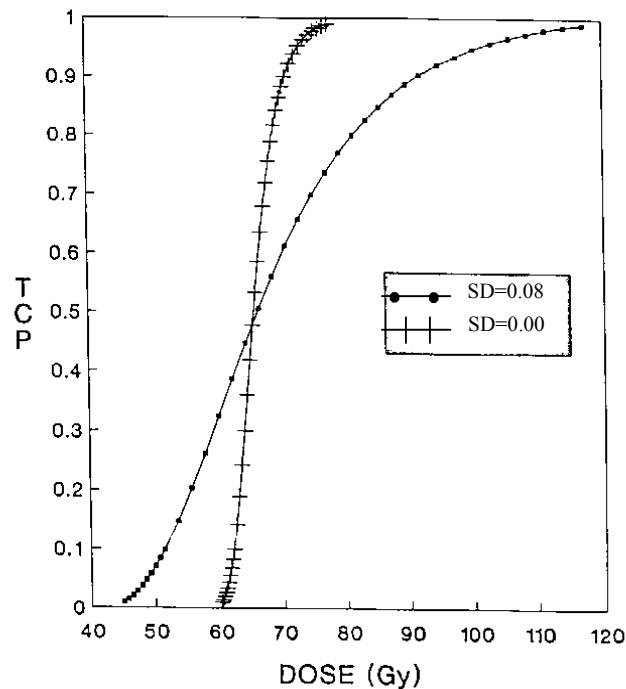


Figure 3.4 Characteristic sigmoidal TCP versus dose curve derived theoretically and experimentally. (Taken from Webb and Nahum 1994)

The optimal dose distribution regarding intratumour variation in the cell sensitivity will show significant variation accordingly. Considering the example from Ebert and Hoban (1996) for a tumour with cell sensitivity 0.35 Gy^{-1} , an intrinsic spatial variation in cell sensitivity with standard deviation 0.08 Gy^{-1} will introduce a difference of about 20 Gy between the TCP curve with uniform and optimal dose distributions. The optimal TCP includes increased dose for those voxels with lower than average cell sensitivity and vice versa. Indeed, a number of authors have investigated how to include intratumour variation in cell sensitivity so that when more data is available, dose distributions can be optimised accordingly (Brahme and Ågren, 1987). In the meantime, Kåver *et al* (1999) have suggested a method to stochastically optimise TCP based on a known variation in interpatient cell sensitivity.

3.3.3. Prostate Carcinoma

Prostate carcinoma is a slowly proliferating tumour, with estimates of the median potential doubling time, $T_{\text{pot}} = 42$ days calculated from a range of 15 to 170 days across the patient population (Haustermans and Fowler 2001). The half life for sublethal damage repair, $T_{1/2} = 1.9$ hrs (95% CI 1.4-2.9 hrs, Fowler *et al* 2001). The cell sensitivity for prostate carcinoma, α , has been estimated at $0.29 \pm 0.07 \text{ Gy}^{-1}$ (Sanchez-Neito and Nahum, 1999). The α/β ratio for prostate carcinoma is currently being reevaluated, with some researchers estimating its value as 1.5 Gy (95% CI 0.8-2.2, Brenner and Hall 1999) and 1.49 (95% CI 1.25 to 1.76, Fowler *et al* 2001). These reported values are substantially lower than the traditionally accepted value of 10 Gy for most tumour cells. The reevaluated value of α/β ratio is now close to (and even lower than) the best estimate value for normal tissue ($\alpha/\beta=3$ Gy). The low α/β ratio for prostate cancer might be explained by the low cell cycle rate, and high proportion of cells in the G_0 phase of the cell cycle.

The ramifications of a low α/β ratio is that the tumour will be less sensitive to fractionation effects. That is, the tumour will respond similarly to normal tissue. The benefit from fractionation is that with each fraction an incremental separation of the late (normal tissue) and early (tumour) effects. New fractionation regimes could therefore be an improvement on the current techniques, and may make much more difference than improvements in the conformality of dose delivery. One such fractionation regime being discussed in the literature is hypofractionation. This regime considers reducing the total target dose appropriately such that the dose per fraction could be increased with no change in tumour control and late sequelae expected.

Such schemes have been used in some centres in Britain for 20 years. Most well known is the 6×6 Gy regime, which has shown similar survival and complication rates to the more conventional 1.8 to 2 Gy per fraction regimes. Further indications for hypofractionation are found in a recent publication that compared two boost doses for prostate, 2×9 Gy compared with 3×6 Gy (Martinez *et al* 2000). In that study, the former regime with the larger boost fraction size was shown to cause significantly higher survival rates than the smaller boost fraction size regime.

The hypofractionation regimes are (Brenner 2000)

- o as efficacious as standard fractionation
- o more convenient for the patient, both in terms of logistics and acute morbidity
- o less resource intensive.

More clinical trials of hypofractionation regimes are currently in progress, and the conventional fractionation regimes will continue to be favoured until further positive findings are reported.

Some centres (such as Memorial Sloan Kettering in the United States) are currently delivering large doses (>80 Gy) to the prostate with over 40 fractions of 2 Gy. These treatments require patients to be treated once every weekday over 8 or more weeks. If target doses as high as 80 Gy are to be prescribed a hypofractionation regime will be well tolerated by the patient due to lowering the total time of treatment. Hypofractionation would also allow more patients to be treated.

In this thesis, the prostate is modelled without the potential doubling time parameters that would be necessary for other rapidly growing tumours and with the conventional fractionation of 2 Gy/fn to the target tissue. The fractionation is considered additionally to the total dose for all tumour control calculations by using the β term in the LQ model.

3.4. Normal Tissue Complication Probability

Normal tissue complication probability (NTCP) is the probability that a certain percentage of the patient population will incur unfavourable reactions in the contiguous tissue at a particular dose. Normal tissues will always receive radiation dose with the treatment of deep-seated tumours with external beam radiation therapy.

3.4.1. Dose-Volume effects

The calculation of NTCP differs directly from the calculation of TCP due to the intended endpoints differing. For normal tissues, the relative volume of the organ irradiated to certain dose levels is used to predict the probability of causing complications. The dose-

volume relationship will differ for each organ and will generally be a mix of two extreme cases, where either a critical dose must be reached or a critical volume must receive a certain dose before complications (or certain known endpoints) arise.

The normal tissue is constructed of functional sub-units (FSU). The irradiation of a single FSU to a certain dose level might alter the functionality of the organ and cause complications. If so, then this organ will be classified under the critical element model or as having serial architecture. Serial organs have a minimal dose-volume effect because once any of the critical elements are damaged, the function of the entire organ is impaired. Alternatively, irradiating a certain proportion of the total organ volume may be required before the functionality of the organ is impaired and complications arise. This is known as the critical volume model or parallel architecture. In the case of the parallel architecture, the FSUs may be more correctly termed Tissue Rescue Units since the organ possesses a certain functional reserve of the Tissue Rescue Unit's that assist in the repair of the functionality following partial volume irradiation. The critical element and critical volume models are extreme cases and most organs will be a combination of the two.

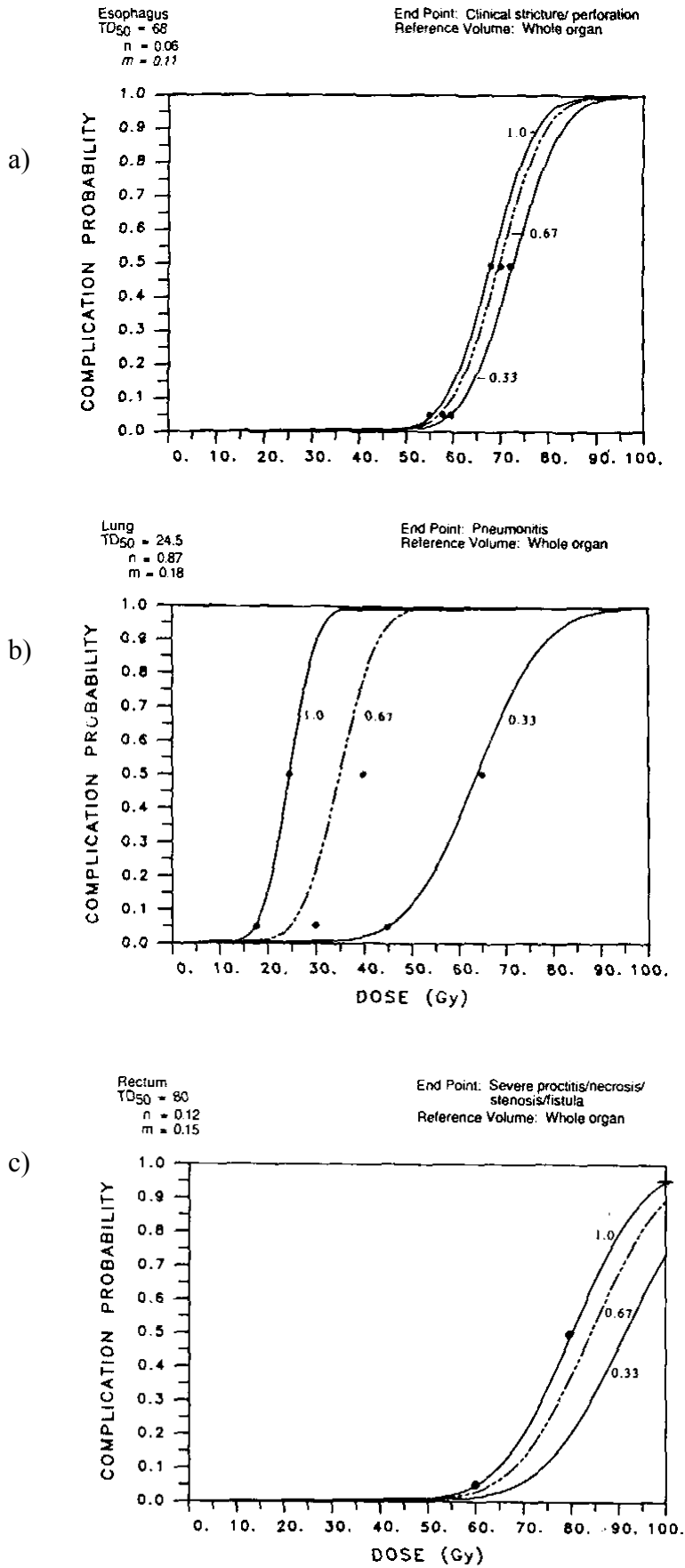
Clinically, the dose-volume effect has been quantified for many organs. The complication probability has been plotted against dose for esophagus, lung and rectum in figure 3.1. The dots indicate clinical data points and the curves represent fitted curves that model the data. Clearly the lung possesses a strong volume effect, whilst the esophagus and rectum are shown to be highly serial.

3.4.2. Lyman-Kutcher-Burman (LKB) model

The dose-volume relationship can be represented by the model suggested by Lyman (1985). The volume effect is described using the parameter n in the power law (Withers *et al* 1986, Schultheiss *et al* 1983)

$$TD_{50}(1) = TD_{50}(v) \cdot v^n \quad (3.20)$$

where $TD(1)$ is the tolerance dose (i.e. that dose causing a known endpoint to 50% of the population after 5 years) following whole organ irradiation, and v is the partial volume defined as $v = V/V_{ref}$, where V is the total volume of the organ and V_{ref} is the reference volume, n is a fitting parameter accounting for the volume effect. The reference volume



would usually be the whole volume.

Figure 3.5 The dose-volume relationship for a) the (mostly serial) esophagus, b) the (mostly parallel) lung, and c) the rectum. Taken from Burman et al (1991) using data from Emami et al (1991).

The normal tissue complication probability for uniform dose D to a volume V of the organ is given by

$$NTCP = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^t \exp\left(-\frac{t^2}{2}\right) dt \quad (3.21)$$

where

$$t = \frac{D - TD_{50}(v)}{m \cdot TD_{50}(v)} \quad (3.22)$$

The mean tolerance dose is defined from $TD_{50}(v)$ and m is another fitting parameter that accounts for the volume effect. Three parameters are then required {i.e. $TD_{50}(1)$, m , n } to define the probability of complications for any organ irradiated to uniform dose, D . Table 3.1 includes magnitudes of various parameters used to describe the response of normal tissues to partial volume irradiation (from Burman *et al* 1991, Kallman *et al* 1992).

Table 3.1 Magnitudes of parameters m, n, D_{50} , s and k used to model normal tissue complications following full volume irradiation for a range of organs. From Burman *et al* (1991) and Kallman *et al* (1992).

Organ	m	n	D_{50} (Gy)	s	k
Brain Stem	0.14	0.16	65	-	-
Esophagus	0.11	0.06	68	3.4	0.47
Liver	0.15	0.32	40	0.23	2.6
Lung	0.18	0.87	24.5	0.0061	3.0
Rectum	0.15	0.12	80	-	-
Kidney	0.10	0.70	28	-	-
Bladder	0.11	0.50	80	1.3	2.9

To extend the Lyman model to allow inclusion of heterogeneous dose distributions, the use of Dose Volume Histograms (DVH) has been proposed by Kutcher and Burman (1989). Kutcher and Burman (1989) proposed a technique to reduce a histogram featuring various discrete volumes with certain levels of dose into a single dose bin. Following Lyman, they conjecture that each dose element of the differential DVH has the same three parameter values as the whole organ, therefore each dose bin of height ΔV_i and dose D_i is adjusted to one with smaller volume ΔV_{eff} and dose D_m using:

$$\left(\Delta V_{eff}\right)_i = \Delta V_i \left(\frac{D_i}{D_m}\right)^{1/n} \quad (3.23)$$

This volume reduction is repeated for each dose element of the DVH until a single bin is derived with dose D_m and effective volume:

$$V_{eff} = \sum \left(\frac{D_i}{D_m}\right)^{1/n} \cdot \Delta V_i \quad (3.24)$$

The effective volume, V_{eff} receiving dose D_m can then be used with equations 3.1, 3.3, or 3.6 to compute NTCP.

3.4.3. Källman k- and s-models

A relationship between NTCP predictions from whole, $P(D,1)$, and partial, $P(D,v)$, volume irradiation was suggested by Källman *et al* (1992),

$$P(D,v) = [P(D,1)]^{v^k} \quad (3.25)$$

where the parameter, k , reflects the magnitude of the volume effect. A large value of k infers a mostly parallel organ (see table 3.1) and vice versa. At $k=-1$, equation 3.25 would be the Poisson model for cell killing, but because $P(D,v)$ must increase as the volume increases, $k>0$ (Zaider and Amols, 1999). Kallman *et al* (1992) originally used v^k in equation 3.25, with $k<0$.

Introducing the linear part of the LQ model for $P(D)$ in equation 3.25, we have;

$$P(D, v) = \exp\left[-\frac{N_0}{v^k} e^{(-\alpha D)}\right] \quad (3.26)$$

Källman *et al* (1992) also describe a technique for considering the architecture of the organ with a parameter, the relative seriality, s . The relative seriality is derived from the case where an organ contains relative fractions of serial ($0 < a < 1$) and parallel ($0 < b < 1$) portions in its volume. Using the simplifying assumption that $b=1$, the relative seriality can be defined from the number of serial, n , and the number of parallel, m , subunits in the organ, $s = m/(n \cdot m) = 1/n$. Low values of relative seriality infer a mostly parallel organ, while large values infer a mostly serial organ (see table 3.1). For a homogeneous dose distribution the NTCP is calculated as

$$NTCP = \left[1 - (1 - P(D))^s\right]^{1/s}, \quad (3.27)$$

where $P(D)$ is the probability for cell killing following dose, D . Using the LQ model, an expression for $P(D)$ is given in equation 3.7 (above). Extending the model for inhomogeneous doses, we have

$$NTCP = \left[1 - \prod_{i=1}^M (1 - P(D_i))^s\right]^{\Delta v} \quad (3.28)$$

Where the i th voxel receives dose D_i , the total number of voxels is M and the relative volume of each voxel, $\Delta v = 1/M$.

3.4.4. Yaes-Kalend/Fenwick model

For serial organs, the original definition states that local failure (i.e. complications) may arise following inactivation of an entire FSU consisting of N cells (Niemerko and Goitein, 1991, 1993, Fowler 1993). However, Yaes and Kalend (1988) had previously suggested that local failure may follow inactivation of any N consecutive cells, out of the $N \times N_F = K$ cells, lying along the length of the irradiated volume, where there are N_F traditional FSUs. Following these concepts, Yaes and Kalend derive,

$$NTCP \sim 1 - \exp[-N_F(1 + N \exp(-\alpha_2 D)) \exp(-N \exp(-\alpha_2 D))] \quad (3.29)$$

where $\alpha_2 = (1+2\beta/\alpha)$, with α and β from the linear quadratic model.

Fenwick (2001a) discovered an error in the derivation of Yaes and Kalend and using a different method derived,

$$\text{NTCP} \sim 1 - \exp[-N_F N (1 + N \exp(-\alpha_2 D)) (1 - \exp(-\alpha_2 D)) N] \quad (3.30)$$

for the same case, given three conditions. The conditions include $N_F \geq 30$, $10 < N < 10^{11}$, and $(N+1)(1-P) > 1$, where P is the probability of cell death after a radiation dose, D. When the conditions are satisfied equation 3.30 leads to an inaccuracy of less than [-2.2%, +2.5%].

3.4.5. Clinical application of NTCP

A lack of clinical data on normal tissue response due to insufficient dose-volume availability and recording has led to NTCP being a less reliable parameter than TCP. Current treatment planning software does provide facilities for recording complete 3D dose statistics, that, when aided by patient reviews, is contributing increasing amounts of data. It is important to note that, as with TCP, the NTCP calculation has limited quantitative significance but can be beneficial for deciding between competing treatment plans when assisted by clinical knowledge.

A major shortfall with the current data is a lack of complication information relating to actual dose distributions. Most of the current models are based on interpolation between ‘known’ complications from whole organ irradiation and partial volume irradiation, where part of the organ receives a uniform dose and the remainder receives none. This requirement is evident from the Kutcher-Burman technique for reducing a dose volume histogram into a partial volume irradiation and interpolating to ‘known’ whole organ irradiation parameters. Zaider and Amols (1999) investigated the clinical accuracy of two NTCP models (Probit and Kallman k-model) for non-uniform dose distributions. They concluded that the extrapolation to (closer to reality) heterogeneous dose distributions produced a model dependent NTCP result. Clearly, expertise regarding the origin of the input parameters and model assumptions is important when implementing the NTCP models clinically.

Moisenko *et al* (2000) compare four NTCP models (Logit, Kallman k-model, Kallman s-model and probit). They examined the effect of changes to the dose distribution, in terms of either increased heterogeneity, boosted CTV dose and boosted total dose, on the change models prediction of NTCP. This was done using two different dose reduction techniques (preferred Lyman and Kutcher-Burman). The preferred Lyman technique calculates the effective dose to the full organ volume. The Kutcher-Burman technique (also known as the effective volume technique) is outlined in §3.4.3 above. Moisenko *et al* (2000) concluded that the relative change in the computed NTCP did depend on the model being used, but the results were consistent for each model.

3.4.6. Rectal complications

3.4.6.1. Grading rectal complications

External beam radiotherapy will always deposit *some* radiation dose in the adjacent rectal tissue. When the deposited dose is too high, rectal complications will occur, including bleeding, severe proctitis, necrosis, stenosis or fistula. The severity of the complication can be graded using the RTOG grading system (Lawton *et al* 1991); grade 0 – no complication; grade 1 – minor symptoms requiring no treatment; grade 2 – symptoms responding to simple outpatient management, life style (performance status) not affected; grade 3 – distressing symptoms altering the a patients life style (performance status) and/or requiring hospitalisation for diagnosis or minor surgical intervention; grade 4 – major surgical intervention or prolonged hospitalisation; grade 5 – death. Other grading systems have been suggested, including the SOMA LENT scale (LENT SOMA, 1995) however the RTOG grading system appears to be the most widely referenced.

From the literature, the predominant complication studied appears to be long term rectal bleeding. The rectum is constructed mainly of muscle, but sensitive structures, the telangiectatic vessels, populate the mucus layer of the rectal wall. These telangiectatic vessels become the site of radiation induced bleeding.

3.4.6.2. Rectum architecture

The early published data on rectal complications (Emami *et al* 1991) suggested that the rectum is a highly serial organ ($n=0.12$, $m=0.15$). However, more recent studies comparing 3D conformal techniques with traditional beam arrangements (Boersma *et al* 1998,

Hartford *et al.* 1996) suggest that the rectum does have a pronounced volume effect. This conclusion is based on a detected benefit from conformal dose distributions that deposit less dose in the rectal wall. Lu *et al.* (1995) demonstrated a clear difference between the grade 0/1 and grade 2/3 complications based the amount of rectal surface area irradiated to greater than 65 Gy (see figure 3.6a). They concluded that a Lyman volume parameter n value of 0.2 (compared with the original calculation of 0.12) might be more appropriate for severe late rectal complications. Fenwick and Nahum (2001b) suggest that the increased volume effect evident in these studies might be present for a population of patients due to inter-patient sensitivity differences. The response of an individual, in similarity with tumour control, should be much steeper than that averaged across the population.

Dale *et al* (1999) used softer endpoints as a measure of rectal complication than the RTOG suggestion, citing them as too severe for patient comfort. Based on a patient questionnaire, Dale *et al* (1999) suggest that for their softer endpoints, the rectum is indeed a serial structure. This is demonstrated by comparing the correlation co-efficient of the composite score (from the questionnaire) against the volume of rectum irradiated to be higher at lower volumes (figure 3.6b). Fenwick *et al* (2001) have conjectured, however, that the limited variety in dose distributions used by Dale *et al* (1999) would not provide the data to detect a volume effect, even if it was present.

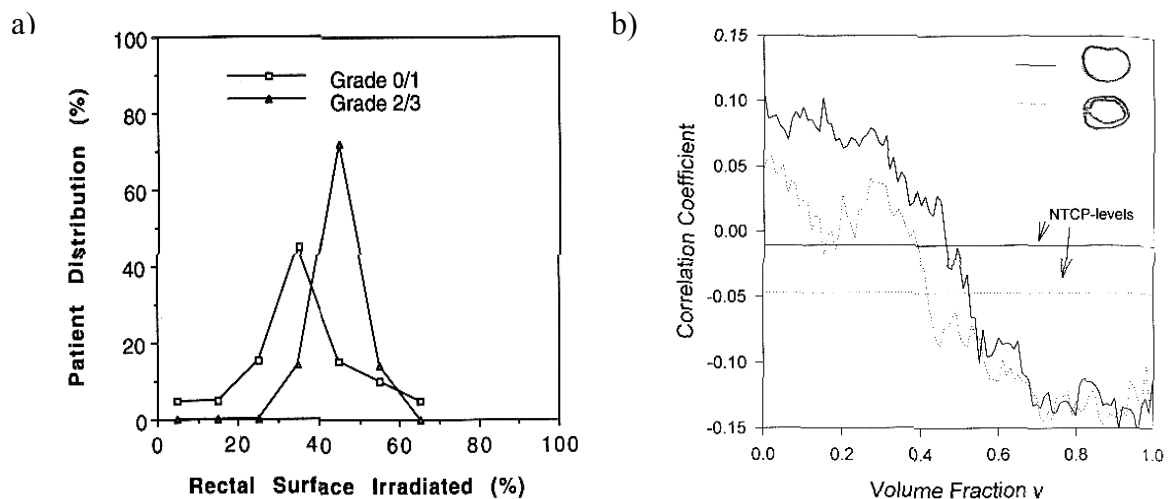


Figure 3.6 a) The distribution of rectal surface area irradiated across patients can be separated by the grade of prostate cancer. Taken from Lu *et al.* (1995) b) The correlation between NTCP and volume is strongest at low partial volumes (less than 0.5) and for full volume delineation. Taken from Dale *et al.* (1999).

3.4.6.3. Dose volume characterisation

Dose-volume histograms of the solid rectum (including contents) have been criticised in the literature (Lu *et al* 1995b, Ting *et al* 1997) because the rectum is a hollow organ and irradiation of the rectum content will not affect the rate of complications. Therefore, other dose volume techniques have been suggested, including the dose wall histogram (DWH) and the dose surface histogram (DSH) and more recently the dose surface map (DSM).

The DWH (Ting *et al* 1997) requires the inside wall of the rectum to be outlined, which is often difficult, due to poor contrast between rectum contents and wall tissue. The DWH is defined as the percentage of rectum wall receiving less than a certain dose. Meijer *et al* (1999) have suggested that the DWH can be automatically calculated from the outside wall contour only by assuming that the sectors of the rectal wall have equal areas.

The DSH (Lu *et al* 1995, Li *et al* 1997) is the percentage of mid-rectum wall (area) that received less than a certain dose. The definitions for the DVH, DWH and DSH are illustrated in figure 3.7 below.

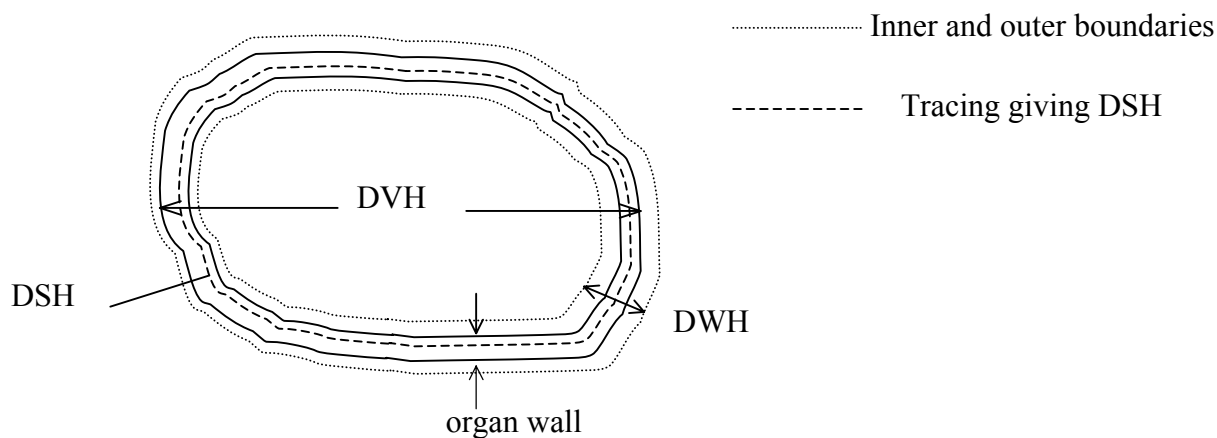


Figure 3.7 A transverse section of the rectum showing different methods of organ delineation for generating histograms. Adapted from Dale and Olsen (1998).

The DSM (Sanchez-Neito *et al* 2001a, Hoogeman *et al* 2001) has been suggested as a valuable technique to maintain the spatial dose-area information of the hollow organ that is lost with other techniques. The DSM is constructed by ‘unfolding’ the delineated rectum wall to obtain a 2D map of rectum length superiorly against the angle subtended perpendicular to the longitudinal axis of the rectum. The dose values are recorded on this map and illustrate through, for example, a colour map the regions of high and low dose.

The DSM should lead to a better understanding of rectal complications. However, they still need to be improved since they do not account for the changes in rectal wall volume through the treatment.

Recently, the DSH has been shown to provide correlation between dose and the incidence of grade 1-3 rectal bleeding (Fenwick *et al* 2001). Fenwick and colleagues have characterised the differential DSH of the rectum from external beam therapy of prostate carcinoma (see figure 3.8 below) with a number of parameters. The parameters tested to empirically confirm prediction of late rectal bleeding include (Fenwick *et al* 2001, Fenwick and Nahum, 2001);

- o PD_{max} is the maximum of the high dose peak,
- o PS is the width of the high dose peak,
- o PD_{hi} is the maximum (%) dose, and
- o f_{hi} is the fractional highly dosed rectal surface, which is assessed by fitting a Gaussian to the high dose peak.

Fenwick *et al* (2001) then compared the 2 year rectal bleeding outcomes from 79 patients with the summarised dose distribution data of these patients. They discovered that the area-normalised integral dose, that is, the average dose multiplied by the total surface area (including 11 cm of rectum length) correlated well (statistically significant) with the occurrence of grade 1-3 rectal bleeding. Other indications, while not as statistically significant as the area normalised integral dose, were the average dose, the length normalised high dose area (calculated from, $f_{hi} * L$), and the length based integral dose to the highly dosed area (calculated from, $PD_{hi}(D_{ref}/100)f_{hi}L$).

Further prognostic factors have been outlined by Jackson *et al* (2001). They list different prognostic factors for each of two maximum dose protocols. For the 75.6 Gy protocol, the factors shown indicate a higher probability of rectal bleeding included a smaller anatomically defined rectal wall volume, the maximum dose to the rectal wall, enclosure of the rectal wall contour inside the 50% isodose, a history of diabetes mellitus, and patient age. For the 70.2 Gy protocol, the prognostic factors included the first and third factors listed above for the higher dose protocol. Interestingly, the 50% isodose is a prognostic

factor for both cases. This might confirm the clinical importance of low dose hypersensitivity because the posterior rectal wall will be receiving only about 0.5 Gy/fraction if the target dose is around the standard 2 Gy/fraction.

Fenwick (2001) fitted the detailed dose distribution information to a parallel tissue response equation describing the local damage in centimetres against the NTCP. Fenwick showed the NTCP to decrease by 1.1% for every 1% fraction of the rectum volume that received a dose greater than 57 Gy. Thus, elucidating a volume effect that conflicts with the established view of the rectum being highly serial. The significance of the volume effect is that highly conformal treatments that restrict the dose deposited in rectal tissue will be of increased value, since thresholds of the volume of rectal surface receiving certain doses are more clearly known.

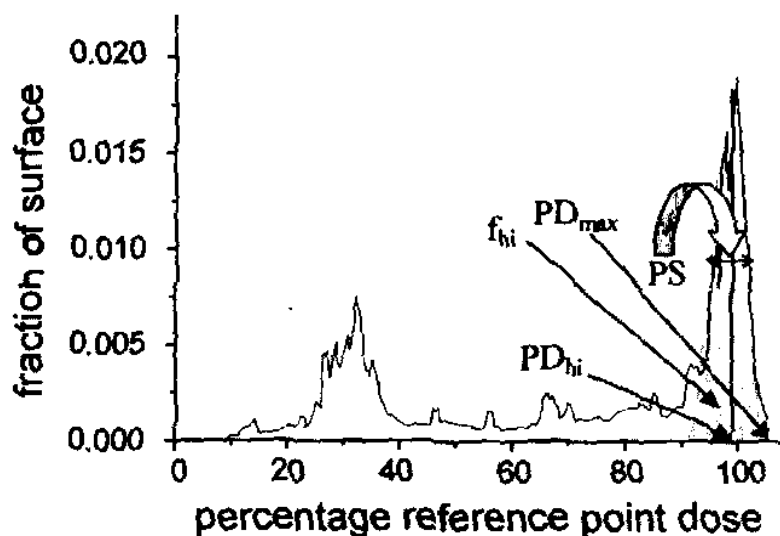


Figure 3.8 Characterisation of the Dose Surface Histogram. From Fenwick et al (2001).

Importantly, the success of the DSH in predicting late rectal effects is based somewhat on the assumption of a parallel organ. If it is serial then Dale and Olsen (1998) suggest from basic theory that hotspots of dose, as long as they are in the rectal wall, will not produce significant differences between the DVH and DSH. Dale *et al* (1999) plotted the correlation coefficient between NTCP and volume fraction for both a hollow and solid rectum (see figure 3.6b). At low volume fractions the separation of the curves for hollow and solid rectums is greatest and reduces as volume increases.

3.5. Uncomplicated tumour control and objective functions

The tumour control and normal tissue control probabilities can be used to indicate the potential for control of the tumour and treatment-induced complications from a given treatment. However, it is important to be able to combine the positive and detrimental effects of each treatment into a single parameter, the treatment utility. Naturally, there are advantages and disadvantages to using a single parameter to decide between competing treatment plans. Generally the array of biological and dose parameters (including TCP, NTCP, EUD etc.) should each be considered with clinical expertise.

In its simplest form the treatment utility is given as the uncomplicated tumour control probability, defined as the probability for controlling a given tumour without complications;

$$UTCP = TCP(1-NTCP). \quad (3.31)$$

The UTCP is defined from the tumour TCP, and the predicted complications of a single nearby healthy organ or tissue. The UTCP will range between zero and unity with the higher utility inferring the more beneficial treatment plan and is bound by the assumption that the complications are independent (Ågren *et al* 1990). Ågren *et al* (1990) define the probability for benefit without complications as,

$$P_+ = P_B(1-P_{I|B}) \quad (3.32)$$

where $P_{I|B}$ is the conditional probability for injury provided that the tumour is controlled. The parameter, P_+ , must then rely on whether the injury and tumour control are correlated or independent. If the tumour control and complication are considered to be independent events then the conditional probability reduces to P_I and equation 3.32 becomes

$$P_+ = P_B(1-P_I) \quad (3.33)$$

which is analogous to equation 3.31 above. Alternatively, if tumour control and complication are considered to be correlated then the conditional probability will equal unity and according to the Bayes Law

$$P_{I|B} = \frac{P_I}{P_B} \quad (3.34)$$

which yields

$$P_+ = P_B - P_I \quad (3.35)$$

for the uncomplicated tumour control. Clinically, only a subpopulation, ϕ of the total number of patients will get complications independent of the tumour, and a strongly correlated group $(1-\phi)$ will also exist, so that the uncomplicated tumour control may be expressed as:

$$P_+ = P_B - P_I + \phi P_I(1-P_B). \quad (3.36)$$

A general description for the treatment utility might be given as (Schulthiess and Orton, 1985)

$$U = TCP \cdot \prod_i (1 - \omega_i NTCP_i) \quad (3.37)$$

where a weight, ω_i , is given to each of the i organs that might incur deleterious effects from the treatment. The clinician would be the professional that is authorised to set the weights given to the importance of avoiding each particular complication and care should be taken if any correlation exists between tumour control and complication or between complications. Generally, only one complication is then considered per organ and only tissues with NTCP calculated will be included.

The utility of the treatment may be used to compare a number of competing treatment techniques manually or it can be used as a radiobiological objective function in computerised optimisation routines. The optimisation routines will calculate the optimal number of beams, their energies, aperture size etc. One of the more important objective functions (Mohan *et al* 1992) includes further constraints to that of the utility (as described above). Mohan *et al* (1992) suggest that the weight is itself a sophisticated function of the NTCP. They constrain the weight by various amounts depending on a clinician derived 'acceptable' NTCP value, P_a , a 'critical' NTCP level, P_c , and a corresponding weight or score, c_a , derived from the acceptable NTCP value. The radiobiological objective function is then;

$$F = TCP \cdot \prod_i C_i \quad (3.38)$$

where the component scores, C_i , are calculated using;

$$C_i = 1 - (1 - c_a) \frac{NTCP}{P_a} \quad \text{for } NTCP \leq P_a \quad (3.39a)$$

$$C_i = c_a \frac{(P_c - NTCP)}{P_c - P_a} \quad \text{for } P_a < NTCP < P_c \quad (3.39b)$$

$$C_i = 0 \quad \text{for } NTCP \geq P_c \quad (3.39c)$$

The term, C_i , is thus derived from a constraining relationship between a score and NTCP, where the score at a value of NTCP equal to P_a is c_a . Examples of the constraints that were used with this model to derive the relationship between the score and the NTCP include a dose-volume constraint for normal tissues, a lower limit on the TCP and upper limits on the skin dose.

3.6. Summary

A number of radiobiological models have been discussed in this chapter, with further details given to the cases for the tumour control probability of prostate carcinoma and the normal tissue complication probability of the rectal wall.

The potential discrepancies in delivered dose, from that planned, can be extrapolated through these radiobiological models to evaluate possible discrepancies in the TCP, NTCP and UTCP from that calculated with the static planned dose distribution. Such calculations are performed in Chapter 6. The variation in each of these parameters is also explored for a range of feasible parameters.

The linear quadratic model will be used to calculate surviving fraction for tumour and normal tissue. The LQ model provides a feasible estimate of the surviving fraction and has been used widely in literature. To calculate NTCP for the rectum, the Kallman s-model will be used. This model was chosen because the rectum is generally considered to be serial (with a known volume effect component also), the model suits a voxel based technique and qualitatively at least, the Kallman s-model has been shown to predict the correct trends given particular DVH input data compared to others in the literature (Moisenko *et al* 2000).

With the calculations of TCP, NTCP and UTCP performed in this thesis it is important to understand the assumptions made for derivation of the radiobiological models themselves, the current clinical uses of the models and their known limits. The current chapter has served to provide the basis for these qualifications to be made.

Chapter 4

Modelling the dosimetric effect of treatment uncertainty

4.1. Introduction

In this chapter, the dosimetric effects of the treatment process are modelled using Monte Carlo and convolution techniques. There are many contributing factors to uncertainty in delivered dose including geometrical, mechanical and computational factors among others. Ultimately these individual uncertainties contribute to overall uncertainty in the dose delivered to the patient (tumour and normal tissues). An understanding of the uncertainty in deposited dose is important because it impacts directly on the treatment planning and delivery processes.

This chapter begins by reviewing the impact of the treatment uncertainties on deposited dose, reviewing modelling techniques from the literature and then the concepts of spatial and dose probability density functions are introduced. A Monte Carlo technique is used to model the entire treatment process (planning and delivery) for a patient population including systematic organ motion uncertainty, random organ motion uncertainty and random setup uncertainty. A novel convolution kernel is derived that includes systematic organ motion error. This kernel is used with the convolution technique to predict mean treatment dose across a patient population. Both Monte Carlo and convolution techniques have the capacity to account for reductions of systematic organ motion error by using averaged organ positions from multiple pretreatment CT acquisitions. Weekly and daily

multiple CT acquisition regimes can also reduce systematic organ motion error and these are modelled using the MC code.

Modelling the reduction in systematic organ motion errors due to the use of multiple CT images to average organ location and accounting for this in the treatment planning algorithm is the predominant novel investigation in this chapter. Variables such as margin size, as well as the magnitudes of random and systematic organ motion, random setup error and penumbra gradients are explored. This investigation of uncertainty in deposited dose leads to a study of the radiobiological effects of the treatment errors in chapter 6.

4.2. Dose uncertainty

Treatment uncertainties hinder the current technological advances in external beam radiation therapy, such as 3D conformal techniques and intensity modulated therapy.

It is important to differentiate clearly between the different sources of uncertainty in order to understand the effect between each of them on the resulting treatment dose distribution. A list of treatment uncertainties and estimates of one standard deviation in dose would include (Kron *et al* 1998);

- o absolute calibration of the treatment machine (1%),
- o characterisation of the beams (1.5%),
- o modelling of radiation transport within the patient (2-5%)
- o day-to-day positioning of the patient (2%)
- o the constancy of the patients' geometry during treatment planning and delivery
- o uncertainty in the clinical description of tumour volume,
- o accuracy of the dose prescription.

All of the above mentioned factors need to be considered when prescribing dose to treat the disease. Other documents (such as ICRU-50, 1993) specify requirements for dose reporting. ICRU-50 requires that an error of 5% in reporting dose to the isocentre is an acceptable tolerance level. The last four factors listed above are difficult to label with a

standard deviation in dose because they involve further geometrical data and require, more aptly, dose-volume data. The day to day patient positioning uncertainty will introduce a spatially varying uncertainty in dose as discussed later.

4.2.1. Modelling dose uncertainty

The current literature provides a very limited number of examples of modelling the dose uncertainty. One of the studies from the literature models the uncertainty in tumour dose with the assumption that the magnitude of dose deposited in the patient varies normally about the prescribed dose (Boyer and Schultheiss, 1988). Standard deviations in dose up to 9 Gy were used to estimate the accumulated effect of most physical sources of uncertainty. Importantly, Boyer and Schultheiss (1988) presumed a spatially uniform uncertainty in dose to account for all sources of uncertainty. This presumption obviously oversimplifies the situation for the particular case of geometrical positioning errors. Beam misalignment due to these positioning errors has demonstrated larger dose variation near the field edges than in the field centre (Michalski *et al* 1993) using portal images. That is, lateral shifts of the patient relative to the beam will cause large fluctuations in dose in the penumbra and small fluctuations in dose in the more uniform central dose region. Therefore variations in the daily patient positioning produce position dependent (spatially non-uniform) dose uncertainty because the amount of dose variation depends on the position of the point of measurement. Likewise, organ motion will also cause non-uniform dose uncertainty.

4.2.2. Probability density functions for position and dose

Measurements of organ motion and patient position distributions provide the information to derive *spatial* probability distribution functions (PDF) for an organ relative to bony anatomy (organ motion) and for a patient relative to the treatment machine (setup errors). The random patient setup PDF can be derived for a population and used, for example, to predict the variability of patient positioning expected. However, it is useful to derive a relationship between the spatial PDF and the amount of dose variability (*dose* PDF) due to the geometric positioning errors.

Direct derivation of the dose PDF has been described in the literature (Leong 1987) using a precalculated dose distribution. This dose distribution is static, and positional uncertainty is modelled as movements of the volume. In figure 4.1 three voxels (at radii labelled r_3 , r_4

and r_5) illustrate points at the high dose, mid dose and low dose sections of the penumbra, respectively.

Patient movements in the room co ordinate system with a stationary incident beam are considered to be the same as a shifting beam (or dose distribution) with a stationary patient. Thus, the voxel centred at radius r_4 in the mid dose region has an equal probability of receiving above or below the prescribed dose. If the standard deviation of the positional PDF is small, then the variation in dose will also be small. But for large standard deviations, the steep slope of the penumbra infers a large range of possible doses. Alternatively, if the voxel is located near the top of the penumbra (radius r_3 for example) a smaller range of doses is possible because the central uniform section of the dose distribution offers only one value of dose. The spatially dependent dose PDFs evident from the positional errors are illustrated in figure 4.2 for several voxels (with off axis distance increasing from radius r_3 to radius r_5) within a particular dose distribution.

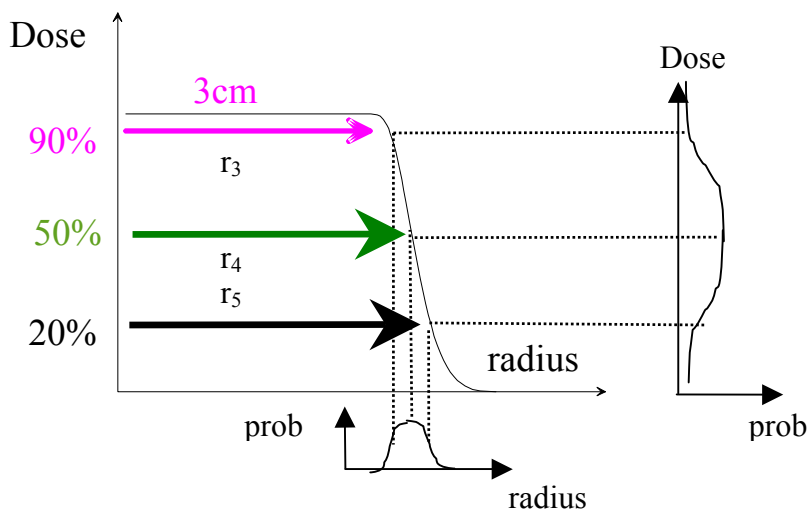


Figure 4.1 Demonstration of the direct derivation of dose PDF from spatial PDF with static dose distribution. (Adapted from Leong 1987). The spatial PDF (below the half dose profile) is used to allocate probability values (a dose PDF located right of the half dose profile) for a particular element of radius positioned originally at 50% dose. This procedure is repeated for other elements yielding dose PDFs as shown in figure 4.2 below.

Dose PDF curves for distances 3 and 5 cm (corresponding to radii r_3 and r_5 respectively) predict mainly high and low doses respectively because these voxels are centred at the upper and lower position of the dose profile. The dose PDF curve for the voxel centred at 4 cm from the central axis (radius r_4) is smeared over a large dose range because it's mean

location is the midpoint of the penumbra. The value of the positional PDF standard deviation is 0.6 cm.

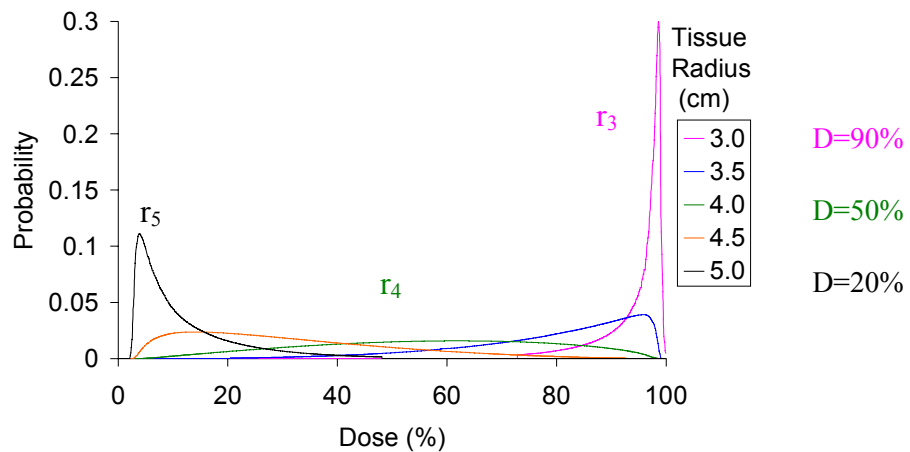


Figure 4.2 Dose PDFs within voxels that are positioned at five distances from the central axis, labelled from Figure 4.1. Only odd numbered curves are shown for brevity.

4.3. Monte Carlo technique

A Monte Carlo (MC) technique involves modelling physical situations by the sampling of random variables. In this section, the radiotherapy treatment process for a patient population including treatment planning and delivery is simulated. The MC technique described here is similar to that described by Killoran *et al* (1997) that was used to calculate a statistically oriented planning target volume.

In practice, following cancer diagnosis and the clinician deciding that the patient will undergo radiotherapy, a number of steps are followed to carry out the radiotherapy. The first stage is the treatment preparation, which involves the patient having a CT scan. The CT image includes a set of transverse 2D images. The tumour volume (GTV) and planning volume (PTV) are outlined in each of these images and the number and orientation of incident beams is decided upon. The second step is the treatment delivery. The planned treatment will be carried out over a number of fractions, with the patient being positioned on the couch using lasers in the treatment room against tattoo's on the patients skin.

4.3.1. Methods

We first model the imaging and planning process (treatment preparation) and then the treatment delivery. Interfraction organ motion is typically defined as a translation relative to bony anatomy, while the setup errors are movements of the bony anatomy relative to the treatment beam. The modelling uses a fixed grid in the room coordinate system, with axes in the left-right (x), anterior-posterior (y), and superior-inferior (z) directions.

4.3.1.1. Sampling from distributions, and the dose grid

The Monte Carlo code is written using the Interactive Data Language software¹. Random deviates are calculated by this software using the Box-Muller method (Press 1989).

Organ position at the time of planning CT imaging is sampled randomly from the corresponding organ motion PDF. This provides organ coordinates, which are then used through the treatment as a reference for planning and dose delivery. The organ position used for the treatment planning is determined from at least one CT image. A possibility of using multiple images is also included in the model. Organ position at CT is represented as a random variable ξ sampled from the PDF of organ motion, which is assumed to be documented from in-house measurements.

Mean organ position for the planning, $\bar{\xi}$, is computed from N_{CT} simulated organ positions using:

$$\bar{\xi} = \frac{\sum_{i=1}^{N_{CT}} \xi_i}{N_{CT}}. \quad (4.1)$$

Once the planning organ position is estimated from the CT scan(s) the dose distribution (or profile in 1D) is centred at that estimated position. The dose distribution is pre-calculated using the Pinnacle³ software for a 10 cm × 10 cm field of an incident 6 MV photon beam.

The treatment is modelled for each patient of the patient population. This modelling incorporates organ misplacement from its mean position at CT and treatment delivery.

¹ Research Systems Inc.

Treatment delivery uncertainties are simulated as translations of the rigid organ from the mean planning position (figure 4.3b). The reference frame for scoring the dose to the tumour is fixed with an origin centred over the actual mean organ position (figure 4.3a).

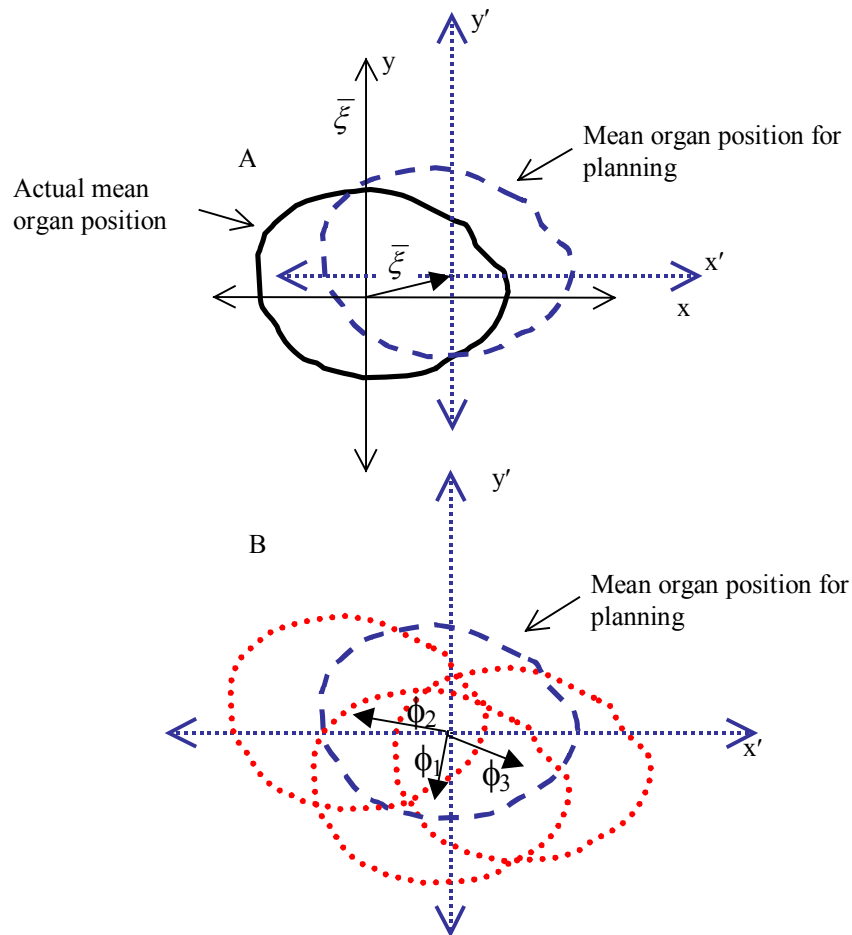


Figure 4.3 (a) Mean organ position is represented by the x,y co-ordinate system. In routine treatment, due to CT uncertainty, the planning image represents the organ in an off-set co-ordinate system (the x',y' co-ordinate system). This co-ordinate system is then used to plan and deliver the dose. The 1D approach in this study uses only the x -component of these 2D shifts. **(b)** Organ positions during the treatment delivery (such as ϕ_1 , ϕ_2 and ϕ_3 for 3 fractions) are measured in the off-set (x',y') co-ordinate system.

Patient setup error and organ motion uncertainties are both considered as independent random variables. By using fixed standard deviations for the organ displacement we therefore assume that its variance does not change during the treatment. These errors may be combined gaining a *treatment delivery error*

$$\sigma_{TD}^2 = \sigma_{SE}^2 + \sigma_{OM}^2. \quad (4.2)$$

The organ displacement relative to the planned position (incorporating patient setup uncertainty) at the j th fraction can be represented as a random variable, ϕ_j , sampled from the PDF with variance given in equation 4.2 at each fraction (see figure 4.3b).

Following the j th fraction, the dose distribution will be shifted by a total displacement of

$$\Delta_j = \phi_j + \bar{\xi} \quad (4.3)$$

from the actual mean organ position.

4.3.1.2. Dose accumulation

For a single incident beam, sample dose, $d_s(r)$, is accumulated in voxels following each fraction. For multi beam treatment, sample dose is combined from all beams and then accumulated following each fraction. The process is repeated over the course of N_{fx} fractions. The value of N_{fx} in a typical treatment (i.e. ~ 30) is sufficiently large (Rudat *et al* 1996) for the discretised distribution resulting from only 30 fractional treatments for each patient to approximate the continuous distributions used in accordance with the Central Limit Theorem.

An additional uncertainty in dose due to other factors is also included in the model as a spatially uniform dose fluctuation in a similar manner to Boyer and Schultheiss (1988). The relative effect of these components is suggested by ICRU-50 to be less than 5% of the prescription dose. A uniform component of dose uncertainty is modelled by sampling a discrepancy from prescription dose, ζ from a normal distribution (with SD=5%, or 0.10 Gy in the case of 2 Gy fractions) and applied to the existing sample dose fraction.

$$d_s^*(r) = d_s(r) + (d_s(r) \cdot \zeta). \quad (4.4)$$

A sample treatment dose for each voxel, $D_s(r)$, is then the sum of the perturbed sample doses, $d_s^*(r)$ for the N_{fx} fraction treatments:

$$D_s(r) = \sum^{N_{fx}} d_s^*(r). \quad (4.5)$$

For a patient population the values of $D_s(r)$ form a distribution that is used to calculate the mean and standard deviation of the treatment dose in each voxel.

4.3.1.3. Clinical example

Prostate carcinoma has been studied extensively in the literature and was chosen to investigate the dose uncertainty for a number of reasons. Firstly, interfraction variations in prostate position have been demonstrated in the literature to approximate a Gaussian distribution, which is easily implemented in the Monte Carlo (and convolution) codes.

Also, the anatomical position of the prostate implies that patient movements will not affect the form of the static dose distribution enough to require recalculation for each fraction. That is, the prostate is distant from significant tissue density changes such as air/tissue interfaces. The bony pelvis will not affect the dose distribution significantly and therefore shifts of the beam entry point will not significantly alter the geometry of the combined dose distributions of the four incident beams.

The dose grid used is sized to include the entire prostate PTV with grid spacing in each direction of 1 mm. Larger grid spacing was investigated, but is limited by the sensitivity required with small magnitudes of positional standard deviation.

Table 4.1 Summary of typical error magnitudes concerning supine treatment of prostate carcinoma used for modelling. Delineation error ranges are due to uncertainty in apex and seminal vesicles localisation. Systematic setup errors quoted do not include the use of a correction protocol.

Direction	Random error (mm)			Systematic error (mm)		
	LR	SI	AP	LR	SI	AP
Target delineation (Rasch <i>et al</i> 1999)				1.7	2-3.5	2.0
Organ motion (Stroom 1999)	0.6	2.5	2.8	0.5	2.5	2.7
Setup error	3.1 (ref 149)	5.4 (ref 149)	4.9 (ref 149)	2.6 (ref 13)	2.4 (ref 13)	2.4 (ref 13)
Total SD (quadratic sum)	3.2	6.0	6.1	3.1	4-4.9	4.1

A typical 30 fraction treatment for prostate carcinoma delivering 60 Gy to isocentre was modelled. We assume that the prostate does not deform or rotate during the treatment.

Prostate rotations are generally small and play a minor role (Bel *et al* 1996). Zelefsky *et al* (1999) measured prostate movements and deformation between 4 CT scans per patient during treatment. They measured the movements of the prostate centre of mass to be well correlated with movement of the respective prostate borders, suggesting that deformation of the prostate may be ignored.

4.3.2. Results

The MC technique was used to simulate the entire treatment process (including treatment preparation and delivery). Mean dose and the standard deviation in treatment dose was calculated for simulated treatments including positioning errors, spatially uniform dose errors and various numbers of pretreatment CT scans. The impact of margin expansion/reduction as well as the number of fields and dose gradients on mean dose and the standard deviation in treatment dose was investigated.

4.3.2.1. Mean and variance in fractionated dose for single incident beam

Figure 4.4 shows the effect of the treatment uncertainties on the dose distribution as delivered to a patient population. The dashed curve represents the profile of the original dose distribution without any corrections for treatment or systematic prostate position uncertainties (from single planning CT). Also shown are an MC calculated dose distribution including only the effects of the treatment delivery errors, profiles of the MC calculated dose distribution incorporating both treatment delivery errors and systematic prostate position uncertainty using 1, 2, or 5 CT scans, and spatially uniform dose error. The spatially uniform dose error follows the original dose profile since it is normally distributed about the original profile.

The plot of mean dose containing only treatment uncertainties (labelled CT_{∞} in figure 4.4a) shows a dose smearing effect from the original dose profile (Leong 1987, Keall *et al* 1999). The effect of incorporating systematic prostate position uncertainty into the mean treatment dose profile is a further dose smearing to that occurring due to treatment delivery uncertainties. That is, a further decrease in dose in the upper penumbral region and a further increase of dose in the lower penumbral region. Comparing the curve for one CT against the original dose profile, the maximum discrepancy between them is about 14 Gy (see figure 4.4b).

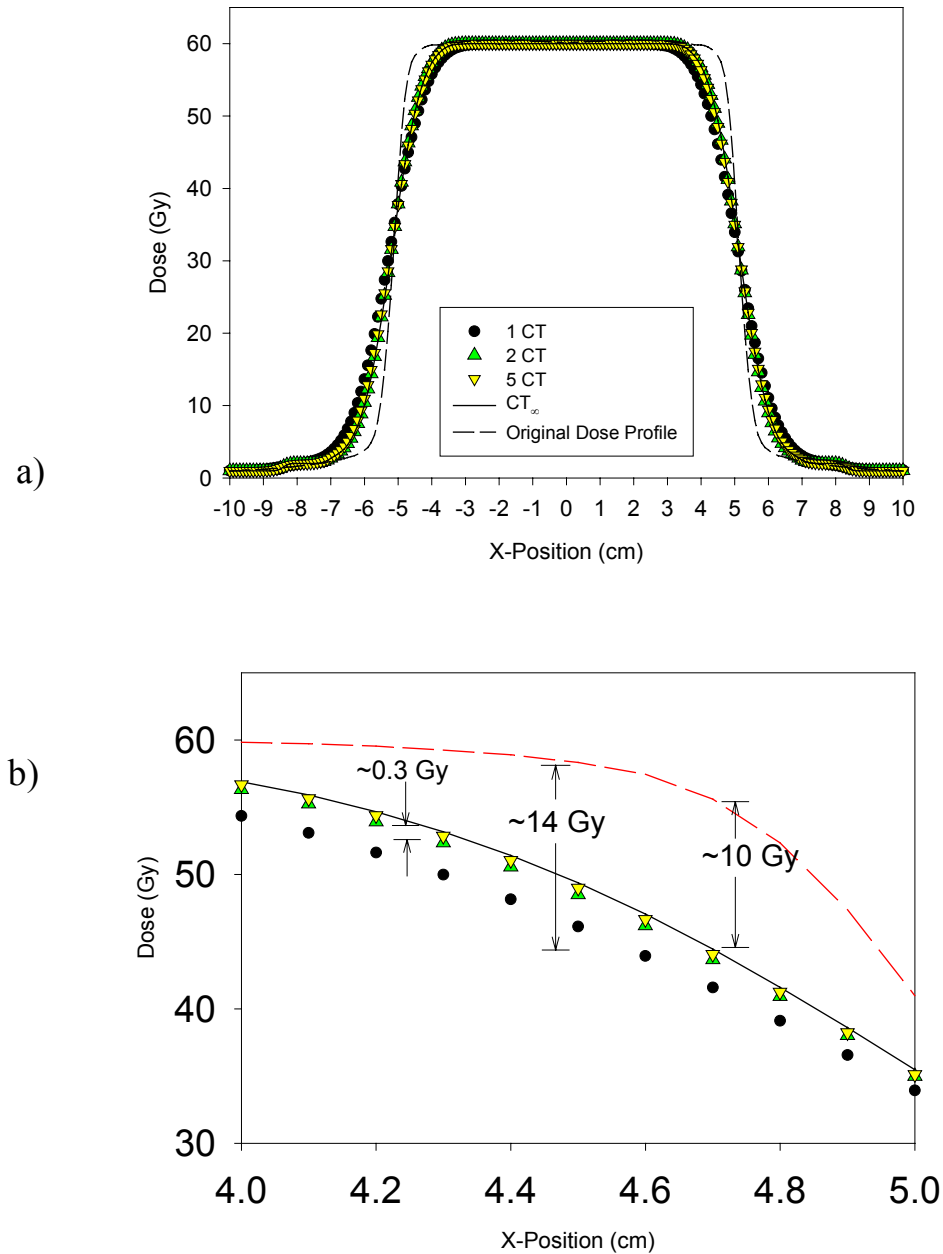


Figure 4.4 (a) Mean dose incorporating uncertainty at both planning and treatment. The dose profile represented by the broken line is the original dose profile and that represented by a solid line includes only the treatment delivery errors. The spatially uniform dose uncertainty follows the original dose profile. (b) Magnified view of penumbra.

The maximum discrepancy between the plot with no systematic prostate position uncertainty but incorporating treatment uncertainty (CT_{∞}) and the original dose profile is around 10 Gy. This illustrates that although most of the differences in mean dose occurs due to the treatment delivery errors, the CT uncertainty *does* contribute to the dose degradation. After averaging organ position from only two temporally spaced CT images pre-treatment, mean dose for the population is within 0.3 Gy of the mean dose calculated

with no systematic prostate position uncertainties (indicated by CT_{∞} in figure 4.4).

Figure 4.5 shows the variation (represented by 1SD) in mean dose to each voxel from the population of treatments. The plot including treatment delivery uncertainty only is again represented as CT_{∞} scans. Figure 4.5 highlights the spatial variation in dose uncertainty due to positioning uncertainties, with peaks occurring in the penumbral regions of the dose profile. These peaks are largest at the point of inflection in the dose profile.

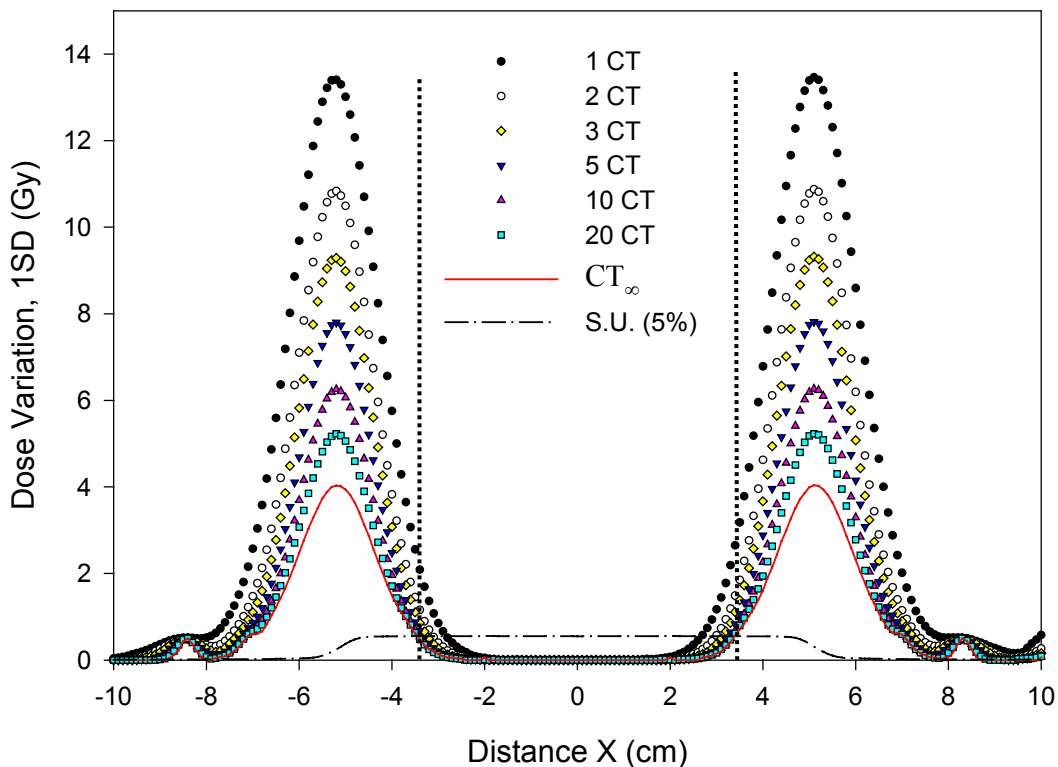


Figure 4.5 Dose variation (1 standard deviation of mean treatment dose) scored in voxels ($\Delta x = 0.1$ cm), using multiple CT scans to estimate mean organ position. The solid line shows dose variation due only to treatment delivery uncertainty. Vertical lines represent position of 95% isodose contour and the dash-dot line represents the spatially uniform dose uncertainty.

Figure 4.5 demonstrates a large reduction in dose variation as the number of CT scans used to average organ position is increased. When using only one CT image to plan the treatment the standard deviation of the dose has a maximum value of ~ 14 Gy, but the maximum value drops to 11 Gy with 2 CT scans and continues to reduce with further scans. With infinite CT scans performed the maximum value of the standard deviation in mean treatment dose calculated is ~ 4 Gy. Over 20 CT scans are needed to reduce the standard deviation to below the 5 Gy level. More importantly, the dose standard deviation

within 95% isodose line (which is often used to treat planning target volume is ~ 10 Gy for one CT scan, dropping to 3 Gy with the number CT scans exceeding 10).

Incorporating the spatially uniform component of dose uncertainty results in dose variation that is proportional to the original dose profile (by definition). The uncertainty of 5% per fraction ($\sigma_d = 0.10$ Gy) is reduced for the 30 fraction treatment by $\sqrt{30}$ (refer to figure 4.5). Thus in the central region of the dose profile where the dose is homogeneous and prescribed at 60 Gy, the standard deviation in mean treatment dose due to a 5% fractional dose uncertainty is $\sigma_D = 0.55$ Gy.

4.3.2.2. Impact of margin size

The size of the CTV \rightarrow PTV margin will obviously affect the position of the 95% isodose and the entire dose distribution. For shrinking CTV \rightarrow PTV margins, the penumbra becomes closer to the tumour periphery as the margin is decreased (refer to figure 4.6a). Thus the uncertainty in dose will also move closer to the tumour periphery. However, averaging multiple organ locations from corresponding images will reduce the systematic organ motion error and this can be used to justify potential margin reductions (as to be discussed in §4.3.3.1).

Obviously reducing any component of the total treatment error will allow margin reductions, and this will lower the dose deposited in contiguous normal tissue. Multiple pretreatment CT scans reduce the uncertainty in mean dose.

4.3.2.3. Impact of magnitude of patient positioning and organ variations

Figure 4.7 shows the variation in treatment dose considering a range of targeting accuracies. As the standard deviation of positioning error increases, the slope of the dose distribution decreases. This has been demonstrated experimentally using radiographic film (McCarter and Beckham, 2000). For each institution it is important to measure individual values of patient setup and organ position variability.

4.3.2.4. Number of fields and dose gradients.

The number of fields and beam shaping technique used will influence the dose gradient of the penumbra. The number of fields has been included into margin ‘recipes’ (refer to §2.7). As the penumbra becomes steeper, that maximum of dose uncertainty increases. This is

particularly important for intensity modulated and highly conformal dose delivery techniques.

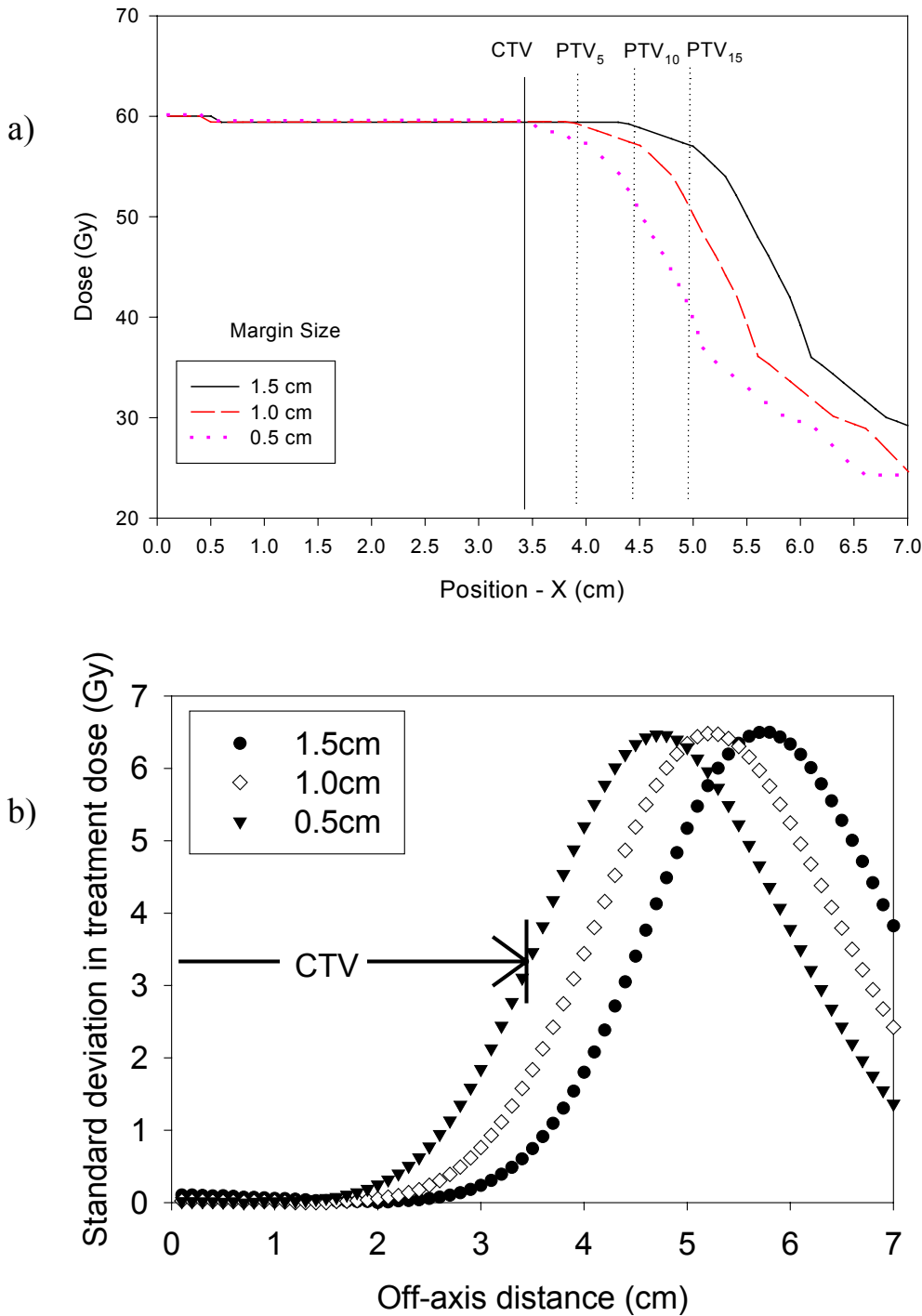


Figure 4.6 a) One dimensional profiles of prescribed dose distributions with three margin sizes (0.5, 1.0, 1.5 cm) and b) the associated standard deviations in treatment dose.

4.3.3. Discussion

4.3.3.1. Possible margin reductions with multiple pretreatment CT scans

As shown previously, multiple pretreatment CT scans can be used to significantly reduce the standard deviation in treatment dose, particularly in the penumbra. Conversely, when the margins are reduced for this standard treatment, the penumbra (and peak of the standard deviation in treatment dose) will approach the CTV. These two effects may be combined to justify margin reductions. Figure 4.8 demonstrates that if the standard treatment utilises one planning CT scan and a margin of 1.5 cm, then an equivalent amount of dose uncertainty at the tumour periphery is present with either 4 pretreatment images and a 1.0 cm margin or 30 pretreatment images and a 0.5 cm margin. The mean dose at this point on the tumour periphery will not differ from that prescribed if the positioning errors are in the average range.

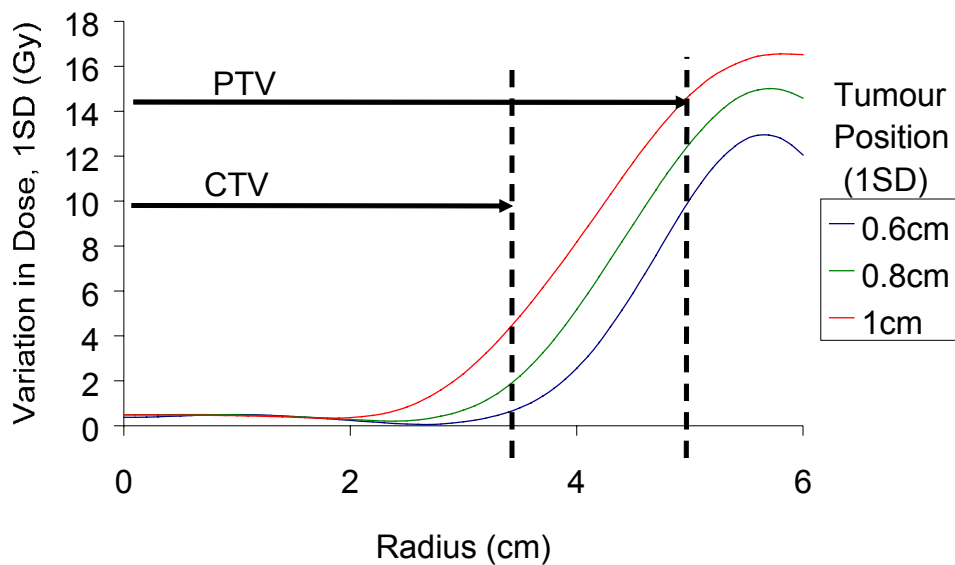


Figure 4.7 Standard deviation in treatment dose using the standard deviation in position to be 0.6, 0.8 and 1.0 cm. The value given as 'tumour position' is the standard deviation equal to the quadratic sum of random interfraction organ motion and random setup errors.

4.3.3.2. Relative importance of systematic and random components

Intuitively it would seem that systematic prostate position uncertainty, being a systematic error for each patient, would have a greater detrimental effect on the treatment outcome

than delivery errors. This intuitive conclusion is only partly supported for a patient population. On one hand, the mean dose affected by systematic prostate position uncertainty is *not* significantly discrepant from mean dose calculated incorporating only treatment delivery errors. In fact, the systematic prostate position uncertainty affects mean dose as if it were an extra random error for a population. And the size of this extra error is smaller than (i.e. about one third) the size of treatment delivery error. On the other hand, however, the variance in mean dose due to systematic prostate position uncertainty is considerably *larger* than that due to the treatment delivery errors. The systematic prostate position uncertainty has the *largest* effect on the variance in mean dose. Consequently, although the improvement in mean dose that is calculated by reducing systematic prostate position uncertainty is relatively small, the potential improvements in precision (reducing variance in mean dose) are large. This is obviously because the number of samples for calculating the variance in mean dose is 30 times smaller than for mean dose and therefore its error is $\sqrt{30}$ times larger.

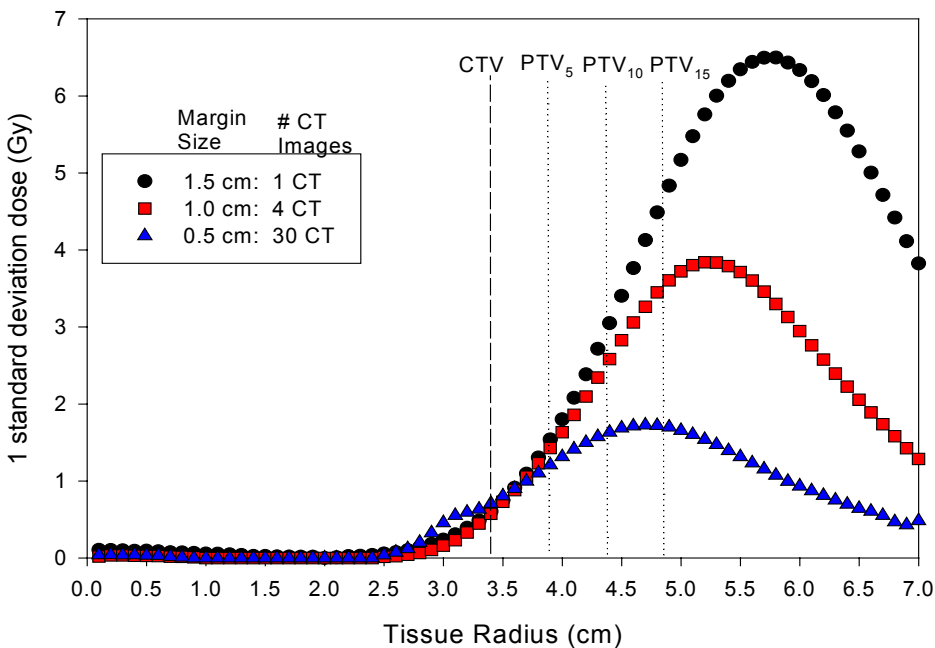


Figure 4.8 Possible reductions in margin size evident from improving knowledge of mean organ position.

4.3.3.3. Comparison of spatially uniform dose error and positioning errors

The effect on mean dose from simulating a combination of positioning errors and spatially uniform dose error is approximately a linear addition of the individual curves in figure 4.5. Therefore the combination is not illustrated in figure 4.5. Positioning errors will

predominately affect the dose delivered to regions of dose gradient at the field edges and they will be particularly important if sensitive normal tissue abuts the target. The spatially uniform dose error, which occurs due to such factors as limited linear accelerator calibration precision, will predominately affect the regions of maximum dose, normally with in the CTV.

4.3.3.4. Dose reporting

Obviously reductions in mean treatment dose will cause decreases in tumour control probability (TCP). Importantly, the fluctuations in dose per fraction inferred from the presented treatment dose variations (refer to figure 4.7) will also have an effect on the TCP. Increased dose heterogeneity leads to rapid loss in tumour control (Ebert 2000) and therefore the TCP reduction due to temporal fluctuations will be present in addition to the loss of tumour control due to mean dose reductions (smearing) caused by the uncertainties for the population. This indicates that treatment outcome is dependent on both mean dose and its variance, and that both of these quantities should be indicated on the treatment plans. Some biological parameters are calculated with the Monte Carlo model developed in this section in Chapter 6.

4.4. Convolution technique

A convolution method has been used to predict mean dose incorporating the treatment delivery errors (Leong 1987, Bel *et al* 1996, Lujan *et al* 1997, Keall *et al* 1999). It was extended to calculate dose variance (Zavgorodni 1997, 2000, Lujan *et al* 1999). The convolution equation used to predict the mean dose is of the form:

$$\bar{D} = \iiint D_0(x-x', y-y', z-z') \cdot f(x, y, z) dx' dy' dz' \quad (4.6)$$

where D_0 is the static reference dose and $f(x, y, z)$ is a variation kernel, which is usually assumed to be Gaussian, hence:

$$f(x, y, z) = \frac{1}{\sigma_x \sigma_y \sigma_z (\sqrt{2\pi})^3} \exp \left[-\frac{(x-\mu_x)^2}{2\sigma_x^2} - \frac{(y-\mu_y)^2}{2\sigma_y^2} - \frac{(z-\mu_z)^2}{2\sigma_z^2} \right] \quad (4.7)$$

where μ_x is the mean x value, which is zero, and σ_x is the standard deviation in the x

direction as prescribed by equation 4.2, and so on.

4.4.1. Derivation of spatial PDF including systematic organ motion error

The variation kernel used with the convolution method can be extended using statistics to include systematic organ motion error from the planning stage. The organ mobility affects delivered dose twice: initially through planning on a potentially displaced image and later during the treatment delivery (van Herk *et al* 1995). For a particular patient the CT uncertainty will result in a systematic positioning error that can be considered random over a patient population. The individual shifts at each treatment fraction form the treatment delivery uncertainty distribution. This distribution combines the effects of the organ motion at treatment with set-up errors and it is fixed for the population of treatments. As a result, the total variance of positional error distribution σ_T^2 for a population of patients is the sum of the three components

$$\sigma_T^2 = \sigma_{OM}^2 + \sigma_{SE}^2 + \Sigma_{OM}^2 \quad (4.8)$$

where Σ_{OM} and σ_{OM} are both related to organ motion, but different notation is used to separate the systematic from the random component, respectively.

Equation 4.8 is true for the case of a single CT image used to plan the treatment, but clearly the definition of organ position at planning will become more accurate as further CT scans are performed. After N_{CT} images are averaged, the standard error in the mean ($\sigma_{s,CT}^2$) should be used in this equation to specify the CT component of the total variance.

This component is reduced from its original value by a factor of N_{CT} as follows

$$\sigma_{s,CT}^2 = \frac{\sigma_{CT}^2}{N_{CT}}. \quad (4.9)$$

Consequently, with multiple pretreatment CT scans used to estimate mean organ position, the variance of the convolution variation kernel will become

$$\sigma_T^2 = \sigma_{SE}^2 + \sigma_{OM}^2 + \frac{\sigma_{CT}^2}{N_{CT}}. \quad (4.10)$$

The convolution method was implemented using equations 4.6, 4.7, and 4.10 to compute mean treatment dose with various N_{CT} and the results compared to the benchmark MC results. The use of convolution technique allows the integration of this approach into the treatment planning software.

4.4.2. Benchmarking against Monte Carlo results

Figure 4.9 demonstrates that systematic prostate position uncertainty can be easily accounted for in the treatment planning calculations. Shown in this figure is the mean dose for a patient population calculated using the convolution method with the variation kernel that includes the effect of systematic prostate position uncertainty through equation 4.10. An excellent agreement is observable between the convolution and the MC results (replotted from figure 4.4). Treatment planning software corrections used to account for the treatment uncertainties are further investigated in Chapter 7.

4.4.3. Margin recipe including systematic error

The systematic organ position error is reduced when the average organ position is used from multiple pre-treatment image acquisitions. The CTV→PTV margin ‘recipes’ (refer to §2.7) include a factor of 2.5 times the standard deviation of systematic error. This standard deviation is the quadratic addition of systematic patient setup (Σ_{SE}), systematic organ localisation (Σ_{OM}) and delineation error (Σ_{delin}). Multiple pretreatment imaging can therefore be directly incorporated into the margin recipe to compensate for the reductions in systematic organ motion error. The margin for systematic error including the number of pretreatment images used to derive the mean organ position N_{CT} may be extended from equation 2.6 using equation 4.9 as;

$$H_{sys} = 2.5 \sqrt{\Sigma_{SE}^2 + \frac{\Sigma_{OM}^2}{N_{CT}} + \Sigma_{delin}^2} \quad (4.11)$$

For images (megavoltage images or CT) acquired during the treatment the inclusion of localisation improvements into say shrinking margin recipes would be useful. However, this would not be as simple to calculate as for the pretreatment image acquisition.

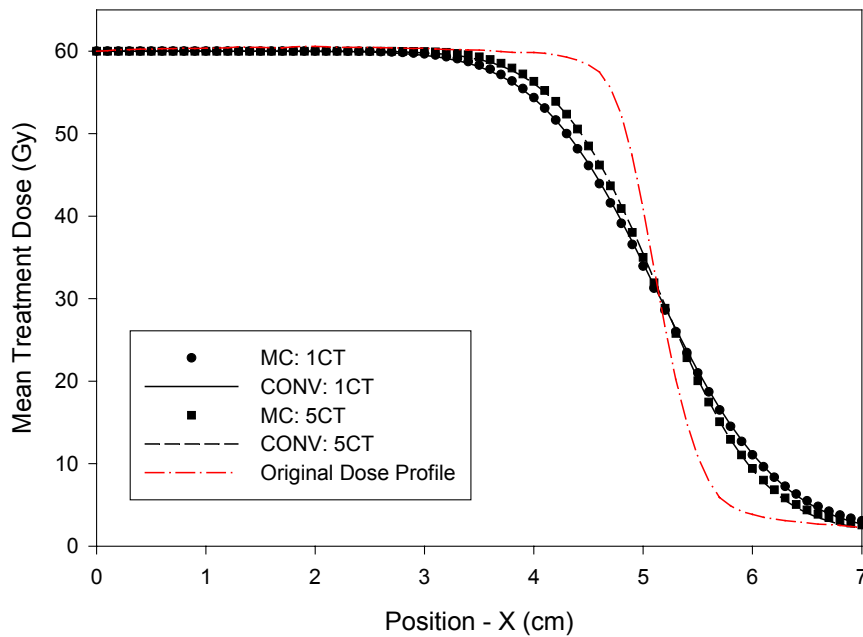


Figure 4.9 Mean treatment dose predicted for 1 and 5 CT scans using the convolution method as compared with MC results. The original dose profile is also shown.

4.5. Multiple CT scans

The systematic discrepancy between the organ position located during the planning CT scan and the mean organ position during treatment has been quantified in this thesis (refer §4.3.2.1) and in the literature (van Herk *et al* 1995, McKenzie *et al* 2000). One method to overcome this is to adapt the delivery following imaging procedures as the treatment course proceeds. Suggested imaging procedures have included kilovoltage x rays, CT scans, and ultrasound (Padhani *et al* 1999, Dawson *et al* 1998, Lattanzi *et al* 1999). This would be similar to patient repositioning following portal imaging to reduce systematic setup errors. As with the repositioning protocols (refer to §2.6) a variety of regimes are possible.

4.5.1. Timing regimes for multiple intra-treatment image acquisition

The effect of the *frequency* of imaging procedures *during* treatment delivery on the mean dose and variance in mean dose is investigated in this section. The MC code accounting for multiple pretreatment imaging (§4.3) is altered here to account for various intratreatment regimes. In particular; imaging done daily with on-line isocentre shifts, imaging done daily

with off-line isocentre shifts using the adaptively improving estimation of mean organ position, and imaging done weekly with adaptively improving estimation of mean organ position.

The pseudo code for modelling each of these regimes is included in figure 4.10 a→c, respectively. In the figures, the MC simulation begins following the initial treatment preparation with the simulation of N_{fx} treatment fractions. Any given treatment fraction may be given following the N_{CT} CT image acquisition sessions.

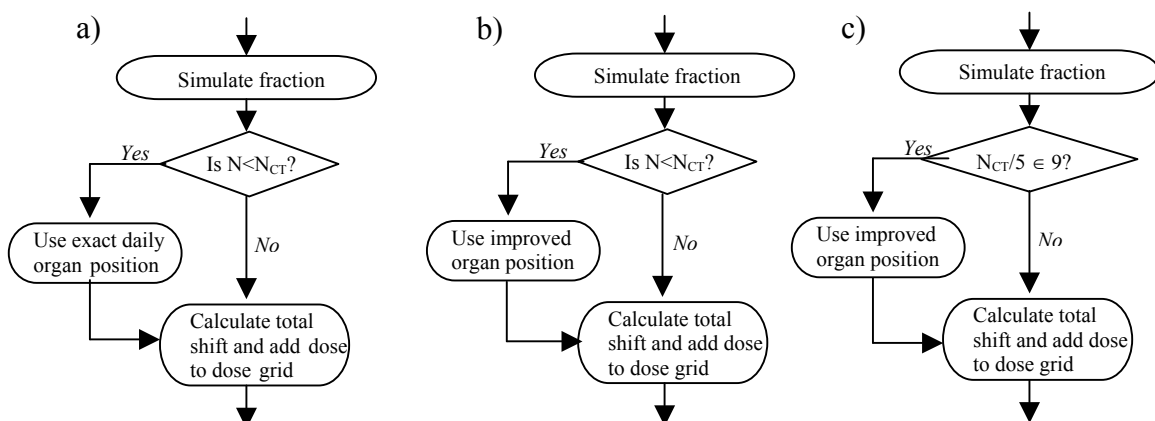


Figure 4.10 Flow chart of regimes for timing multiple imaging

Regime ‘a’ specifies CT image acquisition daily with on-line shifting of the patient through the initial portion of the patients’ treatment. This regime assumes that the patient does not move between the daily imaging procedure and treatment fraction. For this an immobilisation device would be used. The literature provides one example of regime ‘a’ in practice, which studied the resulting patient positioning uncertainty (Lattanzi *et al.* 1998). In practice, regime ‘a’ would be time consuming and restrictive for the patient.

Regime ‘b’ includes daily imaging of the patient with off-line shifting of the patient. However, the patient is allowed to walk from the imaging venue to the treatment couch, and the daily organ position is used to improve the average organ position. Although more practical and comfortable for the patient, if significant improvements in dose deposition accuracy are not present then the workload involved with utilising all the extra information would probably be limiting. Of course, some studies of prostate motion indicate that inter-fraction variations decrease as the treatment progresses and this suggests that only the first portion of the treatment might feasibly be imaged.

Regime 'c' specifies imaging only once per week. This is expressed mathematically in Figure 4.10 as when the total number intended divided by the number of days in the week is an integer. Regime 'c' implies a similar imaging workload to regime 'b' with $N_{fx}=5$. However, with regime 'b' the improved organ location estimate is used for the remaining weeks of treatment, while the same precision is achieved with only days remaining for regime 'c'.

4.5.2. Results

Incorporating regimes 'a', 'b', or 'c' into the treatment process modelled with the MC code is illustrated for mean dose and spatial variance in mean dose.

The curves for both mean dose and one standard deviation in dose (refer to figure 4.11) for the on-line technique (regime 'a') are demonstrated to be similar to the daily CT offline technique (regime 'b'). If daily CT scans were to be used, then the daily offline over the first week of treatment will provide the most advantage considering usefulness and staff workload. Clinically, all of the multiple imaging techniques would obviously be combined with portal imaging schedules for correcting systematic patient setup error (refer to §2.6).

4.6. Monte Carlo modelling of 3D dosimetric impact

The Monte Carlo method (outlined in §4.3) was used to calculate mean treatment dose and the standard deviation in mean treatment dose, incorporating clinically feasible uncertainties in the delivery of the four field 'box' technique (with rectangular fields) commonly employed to treat patients with prostate carcinoma. The prescribed treatment included 64 Gy to be deposited at isocentre in 32 fractions.

4.6.1. Methods

The dose distribution from the four field treatment of a patient treated for prostate carcinoma was extracted retrospectively from the treatment planning system². The dose distributions for each of the four beams were separately calculated forming a set for that

² Pinnacle v5.2g

PTV margin. Three uniform PTV margins were used (0.5, 1.0, 1.5 cm) each composed of a set of four dose distributions. The dose grid encompassed the largest PTV and the rectum with an additional margin around both. Dose calculation used the Pinnacle convolution/superposition algorithm with 0.5 cm voxels. The CTV and three PTVs are illustrated in figure 4.12 with the structures of interest (i.e. prostate and rectum).

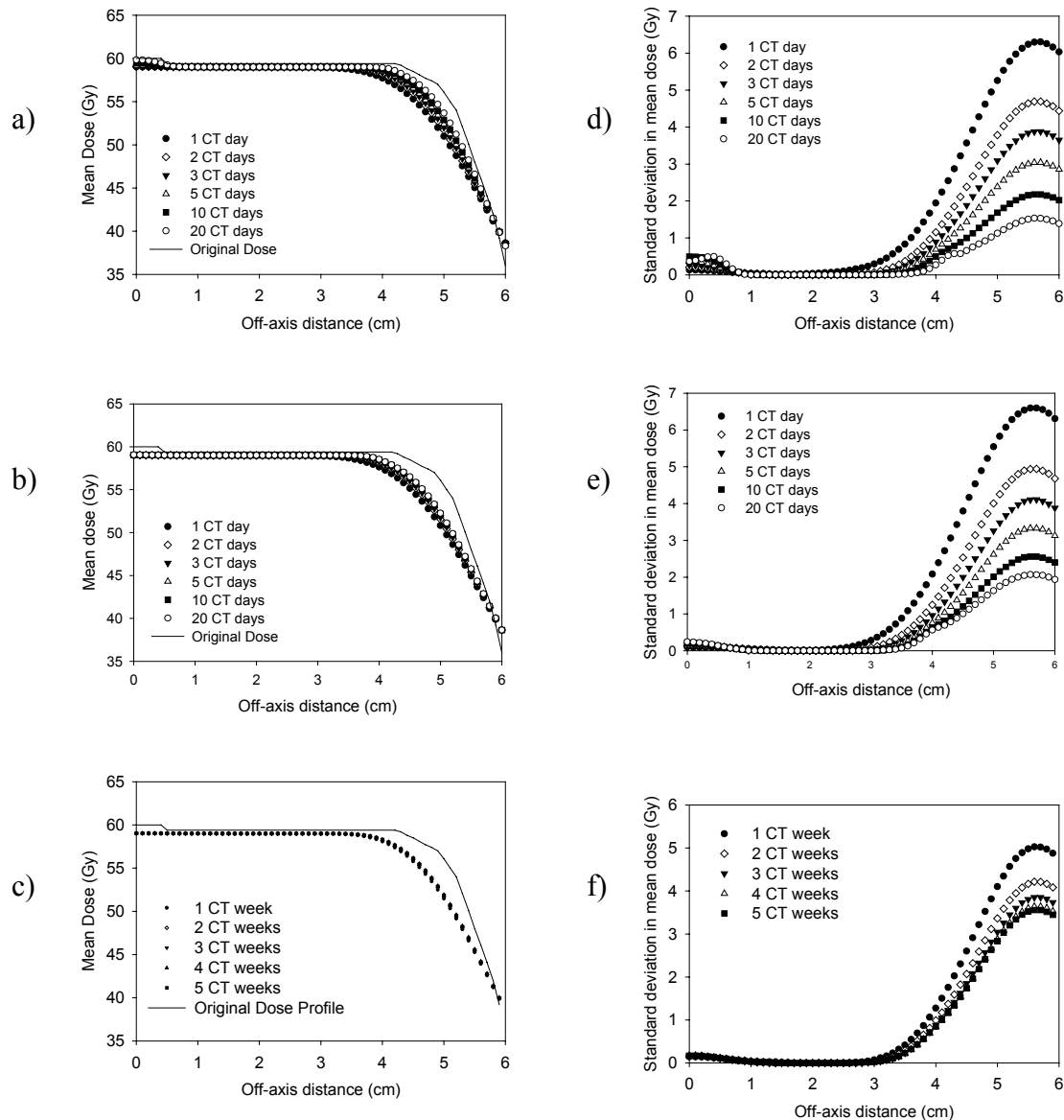


Figure 4.11 Mean dose (a→c) and variance in mean dose (d→f) resulting from incorporating regimes a,b, c into Monte Carlo modelling of the treatment process.

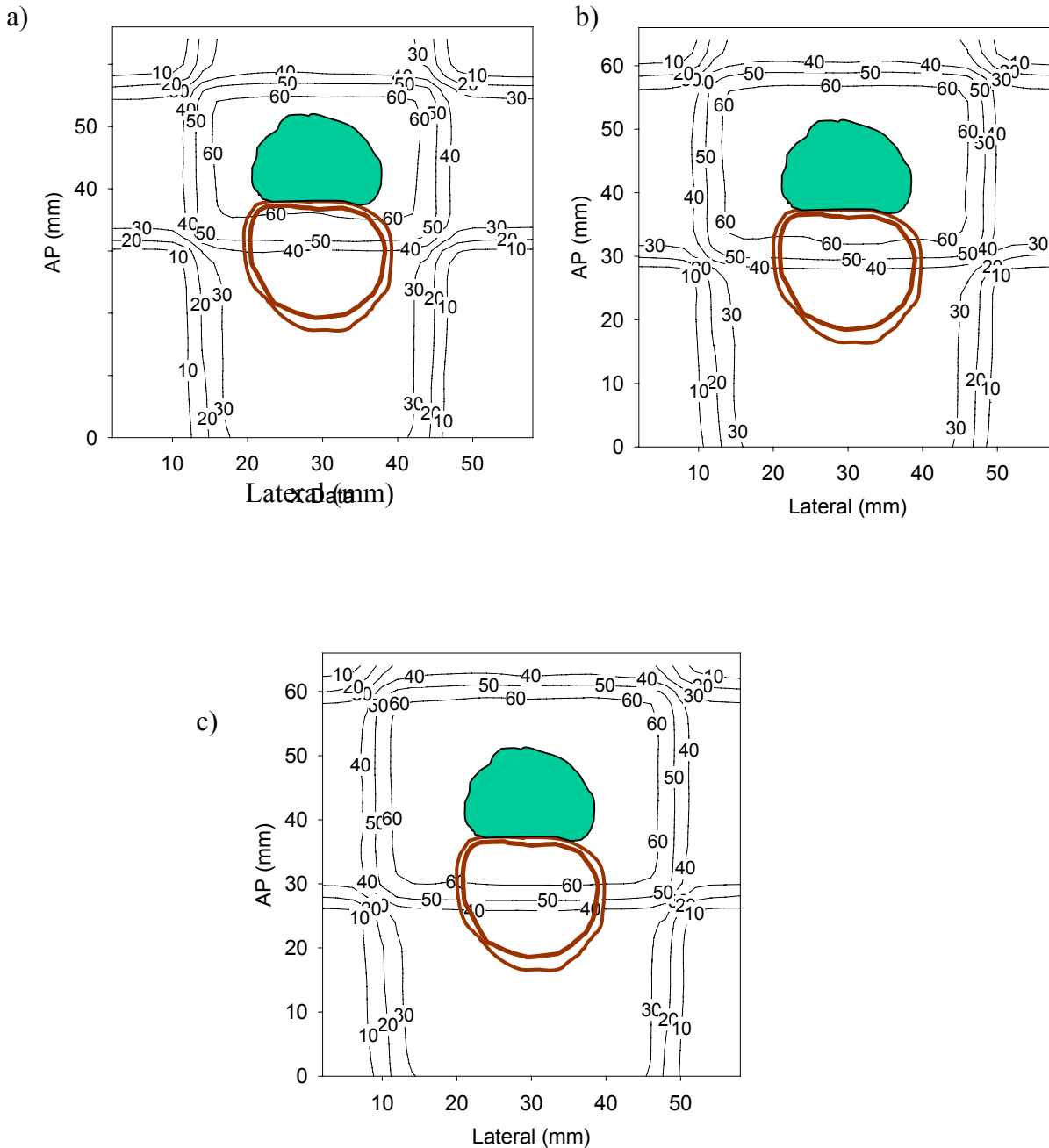


Figure 4.12 Illustration of the prostate gland (GTV), rectum and three dose distributions characterised by margins of a) 0.5 cm b) 1.0 cm and c) 1.5 cm. In each case the 95% isodose indicates the PTV, the green volume is the prostate (GTV & CTV) and the brown volume is the rectal wall.

The previously described MC technique was applied separately to each of the four 3D dose distributions comprising the four field beam design for each patient. At each fraction, the same sampled shifts of the organ and patient were applied to the dose distribution of each beam. Following the 32 simulated prescribed fractions, the four dose distributions were summed, giving a simulated treatment dose distribution. One thousand simulated treatment

dose distributions were created and used to calculate the mean treatment dose distribution and the standard deviation in mean treatment dose.

The convolution technique described in §4.4 was also used to generate mean treatment dose distributions.

4.6.2. Results

Mean treatment dose distributions calculated with the MC and convolution techniques coincided. Only the mean treatment dose distributions calculated with the MC technique are shown.

Mean treatment dose is illustrated in figures 4.13 with 0.5, 1 and 1.5 cm isotropic margins around the tumour volume. Each contour plot show small variation between the mean dose distribution considering a single CT used for planning and the original (planned) dose distribution. The 60 Gy isodose contour of the former is inside that of the latter and vice versa for the 40 Gy isodose contour, illustrating a reduction of the penumbra gradient with positioning uncertainty. As with the 1D case, the deviation between the mean dose distribution based on a single CT scan and that based on an infinite number of CT scans is very small. The difference between all three cases depends on the penumbra gradient as evidenced by comparing the discrepancy along the oblique cross section through the central ‘box’ and the cross section parallel to the axes. A larger discrepancy is present in the former case due to the higher penumbra gradient.

The mean treatment dose, calculated with only spatially uniform interfraction variation in dose, follows the original dose distribution.

The standard deviation in mean treatment dose is illustrated in figure 4.14 below in the transverse slice for the dose distributions including 0.5 and 1.5 cm margins.

For the 0.5 cm margin and in the transverse plane (figure 4.14a) the penumbra is located between lateral positions {7,12} and {23,27} and anterior-posterior positions {10,15} and {22,26}. The standard deviation in mean treatment dose, shown as profiles in figure 4.16a, peaks in these penumbral zones.

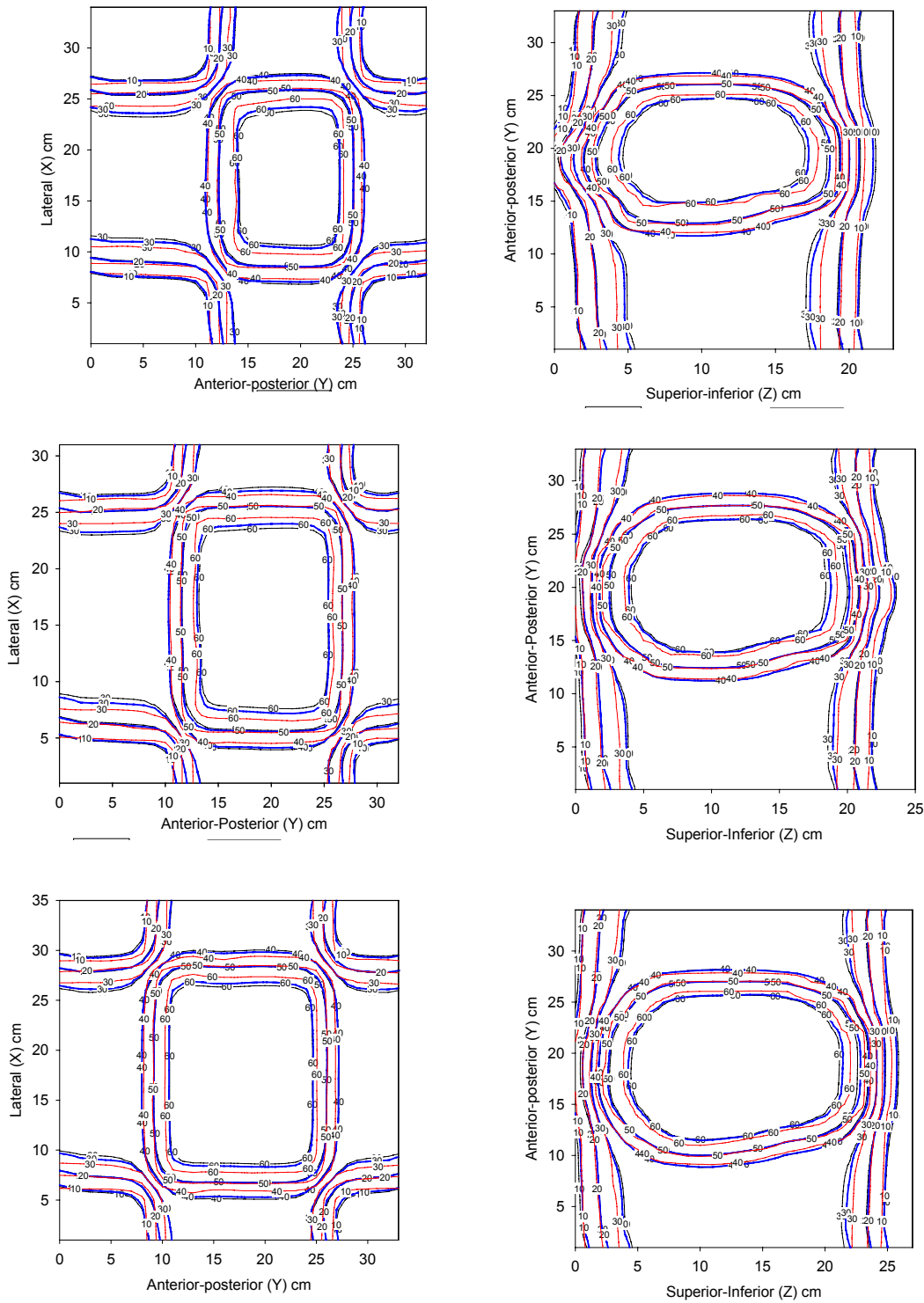


Figure 4.13 Two views of the mean treatment dose calculated with three original dose distributions (for margins of 0.5, 1.0, 1.5 cm) for three cases. The three cases are an original dose distribution (black solid line), a mean treatment dose calculated based on 1 planning CT scan (blue solid) and a mean treatment dose based on infinite planning CT scans (red solid line).

The standard deviation in mean treatment dose is illustrated in figure 4.15 for the scenario of multiple CT scans (1,2,5, ∞) at planning and uniform dose uncertainty (2% and 5%).

The results are shown for each of the three margin sizes along the planes sharing the point (15,20,12). The standard deviation in mean treatment dose, calculated with only spatially uniform inter-fraction variation, is proportional to the original dose distribution.

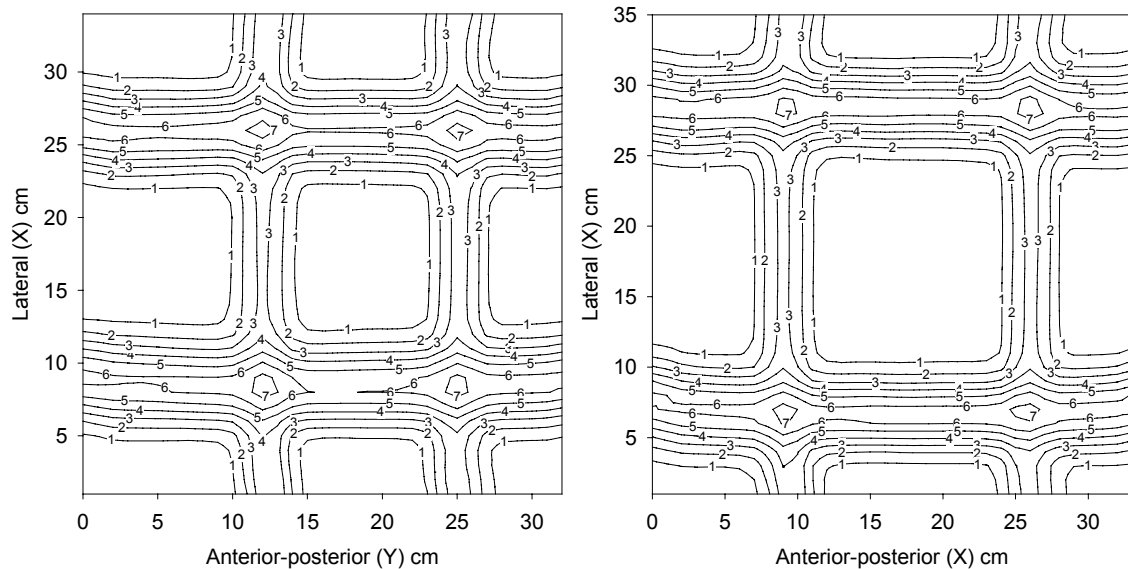


Figure 4.14 Iso-standard deviation plots in the transverse plane with a) 0.5 cm and b) 1.5 cm margin.

4.6.3. Discussion

The mean treatment dose distributions across a population of patients featuring feasible magnitudes of error during treatment preparation and delivery have been modelled. Three original dose distributions were considered to cover the CTV plus margins of 0.5, 1.0, and 1.5 cm.

The discrepancy between planned and calculated mean (actual) dose distributions is shown to be largest at the junctions of orthogonal beams for the four field box technique. Accordingly, the standard deviation in mean treatment dose is largest at these four junctions and peaks with dose ~ 6.5 Gy.

The spatially uniform dose uncertainty results in inter-treatment variations of treatment dose with standard deviation, $\sigma_D \sim 0.6$ Gy for the 5% fractional dose error. This variation between patients prescription doses will occur in the tumour volume.

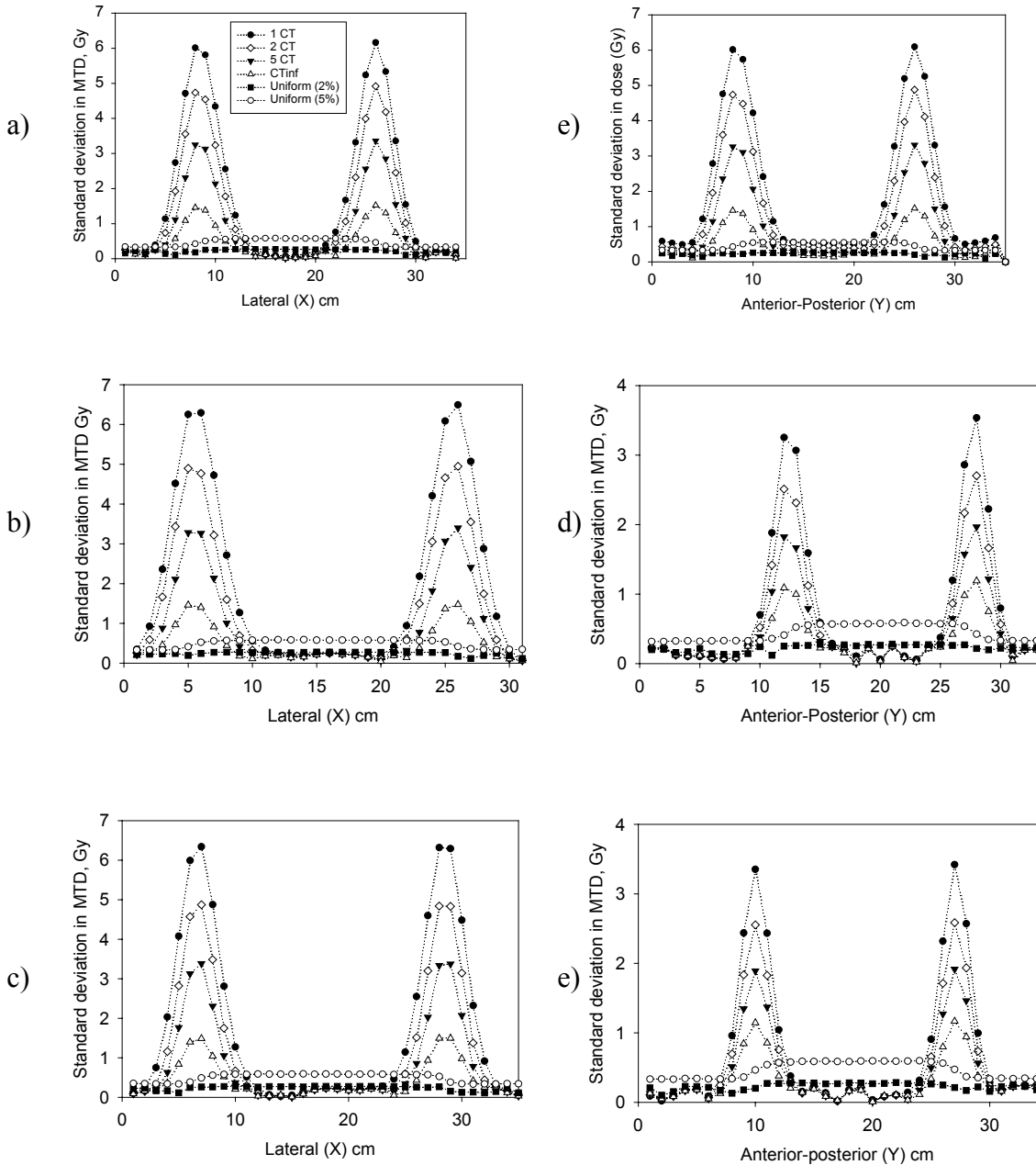


Figure 4.15 Profiles of one standard deviation in mean treatment dose along the lateral (X) and anterior-posterior (Y) direction for the a) 0.5 cm margin, b) 1.0 cm margin and c) 1.5 cm margin.

From the mean treatment dose and standard deviation in mean treatment dose results, due to positioning errors, it appears that the majority of the population will receive the prescribed dose to the prostate gland. Even with the smallest margin (0.5 cm) the largest standard deviation in mean treatment dose of an element of the tumour volume is less than 1 Gy. However, significant variation in dose to rectum is calculated, with the mean dose close to that prescribed.

The mean treatment dose deposited in rectal tissue will obviously depend largely on the

margin and the complication rate will also depend on the architecture of the organ. These radiobiological aspects are examined further in the following chapter.

4.7. Summary and Conclusion

A Monte Carlo and a convolution technique have been used to simulate the radiotherapy process. The Monte Carlo technique provided calculation of the mean treatment dose and standard deviation of treatment dose across a patient population, while the convolution technique provided the mean treatment dose. The impact on mean treatment dose and the standard deviation in treatment dose from a number of situations were investigated including various margin sizes, various magnitudes of the positioning errors, spatially uniform dose uncertainty and organ location averaging from a number of CT scans. The Monte Carlo technique allowed evaluation of multiple CT scans performed before treatment and during treatment as an adaptively conformal technique. A novel convolution *kernel* was derived that incorporated systematic organ position error and included the capacity for averaging organ position from a number of pretreatment CT scans. Averaging organ position in this way reduces the systematic component of organ position uncertainty during treatment and an addition to a published margin ‘recipe’ is proposed to incorporate this.

The averaging of organ position pretreatment is obviously useful when the organ position is varying normally about a true mean position. For sites such as the prostate, the distribution of inter-fraction organ displacements *has* been characterised as being normally distributed (Rudat *et al* 1996). For other sites, such as the lung and abdominal organs, the predominant motion is due to breathing and is not random. For these sites, multiple images can be acquired over a short period of time (less than 10 minutes) to characterise motion (Oppelaar 1999) and estimate organ mean position. If breathe holding is used then the organ position at breathe hold will be random. Furthermore, although the current work uses a Gaussian PDF to describe the interfraction variations, the convolution technique is not limited to normally (Gaussian) distributed organ movements. Therefore, the convolution technique is not limited to the prostate and can be useful for other sites.

The practical conclusions are that large improvements in the dose distribution delivered to the patient can be achieved and that reducing systematic errors is of highest importance.

Chapter 5

Modelling dose deposition to the deforming rectum

5.1. Introduction

The rectum is a dynamic organ that changes shape dramatically with time. For external beam radiotherapy of the prostate, the rectum will be partially included in the CTV and will encounter the large dose variations associated with the beam penumbra. Thus, large interfraction variations in both rectum position and patient position will affect the dose actually deposited in the rectum. The previous chapter considered only interfraction organ translations, which is acceptable for the prostate, but further detail is required to model the deformation of the rectum and to derive a more accurate description of the dose delivered to the dynamic rectal wall.

A considerable amount of work has recently been published on characterising the dose volume characteristics of rectum (refer to §3.4.6.3). Some of this ground work has established a volume effect with the dose-volume characteristics of the rectum. Other workers have proposed various tools for displaying and analysing the dose to the rectum have been proposed. Among the displaying and analysis tools, the most useful has been the dose surface histograms because they have been correlated with complications (Lu *et al* 1995). However, great potential lies with additional consideration given to a dose surface map (DSM). Dose surface maps provide a 2D surface map of spatial dose characteristics. It is the spatial dose characteristics *combined* with the dose-volume characteristics that have

been hypothesised to be important for predicting complications from a particular dose distribution (Fenwick *et al* 2001). If the location of FSU's receiving high dose is important then the DSM is a good technique to illustrate the effect.

The purpose of this section is to investigate the typical accuracy of the dose to rectal wall due to uncertainty in the positioning of beams and deformation of the rectal wall.

5.2. Background

Serial CT studies have revealed the typical magnitude of the variation in position and shape of the rectum (among other characteristics) through out the course of a fractionated external beam radiotherapy treatment. The knowledge arising from such studies is leading to models that describe rectal wall motion.

A number of difficulties arise when attempting to describe the deformation of the rectum, or any organ for that matter. One difficulty is how to describe the deformation in a way that can be consistently understood and may be applied to future individual treatments. Clearly, it is difficult to relate the measured population data to the individual.

Stroom *et al.* (1999) characterised the motion of the rectum from a repeat CT study. They measured the magnitude of the rectal wall volume V and then calculated the mean diameter across the patient population. The mean radius is calculated using:

$$R = V / (2\pi.l), \quad (5.1)$$

where l is the rectum length (~12 cm) for each patient. They also calculated the standard deviation in the radius calculated for each patient, σ_R , and the standard deviation in mean radius across patients, Σ_R . Thus the deformation of the rectum was characterised by the mean radius, the interfraction variation in diameter, and the interpatient variation in mean radius. The rectum will not deform by a simple change in diameter at each fraction, but this is a good first approximation.

The characterisation by Stroom *et al* (1999) leads to a further question of what is the limit in utility of the serial CT data. That is, the serial CT images show the multi dimensional range of motion for a particular patient and a group of patients that may assist in setting the prostate margin. However, the range of prostate motion (and probability of occupying each

of the ‘prostate’ voxels in the planning CT image) is about the limit of prediction. The daily movement cannot be predicted with any certainty from a previous serial CT study (Fontenla *et al* 2001). Daily CT scans will describe the position of the organs in the body, as described in the Adaptive Radiotherapy (ART) technique (Martinez *et al* 2001). At least one commercial manufacturer has produced a CT scanner on rails that is attached to the linear accelerator for techniques such as ART. Currently, however, for various reasons (financial and temporal) ART or serial CT scanning are not common techniques.

A second method is to remove the reliance on predicting the amount of variation by using a fixed rectum size (request patients void, or prescribe laxatives, before each stage) or inserting a device in the rectum to limit, or at least measure, prostate motion (Ten Haken *et al* 1991).

In the future, through imaging, deformation vectors might be defined that track the motion of individual sub volumes within the rectum. Tracking motion of tissue sub volumes is the objective of implanted seeds in the prostate, but this does not give a comprehensive description of the movements. Yan and Lockman (2001) assumed that tracking motion of sub volumes was possible and investigated the impact of this knowledge on accumulating dose to the deforming rectum.

They set out a framework, where the rectal wall is modelled as a volume, V , containing a number of sub volumes, v . The position of any sub volume during the treatment at time, t , will be given by;

$$x_t(v) = x_0(v) + u_t(v), \quad (5.2)$$

where $x_0(v)$ is a vector describing the position of the sub volume at the time of planning, and $u_t(v)$, is a vector describing the possible displacement from that original position. For translations of the organ, $u_t(v)$ will be equal for all sub volumes. While for organ deformation, the value of $u_t(v)$ will differ depending on the position of that particular sub volume within the organ. Therefore, the description of the deformation will be a complicated function and a generalised description is needed. Yan and Lockman (2001) propose the general form of the displacement of a single sub volume as;

$$u_t(v) = u_t(v') + E_t \bullet [x_0(v) - x_0(v')] + \Delta \quad (5.3)$$

where $u_i(v')$ is a reference point, E_t is a rotation vector, and Δ is a non linear term describing deformation. The value of Δ will be zero for rigid body motion and non zero otherwise. The value of Δ will depend on the tissue properties (such as compressibility and tensile strength) of the organ in question.

The variation in dose is then calculated for two dose distributions, a conventional dose distribution and a dose distribution optimised for treatment uncertainties (Lind *et al* 1993). The amount of dose fluctuation is shown to be dependent on the position of the sub volume with respect to the dose distribution. These results concur with the dose PDFs illustrated in §4.3 of this thesis. A simplified model is used in the next section to simulate systematic and random motion error for the rectum.

5.3. Methods

A model has been developed in this work to simulate rectal wall movements during the course of an external beam prostate treatment. The movements are separated into shifts of the geometric centre of the rectum, and changes of the rectal wall radius to model rectal deformation. The rectal wall geometry is taken from transverse CT slices where both the inner and outer walls have been delineated.

5.3.1. ‘Original’ and ‘Initial’ rectum geometries

5.3.1.1. Original geometry

The shape of the rectum (rectum geometry) is taken from a multi-slice CT scan, where the inner and outer rectum walls were delineated. This series of delineated areas (in each CT slice) is the original rectum geometry. Consequently, the rectum $B(x,y,z)$ is a volume constructed from a set of sub volumes (voxels) in each transverse slice.

The rectum geometry in our model is characterised using the raw data from CT slices and is not exactly perpendicular to the rectum length. The geometric centre is located in the anatomical coordinate system, $GC(x,y,z)$. Figure 5.1 shows the rectal wall sub volumes each defined within rectal wall segments of area, A_0 , subtended by angle $d\theta$ with inner radius, $r_{in}(\theta)$, and wall thickness, $w(\theta)$. The resolution of the dose grid is employed to set the size of the rectal sub volumes, and therefore the number of rectal sub volumes is dependent on the resolution of the dose grid. Each rectal sub volume is of equal and

constant size.

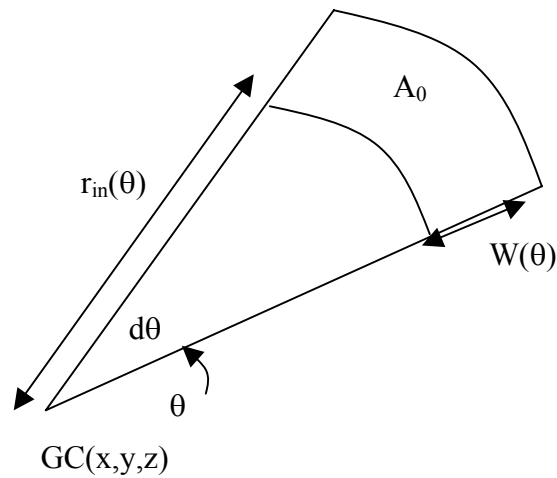


Figure 5.1 Schematic of the characterisation of the rectum geometry A rectal wall segment will area, A_0 , subtended by $d\theta$ of distance $r_{in}(\theta)$ from the geometric centre, and of thickness, $w(\theta)$.

Defining the size of rectal sub volumes by the dose grid resolution was done following some preliminary considerations. First, the original region of interest data set for the rectum was investigated to quantify the likely number of voxels in each rectal wall segment subtended in intervals of 1 degree. The original inner radii and wall thickness for a z slice are shown in figure 5.2 below. With mean radius $\sim 15 \pm 2$ (1 SD) mm and mean wall thickness $\sim 2 \pm 1$ mm the area of the ‘typical’ rectal sub-volume is $\sim 200 \text{ mm}^2$.

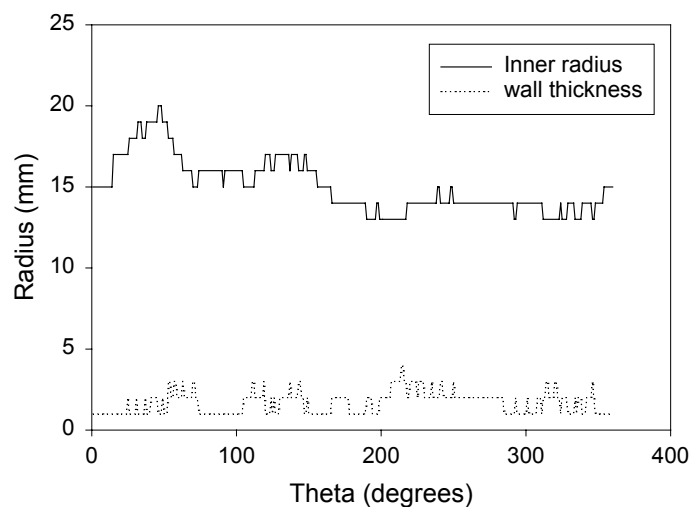


Figure 5.2 Plot of inner rectum wall radius, and wall thickness versus angle for a characteristic slice.

The subtending angle was selected to be small enough so that the characterisation is reduced, as close as possible, to 1D along the radius for each subtending angle. The perimeter of rectal wall included in the typical case above would be ~ 0.15 mm. Therefore for some angles, the ray line defining the rectal wall segment area will pass through the same voxels as adjacent ray lines. This is accommodated by scanning in only one direction (say, anti-clockwise to be congruent with the figures) and remembering which voxels have been counted.

The subtending angle of rectal wall sub volumes along the rectum length is used to construct the DSM. The DSM used in this thesis differs from those mentioned in the literature (Hoogeman *et al* 2001, Sanchez-Neito *et al* 2001). Both of these workers include the curvature along the length of the rectum. That is, the subtending angle of the rectal wall is measured perpendicular to the length of the rectum and the surface area is then weighted according to the vertical angle in that slice. Since this is only a small change we do not include curvature along the rectal length.

5.3.1.2. Initial Geometry

It is assumed that across patients and treatment fractions, the rectum geometry will be constant, but the position of GC (geometric centre of the rectum) may vary, and so will the rectum radius. Clearly, the sample geometry taken from a single CT image will not be sufficient to model the geometries across the patient population, particularly the size of the geometry. Thus, to increase the robustness of the rectum geometry, the *original* rectum geometry is scaled to conform to the population data accrued by Stroom *et al* (1999) giving the *initial* geometry. The scaling process is done to generalise the size of the rectum geometry (which might differ substantially from the population mean) following these steps.

First, the average outer radius (inner radius plus wall thickness) is calculated across all segments as follows:

$$\bar{r} = \frac{\sum_{z=0}^{N_z} \sum_{\Theta}^{360^\circ} (r_{in}(z, \Theta) + w(z, \Theta))}{N_z \cdot 360} \quad (5.4)$$

for the number of CT slices, N_z . The population mean radius, \bar{r}_{pop} , from Stroom *et al*

(1999) is then used to derive a scaling factor, \bar{r}/\bar{r}_{pop} , to scale the individual rectum radii in the original rectum geometry.

5.3.2. Modelling rectum deformations

The MC based method used in the current investigation is similar that used to model the effect of rigid body translations of the prostate (c.f. §4.3.1). Two steps are modelled for each patient (planning and treatment delivery). However, at each time interval the rectum will deform and the geometric centre of rectum will translate. The translation of the geometric centre needs little explanation because it follows the previously outlined methods for modelling prostate translations. Thus, this section is dedicated to explaining the theoretical considerations taken to model rectum deformation

Deformations of the rectum are modelled as changes in rectum radius from the population mean radius (n.b. all input parameters are discussed in §5.3.5.2). The magnitude of the inter fraction change in radius is sampled from the distribution of rectum radii (provided in Stroom et al 1999). A single sampled variable, ζ , is used to deform the entire rectum. Since the magnitude of the sample change in radius will depend on the initial radius in that segment of rectum wall a scaling procedure is performed. For inner rectum radius $r_{in}(z,\theta)$ a scaled change in radius, $\Delta r(z,\theta)$, is calculated from the sampled variable:

$$\Delta r(z, \Theta) = \zeta \cdot \left(r(z, \Theta) / \bar{r}_{pop} \right) \quad (5.5)$$

Effectively this means that if the rectum radius in a particular z slice is smaller than the mean radius along the length, the change will be reduced from the sampled change. Conversely, those sections of rectum wall with radius larger than the mean radius will have increased change from that sampled value. From examining rectum geometries across patients in the clinic, it is believed that the scaled change of radius is more accurate than assuming a uniform change of radius for all z slices. The scaled change of radius will however be less accurate than methods acknowledging the biomechanics of rectal tissue that allow each rectal wall segment to be scaled, not only with initial radius but with adjacent wall segments also (Yan and Lockman, 2001).

Another assumption is that following each change of radius the rectal wall segment area is kept constant. This infers two main considerations: that the rectal volume is constant, and

that the wall thickness of each rectal wall segment will change accordingly. Figure 5.3 demonstrates typical changes of wall thickness implied by the assumption of constant rectal wall segment area.

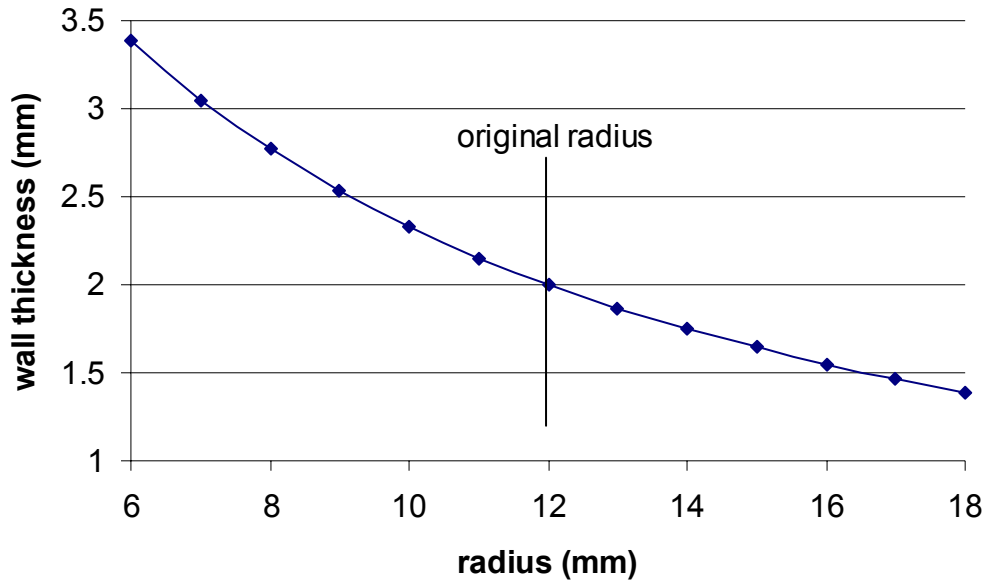


Figure 5.3 Calculated wall thickness (equation 5.7) with changes of rectal wall radius.

A number of studies in the literature have measured the change in rectum volume (Tait *et al* 1993, Melian *et al* 1997, Pavel *et al* 2001). Melian *et al* (1997) show systematic differences in rectum volume (including contents) of $\sim 50 \text{ cm}^3$ between patients and $\sim 30 \text{ cm}^3$ between fractions for a single patient. Pavel *et al* (2001) measured the standard deviation in rectum volume to be 22% of the original volume. No studies were found in the literature that measured the inter fraction change in *rectal wall* volume. In this thesis constant *rectal wall* volume is assumed. Wall thickness changes to maintain constant rectal wall volume.

Figure 5.4 identifies the symbols used to describe changes in rectal wall thickness. The change in wall thickness, $\Delta w(z, \theta)$ can be calculated from the original segment area;

$$A_0 = \pi \left[(r_0 + w)^2 - r_0^2 \right] \quad (5.6)$$

Rearranging equation 5.6 and solving the quadratic equation in wall thickness gives:

$$w = -r_0 \pm \sqrt{A_0/\pi + r_0^2}, \quad (5.7)$$

where only the positive root is a physical solution. For deformed radius, r_{def} , the deformed wall thickness is then;

$$\Delta w = -r_{def} + \sqrt{A_0/\pi + r_0^2} . \quad (5.8)$$

where $r_{def} = r_0 + \Delta r$.

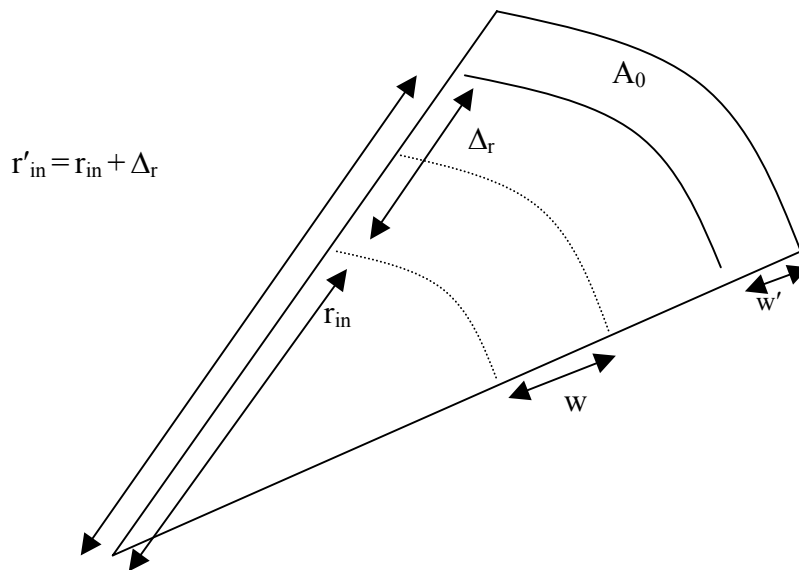


Figure 5.4 Rectum segment has constant area. Dashed segment is original segment.

5.3.3. Modelling planning CT image acquisition

For the purpose of modelling we assume that mean positions of the prostate and rectum as well as mean rectum radius is known for the patient population. For a single patient, the rectum position and dimensions at the time of the planning CT acquisition will differ from the population mean, but the average position and dimensions will be close to that for the population over an entire fractionated treatment.

The rectum dimensions as imaged in the planning CT scan will differ from the true rectum dimensions (in a similar way to the prostate position at planning). In each z plane they are sampled from the radius distribution to vary about the population mean dimensions. Movements of anterior rectal wall will influence the position of the prostate. We assume that these movements are correlated. Therefore variance of the rectum radius distribution combined with that of the geometric centre (GC) of the rectum should sum to the variance

of prostate movement. Lateral rectum deformations will not impact on prostate position and SI deformation is not modelled.

The geometric centre of the rectum will be shifted in the planning CT image from the true position as mentioned in §3.3.1 for the prostate. Briefly, the position of the mobile organ at the time of CT imaging will be a sampled position in the distribution of possible organ positions.

Averaging multiple rectum dimensions and positions from multiple temporally spaced CT image sets will undoubtedly improve the estimation of the mean rectum dimensions about the geometric centre of the rectum. Multiple pretreatment imaging to average dimensions and location is modelled. Clinically, in most cases, the clinician would improve the definition of CTV following each successive image set acquisition and may use reduced margins (c.f. equation 4.11).

The initial rectum geometrical data and the pre-calculated dose distribution are placed on a 3D Cartesian grid (see figure 5.5). A shift of the geometric centre of the rectum is done over the dose grid for the entire organ. Figure 5.5b shows a simple shift of the rectum GC posteriorly. For the calculation of biological indices in the next chapter (c.f. §6.2.2) the prostate is assumed to move with the anterior rectal wall contrary to the depiction in figure 5.5b.

Deformation is calculated as a change in radius and requires a separate calculation for each rectal wall voxel. The rectal wall voxels are mapped by the treatment planning system on a Cartesian grid. Therefore sampled values of radius need to be related to the GC. The *Cartesian shift* is the change in position of a rectal wall voxel from the original (mean) position in Cartesian units. The Cartesian shift is calculated for each voxel as $\Delta x_{def} = \Delta r \cdot \sin(\Theta)$ laterally, and $\Delta y_{def} = \Delta r \cdot \cos(\Theta)$ in the AP direction. The deformation may be generalised by a change to the function defining the location of voxels allocated as rectal tissue, that is;

$$B(x, y, z) \Rightarrow B_{def}(x + \Delta x_{def}(z, \Theta), y + \Delta y_{def}(z, \Theta), z) \quad (5.9)$$

The average rectum dimensions, following multiple CT scans, can be calculated as;

$$\bar{B}_{CT}(x + \Delta \bar{x}_{CT}(z, \Theta), y + \Delta \bar{y}_{CT}(z, \Theta), z) \quad (5.10)$$

where

$$\Delta\bar{x}_{CT}(z, \Theta) = \frac{\sum_{i=1}^{N_{CT}} \Delta x_{CT,i}(z, \Theta)}{N_{CT}} \quad (5.11)$$

and similarly for the y deformation. Deformation in the z plane is not included in the model.

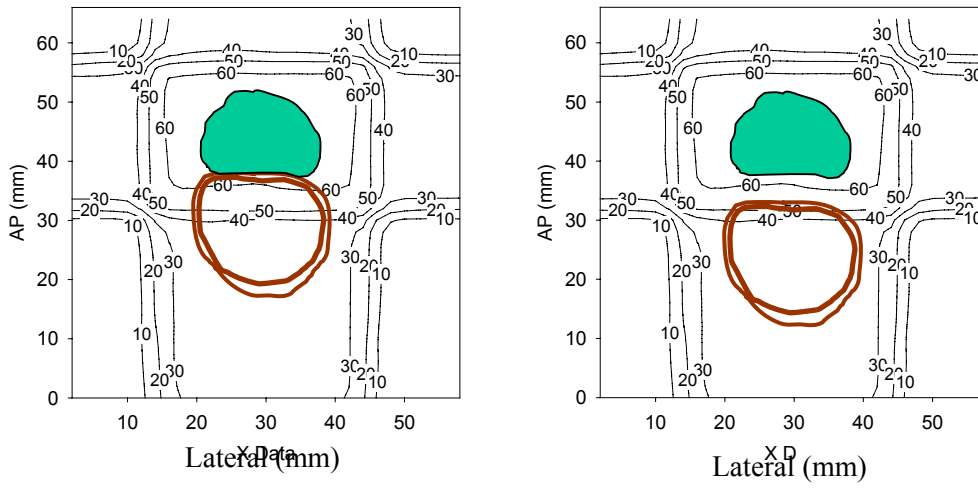


Figure 5.5 Modelling shifts of the rectum GC is done by shifting the entire organ within a fixed dose grid. a) The rectum GC position in the original CT planning image is compared to b) the position (shifted posteriorly) in a later fraction, or CT image acquisition.

As mentioned above, the geometric centre of the rectum as shown in the initial planning CT image will also not reflect the true mean geometric centre. Therefore, the average geometric centre of the rectum (over a few CT sessions) will have vector co ordinates:

$$GC(x + \Delta\bar{x}_{GC}, y + \Delta\bar{y}_{GC}, z) \quad (5.12)$$

where $\Delta\bar{x}_{GC}$ and $\Delta\bar{y}_{GC}$ are calculated similarly to $\bar{\xi}$ in equation 3.3 from N_{CT} pretreatment CT scans to improve localisation precision. The vector describing a shift of the geometric centre of the rectum will not depend on the z slice or the angle, θ , subtending that rectal wall segment.

The modelled treatment planning concludes with the sampled mean geometric centre of the rectum and mean radius (for each z and θ).

5.3.4. Modelling treatment delivery

Following each fraction the geometric centre of each transverse rectum slice will be described by the vector coordinates:

$$GC(x+\Delta x_{gc}(z), y+\Delta y_{gc}(z), z) \quad (5.13)$$

where $\Delta x_{gc}(z)$ and so on reflect a shift of the geometric centre from the original GC due to random interfraction setup errors and organ motion. The dimensions of the rectum will also change from the population mean dimensions, following equation 5.9 above, with Δx_{def} due to an interfraction change of rectum radius (deformation). No time trend has been modelled following a serial CT study in literature (Lebesque et al 1995) demonstrating constant random rectum wall motion.

To summarise, the dose deposited in each rectum wall segment will depend on the current position of that wall segment accounting for;

- o systematic change in the geometric centre (shift), $\Delta \bar{x}_{GC}$
- o systematic rectum radius error (deformation), $\Delta \bar{x}_{CT}(z, \theta)$
- o systematic patient position error (shift), $\Delta \bar{x}_{CT}$
- o random interfraction changes in the geometric centre (shift), Δx_{gc}
- o random interfraction changes in the rectum radius (deformation), $\Delta x(z, \theta)$
- o random patient position error (shift), Δx .

In order to calculate the dose to the voxel of tissue (moving during the treatment) the dose deposited to the *moving* voxels will then be translated to the *stationary* voxels in the original co ordinate system.

This is the dose *collected* by the moving voxels through the treatment process. Thus, at every fraction of the simulated treatment, the dose deposited into rectum voxels will exist in the dose grid co ordinates, $B \in D(x, y, z)$. This translates to the dose from voxel

$$D(x, y, z) \Leftarrow D(x + x', y + y', z + z') \quad (5.14)$$

where the primed variables include all of those uncertainties listed above. Explicitly, this may be expressed as;

$$x' = \Delta\bar{x}_{GC} + \Delta\bar{x}_{CT}(z, \theta) + \Delta\bar{x}_{CT} + \Delta x_{gc} + \Delta x(z, \theta) + \Delta x \quad (5.15a)$$

$$y' = \Delta\bar{y}_{GC} + \Delta\bar{y}_{CT}(z, \theta) + \Delta\bar{y}_{CT} + \Delta y_{gc} + \Delta y(z, \theta) + \Delta y \quad (5.15b)$$

$$z' = \Delta\bar{z}_{CT} + \Delta z \quad (5.15c)$$

In equation 5.15 lower case *gc* has been used to denote that this is an inter-fraction shift of the geometric centre. The use of capitalised *GC* is reserved for describing a systematic shift of the geometric centre. Changes in rectum dimensions will imply different changes of radius in each *z* slice and for each rectal wall segment. Therefore, a shift of rectal wall voxels due to deformation is dependent on *z* and θ in equation 5.15 above.

Dose is accumulated to rectal wall sub volumes (following equation 5.15) through 30 fractions of treatment. This process is repeated for a population of 1000 patients. Patient specific data is calculated with set systematic errors to evaluate the effect of full and empty rectum during the planning CT scan.

5.3.5. The input data

5.3.5.1. Geometry

The original rectum geometry and three planned dose distributions (reflecting three PTV margins about the same prostate CTV) were accessed from the Pinnacle (v5.2g) TPS. This particular TPS saves the dose matrix related to each incident beam in an easily located directory. Parameters relating to the dose matrix including matrix dimensions, grid size, and origin are saved by the software in a text file. The original rectum geometry is also saved in a text file. The original rectum geometry is represented as a series of Cartesian co ordinates. Each co ordinate is defined (in close to real time) as the ROI is being delineated in each CT slice. A linear interpolation is performed for the case where ROI points are separated by more than one voxel.

5.3.5.2. Uncertainty parameters

From the serial CT study performed by Stroom *et al* (1999) the parameter values for rectum size and position variations shown in table 5.1 were taken. The table also shows the values of patient positioning errors for prostate treatments.

Table 5.1 The parameters defining systematic and random changes in rectum geometry

Uncertainty parameter	Value (mm)
Population mean rectum radius, \bar{r}_{pop}	17.5
Systematic rectum radius standard deviation, Σ_r	6
Random rectum radius standard deviation, σ_r	3
Systematic patient position error, Σ_{SE} (LR,AP,SI)	2.4, 2.8, 1.6
Random patient position error, σ_{SE} (LR,AP,SI)	2.4, 2.8, 1.6

No statistics on the variability of the geometric centre of the rectum was found and therefore this parameter was set to zero.

5.3.6. Calculations

The mean and standard deviation in mean dose was calculated for a set of parameters. The parameters include the number of pretreatment CT scans (reducing the systematic error in prostate PTV field position), and the planned dose distribution used (reflecting three CTV-PTV margins). Calculations were performed to model a single patient with specified systematic error and also to model a population of patients with a sampled range of systematic errors across the population. For the individual patient calculation, the rectum radius in the single CT image set was specified to include a systematic error. Two systematic error values were used.

The first systematic error forced the rectum to be 2 standard deviations (~5.6 mm) larger than the mean rectum wall radius in the planning CT scan to model a full rectum at planning. This type of systematic error will force the sampled changes of radius (during the course of treatment) to be reduced from that in the planning CT image. The sampled changes of rectum radius will be symmetrical about the mean position. However, during

treatment delivery the rectum will tend to be further from the PTV.

The second systematic error conversely forces the rectum to be 2 standard deviations smaller than the mean rectum wall radius in the planning CT scan to model an empty rectum at planning.

The mean DSH is calculated using:

$$\overline{DSH}(d) = \sum_{i=1}^{N_{tx}} \frac{DSH_i(d)}{N_{tx}} \quad (5.16)$$

where $DSH_i(d)$ is the surface area taken to at least dose, d , for the i th patient.

The mean and standard deviation in the mean dose surface map are calculated for each rectal wall voxel. Each voxel is a segment on the interior rectal wall with location given by the subtended angle (refer to figure 5.1) and rectal wall length (increasing superiorly).

5.4. Results

5.4.1. Planned rectum dose distributions

The planned rectum dose distribution for each of the margins are summarised as dose surface histograms in figure 5.6, and dose surface maps in figure 5.7.

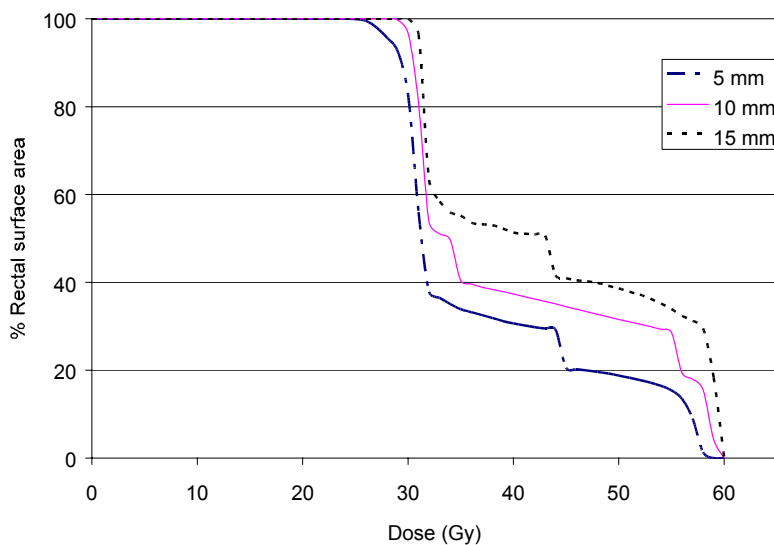


Figure 5.6 Dose surface histograms of the planned dose distributions with CTV-PTV margins of 5, 10, or 15 mm.

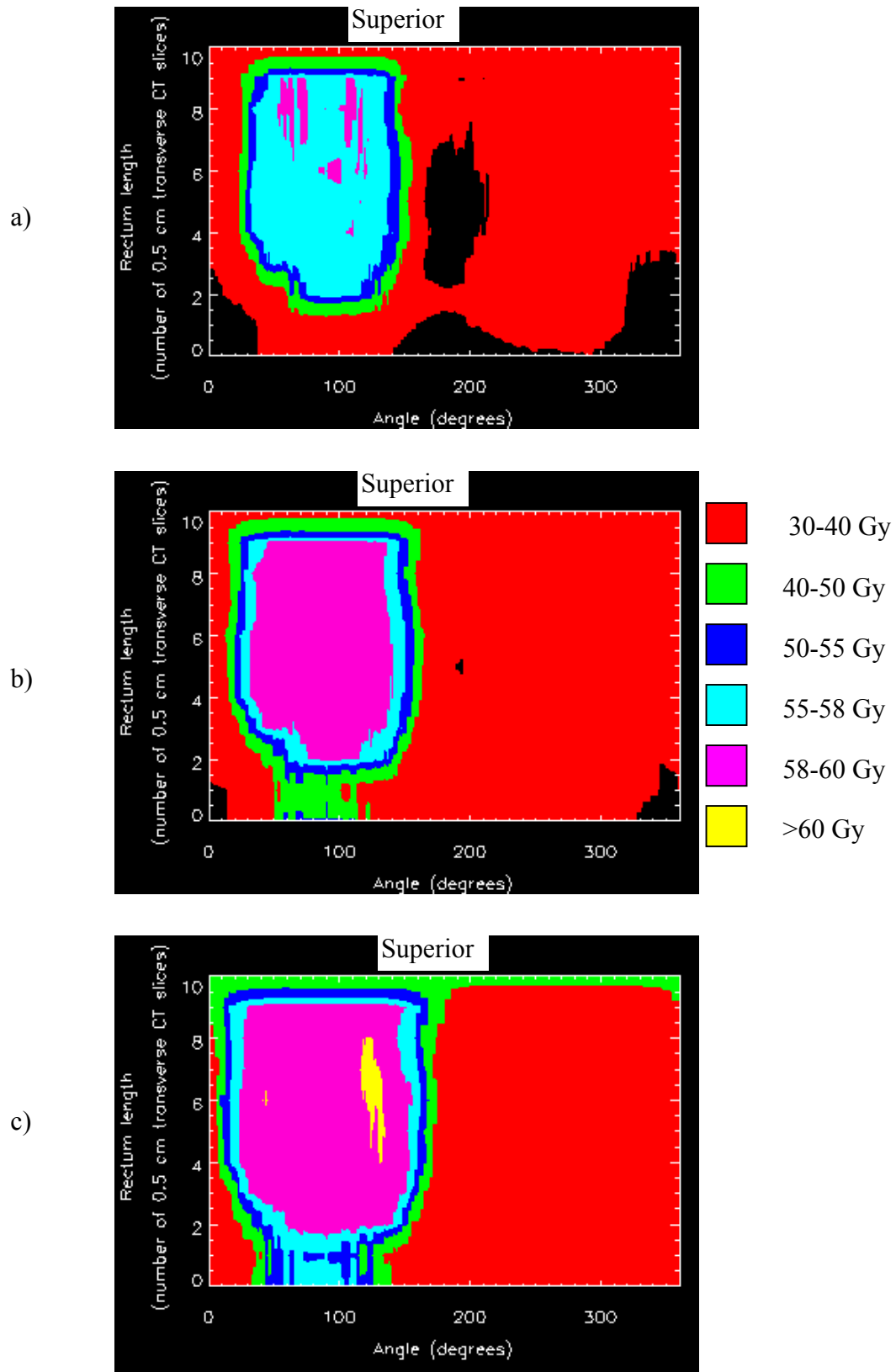


Figure 5.7 Dose Surface maps of the planned dose distributions with CTV-PTV margins of a) 5 mm, b) 10 mm, or c) 15 mm. Orientation: Left=0°; Anterior=90°.

5.4.2. Interfraction variations

The interfraction rectal wall deformations were simulated with a set systematic error and random interfraction errors. Two main cases were simulated: a patient with empty rectum at planning and a patient with full rectum at planning.

5.4.2.1. Systematic error: empty rectum at planning

The systematic error caused by an empty rectum at planning was modelled by setting the rectum radius decreased from the mean rectum radius. The set of dose surface histograms comparing the planned dose distribution, for each margin size, with the calculated mean dose distribution incorporating both the systematic and random errors is given in figure 5.8 below.

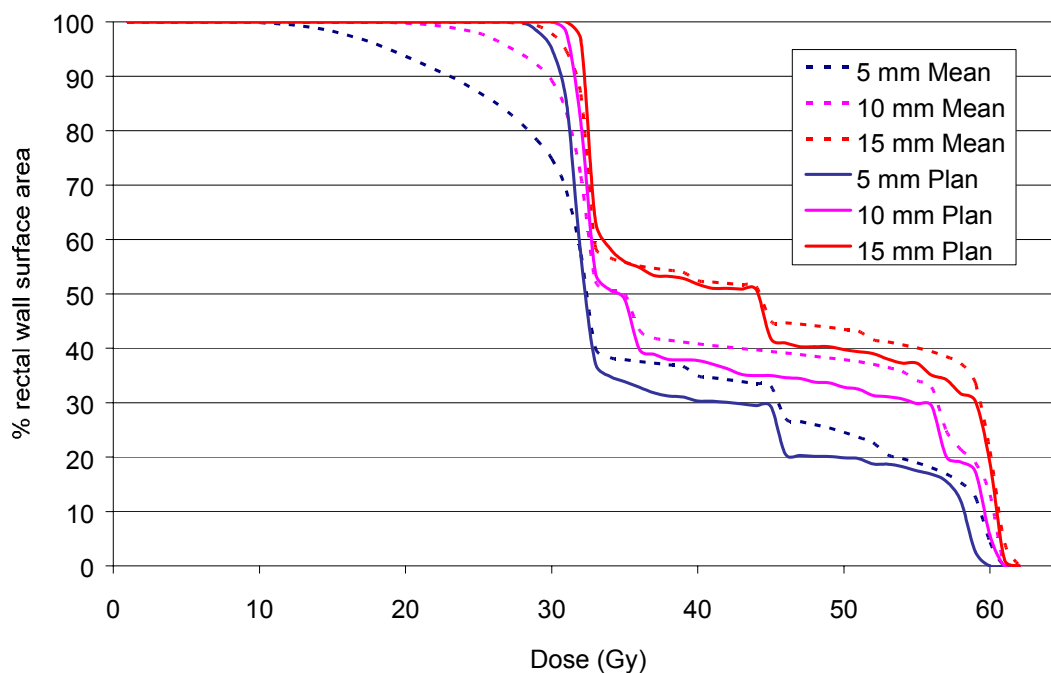


Figure 5.8 DSH showing the mean and planned dose distributions modelling an empty rectum at planning with three CTV-PTV margins.

Figure 5.8 shows two major trends; the percentage of rectal surface area receiving dose greater than ~32 Gy (53% of target dose) is generally increased from that planned, and the percentage of rectal surface area receiving dose less than ~32 Gy is generally reduced from that planned. This confirms the trend that an empty rectum at planning will generally shift the rectum into the PTV. The difference between the mean and planned dose is greatest

with the 5 mm margin. For example, the lowest planned dose with a 5 mm margin is ~28 Gy, but the lowest mean dose is ~10 Gy. Also the mean dose to 20% of the rectal wall is increased by ~7 Gy from the plan.

The difference between the planned dose and mean dose (i.e. $D_0 - \bar{D}$) is plotted in figure 5.9 below as dose surface maps for each margin size. These maps enable visualisation of the location of dose difference. In each of the dose surface maps the black sections infer that the range of values signified by colours has been exceeded. The mean dose is increased from the planned dose where $D_0 - \bar{D} < 0$. The range of difference values (i.e. $D_0 - \bar{D}$) reduces as the margin is increased, from -20 Gy to 22 Gy with the 5 mm margin to -18 to 7 for the 15 mm margin. This indicates reduced stability with the smaller margin.

With a 5 mm margin the increase in dose generally occurs in the inferior anterior rectal wall, with some portions receiving greater than 15 Gy below the planned dose. The reductions in dose generally occur in the posterior lateral wall coinciding with the PTV (i.e. the middle slices superiorly). The mean dose is reduced from the planned dose in some portions of the rectal wall by as much 15 Gy. However, over 60% of the rectal wall surface area has a mean dose within 5% of the planned dose.

With a 10 mm margin the increase in dose occurs in the inferior anterior rectal wall. The reductions in dose occur mainly in the right lateral wall. The largest increase in dose is greater than 15 Gy above the plan, while the largest decrease is less than 10 Gy below the plan. The 10 mm margin has greater than 85% of the rectal wall surface area within 5 Gy of the planned dose.

With a 15 mm margin the increase in dose occurs in the inferior anterior lateral rectal wall, with some small portions receiving greater than 15 Gy above the planned dose. Dose reductions are present in the anterior and posterior rectal wall; however, the maximum reduction in dose is only 5 Gy. The proportion of rectal wall receiving a mean dose relatively indiscriminate from the planned dose is about 95% of the surface area. Thus as the PTV is increased the effect of this systematic error (i.e. an empty rectum at planning) is reduced.

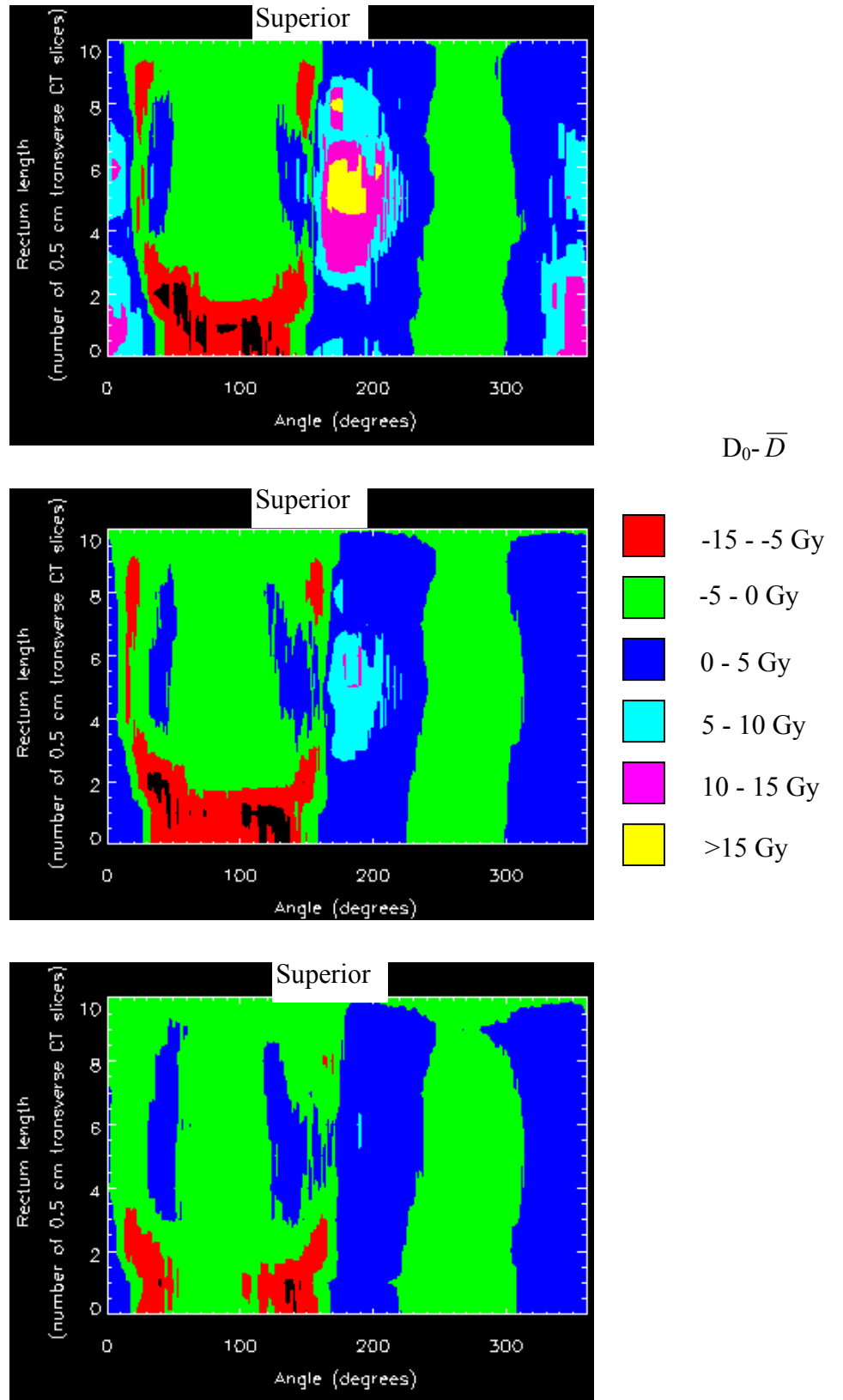


Figure 5.9 Dose Surface Maps showing the difference between planned and delivered rectal dose distributions with empty rectum at planning for a) 5 mm margin, b) 10 mm margin, c) 15 mm margin. Orientation: Left=0°; Anterior=90°.

5.4.2.2. Systematic error: full rectum at planning

Individual patient treatments were also simulated with the systematic error of a full rectum in the planning CT scan. This meant that the planning CT image set demonstrated the radius of the rectum to be increased from the mean value.

In this case, the surface area receiving high dose (>80% of target dose) is reduced from that planned for each margin as illustrated by the dose surface histograms (figure 5.10) below. This indicates that the isocentre is further from the geometric centre of the rectum, implying that during the course of treatment the rectum will be further out of the PTV than planned.

The planned dose distribution will generally predict greater dose to the rectal wall than it will actually receive. In the dose range from 35 Gy to 58 Gy the mean is about 5% reduced from the plan. Employing a 5 mm margin showed a larger reduction in the mean (~10% rectal surface area) at 55 Gy.

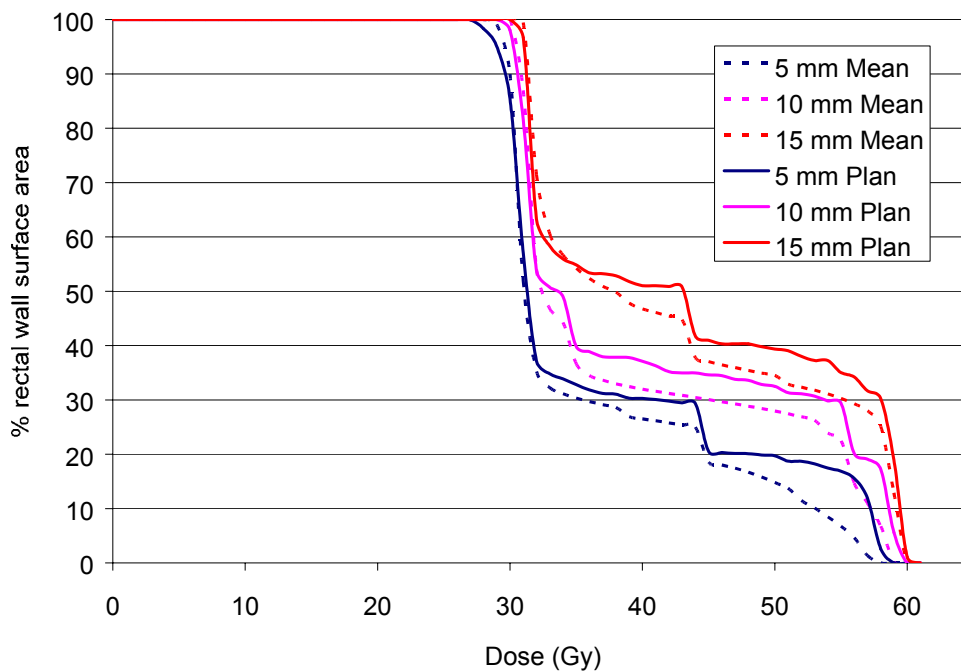


Figure 5.10 DSH for planned and mean (calculated) dose distributions with 5, 10, and 15 mm margins, including a full rectum at planning.

The location of discrepancy between the planned dose distribution and that delivered can be visualised using dose surface maps. The dose surface maps indicating the difference

between planned and mean delivered dose is illustrated in figure 5.11 (below) for each margin size.

Employing a 5 mm margin will cause an increase in the dose to the posterior rectal walls that is generally less than 2 Gy from the planned dose. Decreases in dose, as large as 16 Gy below that planned, occur in the lower anterior rectal wall. Despite this large magnitude of dose reduction, approximately 90% of rectal surface area will be within 5 Gy of the plan.

The mean rectal dose with a 10 mm margin shows increases in the posterior lateral walls of less than 2 Gy from the plan. The decreases in dose occur in the mid anterior wall, with deviations as large as 12 Gy below the plan. Approximately 85% of the rectal wall shows a mean dose that is relatively (i.e. < 5 Gy) unchanged from the plan.

With a 15 mm margin, a small increase (< 2 Gy) is present in the posterior lateral rectal walls. A decrease in dose is present in the lower inferior rectal and inferior portions of the lateral rectal walls. As with the other margin sizes, approximately 90% of the rectal surface area was within 5 Gy of the planned dose. Therefore this systematic error (i.e. full rectal at planning) appears to be relatively unaffected by the size of the PTV.

5.4.3. Interpatient variations

Across a population of patients a range of systematic errors will occur additional to the random errors. Figure 5.12 illustrates the rectal wall dose surface histograms from 20 sampled treatments including both systematic and random errors across the population (dashed curves) for each margin size tested. The planned rectal wall dose surface histograms for each margin are also shown (solid curves). The dose surface histograms in figure 5.12 include the extreme outcomes indicated in the previous section (c.f. figures 5.8 and 5.10) with fixed systematic errors (and possibly beyond) as well as many outcomes in between.

The mean rectal dose for each patient does not change significantly across the population. Furthermore, the planned and the mean dose distributions calculated with only one pretreatment CT scan are almost equivalent. This is due to the use of normal distribution for sampling systematic error combined with limiting the potential increase of the rectal wall diameter to the physical diameter of the pelvic inlet (which did not change between modeled patients since only one patient image was used).

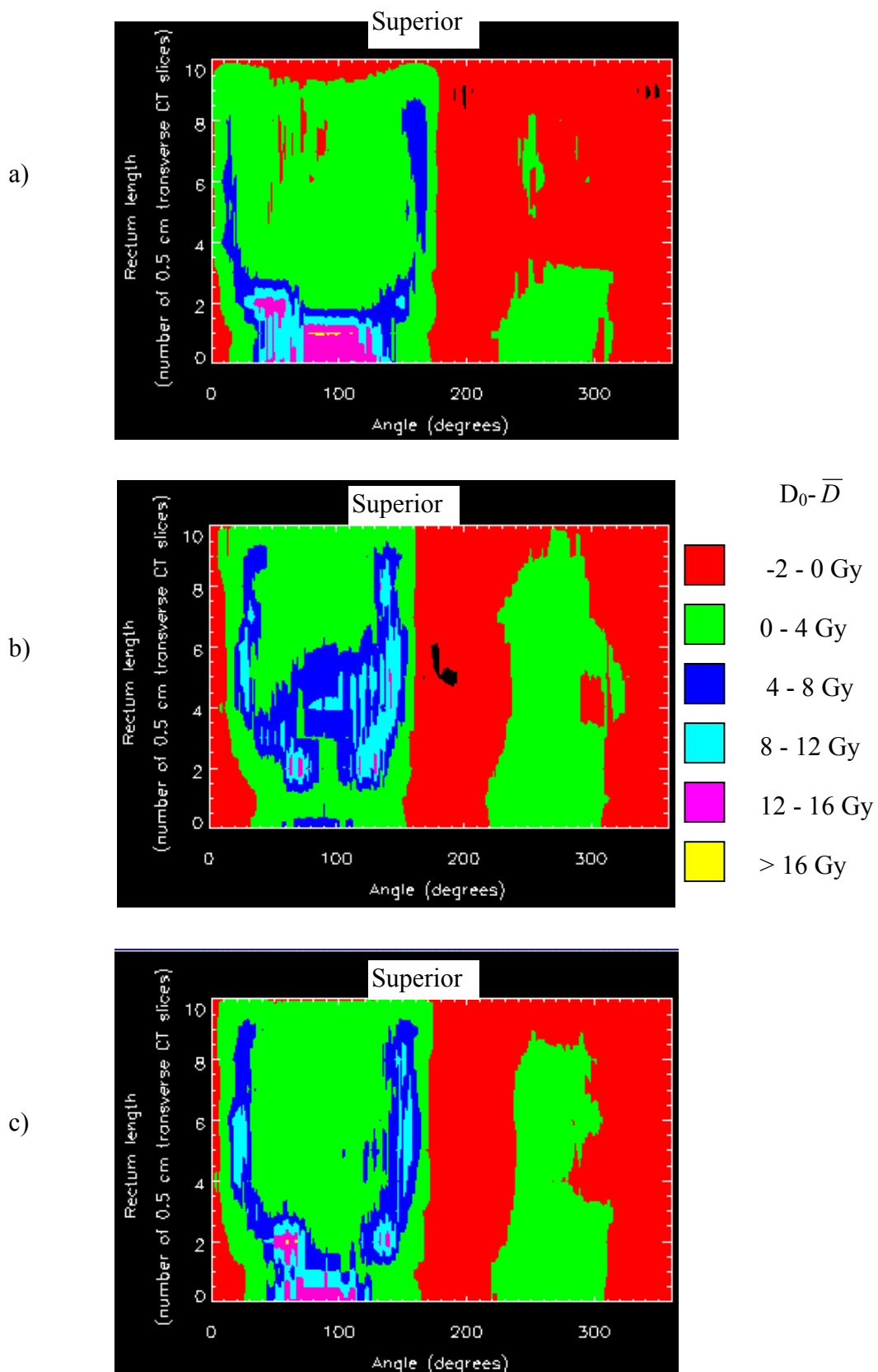


Figure 5.11 DSM showing where the difference dose occurs for margins of a) 5 mm, b) 10 mm, and c) 15 mm with full rectum at planning. Orientation: Left=0°; Anterior=90°.

The number of CT images would, of course, affect the standard deviation in the mean rectum position. As this number, N_{CT} , increases the standard deviation would be reduced as $\sim \frac{1}{\sqrt{N_{CT}}}$. Consequently, the number of pretreatment CT scans did not affect mean rectal dose. Therefore in this section the term, *mean dose*, will imply that a single pretreatment CT scan was used for planning purposes.

Despite the similarity between the mean inter-patient rectal doses, for all margins tested, significant differences did occur in the rectum dose for individual patients. This is reflected in the standard deviation in mean rectal wall dose (see figures 5.13, 5.14 and 5.15 below).

For the 5 mm and 10 mm margins, a large SD in dose did occur at three locations in the rectal wall, including; length-wise along the anterior lateral wall, in the lower anterior inferior wall, and in the middle (superiorly) of the right lateral wall. These locations lie in regions of dose gradient (c.f. planned DSMs in figure 5.7 above). Employing a 5 mm margin the anterior lateral wall of the rectum is positioned in the planned lateral penumbra of the dose distribution. The inferior portion of the anterior rectal wall is positioned in the planned inferior penumbra. The inferior portion of the rectal wall (below the 4th CT slice) has a smaller radius than the superior portion. The highly variable dose at 190° corresponds to the left lateral wall (approximately slice 5) where the planned dose is below 30 Gy due to the posterior and lateral distance from the prostate. The opposing (right) lateral rectum wall received a higher dose indicating that the rectum is not centred laterally in the field.

With the 10 mm margin, the interpatient dose difference in the left lateral wall was removed by averaging just 2 pretreatment CT scans. The left lateral wall has a higher planned dose with the 10 mm margin than with the 5 mm margin. Even with infinite pretreatment CT scans the variation in inferior anterior wall is greater than 2 Gy and the surface area with dose SD greater than 1 Gy extends along the anterior lateral wall aswell.

With the 15 mm margin the SD in dose is noticeably shifted posteriorly compared to the smaller margins (c.f. figures 5.13 and 5.14 above). The high dose surface area is increased in the inferior portion of the anterior rectal wall, and a band of SD (not present with smaller margins) occurs in the superior portion of the rectal wall. With a 15 mm margin the superior rectal wall is positioned in the superior-posterior dose gradient. As the margin size is reduced the dose gradient shifts inferiorly, away from the posterior rectal wall.

b)

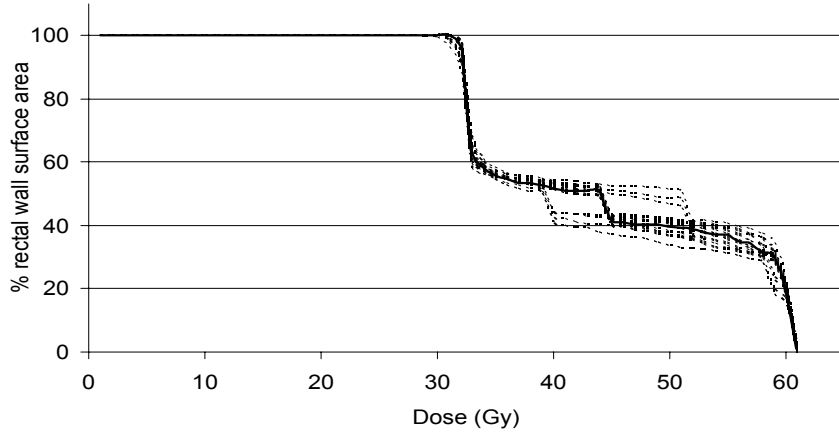
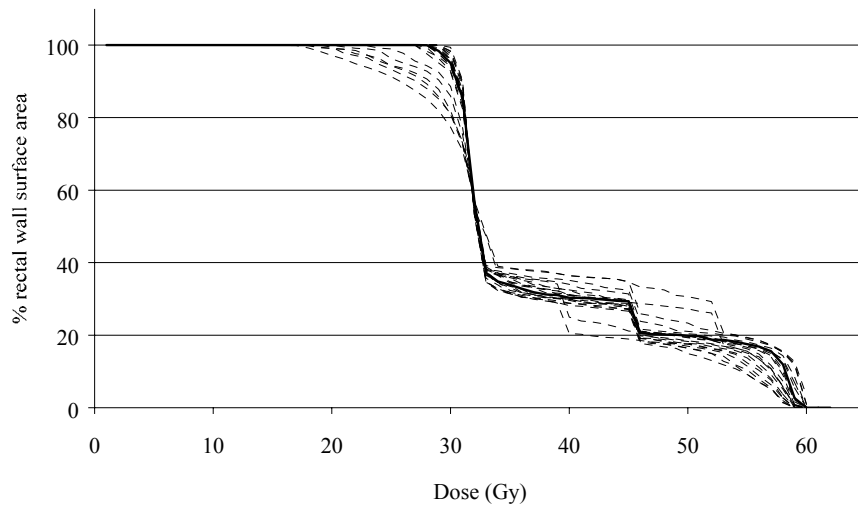
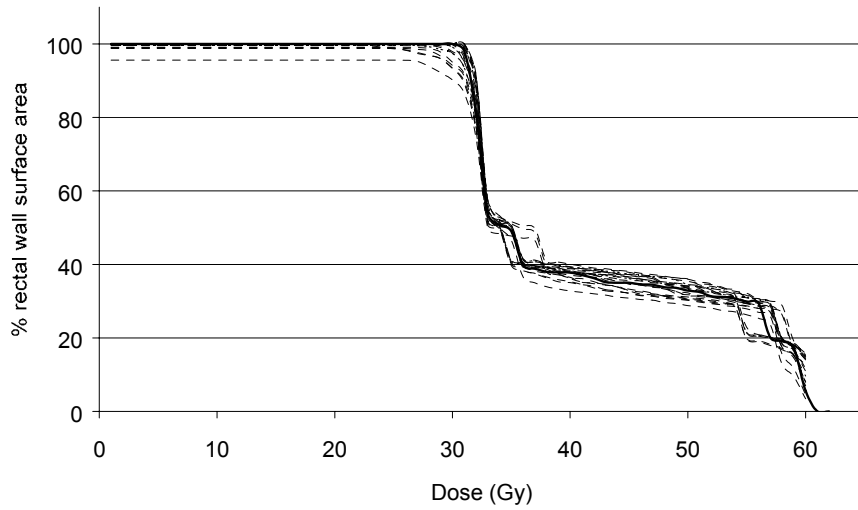


Figure 5.12 Dose surface histograms of the rectal wall for dose distributions with a) 5 mm b) 10 mm, and c) 15 mm margin. The three planned dose distributions are solid lines and the 20 DSHs including

c)



random and systematic errors are dashed lines. For dose greater than 32 Gy, the individual patient DSHs are symmetrical about the planned DSH across the population.

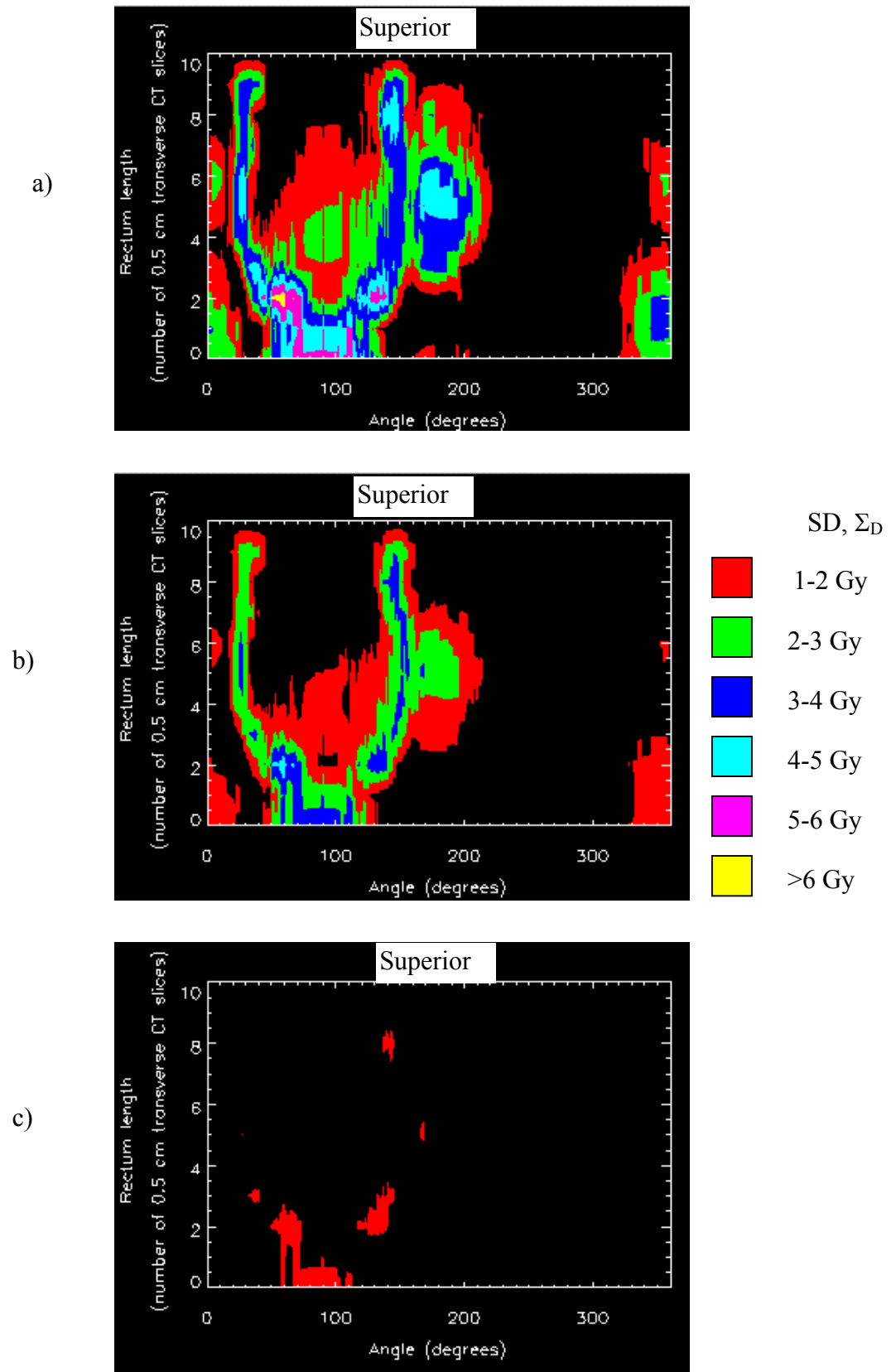


Figure 5.13 The standard deviation in rectal wall dose calculated with 5 mm margin and a) one pretreatment CT scan with, b) two pretreatment CT scans, and c) infinite pretreatment CT scans. Orientation: Left=0°; Anterior=90°.

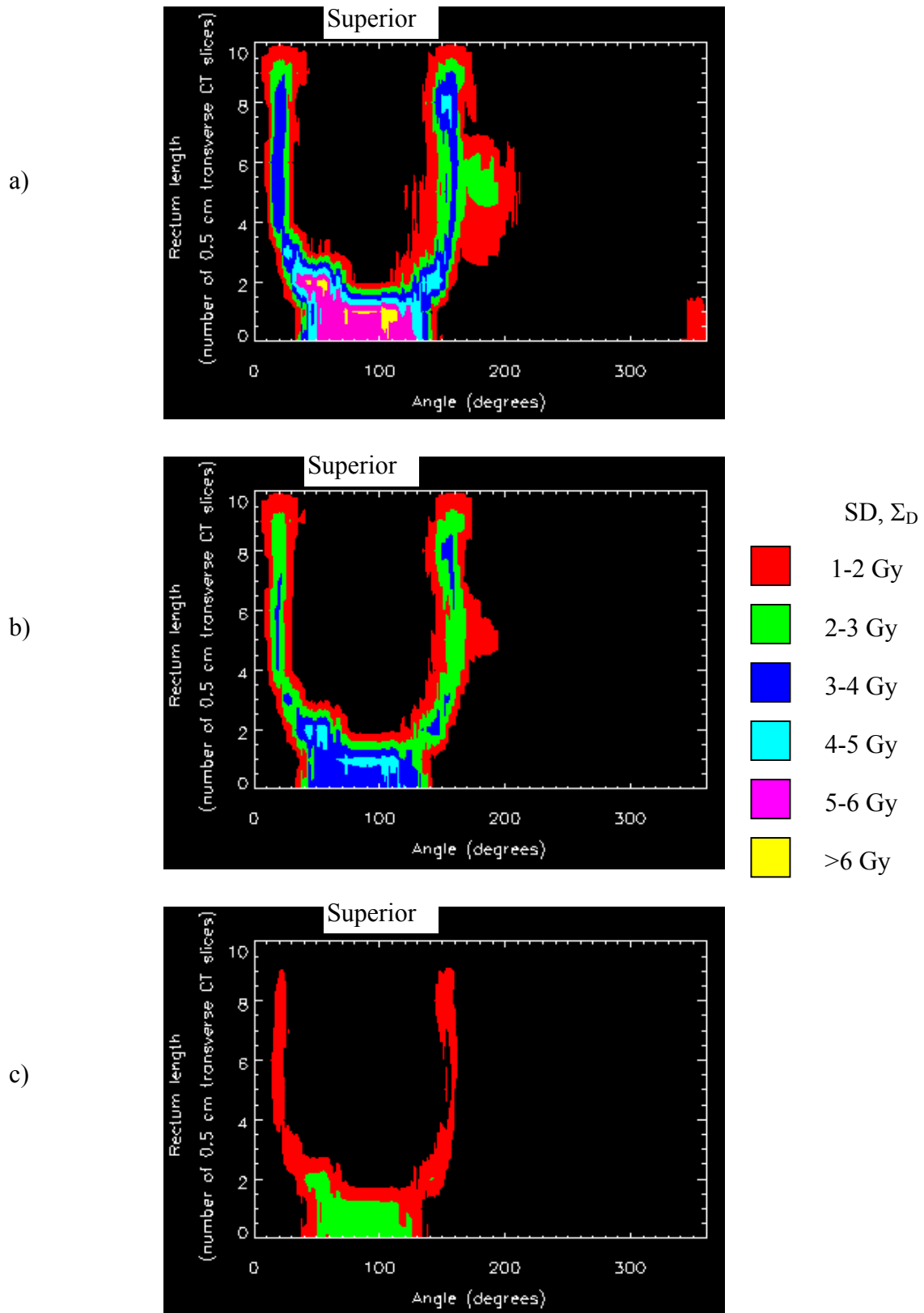


Figure 5.14 The standard deviation in rectal wall dose calculated with 10 mm margin and a) one pretreatment CT scan with, b) two pretreatment CT scans, and c) infinite pretreatment CT scans. Orientation: Left=0°; Anterior=90°.

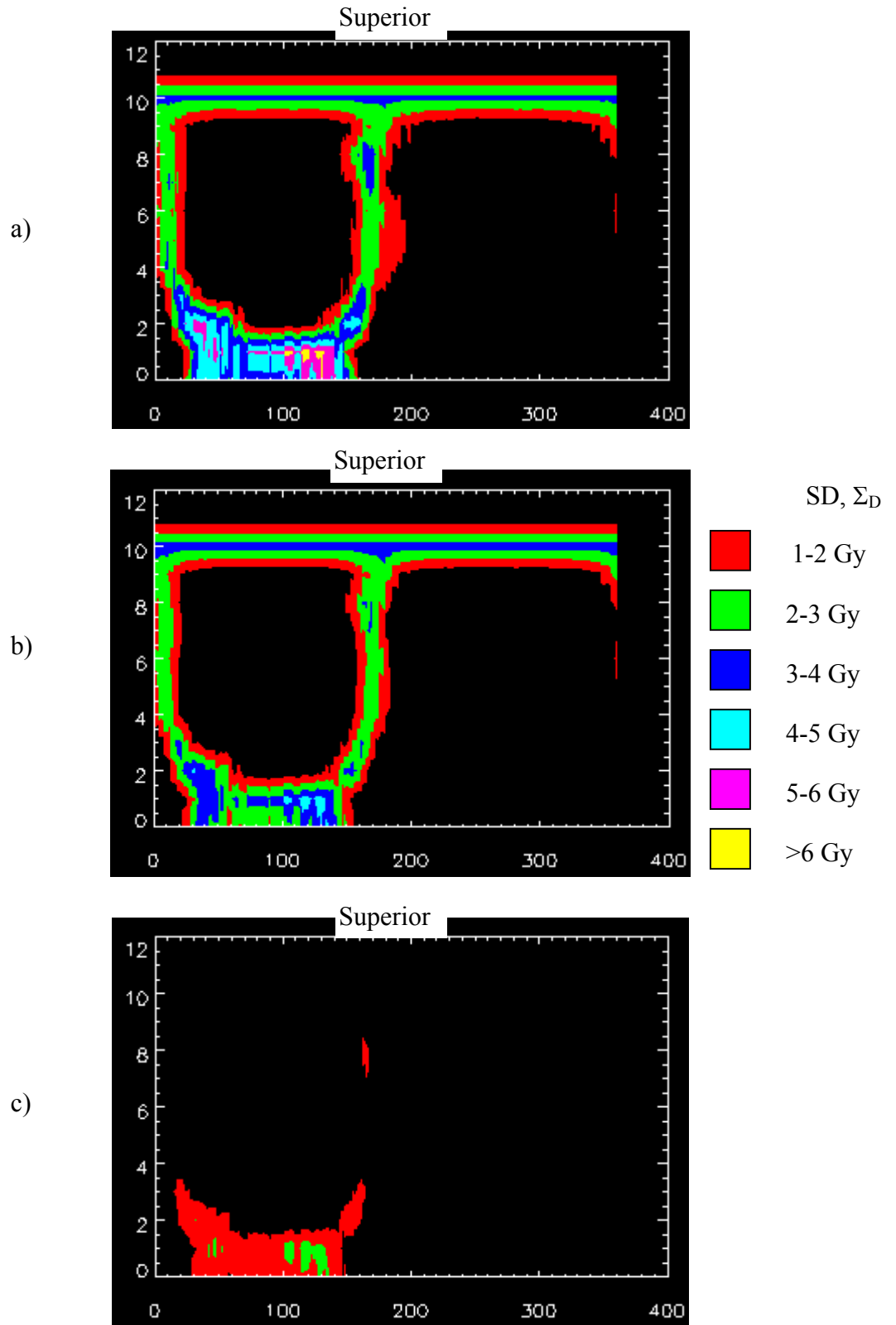


Figure 5.15 The standard deviation in dose presented as a DSM. A margin of 15 mm is used with a) one, b) two, and c) an ‘infinite’ number of pretreatment CT scan information. Orientation: Left=0°; Anterior=90°.

5.5. Discussion

The rectum will deform during treatment and this has been shown to impact on the individual patient and the population averaged dose distributions. The size of the margin is naturally of fundamental importance. Three margin sizes were modelled, and as the size of the margin was increased the rectal wall surface area receiving high dose increased.

For an individual patient with empty rectum at planning, the PTV will be placed closer to the position of the mean anterior rectal wall. The dose surface map shows increases in the surface area receiving high dose (greater than ~50% target dose) from that planned and lower percentages of surface area receiving low doses (less than ~50% target dose). For the smallest margin size (5 mm) the reduction in surface area receiving low doses is markedly greater than for the large margin size (15 mm). The mean dose surface maps show that the posterior penumbra is shifted posteriorly, in a similar way to increasing the margin size.

For an individual patient with full rectum at planning, the field will, predominantly, be placed further from the mean anterior rectal wall position. The DSH shows decreases in the surface area receiving high dose (greater than ~30 Gy), the maximum dose is reduced while the surface area receiving low dose (less than ~30 Gy) is marginally larger. The amount of surface area reduction at the higher doses is greater for the smaller margin. The mean dose surface maps show that for the 5 mm margin the posterior penumbra is brought anteriorly into the anterior rectum wall. The mean dose is deposited anterior to the plan for the other margin sizes as well. For the 15 mm margin this causes the superior border of rectal wall data set to interact with the superior-posterior penumbra.

With the simulated full rectum at planning systematic error, the difference between planned and mean dose was demonstrated with dose surface maps and appeared to be independent of the PTV. With each margin size about 90% of the rectal surface area was less than 5 Gy from the planned dose. However, the simulated empty rectum at planning indicated that the (relatively) unaffected fraction of rectal surface area increased from ~60% with a 5 mm margin to ~95% with a 15 mm margin.

The interpatient results show that mean dose to rectum will not be significantly different from the planned dose across a patient population. This follows directly from the assumption of a (symmetrical) Gaussian PDF to describe interpatient variation. Reduction

in the variability of rectal dose received occurs when the organ position is averaged across multiple pretreatment CT image sets, particularly with the smaller (5 mm) margin. The reduction in dose occurred in the areas of the rectal wall (from the planning CT) that coincide with planned dose gradient. The use of multiple pretreatment CT images further reduced this effect. Major benefit for the 5 mm margin was calculated for the anterior lateral wall, inferior anterior wall and a section on the left side of the lateral wall. The initial effect from sampling rectal wall position with one CT image was reduced with the 10 mm margin. With the 15 mm margin, the major location of interpatient variability in dose was a band around the superior portion of the rectal wall, but this reduced substantially with the use of information from multiple CT image sets.

The modelling of rectum deformation in this Chapter has a number of critical assumptions that impact on the results. Firstly, the interfraction variation in rectal wall radius is initiated from a single sampled variable, constraining the geometry in each transverse CT slice. This produces uniformity in motion along the length of the rectum that may not be present naturally. The alternative is to use a database of possible geometries and sample variations amongst and between those present in that database. However, in that case, much more data would need to be collected. In any case, the local deformations in the rectal wall shouldn't produce more than small areas of increased exposure (surface area) to target dose. Considering these factors, the current technique is still a good approximation and should give relatively sound and accurate results.

Secondly, the original data set may not be representative of the rectum geometry or size for the patient population. The first order approximation used included scaling this original geometry according to a measured distribution of inter-patient mean rectum diameters. While higher order techniques would produce more accurate modelling, the effect on dose is expected to be small.

Lastly, the changes in rectum radius were modelled about the geometric centre of the rectum. The model was developed to incorporate motion of the geometric centre, but no data was found in the literature and it would be a difficult (and not otherwise useful) parameter to measure. To some extent, motion of the geometric centre of the rectum was included in (and probably over compensated for by) the parameters defining motion of the rectal wall.

Clearly, a model incorporating mechanical data on the rectal tissues (such as described above, see §5.2) would produce meaningful generalised information on movement from a small number of measured parameters (Yan and Lockman 2001). That is, by measuring a fixed number of displacement vectors (tracking movement of labelled rectal wall voxels) further displacement vectors might be calculated based on the tissue properties. In this way, the ART process is made less labour intensive and more eloquent. It is important and useful to study the effect on rectal wall dose from those uncertainties present in current clinical practise.

This chapter investigated more comprehensive modelling of rectal wall deposition than that presented in the previous chapter. The rectum will change radius during treatment, and thus rectal wall tissue will displace towards, away, and laterally to the high dose target volume (respectively, in the case of rectum expansion for the anterior, posterior and lateral walls). Therefore, the assumption of linear translations of the whole rectum, such as has been described of the prostate is obviously an over-simplification.

The rectum has been included in many clinical studies of tolerance doses because of its proximity to the prostate, the high incidence of prostate cancer amongst men worldwide, and the implementation of techniques of IMRT used with dose escalation to treat the disease. A 60 Gy treatment was modelled in this chapter, however, in the current climate many centres may be treating to higher doses, as high as 90 Gy and potentially higher. Those centres treating to high dose will probably be using a more tightly conforming dose volume than the dose distribution created by a four field box technique. The results presented are dependent on the technique (mechanical dose delivery and dose computation) as well as the maximum dose. With sharper dose gradients a larger variation in dose will occur. Further study may be useful for a range of dose distributions (other than margin size differences) and a range of target doses.

5.6. Conclusions

The model of interfraction rectal wall motion studied in this chapter produced knowledge of the most probable dose deposited in rectal wall tissue.

Individual patients with treatments designed using a CT image set where the rectum is larger than average will receive substantial reductions in mean dose from that planned. The

largest effect will be with a 5 mm margin.

Conversely, those individual patients with treatments designed using a CT image set where the rectum is smaller than average may receive larger areas of rectal wall with high dose. Again the plan with a 5 mm margin is more sensitive to dose variation than the plans with larger margins.

Across a population of patients, a Gaussian interpatient systematic error, will not largely affect the mean rectal dose. However, the inter-patient variation in rectal dose will be significant. For the 5 mm margin, the major dose uncertainty occurred in the anterior lateral rectal wall, the inferior anterior wall, and (for the chosen case) in the left lateral wall. The later dose uncertainty occurred due to the particular geometry dictating that the left lateral rectal wall was lateral to the lateral penumbra. The averaging of rectal position in multiple pretreatment CT scans reduced the variability in delivered dose across the population for this margin. For the 10 mm and 15 mm margins, averaging rectal position from extra pretreatment CT scans did not have as marked an effect as for the 5 mm margin. The position of dose gradient (posterior penumbra) moves posteriorly as the margin is increased. Thus, for the 10 mm margin, the size of the left lateral wall dose variation is reduced. The posterior location of the dose uncertainty is present further posteriorly with the 15 mm margin and the superior limit of the rectal wall data set begins to be affected by the superior-posterior penumbra.

Overall, the individual patient may receive up to 15 Gy (i.e. 25% of target dose) above or below that planned depending on the rectal geometry in the planning CT image set. The majority of dose uncertainty occurs in the lateral rectal walls and therefore the change in high dose volume (i.e. that volume receiving >80% CTV dose) is not significantly variable.

Chapter 6

Modelling the radiobiological effect of treatment uncertainty in radiotherapy

6.1. Introduction

The treatment of prostate carcinoma with external beam radiotherapy is performed with knowledge of treatment uncertainties. Consequently, a margin is selected that encompasses the tumour and ensures full (prescription) dose is given to the diseased tissue. As investigated in previous chapters, due to the treatment uncertainties, the dose deposited in the prostate gland and rectal wall will vary between fractions for individual patients, and will vary between patients across the treated population.

This chapter investigates the effect on Tumour Control Probability (TCP), Normal Tissue Complication Probability (NTCP) and Uncomplicated Tumour Control Probability (UTCP) from the uncertainty in delivered dose, and radiosensitivity.

6.2. Tumour Control Probability

The tumour control probability is the probability of completely eradicating all clonogens from the local tumour site. Much work has been done to characterise the survival of patients with prostate carcinoma following irradiation as previously outlined (c.f. §3.3).

In this section, two TCP investigations were done; 1D and 3D. The one dimensional case examined the broad context of the biological effect of the treatment errors. The 3

dimensional case examined a population of simulated prostate treatments, with feasible parameter values to investigate the best estimate of clinical impact from the treatment uncertainties.

6.2.1. Background

Interfraction movements of the prostate and beam will cause the delivered prostate dose to vary from that planned. The variations in dose delivered will impact on the individual's TCP, the mean TCP across the population and the standard deviation in mean TCP across the population. Brahme (1984) noted that small cold spots of low dose will drastically reduce tumour control. Conversely boosting a volume within the tumour has been shown to increase TCP by a relatively small amount. These are direct consequences of the form of the relationship between TCP and dose predicted by the models. As shown by the investigation into dose uncertainty done in this thesis, most dose uncertainty occurs at the beam edges. Current treatment planning techniques acknowledge this by ensuring a safety margin between the tumour and treated volume.

In 1988, Boyer and Schultheiss evaluated the impact of dose uncertainty using a convolution of TCP with a Gaussian function in dose. Clearly the use of a Gaussian dose PDF ignores the radial dose variation ($\sigma_D(r)$) previously derived (refer to §4.2.2). This chapter will investigate effects of these dose variations, as well as interpatient radiosensitivity variation, on tumour control.

6.2.2. Method

Tumour control probability is first calculated with a 1D dose profile and then a more detailed and (clinically) accurate calculation is performed. In this simulation a tumour and treatment field are both assumed to be spherical. Therefore the single dimension represents the radius of a sphere centred on a tumour. The 1D dose profile is used to investigate the impact of three separated issues; prostate motion combined with patient positioning error (spatially non uniform dose error), spatially uniform dose error, and inter-patient variation in tumour radio sensitivity. These three issues were simulated using field margins equal to 0.5 cm, 1.0 cm, and 1.5 cm.

Tumour control probability for the n th patient is calculated using (Webb and Nahum 1993):

$$TCP_n = \prod_{x=0}^{x=X} \exp[-r(x) \cdot V_t(x) \cdot S_n(D, \alpha, \beta, x)] \quad (6.1)$$

with clonogen density, $\rho(x)$, partial volume of annuli, $v_t(x)$, and the surviving fraction of the n th patient, S_n is dependent on the total dose deposited in tumour tissue, D , the tumour radio-sensitivity, α , and fractionation factor, β . The impact of three issues that contribute to uncertainty in tumour control is investigated.

For the spatially non uniform dose errors, the (laterally shifting) fraction dose is accumulated in tumour voxels (c.f. §4.3). The fraction dose for an individual's treatment is shifted laterally from the position planned for delivery. Thus, the fraction dose delivered to a voxel positioned a distance, Δx , from the planned position, x_0 , is given as:

$$d_i(x) = d_0(x_0 + \Delta x(\sigma_{TD})) \quad (6.2)$$

where Δx is the shift sampled from the treatment uncertainty distribution with standard deviation, σ_{TD} . The treatment uncertainty distribution describes position variations of the tumour relative to the incident fluence and has variance equal to the sum of the patient positioning error variance and the prostate motion variance (refer to equation 4.2).

The systematic impact of prostate motion due to use of a single CT image can be reduced by averaging tumour position from a number of pretreatment CT scans. Thus, the random position of the prostate (centre of mass) relative to bony anatomy is sampled from the prostate position distribution a number of times, and the average position is used to position the planned dose distribution.

For the spatially uniform dose error (c.f. §4.3) the fractional treatment dose, d_i , is perturbed from the planned dose giving:

$$d_i^* = d_0 + \Delta d_i(\sigma_d) \quad (6.3)$$

where d_0 is the planned fraction dose and Δd_i is the sampled dose variation for the i th fraction. The magnitude of the dose variation at each fraction is sampled from a (Gaussian) distribution with standard deviation, σ_d , equal to either 4 cGy (2%) or 10 cGy (5%) for each 200 cGy fraction.

Variation in patient tumour radio sensitivity across the patient population is modelled by sampling the individual's tumour radio sensitivity from the (Gaussian) population

distribution. Tumour control probability for the n th individual is then calculated with radio sensitivity given as;

$$\alpha_n = \alpha_0 + \Delta\alpha_n(\sigma_\alpha), \quad (6.4)$$

where the planned (or expected) cell sensitivity, α_0 , is varied for that patient by $\Delta\alpha_n$, which will be dependent on the standard deviation, σ_α , of the population distribution of radio sensitivities.

The impact of each of these issues is investigated in 1D with three dose profiles describing CTV margins of 0.5 cm, 1.0 cm and 1.5 cm.

Following the initial 1D investigation of the role and relative impact of each issue on TCP, a thorough 3D investigation was performed. The 3D case includes accurate geometrical description of the tumour volume, dose distribution, and tumour characteristics. TCP is calculated for both the individual (with set systematic error), and across a patient population. The population results are described by a mean TCP and the standard deviation in mean TCP.

6.2.2.1. Input data for 1D case

In one dimension, the dose distribution is described by a dose profile. This dose profile is achieved by averaging the steepest (oblique) and shallowest (horizontal) dose gradients from the four field box dose distribution. A representative dose distribution is shown in figure 6.1 below with straight lines indicating the profile orientations.

From the dose profile, the tumour plus CTV-PTV margin was assumed to occupy the space from the centre to the 95% isodose (see figure 6.2 below). This is in accordance with current treatment planning techniques that define the PTV before calculating the dose distribution.

Prostate volume was taken as a sphere with radius equal to the tumour radius. The original dose profile with a 1.5 cm margin was modified to dose profiles with smaller margins of 0.5 cm and 1.0 cm by deleting the central portion of the original profile. In this way the penumbra gradient is unchanged.

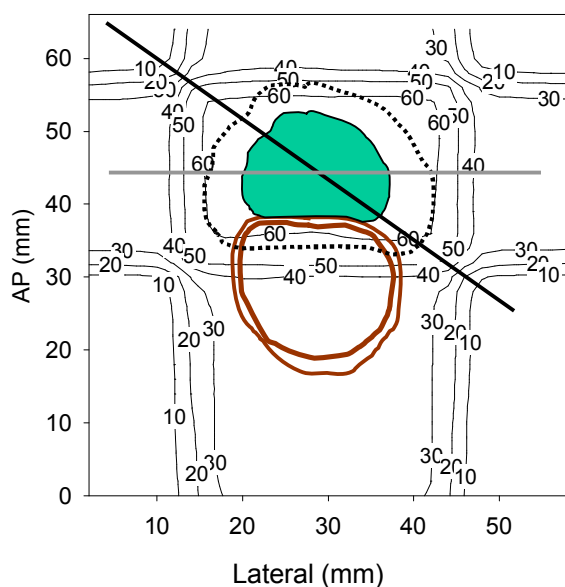


Figure 6.1 Isodose contours for typical prostate treatment. The CTV (solid and filled), PTV (dotted), and rectum (brown) are shown, with the oblique and horizontal lines indicating the position of dose profiles used.

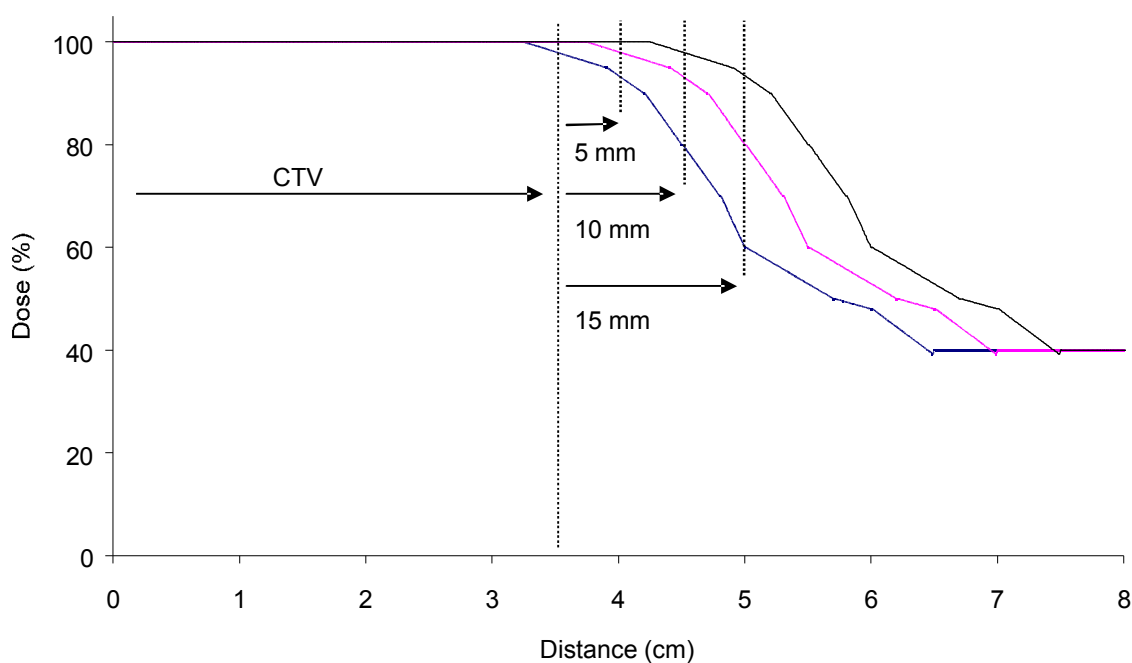


Figure 6.2 The dose distribution for 1D TCP calculations.

The prescribed dose to the isocentre is 60 Gy in 30 fractions over 5 weeks. The parameters used for modelling treatment uncertainties are given in table 4.1 with the exception of tumour radio sensitivity. No account for tumour repair or repopulation during this theoretical treatment is taken. The tumour has arbitrary volume 165 cm^3 (corresponding to

a radius of 3.4 cm), with clonogen density within the GTV of 10^7 cm^{-1} and LQ model parameters $\alpha = 0.35 \text{ Gy}^{-1}$, $\beta = 0.035 \text{ Gy}^{-2}$. Webb and Nahum (1993) fitted this value of cell sensitivity (α) to laboratory data for bladder cell survival and computed the required interpatient variation to be 0.08 Gy^{-1} (1 SD). Intratumour and inter-fraction variation in cell sensitivity are not included in the calculations.

6.2.2.2. Input data for 3D case

The prostate geometry, dose distribution and dose grid parameters were all accessed from Pinnacle³ TPS. The prostate geometry included the vector coordinates of a clinician outlined prostate region of interest in each transverse CT slice. The dose grid matched the superior-inferior positioning and spacing of the CT slices, and therefore coincided with the prostate geometry reference frame.

The prostate is considered to be constructed of prostate subvolumes (or voxels). The AP and lateral dimensions of each subvolume is defined by the dose grid, and the SI dimensions are defined by the CT slice thickness.

As with the 1D case (above) the parameter values for treatment uncertainty are given in table 4.1, with the exception of the interpatient radio sensitivity. The current literature describes the prostate (c.f. §3.3.3) by $\alpha = 0.29 \pm 0.08 \text{ Gy}^{-1}$ (Sanchez-Neito *et al* 2001b). This value was used in the following calculations. The value of β used was calculated for each patient using a fixed α/β ratio of 10 and their (sampled) α value.

6.2.2.3. Calculations

Tumour control probability is calculated with sample surviving fraction based on the linear quadratic (LQ) formalism (Fowler, 1989). Surviving fraction for the prostate sub volume at vector position, x , following an N fraction treatment is computed using equation 6.1 (above).

A Monte Carlo method was used to randomly sample dose as specified in equations 6.2 to 6.4. This was done for a population of 5×10^4 patients. Distributions of treatment dose were calculated for the population and used to compute the mean and variance of the treatment dose. TCP values were calculated for each patient from the population and then distributions of patient TCP were used to compute mean, mode and variance of the population TCP.

6.2.3. Results

Tumour control probability is presented using 1D and then 3D input data. The 1D investigation explores the impact of margin size, penumbra steepness and the number of pre-treatment CT scans with spatially non uniform dose uncertainty, and then investigates the impact of spatially uniform dose uncertainty and the inter-patient tumour radio-sensitivity. The 3D investigation follows with the inclusion of spatially uniform and non-uniform as well as inter-patient cell sensitivity heterogeneity with three margins in the calculation of mean TCP. These calculations include multiple pretreatment CT scans. The 3D data is also used to calculate the effect of certain systematic errors on TCP for the individual patient.

6.2.3.1. Impact of margin size

Calculations were performed using the 1D dose profile with margins of 0.5 cm, 1.0 cm, and 1.5 cm, and with a fixed magnitude of simulated treatment error. The planned dose distributions are shown in figure 6.2. The dose distributions with margins of 1.0 cm or 1.5 cm are planned to deposit 100% of prescription dose to the CTV, while the dose distribution with 0.5 cm margin will have slight penumbra in the edges of the planned CTV. In this case, the minimum planned CTV dose is 98% of prescription dose.

The mean TCP across a patient population is illustrated in table 6.1 and figure 6.3 below. The magnitude of the decrease in TCP from that calculated with the planned dose distribution is negligible for the population if CTV-PTV margins of 1.0 cm or greater are used. With the 0.5 cm margin, the reduction in TCP from the plan (at 60 Gy) is 0.07, and the surrogate loss of dose at planned TCP values of 0.5 and 0.8 are 0.7 Gy, and 1.4 Gy, respectively. The reduction in TCP indicates a shift of the mean TCP to higher dose, while the different loss of dose values at each planned TCP indicates that the slope of the mean TCP is also reduced from that planned.

The mean TCP calculated with 1.0 cm and 1.5 cm margins were very close (<1%) to the planned TCP. Similarly, for these margin sizes, the difference between the mode TCP and the plan was also small (<1%). Accordingly, improving the systematic positioning accuracy did not affect the mean or mode TCP for these margin sizes. However, the calculation of mean TCP with a 5 mm margin around the CTV was sensitive to systematic error.

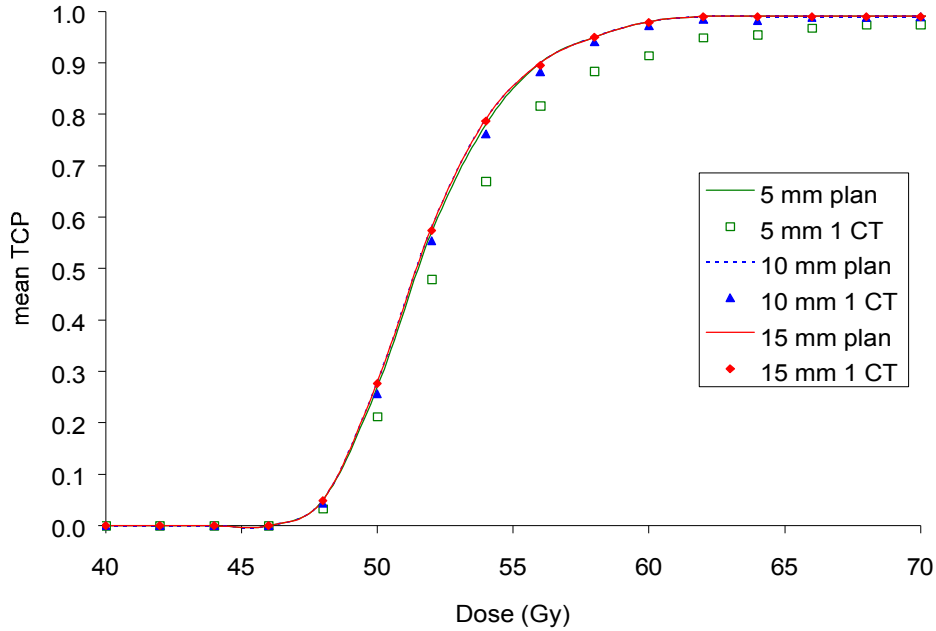


Figure 6.3 TCP calculated with planned dose distribution versus mean calculated with CTV-PTV margins of 0.5 cm, 1.0 cm and 1.5 cm (incorporating treatment uncertainty). The magnitude of treatment uncertainty is fixed for all cases.

Table 6.1 The effect of margin size on TCP incorporating treatment uncertainty. The difference between planned TCP and mean TCP with 1 CT (in percentage points), as well as the difference in TCP between the planned and calculated mean TCP are shown.

Margin (cm)	DTCP _{D=60 Gy}	DD _{TCP=0.5 (Gy)}	DD _{TCP=0.8 (Gy)}
0.5	7%	1.4	0.7
1.0	1%	0.4	0.5
1.5	<1%	0.04	0.05

To reduce the systematic component of prostate motion error, a number of organ locations may be averaged from pretreatment CT scans. Since the standard treatment will rely on a single pretreatment CT scan the nomenclature of mean and mode TCP will imply that this is the case, unless otherwise stated. The TCP calculated with the planned (or intended) dose distribution will be referred to as the planned TCP.

Figure 6.3 shows that the dose distribution with 5 mm margin will be sensitive to

systematic errors. In this case, multiple pre-treatment CT scans do lead to an increase in mean TCP. The reduction in (prostate motion) systematic error achieved by positioning the PTV based on 5 pretreatment CT scans improved the mean TCP by 3%.

The number of CT scans used to average organ location also plays a role in the repeatability of treatments. That is, the standard deviation in mean TCP is influenced by the systematic error. A reduction in the standard deviation in mean TCP for each margin by ~5% is possible by increasing from one to five pretreatment CT scans.

The variation in TCP for the individual patient across the population is described by the standard deviation. For the case with 1 CT and margins of 0.5 cm, 1.0 cm and 1.5 cm the peak standard deviation in mean TCP is 0.23, 0.1, and 0.04, respectively.

Population statistics allow further generalisation to the most probable patient outcome, when each of the uncertainties is separately considered. The mode of TCP versus dose, shown in figure 6.4 illustrates steep transitions from low TCP to a high TCP across the population matching the planned (or expected) outcome.

6.2.3.2. Impact of penumbra steepness

The literature (van Herk *et al* 2001) suggests that a radiation beam profile can be described by the convolution of a square function with a Gaussian distribution (with standard deviation, σ_p) describing the penumbra (c.f. §2.7.1). The values of σ_p from the four-field prostate dose distribution were measured to be ~5 mm across the oblique and ~6 mm laterally. For a single beam in plane geometry incident on a water phantom the value of σ_p is ~3 mm. With some delivery techniques, the penumbra gradient may be greater than that typically produced with the 4-field beam orientation and it is useful to investigate the impact of such penumbra gradients. Thus, the mean TCP and its variance were calculated with such a dose profile.

The difference between the planned TCP and mean TCP is shown in table 6.2 (below) for each of the margin sizes. Comparing this table with table 6.1 for the original dose profile, the main difference is the value of $\Delta D_{TCP=0.8}$ for the 0.5 cm margin. This dose difference at TCP = 0.8 is triple the value of that calculated with the averaged four field dose distribution. This emphasises that geographical misses of the tumour volume will be less well tolerated (in terms of TCP) if the penumbra width is small. With sharply defined high dose volumes the margins may need to be larger than with conventional techniques to

accommodate this.

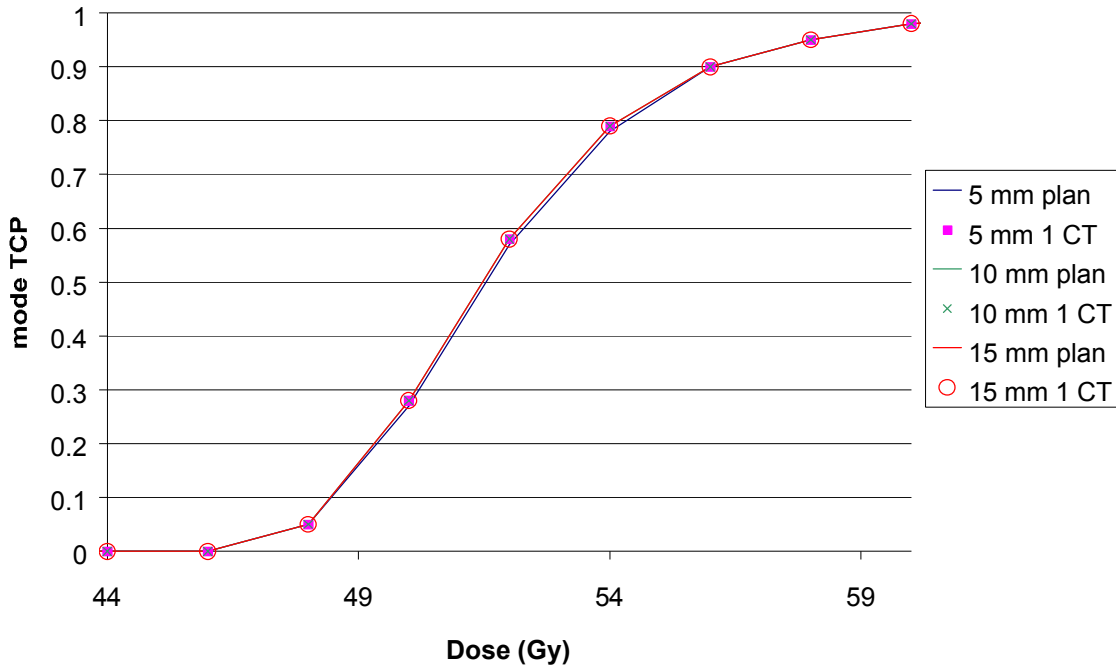


Figure 6.4 TCP calculated with planned dose distribution versus mode TCP calculated with CTV-PTV margins of 0.5 cm, 1.0 cm and 1.5 cm (incorporating treatment uncertainty). The magnitude of treatment uncertainty is fixed for all cases.

Table 6.2 The effect of margin size on TCP incorporating treatment uncertainty and steep dose gradient. The difference between planned TCP and mean TCP at a 60 Gy dose level (in percentage points), as well as the difference in dose between the planned and calculated mean TCP at two levels of TCP are shown.

Margin (cm)	DTCP _{D=60 Gy}	DD _{TCP=0.5} (Gy)	DD _{TCP=0.8} (Gy)
0.5	10%	0.7	2.2
1.0	2%	0.2	0.3
1.5	<1%	0.05	0.07

Additionally, for the 0.5 cm margin, the mean TCP rises very slowly ($\Delta D = 30\text{Gy}$) from TCP=0.9 to 0.95 (as shown in figure 6.5). This is a consequence of the severe penalty for a large shift of the tumour relative to the fluence. Clearly, if the tumour is adequately covered by the PTV then mean TCP will not be affected by the spatially non uniform dose

error. This is supported by the results for the 1.0 cm and 1.5 cm margins that show only modestly greater values with the smaller penumbra width than the previous results in table 6.1.

The sharper penumbra causes an increase in the standard deviation in mean TCP (see figure 6.5). Thus, a larger variation in tumour control is evident. The peak values of the standard deviation in mean TCP are 0.31, 0.15 and 0.06 for the 0.5 cm, 1.0 cm and 1.5 cm margins respectively. This represents increases of 0.07, 0.05 and 0.02, respectively. The mean TCP also extends to a higher dose level than with the conventional four field dose distribution which emphasises the harsh penalty for geographical misses.

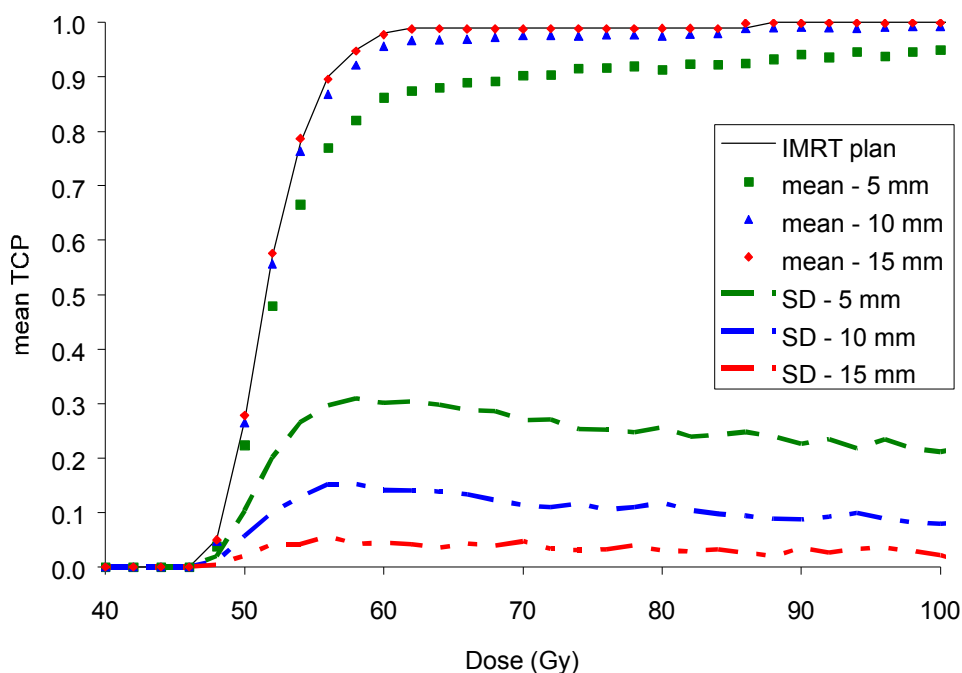


Figure 6.5 Mean TCP calculated using dose distribution with steep penumbra compared with the standard dose distribution.

6.2.3.3. Impact of uniform dose uncertainty and interpatient heterogeneity

Intuitively, the margin size should not affect the variation in TCP due to uniform dose uncertainty or interpatient heterogeneities because the TCP is calculated with dose to CTV voxels. Since the margin size (with the exception of margins of less than the distance between 100% and 95% dose) will not affect the planned CTV dose then it will not affect TCP incorporating the spatially uniform dose uncertainty or interpatient heterogeneity.

Thus, the results presented include the 1.5 cm margin alone.

Figure 6.6 shows mean TCP calculated including spatially uniform dose errors, spatially non uniform dose errors and mean TCP with interpatient variation in tumour radio sensitivity.

The spatially uniform dose uncertainty causes a small decrease in TCP(D) slope. There are two possible causes for this reduction in slope. The first is that this could be due to the variation in dose per fraction, since the corresponding mean treatment dose for a population of patients is indiscriminate from the original dose profile. However, the total dose is not fixed for a patient. Therefore, variations in the total patient dose will exist and these are likely to affect mean population TCP as illustrated in figure 6.6.

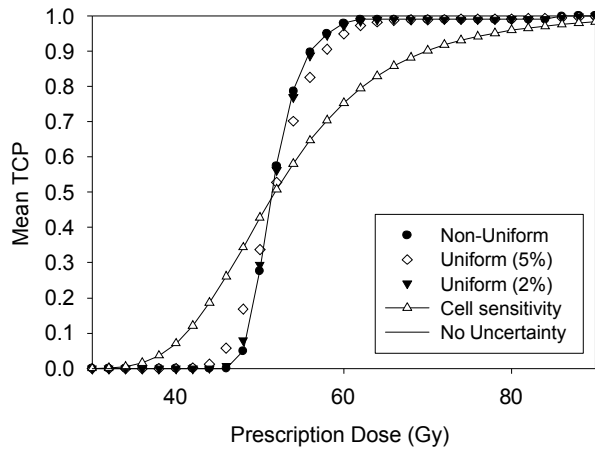


Figure 6.6 Mean tumour control probability for treatments incorporating nonuniform dose uncertainty, uniform dose uncertainty and varying cell sensitivity interpatient.

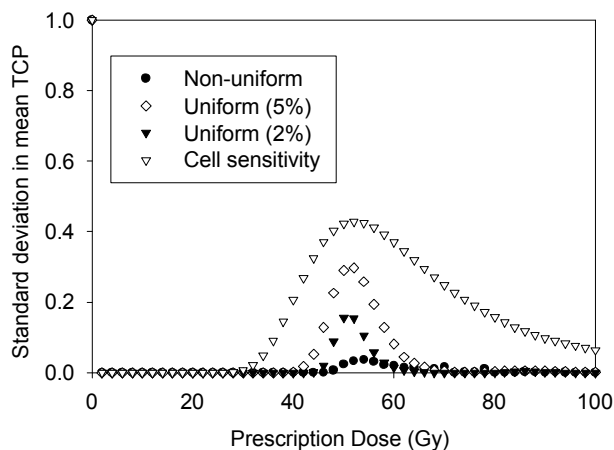


Figure 6.7 Standard deviation in mean tumour control probability incorporating spatially non uniform dose uncertainty, spatially uniform dose uncertainty and varying cell sensitivity inter patient.

The variation (1 standard deviation) in TCP at particular dose levels is shown in figure 6.7 for each of the uncertainties. The magnitude of uncertainty in mean TCP for a given dose level is dependent on the slope of the TCP(D) curve at that dose level. The magnitude of the variation (1SD) in mean TCP is shown to be large and can be larger than the mean value itself. An upper limit of TCP equal to unit is enforced. Bear in mind that the population TCP distributions are not Gaussian. Therefore straight-forwardly combining the quoted means and standard deviations will often give non physical results i.e. probability greater than one or less than zero.

Considering this, the distribution of TCP over a patient population allows clarification of the potential impact of these three types of uncertainty on the treatment outcome. For the case of zero uncertainty, the distribution of TCP values will take the form of a delta function at the single value of TCP corresponding to the prescribed dose and specified tissue properties. Figure 6.8 shows the distribution of TCP for a patient population, with TCP calculated to separately include the three types of uncertainty at three prescribed doses. The three prescribed dose levels were chosen to give a low probability, a midrange probability and a high probability of tumour cell survival across the patient population. The TCP calculated without any uncertainties included in the calculation is also shown in figure 6.8 as a vertical dashed line. The TCP distribution plots are shown with a log probability scale to illustrate the probability down to very small values. A dashed horizontal line at $TCP = 0.01$ highlights and separates the relative number of treatments with negligibly low probability of tumour control.

Introducing uniform dose uncertainty into the calculation of patient population TCP's results in a broadly peaked distribution of patient TCP values, particularly at high and low doses. At each prescribed dose the uniform dose uncertainty contributes to almost the complete range of possible tumour outcomes i.e. from no control to complete control. A significant proportion of the sample TCP values (i.e. those larger than ~ 0.2) for the 48 Gy (lowest) prescribed dose have a chance of less than 0.01 of occurring. For the mid-range prescribed dose (52 Gy), the sample TCP values are evenly distributed with probability of ~ 0.01 . While at the 56 Gy (highest) prescribed dose, those sample TCP values less than ~ 0.7 have a very small chance of resulting from this dose and the distribution peaks near the expected sample TCP value. Therefore the mean TCP curve for uniform dose uncertainty shows a balance between outcomes for different patients. It does not mean that all patients are likely to have this value of TCP. In fact the number of patients with this

TCP could be negligible (see, for example, the curve with variable radio sensitivity in figure 6.8b).

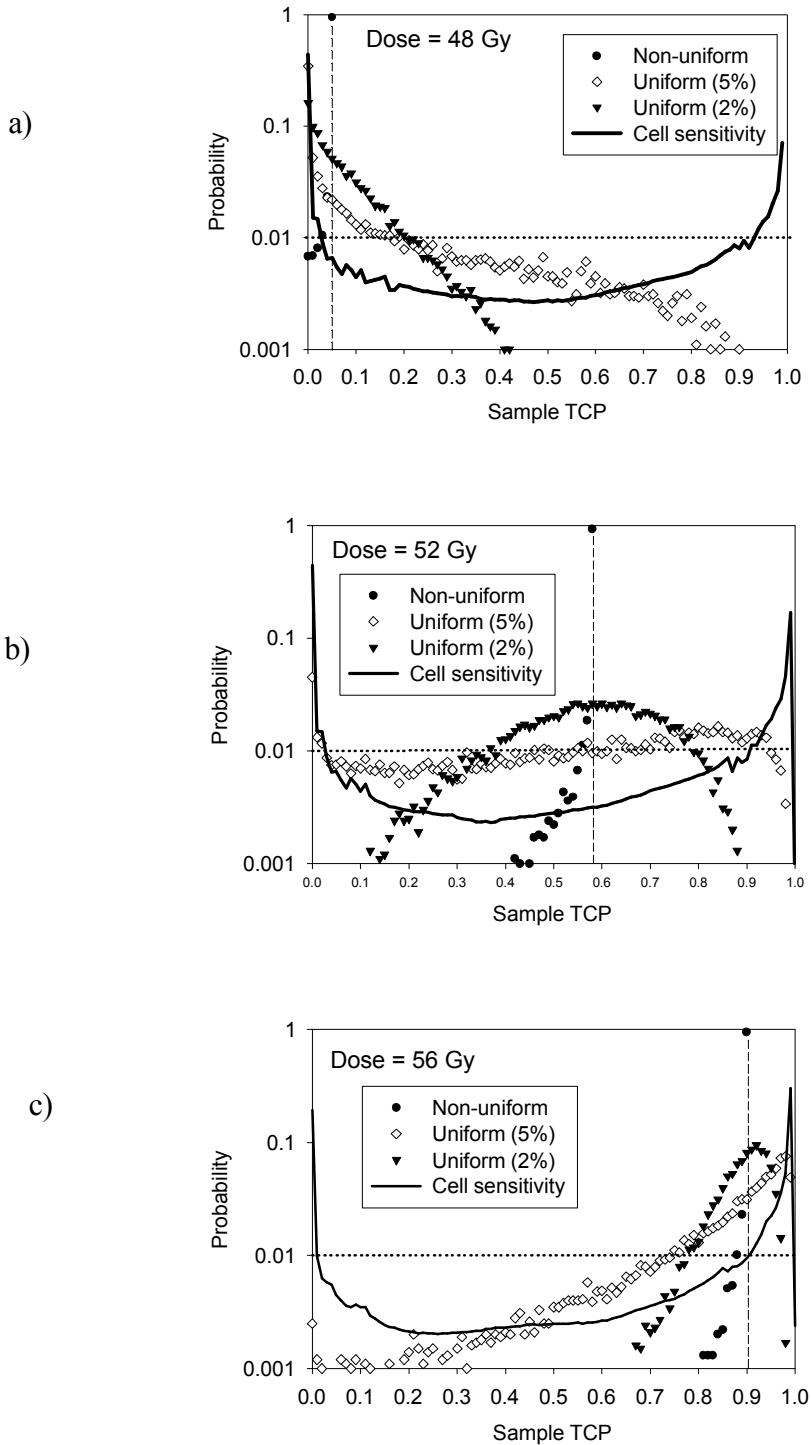


Figure 6.8 Distributions of TCP for three dose levels a) 48 Gy, b) 52 Gy, and c) 56 Gy incorporating dose uncertainty (uniform or non uniform) and interpatient cell sensitivity variation. The exact calculated TCP at these dose levels (shown as vertical dashed line) are 0.05, 0.58 and 0.90, respectively.

Non uniform dose uncertainty, as mentioned previously, results in relatively small dose variation within the tumour volume – but this is directly dependent on the margin size and the magnitude of the treatment uncertainties. Therefore, with the 1.5 cm margin, the non-uniform dose uncertainty causes sharply peaked distributions of TCP for each dose level, although it still spreads out slightly from the initial delta functions representing planned TCP. This is illustrated by the range of sample TCP values with probability greater than 0.001 for each of the dose levels being ~0.05, 0.1, and 0.05 respectively. The most probable TCP value (the peak) has a probability of very near to one.

Introducing interpatient variation in cell sensitivity results in a wide distribution of tumour control across the patient population for each prescription dose. All three tested prescription dose levels give rise to the possibility of complete tumour control and no tumour control. Moreover, the probability of a patient having a mid range value of TCP is low. The distribution of sample TCP is peaked at both zero and near one. The most probable outcome then seems to switch between only these two outcomes with the relative proportion of each dependant on the dose.

Examining this point further; by neglecting cases with TCP less than 0.01 (below dashed line) the TCP distributions become bi stable for all three dose levels. This indicates that at these dose levels the treatment outcome depends primarily on individual patient radiobiological response (and secondarily on the delivered dose). If the dose is increased the importance of variation in patient radio sensitivity is reduced because those radio-resistant tumours are given the dose they require to be eradicated. This point is further expanded on in the discussion.

Again, population statistics allow further generalisation to the most probable patient outcome, when each of the uncertainties is separately considered. The mode of TCP versus dose, shown in figure 6.9, illustrates steep transitions from low probability of tumour control to a high probability of tumour control across the population. To gauge the steepness, the curve containing no uncertainty (from figure 6.6) is also featured in the mode TCP plot. The interval between points on the curve is fixed at the fraction size of 2 Gy.

This may limit the steepness of the curves.

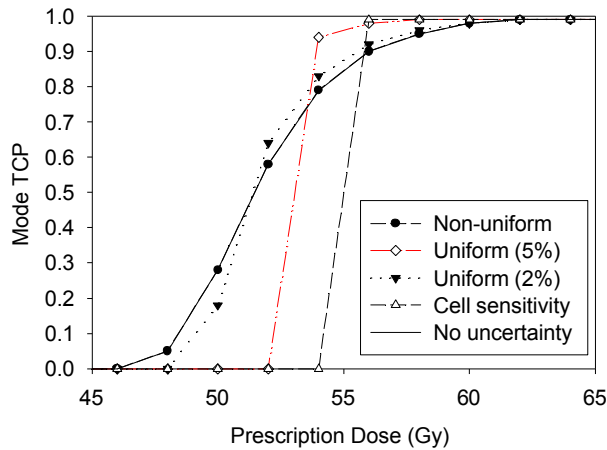


Figure 6.9 Mode of TCP over a patient population.

The uniform dose uncertainty and varying cell sensitivity both give rise to a mode TCP gradient that is steeper than the mean TCP curve and shifted to higher dose. This suggests that despite the introduced uncertainties, patient tumour control is highly dependent on selecting the correct prescription dose. For non uniform dose uncertainty the mean and mode TCP both closely follow the TCP values calculated without any uncertainty.

The differences between mean and mode TCP occur with relatively large spatially uniform dose error (5%) and the radio sensitivity. In both of these cases the mode TCP is shifted to higher dose. This means that a higher dose is required in these circumstances for most of the population. The mode TCP curves are also steeper than the mean TCP curve for these two cases. This implies that the threshold dose exists to achieve local control in most of the population. This threshold dose will be increased with increased treatment uncertainty. Supporting this, the mode TCP with interpatient cell sensitivity heterogeneity is positioned at a higher dose than that calculated incorporating uniform dose uncertainty.

Where no treatment uncertainty is present, mode TCP is equal to mean TCP for a population, and this TCP value will also correspond to the probability of tumour control for every patient (as they are identical – no uncertainty). Mean values of the dose and radio sensitivity should, of course, be the same in these two situations.

For a selected range of doses above the threshold dose, most patients, in populations with variable radio sensitivity or encountering spatially uniform dose errors, will have a higher probability of local control than those individuals in non variable populations. This reflects the dose when the mode TCP is greater than the mean TCP for the population, and is

evident in figure 6.8 above. The meaning of this can be explicitly demonstrated for the situation shown in figure 6.8. Consider the prescription dose equal to 54 Gy. In this case approximately 95% of the patients from the population with variable radio sensitivity would have a TCP ≈ 1.0 and approximately 5% would have nearly zero TCP. If all patients would have the same value of radio sensitivity then all of them would have had TCP ≈ 0.8 .

6.2.3.4. Results using 3D input data

Three dimensional input data was used to obtain the best estimate of the effect of treatment errors on tumour control. Generally the radio sensitivity of patients will not be known. Consequently, interpatient variability in radio sensitivity is modelled as standard across the patient population.

The impact of systematic errors on the TCP of an individual patient was calculated with parameters modelling two scenarios; an empty (smaller than average) rectum at planning, and a full (larger than average) rectum at planning. Obviously, these systematic errors will impact on the position of the prostate at planning. The mean TCP and standard deviation in mean TCP (error bars) are illustrated below in figure 6.10.

In the case of an empty rectum in the planning CT scan, the prostate is determined to be posterior from the mean position. Thus, the prostate will tend to be relatively anterior during treatment. Conversely, with a full rectum at planning, the prostate will tend to be relatively posterior during treatment.

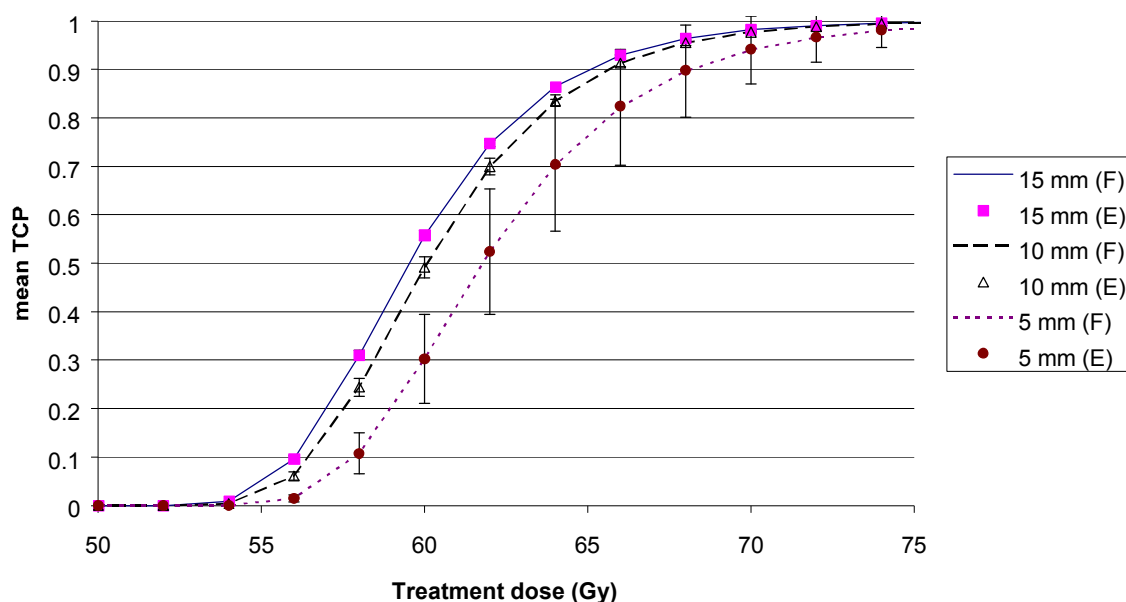


Figure 6.10 TCP calculated for an individual patient with (F)ull or (E)mpty rectum in planning CT scan with margins of 0.5 cm, 1.0 cm, or 1.5 cm.

Importantly, the systematic errors are equal in magnitude (in the anterior and posterior directions) and the margin is uniform. Therefore both systematic shifts should have the same effect on TCP. This is supported in figure 6.10 by the mean TCP being almost equivalent for each of the systematic errors.

The error bars associated with each curve in figure 6.10 indicate the potential impact of random treatment uncertainty. The error bars increase as the margin size is decreased as a consequence of the increased risk of a geometrical miss.

Across a large population of patients, a range of systematic prostate position errors will occur. The mean TCP across a population and the standard deviation in mean TCP are listed in table 6.3 below for three cases including *planned* (which incorporates the planned, or intended, dose distribution), *random only* (which assumes that there is no systematic error), and *systematic and random*. All cases include inter patient variation in tumour radio sensitivity.

Table 6.3 Mean TCP at 64 Gy across a patient population for three margin sizes, with error given as one standard deviation in mean TCP.

Margin	Planned	Random only	Systematic + Random
1.5	0.61 ± 0.32	0.63 ± 0.31	0.60 ± 0.31
1.0	0.62 ± 0.33	0.59 ± 0.32	0.56 ± 0.33
0.5	0.57 ± 0.33	0.53 ± 0.31	0.54 ± 0.33

Three main trends (evident from table 6.3) exist across a population of patients. These include; negligible change at each margin with or without error, a small reduction in TCP as the margin is reduced, and an intrinsic uncertainty ($SD > 0$) exists for planned TCP due to inter patient radio sensitivity variations.

The most prominent effect across the population is the standard deviation in the planned TCP. Following the plot of standard deviation in TCP from figure 6.7 the maximum value occurs where TCP is 50%. For the population-based results, the 50% TCP occurs between

58 Gy and 63 Gy depending on the margin size. Thus, the values of standard deviation shown in table 6.3 (at 64 Gy) should be close to their maximum. If the dose level were increased, this uncertainty could be reduced.

6.2.4. Discussion

In this study, a set value of random positioning error was used. Dose based margin equations can be used to size the margin (as outlined in §2.7.1.1). Using equation 2.6 with the values of systematic and random error applied in this study the calculated margins are 14 mm, 16 mm, and 8 mm in the AP, SI and LR direction, respectively. In this study uniform margins were used. The mean TCP for an individual patient was shown to have a significant uncertainty associated with a margin of 5 mm. However, the next largest margin (10 mm) did not demonstrate any deleterious effects from the systematic or random errors. Clearly, the dose based margin equation does not correlate with the calculated tumour control. The dose based margin equation naturally does not account for any radiobiological effects, but it should be emphasised that these equations do not infer any profound clinical impact, only coverage probability.

The random and systematic errors will evoke larger uncertainty in the TCP with sharply defined dose distributions. That is, the difference for TCP between an adequate and an inadequate margin increases. This was indicated by an increase in the standard deviation in mean TCP for the single field dose profile against the four field conventional dose profile.

The effect of a spatially uniform dose uncertainty on mean TCP was modelled as a 2% or 5% error in the fraction dose. Across a population of patients this error will even out. But each individual patient will receive a fluctuating fraction dose and a total dose higher or lower than prescribed. The patient TCP is calculated from the total dose of that patient and the distribution of sample TCP (refer to figure 6.8) shows a range of outcomes at each prescription dose. The range extends beyond the planned TCP. This suggests that some patients with insufficient prescribed dose have a chance at actually benefiting i.e. receiving higher doses that lead to higher cure rates. For uniform dose uncertainty this results from the entire irradiated volume receiving higher dose. While for the non uniform dose uncertainty the maximum tumour dose does not change but the volume of tumour receiving 100% dose may increase. Certainly, the contiguous normal tissue (such as rectum or bladder for prostate treatments) would also receive an increased dose in this circumstance.

The variation in cell sensitivity across a population of patients is shown to result in a double peaked distribution of TCP values across the patient population. This distribution peaks at TCP values of zero and one, and the probability of mid range TCP values is low (<1%). The mean TCP for a patient population is shown to be the fraction of patient population with high (approaching to unit) value of TCP. This results from the combination of a large relative uncertainty in cell sensitivity and the steepness of the individual TCP curve with cell sensitivity.

The TCP equation (equation 3.17) can be considered as a function of cell sensitivity for a fixed dose. Figure 6.11 shows the range of TCP values covered by one and two standard deviations of cell sensitivity at different dose levels from 48 Gy to 85 Gy. Also shown in figure 6.11 are the two values for tumour radio sensitivity, α_1 and α_2 , which were used in the 1D and 3D investigations, respectively.

With the more radio resistant value of cell sensitivity ($\alpha_2=0.35 \text{ Gy}^{-1}$) used in the 1D study, the range of interpatient variation at the lower doses (48 Gy and 56 Gy) covers the range of tumour outcomes. Furthermore, at the lowest prescription dose, two standard deviations of variation only permits TCP values barely greater than zero.

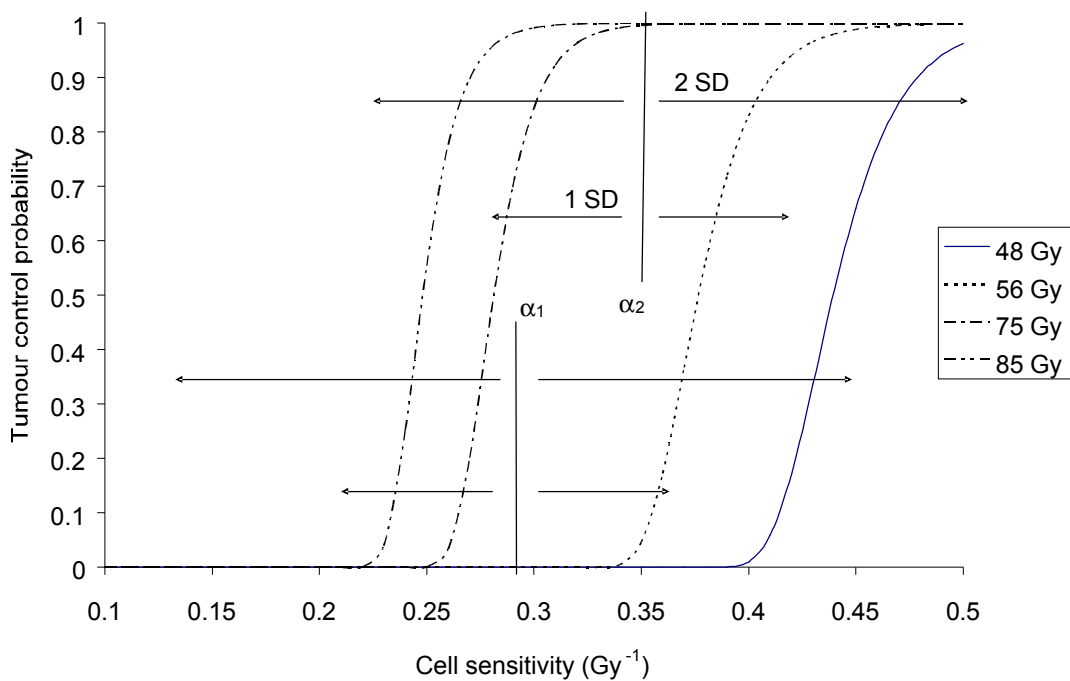


Figure 6.11 Plot of TCP versus cell sensitivity. Two values of cell sensitivity ($\alpha_1 = 0.29 \text{ Gy}^{-1}$, $\alpha_2 = 0.35 \text{ Gy}^{-1}$) and the range covered by one and two standard deviations in cell sensitivity are illustrated. See text for further description.

Some radiotherapy centres (such as Memorial Sloan Kettering cancer centre in the United States) are escalating dose above 80 Gy. Increasing the dose allows the more radio resistant tumours that may not have been treated successfully at lower doses to be controlled. In figure 6.11, the curve for 81 Gy lies in the region well outside 1 standard deviation from α_2 , which shows that this dose would control over 68% of the patient population. On the other hand, this curve is just outside the region covered by 2 standard deviations. This indicates that 81 Gy would control a little less than 95% of the patient population. This data is in agreement with the results from MSKCC where they reported controlling 95% of the population with 81 Gy target dose (Zelefsky 2001). The most recent value of prostate carcinoma cell sensitivity in the literature, α_1 (Sanchez-Neito *et al* 2001b) is lower than the value used in the 1D study, α_2 . This signifies that prostate tumours are more radio resistant than previously thought. Therefore, with the lower doses shown in figure 6.11, even for those patients at the higher end of the range of cell sensitivities the TCP is low. With the escalated doses the TCP the values of TCP are 70% and 98% for the 75 Gy and 85 Gy doses, respectively.

Examining the four dose levels in figure 6.11 at the 50% TCP level the separation between the two lower dose curves is larger than the separation between the two escalated dose curves. This highlights the diminishing return (in terms of TCP) as the dose is escalated.

Zagars *et al* (1987) suggest that the intratumour variation in cell sensitivity is smaller than the interpatient cell sensitivity. This would reduce the relative uncertainty in cell sensitivity if we could measure tumour sensitivities for individual patients and not a population. The magnitude of intratumour variation is still unknown.

Sanchez-Neito *et al* (2001b) suggest that a small percentage (<1%) of the population are poorly suited to radiotherapy (due to intrinsic radio resistance) and other treatment options should be pursued for these patients. Certainly, the distributions of TCP over a population represented in figure 6.8 agree with this assertion.

In this study, the dose distribution is homogeneous in the PTV with no hotspots or cold spots. This dose distribution is typical for treating prostate cancer. For other sites, where hot spots and cold spots exist, spatially non uniform dose errors will have a larger effect. Sanchez-Neito and Nahum (1999) use the delta-TCP (Δ TCP) concept to examine the effect of hot and cold spots, compared to an original planned dose distribution. The Δ TCP is calculated as:

$$\Delta TCP_j = \sum_i g_i(s_a) \cdot TCP(a_i) \cdot \left[1 - \frac{BCP_j(a_i, D_p)}{BCP_j(a_i, D_j)} \right] \quad (6.5)$$

where the differential DVH is used to extract the bin control probability for the j th bin receiving a dose D_j , and g is the probability of the tumour having cell sensitivity α_i . Sanchez-Neito and Nahum (1999) calculate that the cold spots reduce the TCP by more than the respective increase from a hot spot of equivalent magnitude. This had been previously shown with an earlier model for surviving fraction by Brahme (1984). Therefore the TCP for a patient treated with a heterogeneous dose distribution incorporating geometric uncertainty would be expected to be reduced from the planned TCP and the reduction should be indicated by the lowest dose.

6.3. Normal Tissue Complication Probability

Normal tissue complication probability is the probability that a certain percentage of the patient population will incur unfavourable reactions to the tissue at a particular dose.

6.3.1. Background: Incorporating treatment uncertainty into NTCP calculation

Fenwick *et al* (2001) conjectures that the uncertainty in the actual dose deposited from the planned dose distribution is a factor of some concern. However, prior work of his (Fenwick 1999) had calculated that the impact of setup errors and rectum movements on NTCP is “surprisingly limited”. Lu *et al* 1995 investigated the effect of setup errors and rectum motion on the prediction of NTCP using both DSHs and DVHs. They modelled the effect of the positioning uncertainty by applying a range of margin sizes and demonstrated that DSHs provide a more accurate description of NTCP than DVHs. Raggazzi *et al* 1997 convolved a position PDF with a prostate dose distribution and calculated the resultant NTCP, with a range of margins and PDF standard deviations. They found that NTCP was not strongly affected by the errors. But importantly, their method did not account for fluctuations in dose per fraction, they only accounted for a mean dose. Lebesque *et al* 1995 serially CT scanned a series of patients through treatment delivery to investigate whether the DVH, DWH and NTCP derived from the planning CT scan is indicative of the entire treatment course. They found that the rectum changes shape dramatically, and randomly, through the treatment. However, the variation in high dose (>90% target dose) wall volume

was relatively small (1SD = 14%). Consequently, the NTCP calculated with rectum (including contents) was approximately equal to NTCP calculated from the rectal wall inferring that the planning CT could be used confidently.

6.3.2. Methods

Chapter 5 investigated the dosimetric impact of rectal wall motion and patient positioning, while the current investigation integrates those data into the calculation of the normal tissue complication probability to further study the effect of these uncertainties.

Normal tissue complication probability for late rectal bleeding is calculated using the linear quadratic model for FSU (i.e. assumed to be contained within a voxel) complication probability and the Källman s-model to combine the voxel complication probabilities into an organ complication probability. Surviving fraction was calculated for each simulated patient following the modelled 30 fraction treatment, including the accumulated dose to the deforming rectal wall as per the model developed in Chapter 5.

6.3.2.1. Fitting Linear-Quadratic parameters to late rectum complications

The literature (Emami *et al* 1991, Kallman *et al* 1992, Hartford *et al* 1996, Metcalfe *et al* 1997, Sanchez-Neito *et al* 2001b) provides measured clinical parameters for late rectum complications (i.e. severe proctitis, necrosis, stenosis and fistula). These parameters include $D_{50} = 76$ Gy (the whole organ dose leading to 50% complication rate), $D_5 = 60$ Gy, $\alpha/\beta = 3$ Gy, and $n=0.24$ (related to the relative seriality parameter, $s=1/n$). Normal tissue complication probability for uniform irradiation of the entire organ is then calculated using;

$$NTCP = \left[1 - \left(1 - P_{LQ}(D)^s \right) \right]^{1/s}, \quad (6.6)$$

where $P_{LQ}(D)$ is the linear quadratic equation for cell killing,

$$P_{LQ}(D) = \exp \left[- N_0 e^{-\alpha D - \beta D^2} \right]. \quad (6.7)$$

Setting the initial number of FSU's (N_0) to 10^6 , the value of cell sensitivity was manually adjusted along with the variance in interpatient cell sensitivity to achieve an NTCP curve that passes through the D_5 and D_{50} values. The fitted value of cell sensitivity for late rectum complications is $\alpha = 0.151 \pm 0.023$ Gy⁻¹. The value of β used was calculated for each

patient using a fixed α/β ratio of 3 and their (sampled) α value.

6.3.2.2. Modelling individual treatments and patient populations

The literature (Rudat *et al* 1996, Roeske *et al* 1995, Melian *et al* 1997) describes the prostate to move randomly in the AP, LR and SI directions. This motion has been strongly correlated with rectum distension and weakly correlated with bladder filling for patient positioned supine (Zelefsky *et al* 1999, Roeske *et al* 1995). Bladder volume may be more important for those patients treated prone (Melian *et al* 1997). In the AP direction we assume that the prostate is in contact with the anterior rectum wall and the geometric centre of the rectum is fixed. Thus, prostate position at any time in the AP direction is assumed to follow the sampled position of the anterior portion of the rectum wall.

The biological effective dose (refer to equation 3.11) for rectal tissue was continuously calculated following each accumulated fractional dose for each rectum voxel. The voxel biological effective dose following the entire 32 fraction treatment is combined across the rectum ROI voxels and used to calculate a sample NTCP value using equation 3.28. A population of NTCP values is calculated from N_{tx} simulated treatments. A number of model parameters of the model are tested including various margin sizes, various levels of targeting accuracy and various numbers of CT scans used to average prostate position.

Three uniform CTV-PTV margins were tested (0.5, 1.0, 1.5 cm) with the MC code to calculate NTCP including the effects of systematic organ motion error, and random errors. A specific dose distribution was created for each margin, such that the 95% isodose encompassed the PTV.

6.3.3. Results

6.3.3.1. Individual patients

The effect of two separate systematic errors (c.f. §5.3.6 for description of the systematic errors) on NTCP for an individual patient was investigated. The NTCP values calculated with full or empty rectum are plotted in figure 6.13 with each of the three planned dose distributions.

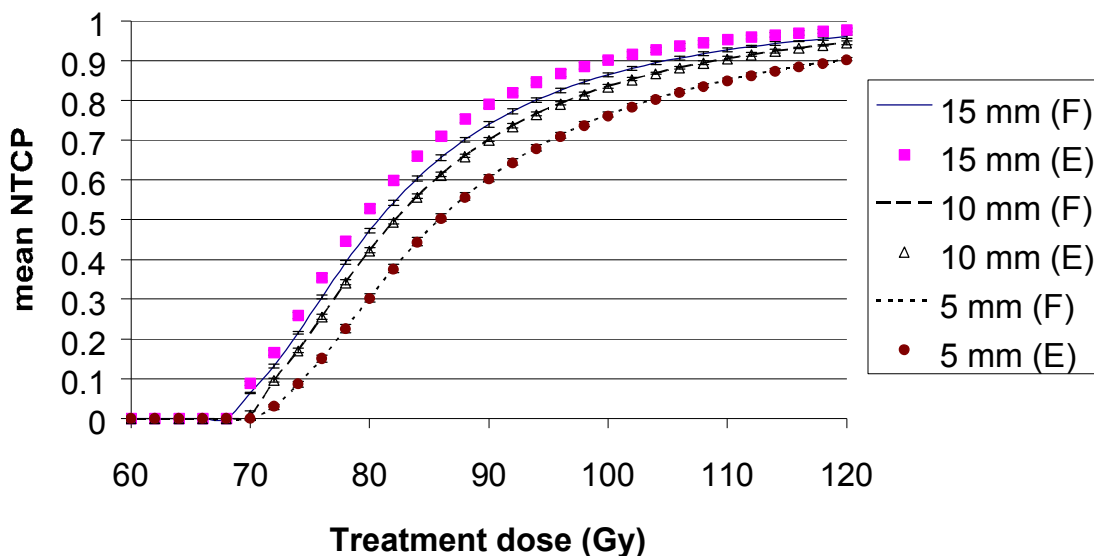


Figure 6.13 Mean NTCP calculated for individual patients with either full (F) or empty (E) rectums in the planning CT scan and with margins of 0.5 cm, 1.0 cm, or 1.5 cm. Table 6.4 NTCP across a patient population (N=1000) with D=64 Gy

During the course of treatment random changes in the rectum radius and beam/patient positioning will occur and give rise to variation about the mean values. The variation is indicated in figure 6.13 by error bars. The error bars indicate one standard deviation in NTCP accounting for the random uncertainty.

Figure 6.13 shows that patients treated using 5 mm or 10 mm margins have negligible effect from either systematic errors. The mean NTCP calculated using a 15 mm margin shows an increased complication for the patient with an empty rectum in the planning CT scan as compared to the patient with a full rectum in the planning CT scan. With the 15 mm margin, almost half of the empty rectum is planned to be included in the PTV. An empty rectum will consequently imply that the rectum will receive a higher dose during the treatment. This raises the mean dose and the volume of rectum receiving target dose during the course of treatment.

In the clinically important region of dose for this particular plan (<70 Gy) the mean NTCP curves for each systematic error are relatively close (<0.05 separation) and it is only at higher doses that for the 15 mm margin the two curves separate. The planned dose distribution used in this study delivered 64 Gy to the PTV and therefore an assumption is made at higher doses. The assumption is that by systematically increasing the dose the distribution of dose is still acceptable. At higher doses, the planned distribution of dose to the rectum may not have been acceptable, and an alternative distribution designed.

6.3.3.2. Population based results

The mean NTCP is calculated for a patient population accounting for interpatient variables (systematic organ motion error and interpatient radio sensitivity variation) and the interfraction variations in rectum diameter and patient/beam alignment. The results are given in table 6.4 for three PTV margin sizes. The three situations modelled include;

- 1) using the planned dose distribution
- 2) allowing only random errors (i.e. no systematic error in rectum diameter)
- 3) allowing both random and systematic errors.

In the case of *systematic and random* errors, a single planning CT scan is used to plan the treatment. While for the *random only* case, the CT image is assumed to represent the true mean position (following “infinite” N_{CT}).

Table 6.4 NTCP across a patient population (N=1000) with D=64 Gy

Margin	Planned	Random	Sys + Rand
1.5	0.08 ± 0.14	0.08 ± 0.14	0.08 ± 0.13
1.0	0.06 ± 0.11	0.05 ± 0.11	0.04 ± 0.10
0.5	0.03 ± 0.09	0.03 ± 0.08	0.03 ± 0.08

There are three main trends apparent from table 6.4 including small change in mean NTCP or standard deviation values at each margin with or without error, a general reduction in mean NTCP and the standard deviation in mean NTCP as margin decreases, and an intrinsic uncertainty ($SD > 0$) evident even for case where the planned dose distribution was used. This intrinsic uncertainty is due to inter-patient variation in rectal wall radiosensitivity.

6.3.3.3. Impact of fluctuations in fractional dose

The impact of fluctuations in rectal dose between fractions was studied by calculating NCTP across a population of patients where the deposited dose fluctuated for each fraction symmetrically about the planned dose. A 5% spatially uniform dose error was applied to

the calculation of rectal wall NTCP for each of three margin sizes and showed a minimal change from the NTCP calculated with the planned dose distribution (see figure 6.14).

Mean NTCP calculated with spatially uniform dose error has a reduced gradient from the planned NTCP and is slightly shifted to lower dose levels. However, both of these effects are small. In the clinical dose region (< 70 Gy) the mean NTCP is generally increased from planned NTCP. This indicates that a fluctuating total dose to the normal tissue is more damaging (on average) across the population than if the planned dose were given. The increase in mean NTCP at 64 Gy is ~ 0.01 for the 15 mm margin. The increase is less pronounced as the PTV margin is reduced.

The gradient of the mean NTCP curve including spatially uniform dose error also decreases as the PTV margin decreases. This indicates a diminishing return (in terms of NTCP) as the dose level is increased.

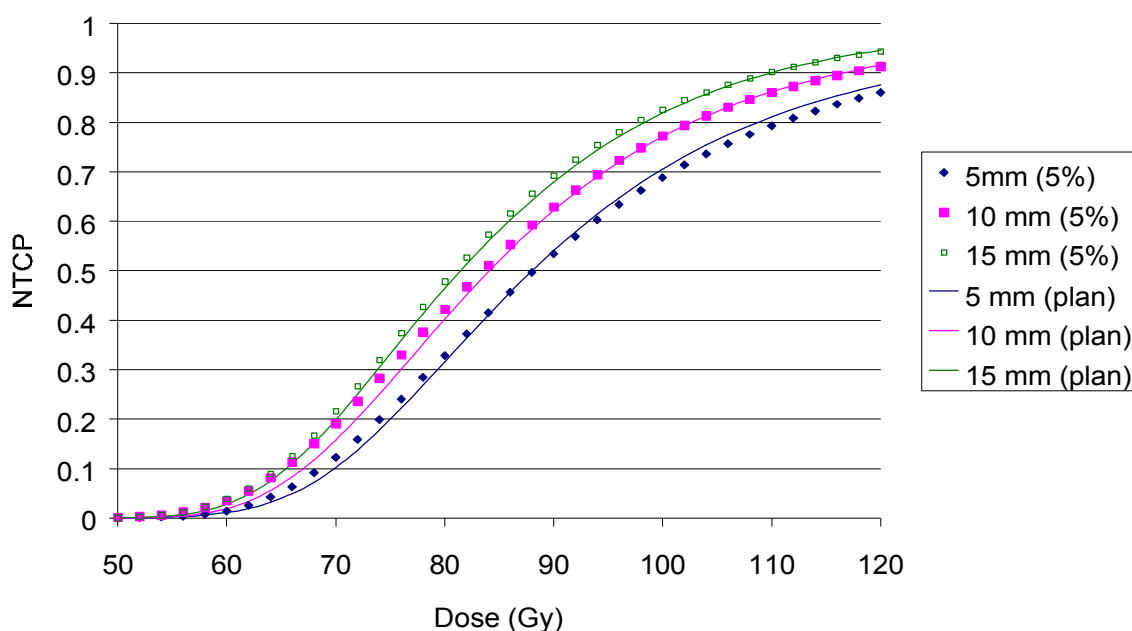


Figure 6.14 NTCP calculated with planned dose or with a 5% spatially uniform dose error at each fraction of treatment.

Effectively, the trends shown with a spatially uniform dose error infer that the proportion of patients predicted to suffer complications based on the planned dose, even if the patient and organs did not move, will be minimally under predicted.

6.3.3.4. Comparison with mean treatment dose

As an alternative to calculating NTCP for individual patients and then averaging from the population of NTCP values, the average dose might be used to calculate NTCP. In this section, NTCP is calculated in both of these ways and compared.

The mean dose deposited in the rectal wall can be approximated using the precalculated dose surface map data. Use of the DSM data assumes the thickness of the rectal wall (in each angular segment of each transverse slice) receives the same dose as deposited at the outer rectal wall surface. If this assumption is permissible then precalculated (or adaptively accumulated) dose surface information could feasibly be used to calculate NTCP.

To test this assumption NTCP is calculated with both the planned dose distribution and also with the DSM from the original dose distribution (see figure 6.15).

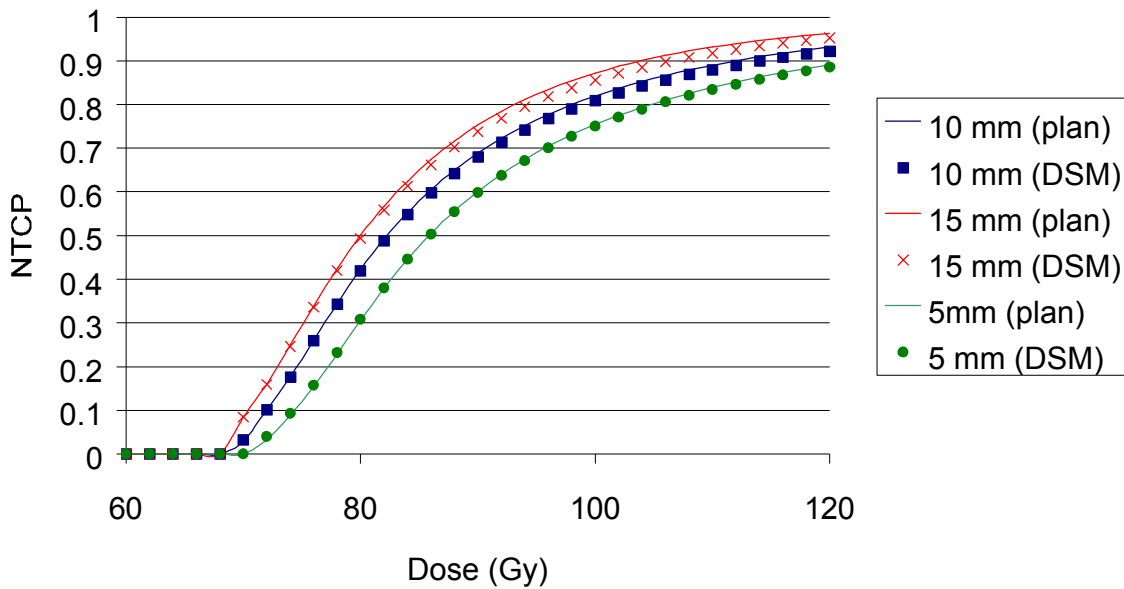


Figure 6.15 Comparison between NTCP calculated with the planned dose distribution against NTCP calculated assuming that the planned surface dose (from DSM) is deposited uniformly in each angular rectal wall segment.

For clinical doses figure 6.15 shows that the assumption of uniform dose through the thickness of each angular segment of rectal wall has a negligible effect on the value of NTCP calculated. Thus, the precalculated dose surface data can be used to approximate mean dose in the clinically relevant range of doses. The NTCP calculated using a precalculated population mean dose is compared in figure 6.16 to the average NTCP across a population.

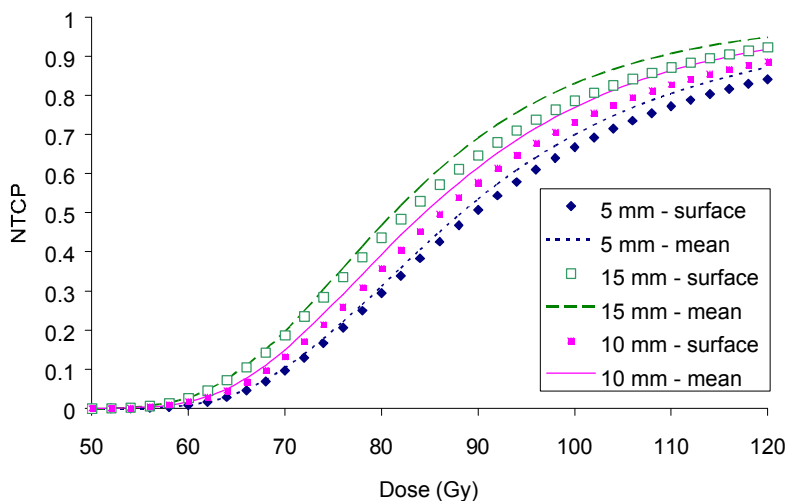


Figure 6.16 Comparison of mean NTCP calculated with mean dose (mean) against the calculated rectal wall (surface) dose. Both sets were calculated for a population of patients, with each patient being planned from a single CT image set.

In the clinically relevant range of doses (<70 Gy) the NTCP calculated using the mean dose is close to the NTCP derived from the MC calculation with a 5 mm margin. With a 10 mm or 15 mm margin the value of NTCP calculated with the mean dose is reduced from the MC calculated. The difference is small (with maximum deviation of 0.02 at 70 Gy) in this dose range. Neglecting systematic errors, the NTCP calculated using the mean dose is negligibly different from the MC calculated values in the clinically relevant dose range (60-80 Gy). The comparison is shown in figure 6.17 for the three margin sizes.

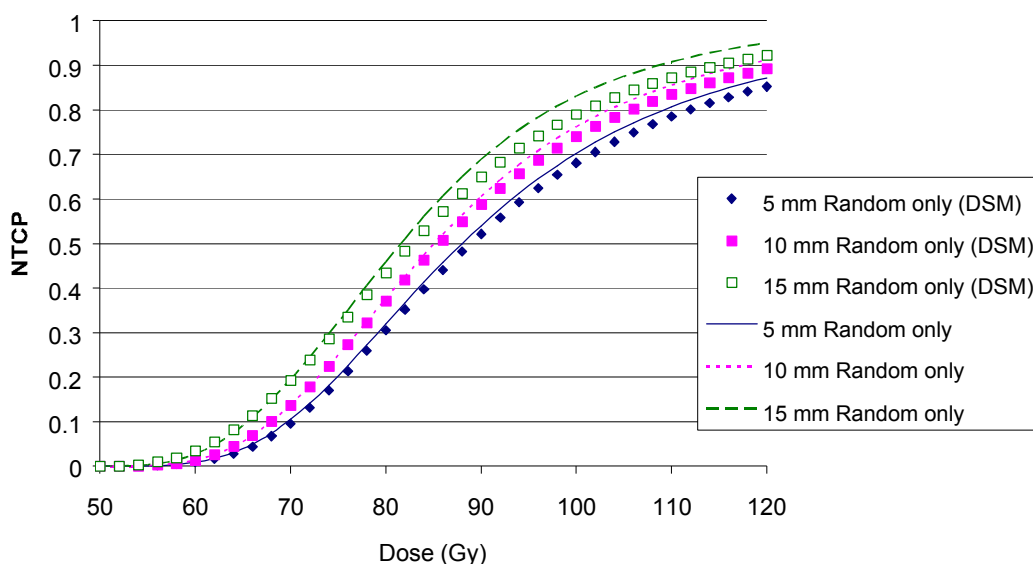


Figure 6.17 Comparison of mean NTCP calculated with the mean dose against the MC calculated rectal wall dose. Both sets were calculated for a population of patients, with each patient being planned using the mean organ position.

Given that the magnitudes of the deviations in NTCP are quite small the statistical accuracy of the calculations is paramount. Following that the number of sample treatment NTCP values averaged was 10^3 in most cases the standard deviation in the mean values can be approximated by $\frac{1}{\sqrt{10^3}}$ i.e. $\sim 3\%$. In some cases, a larger number (i.e. 5×10^3) of iterations were done, which increased the precision to $\sim 1\%$ for those cases.

6.3.4. Discussion

This work has shown that the impact of geometric errors on the mean NTCP across a population is small. The simulated treatments included a single magnitude of random treatment uncertainty across the population. Each simulated patient was modelled with systematic uncertainty, sampled radio sensitivity and positioning error. Surprisingly, the NTCP calculated for an individual patient incorporating large systematic errors also had only a small effect, however the margin size did affect the standard deviation in mean NTCP.

Other studies have also shown that the effect of organ motion and patient positioning errors has only a small effect on NTCP (Fenwick 1999, Lu *et al* 1995, Raggazzi *et al* 1997). Theoretically, since the rectum has been shown to produce a volume effect, changes in percentage volume receiving target dose levels should produce deviations in the calculated NTCP.

The dose surface maps in Chapter 5 have shown that although large deviations in dose are possible due to variations in rectum diameter, the geometry of the rectum means that these changes occur along the lateral rectal walls. Thus, the actual changes in high dose volume are not large. This is supported by the work of Lu *et al* (1995) and Lebesque *et al* (1995). Lu *et al* (1995) modelled the effect of organ motion/setup errors by comparing DVHs against DSHs between margin sizes. They showed that as the proportion of rectum irradiated increases with margin size the magnitude of the increase is smaller in percentage surface area than in percentage volume. Lebesque *et al* (1995) used serial CT scans during treatment delivery to show that the variation in high dose rectal wall volume was relatively small (1SD = 15%) and that the change in the high dose volume (<90% target dose) was proportional to the total volume changes (including filling).

Also contributing to the small effect on NTCP from the treatment uncertainty is the

symmetry of the position PDF (Gaussian) used in each case. That is, the probability of the rectum expanding from the mean position is the same as the probability of contraction. Thus, interfraction variations will ‘even out’ across an entire treatment. Across a population of patients the systematic errors, modelled using a Gaussian distribution, will also average to zero across a large number of patients.

Raggazzi *et al* (1997) used the Lyman-Kutcher-Burman (LKB) DVH reduction scheme to calculate NTCP (see also §3.4.2 for description of the scheme). They modelled the effect of random organ motion errors and patient positioning errors performing a convolution of a position PDF with a prostate dose distribution and calculating NTCP using the mean dose. The calculated NTCP values incorporating random errors do produce reductions in NTCP from the NTCP calculated with the planned dose distribution. They suggest this is due to the reduction in average dose at the top of the dose distribution penumbra coinciding with the rectal wall tissue.

Using the model described earlier, NTCP was calculated with two sets of parameters: Set 1 ($TD_{50} = 76$ Gy, $n=0.12$, $m=0.15$); and Set 2 ($TD_{50} = 76$ Gy, $n = 0.24$, $m=0.15$). Raggazzi *et al* (1997) used values similar to those of Set 1 with $TD_{50} = 80$ Gy, however they only modelled random errors for individual patients. The calculated NTCP values for three margin sizes and two dose levels (modelled by linearly scaling the DSH) are shown in figures 6.18 and 6.19 for an individual patient with full (larger than average) rectum at planning, or empty (smaller than average) rectum at planning. That is, for the individual we have additionally modelled an empty or full rectum at planning that introduces a systematic error for that patient.

The NTCP calculated using the mean dose surface histogram with the LKB scheme predicts higher NTCP than the voxel-based Källman model. Evidently, the parameters and parameter values are not equivalent between models.

In the figures 6.18 and 6.19 NTCP increases with margin size and is larger for the treatment delivering 70 Gy to the tumour compared to the 60 Gy treatment. The larger volume effect is modelled in figure 6.18 ($n=0.24$). The 60 Gy treatment shows an increasing variation in NTCP between the two systematic errors as the margin is reduced. With a larger target dose, the discrepancy between the effects of systematic error is much reduced, but the overall NTCP is greater. This reflects that 60 Gy is in the middle (of the NTCP versus dose curve) while 70 Gy is near the upper limit.

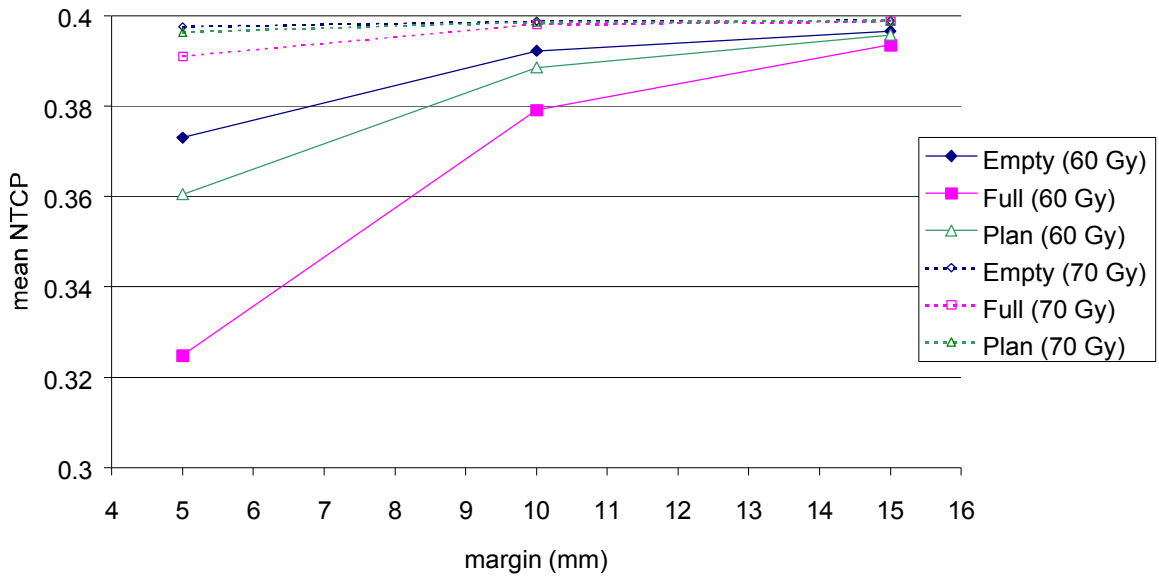


Figure 6.18 NTCP calculated using the mean dose with $n=0.24$, $m=0.15$ for an individual patient with systematic error.

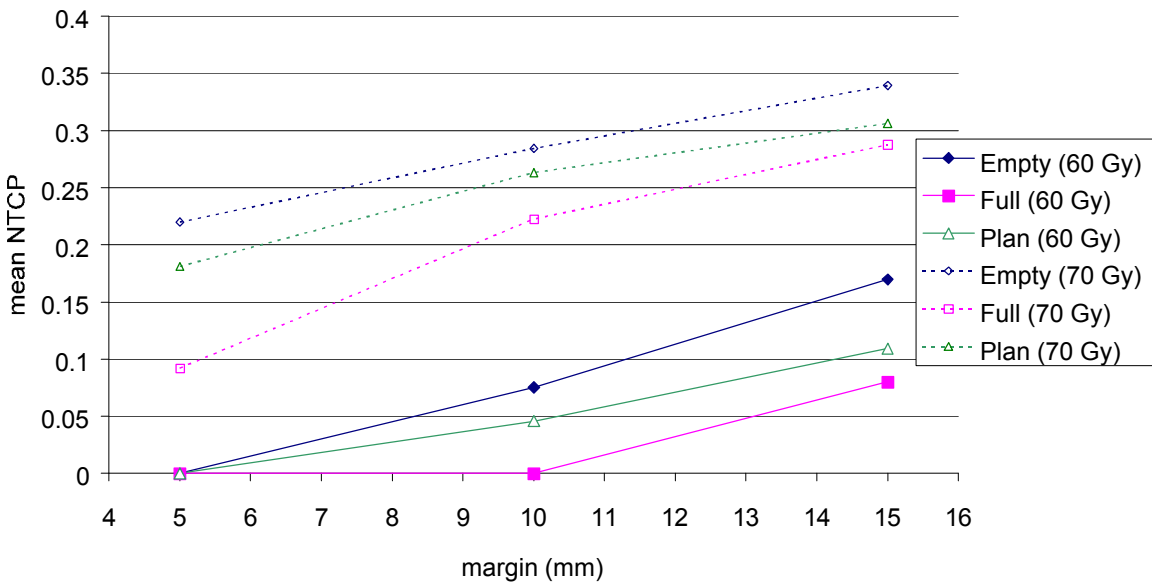


Figure 6.19 NTCP calculated using the mean dose with $n=0.12$, $m=0.15$ for an individual patient with systematic error.

The serial structure of the rectum (Hall, 2000) should produce a steeper increase in NTCP with dose once the threshold dose is surpassed. In figure 6.19, the lower dose level (60 Gy) with the 0.5 cm margin predicts zero NTCP for an empty rectum at planning. As the

margin is increased the NTCP appears to increase at an increasing rate, however since there are only three data points one cannot be sure. Certainly, with $n=0.12$, the 70 Gy curves show a larger spread of NTCP values between the situation modelled than with $n=0.24$.

The mean dose surface histogram calculated across a population is also used to calculate a population based estimate of NTCP. Naturally following from the DSHs, the NTCP did not vary significantly from that calculated using the planned dose distribution.

Importantly, the DSH reduction schemes assume that the mean dose gives the same amount of complications (i.e. calculated NTCP) as the calculation with fluctuating fraction dose. It has been shown for NTCP that the fluctuation in fraction dose deposited in rectal tissue does produce a deviation in the calculated NTCP. The deviation will be dependent on the margin size.

The models and their parameter values used in this study have been taken from the literature and are believed to be feasible. However, they are based on incomplete clinical data, and care should be taken when extracting clinical conclusions from the results.

6.4. Uncomplicated tumour control probability (UTCP)

The uncomplicated tumour control probability provides a single value of the probability of a favourable outcome. If normal tissue complication is considered equally detrimental as tumour control is considered beneficial then equation 3.31 can be used. More generally, the weight of importance placed on a given complication is closer to reality.

6.4.1. Methods

Uncomplicated tumour control probability is calculated using equation 3.31 for a population of patients with various configurations of error incorporated. The calculation of UTCP is carried out for each patient of the population. A general assumption is that the motion of the anterior portion of rectal wall is correlated with the anterior-posterior motion of the prostate gland.

The individual patient is modelled with a single value of radio sensitivity and systematic organ motion error. The systematic error will be either a full rectum at planning (which

will push the prostate anterior in the planning CT scan) or an empty rectum at planning. Random errors are simulated through the course of each simulated treatment. The random errors include deformation of the rectum (modelled as changes of rectum radius and associated changes of rectal wall thickness), motion of the prostate, patient setup errors (spatially non uniform dose error) and spatially uniform dose error (SUE, assumed to be 5% of fraction dose).

The interpatient uncertainties include variation in the radio sensitivity of the prostate and rectum, systematic errors captured in the planning CT scan, as well as all uncertainties attributed to individual patients (see above). The radio sensitivity of the tumour and rectum are assumed to be uncorrelated. No literature was found to support or oppose this assumption. The systematic error includes rectum deformation from the mean treatment size and the associated shift of the prostate in the planning CT scan. The systematic error can be reduced by averaging organ location from a number of pre treatment CT scans as described in earlier sections.

6.4.2. Results

6.4.2.1. UTCP calculated for an individual patient

Calculations of mean UTCP with systematic errors simulated at planning are shown in figure 6.20 below for the three margins investigated. The error bars indicate one standard deviation due to the random treatment errors (including prostate and rectal wall motion as well as patient setup errors).

With a 5 mm margin mean UTCP is calculated to peak with target dose 70 Gy and a UTCP value of 0.94. Neither of the systematic errors have a notable effect on the value of UTCP calculated. At doses smaller than the peak UTCP dose, the prostate TCP is dominant. Thus, in this dose range the variation in UTCP is significant (1SD in mean UTCP \sim 0.1) due to the insufficiency of the 5 mm margin to cover the prostate on all occasions i.e. a geographical miss is possible with this margin size.

The mean UTCP calculated with a 10 mm margin with either full or empty rectum at planning showed negligible effect on the value of mean UTCP for the individual patient. The peak value of mean UTCP will be at dose 69 Gy with mean UTCP equal to 0.97. The small influence on UTCP from the systematic errors arises from the margin being large

enough to avoid geographical misses and not too large to cause significant increases in NTCP. The NTCP for rectum is relatively quickly varying with increases in high dose volume (compared to other normal tissues) (Emami *et al.* 1991). However, since the dose variation occurs in the lateral rectal wall, the change in volume is small.

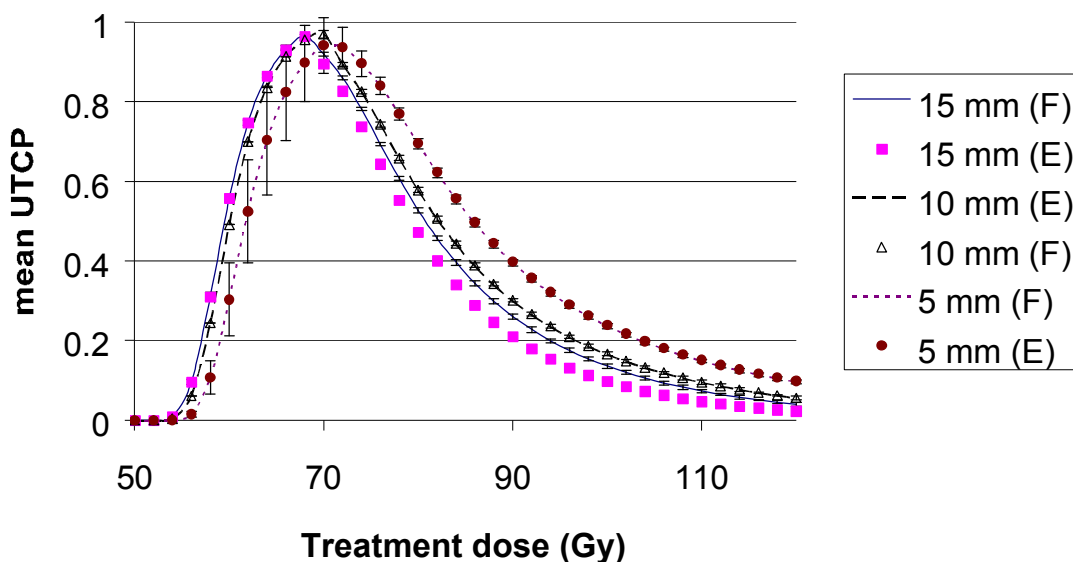


Figure 6.20 Mean UTCP calculated for a population of identical patients with fixed systematic error.

With a 15 mm margin the mean UTCP peaks with target dose 68 Gy at a UTCP value of 0.96. For target dose lower than the peak value of UTCP the effect of the systematic errors are negligible because in this dose range the TCP dominates and the 15 mm margin is more than sufficient to avoid geographical misses of the prostate. However, for doses larger than the peak dose, the NTCP dominates the UTCP value. In this range of doses a difference does exist between the UTCP calculated with full or empty rectum at planning. Those patients planned with empty rectum at planning have a smaller calculated UTCP than those patients planned with full rectum at planning. This agrees with the NTCP results for individuals (refer to figure 6.19) where the curve with empty rectum is above that for the full rectum since UTCP is proportional to $(1-NTCP)$. The variation in UTCP due to the random errors is negligible with a 15 mm margin.

6.4.2.2. Population based results

The value of mean UTCP for a population varies from that calculated for an individual patient because the patients will have varying radio sensitivities and their treatment plans will include varied magnitudes of systematic error. The peak value of mean UTCP

averaged across the patient population, the standard deviation in mean UTCP and the dose required for this peak value are tabulated in table 6.5 below.

Table 6.5 Maximum value of mean UTCP across a population with 1 SD uncertainty. The dose required for maximum UTCP is given in brackets. The planned situation includes no errors.

Margin (mm)	Sys + Rand	Random only	S.U.E. (5%)	Planned
5	0.61±0.28 (74)	0.60±0.29 (72)	0.58±0.28 (72)	0.64±0.28 (72)
10	0.61±0.28 (70)	0.59±0.30 (72)	0.56±0.29 (70)	0.61±0.30 (68)
15	0.60±0.30 (67)	0.58±0.30 (68)	0.56±0.30 (68)	0.59±0.29 (68)

Comparison of the figures in table 6.5 with those extracted from figure 6.17 leads to three primary differences between treating a varied population of patients and an individual patient. These differences include the population based calculations of mean UTCP being spread over a larger range of doses than for the individual patients, the mean UTCP is generally lower for the population and the population shows larger variation in mean UTCP. These differences are mainly due to variation in radio sensitivity between patients.

The peak value of UTCP is minimally affected by the margin size. This is demonstrated by the largest increase in peak UTCP (from table 6.5) with margin reduction being 0.05. That increase in peak UTCP is present with the planned case, while for each of the modelled errors the increase is reduced to ~0.02. However, the deposited dose giving the peak UTCP does change with the margin size.

The largest value of mean UTCP is calculated for the case with the smallest margin combined with the nominal planned dose distribution, and the smallest value of mean UTCP with the 5% spatially uniform dose error. The highest dose needed for peak UTCP is calculated with the smallest margin because the penumbra is too close to the prostate.

As with the calculations of TCP and NTCP, the calculation of UTCP demonstrates a large variation between patients. Table 6.5 shows that across all modelled cases the variation in mean UTCP ranges from 0.28 to 0.30 for peak UTCP. Considering this size of the standard deviation of UTCP, the differences between results accounting and not accounting for systematic errors are small. Also, the variation in mean UTCP is minimally affected by the

margin size.

Mean UTCP calculated incorporating both systematic and random errors is illustrated for each of the margin sizes in Figure 6.21 below. This figure shows peak UTCP at 67 Gy with a 15 mm margin and 74 Gy with a 5 mm margin. Thus for relatively similar peak UTCP values with each margin, the extra dose required for the smaller margin is approximately three to four 2 Gy fractions. Comparing this with the nominal planned case, in table 6.5, the increase in dose for peak UTCP is equivalent to approximately two 2 Gy fractions, but the peak UTCP does improve.

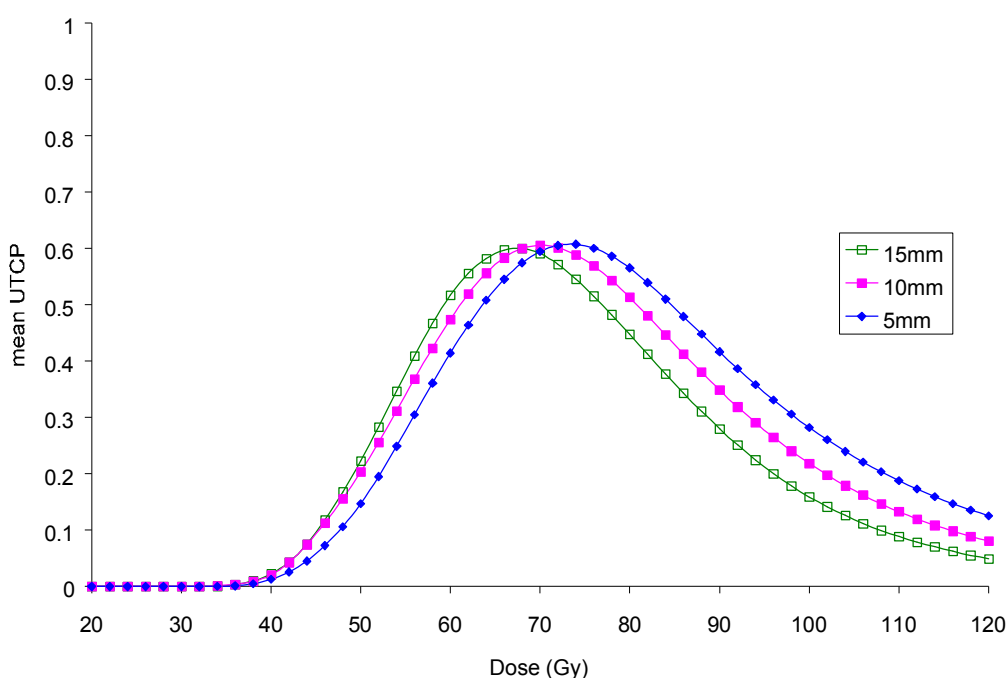


Figure 6.21 Mean UTCP (ICT) versus dose for margin sizes 0.5, 1.0, and 1.5 cm.

Mean UTCP for each situation at 64 Gy and 70 Gy is plotted against margin size in figure 6.22 below. The mean UTCP values at 64 Gy fall inside a more narrow range (i.e. 0.47 to 0.59) for all situations modelled and with each margin, than with a 70 Gy prescription dose (i.e. 0.51 to 0.66).

At 64 Gy, the UTCP versus margin size curves (in figure 6.22a) follow the corresponding TCP versus margin size data (table 6.2). As the margin is increased the UTCP increases accordingly. This is most evident for the mean UTCP calculated with spatially non-uniform dose errors. From figure 6.22a, these two curves are shown to increase markedly towards the planned UTCP as the margin is increased from 0.5 cm to 1.0 cm. This increase is attributable to the corresponding increase in TCP between these margin sizes caused by

improved targeting accuracy. The curve for systematic and random errors is located at lower UTCP than the curve for random errors only. Across a patient population, the additional systematic error has a detrimental effect on the mean tumour control.

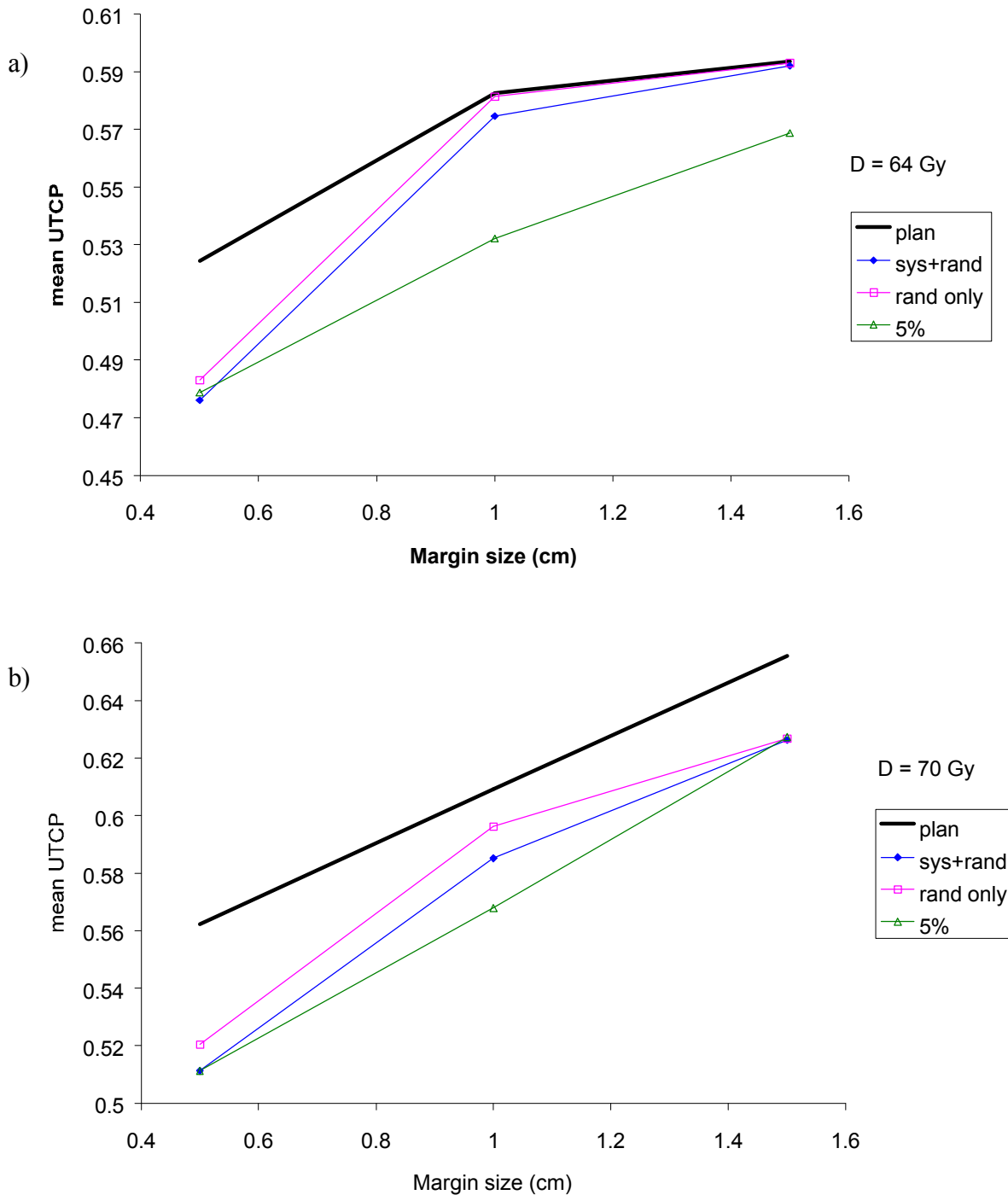


Figure 6.22 Mean UTCP against margin size at a) 64 Gy and b) 70 Gy.

At 70 Gy, the UTCP versus margin size curves (in figure 22b) follow the corresponding TCP versus margin size data (table 6.2) except for the 1.5 cm margin. With a 70 Gy

prescription dose and a 1.5 mm margin the NTCP begins to rise as shown in figure 6.19 above. Consequently, the curves for systematic plus random position errors and random positioning errors appear to become asymptotic in figure 6.22b as the margin is increased.

At both dose levels (64 Gy and 70 Gy) the spatially uniform random dose error with standard deviation 5% of prescription dose tends to follow the shape of planned UTCP curve at lower values of UTCP. This is a product of the corresponding TCP values, which are reduced by the fluctuating dose (as shown in figure 6.5). At these dose levels the NTCP does not vary from the planned NTCP (as shown in figure 6.14).

6.4.3. Discussion

The calculation of UTCP has included an equal weighting of NTCP and TCP (refer to equation 3.31). This implies that a complication is of equal detriment to the benefit of tumour control and therefore the weighting will impact on the conclusions made. Infact, most of these conclusions may have been made from the separate calculation of TCP and NTCP. Further clinical value might be obtained from unequal weighting of TCP and NTCP (such as with equation 3.37), however, the determination of each of the weightings would add a further estimated variable.

The use of UTCP in this investigation does not seek to endorse equal weighting of the tumour control and normal tissue reactions. The aim is to provide a simple combination of benefit against detriment to highlight the importance of margin size, reinforcing the conclusions of the previous sections. That is, a margin of 5 mm combined with the values of setup error and organ motion is probably too small, while conversely a margin of 15 mm is probably too large. Moreover, the UTCP itself is not intended to provide the ideal margin size, at least due to equal footing of control and complication.

From the planned dose distribution, calculation of UTCP appears to indicate that the ‘best’ margin size (of those tested) is the 1.0 cm margin. However, incorporating treatment uncertainties into the calculation demonstrates that this may not be the case. The ‘best’ margin may be larger than 1 cm.

The calculation of an optimal margin was shown in §2.6.1 to compensate for systematic and random positioning errors only. It should also include biological indices such as the tumour control probability and/or normal tissue control probability. Van Herk *et al* (2001)

presented research linking TCP with functions describing population distributions of certain treatment uncertainties (c.f. §2.6). Lind *et al* (1993) optimised a dose profile to account for geometrical uncertainty. These works lead to the ultimate goal of radiobiological optimisation, that provides a holistic approach to radiotherapy as outlined, for example, by Lof *et al* (1998). Lof *et al* (1998) seek to optimise the uncomplicated cure probability (P_+) based on four stochastic functionals; fluence, biological, fractionation and temporal components. Being derived from stochastic variables, P_+ itself will be stochastic and optimisation algorithms calculate the expectation value, EP_+ .

Patient positioning errors will influence the fluence profile incident to the tumour, and combined with organ motion, deformation and density changes will influence the temporal deposition of dose to the tumour. To overcome this temporal component the exact position, geometry and density of all organs will need to be known on each given treatment day. Practical concerns come into consideration to gather such information without their acquisition becoming invasive and the labour input outweighing the therapeutic gain. However, as a first approximation some general forms of distributions (predominantly Gaussian) have been used to investigate the optimisation method (Lof *et al* 1998).

Through the optimisation process, particularly for inverse treatment planning, the prescription of a margin around the CTV may become redundant. Instead, beam portals are designed that are functions of all the known treatment parameters. Naturally, the planner will not know whether the position of organs inside any particular patient will be more or less variable than the population data for that treatment technique. Therefore, the planner is required to apply, at least, the population statistics and at most the maximum values obtained from the population statistics to the generation of an intended dose distribution.

The use of population statistics may not apply to the individual. Hence the initiation of adaptive radiotherapy, which seeks to initially consider individuals as conforming to the population distribution of treatment uncertainty while thorough imaging studies are performed to individualise the treatment to that patients position statistics (and ultimately, their biological condition). The UTCP could be used in this adaptive process.

From the current work, the status of the rectum in the planning CT image did not cause significant variation to UTCP for individual patients. However, across a patient population the inter-patient variation in UTCP was large (with standard deviation typically ~ 0.3 , or 40%). This is predominantly due to the inter-patient variation in rectum radiosensitivity

being large (with standard deviation 15% of the mean). At the standard dose levels investigated (i.e. less than 70 Gy) the dose variations alone did not substantially affect the mean UTCP. This is gauged from the results for individual patient simulations where radiosensitivity was fixed. However, with the 0.5 cm margin, the mean UTCP did vary (with standard deviation ~ 0.1) at lower doses due to low and variable TCP.

6.5. Conclusions

Uncertainty in the dose deposited to tumour and normal tissue has been shown to impact on the biological indicators of TCP, NTCP and UTCP. The clinical example of treating prostate carcinoma with a four field box technique using three different uniform margins was used to test the sensitivity of a number of treatment uncertainties on calculated outcome. The outcome (simulated as TCP, NTCP and UTCP) for an individual patient, as well as averaged across a population of patients was calculated.

The prostate TCP was insensitive to the magnitude of geometrical errors with treatment margins of 10 mm and 15 mm. However, reducing the margin to 5 mm, produced a considerable variation in patient TCP across the population. Fluctuations in the dose were shown to reduce the gradient of mean TCP against dose. The effect on mean TCP from the dose uncertainties were masked beneath the considerable interpatient variation in radio sensitivity.

The dose deposited in rectal wall tissue varies noticeably between treatment fractions. However no significant change in mean NTCP was calculated. This agrees with the conjecture of Fenwick (2001) and calculations of Raggazzi *et al* (1997) and Lu *et al* (1995). The effect on mean NTCP from the dose uncertainties were masked beneath the considerable interpatient variation in radio sensitivity. Interestingly, fluctuations in fraction dose did affect the mean NTCP. Figure 6.14 compared NTCP calculated with the intended dose distribution against NTCP with variable fraction (using a standard deviation in dose of 5%). The fluctuating dose causes the gradient of the mean NTCP curve to reduce in similarity with the effect of fluctuating dose on the TCP. This leads to the mean NTCP curve crossing the planned NTCP curve. However, the rectum's volume effect plays a role, as illustrated in this figure by the mean and planned NTCP curves crossing at higher doses as the margin was reduced. Considering the geometrical errors, the volume of rectum receiving high dose fluctuated between fractions (as implied from the variation in rectal

surface area from the dose surface histograms in Chapter 5, refer to figure 5.12). NTCP calculated using the distribution of dose within the width of the rectal wall was shown (see figure 6.15) to be very close to the NTCP calculated with data from the dose surface histograms (i.e. uniform dose from each rectal wall surface voxel). This extenuated that the variations in volume receiving high dose were surprisingly low since they coincided with narrow lateral walls of the rectum.

In the dose range presented in figure 6.22, incorporating treatment errors leads to mean UTCP that increases with margin enlargements from 0.5 cm to 1.5 cm and possibly beyond. In this dose range UTCP follows the relation between TCP and margin size, because the prescribed dose was not high enough to cause substantial rectal complication probability. However, the 0.5 cm margin was more heavily penalised for geographical misses of the tumour. The dose-based estimate of optimal margin size from van Herk *et al* (2001) is 0.8, 1.4, 1.6 cm in the LR, AP and SI directions respectively. In this study, the outcomes are predominantly dependent on the AP margin because of the assumed interaction between anterior-posterior rectal wall movement and prostate motion. Therefore, comparing the UTCP results with the calculated AP margin, this study shows that the biological parameters are less sensitive than the dose-based calculations to treatment variations.

Chapter 7

Treatment planning algorithm corrections to account for and display dose uncertainty in radiotherapy

7.1. Introduction

7.1.1. Possibilities for future radiotherapy treatment planning

From the literature discussion in Chapter 2 it is clear that a number of uncertainties within the treatment planning process are compromising technological improvements in radiotherapy. The major treatment uncertainties include patient positioning, organ motion, and region of interest delineation. The literature review in Chapter 2 also described a number of modern methods to reduce/account for these uncertainties.

In the holistic approach to RTP the discussion and basis for this chapter may be woven into each of the techniques discussed in that review. The uncertainty in radiotherapy needs to be reduced for many reasons, but there are currently limits to the amount by which it may be reduced. That is, even if the patient is rigidly fixed to the couch each day of treatment, imaged, and (re-)planned in that position an uncertainty still exists. For

example, incorrect tumour delineation because of a lack of biological information in the CT image or simply poor contrast, machine output fluctuations, radio resistant tumour (or radio sensitive normal tissue). If daily imaging is too labour intensive (for the entire treatment) then predictive techniques need to be developed and knowledge from serial CT studies need to be implemented.

Ten Haken *et al* (2001) presented a statistical method to include both patient and population specific distributions of uncertainty. Other workers have presented work with a similar goal (Lof *et al* 1998, Mageras *et al* 1999) fuelled by interpatient differences and the chance that any given patient may not conform to the population distribution.

7.1.2. Purpose

An uncertainty in the dose delivered to target and normal tissues exists. Moreover, the fluctuations in delivered dose may have an effect on tumour and normal tissue responses to radiation. It is therefore important to include in treatment planning systems a means to evaluate the potential errors and predict their (dosimetric and radiobiological) relevance. Accordingly, the effect of potential errors could be accounted for more extrinsically in the planning process.

Furthermore, the current treatment planning algorithms could be improved to (optionally) include the statistics of random errors and systematic errors. This can be achieved for each of the 3 most common groups of treatment planning algorithms including correction-based (Milan/Bentley with inhomogeneity correction) calculations, convolution/superposition, and Monte Carlo.

Once the basic input data (i.e. beam and uncertainty data) has been included into the treatment planning computer, visualisation tools are necessary to evaluate their effect. A number of visualisation tools are explored in this chapter.

In addition to visualisation, these tools would also be used in comparison of rival plans. Information accrued relating to the treatment errors may be used for predicting suitable CTV-PTV margins, however, added value may be achieved by also allowing planners to

visualise dose related ramifications of certain choices; hence further intellectualising the decision making.

7.2. Modifications to dose calculation algorithms for photons

Current treatment planning software enables the user to calculate the dose deposited in tissue based on CT images and linear accelerator output information. The algorithms used require slightly different input data to calculate dose and have associated accuracies. The most common dose calculation technique is the correction based technique, but the more recent convolution/superposition technique* will soon become the most widely available. Monte Carlo techniques have long shown promise but have not been presented in commercial systems yet.

With each of these dose calculation techniques, there is a natural point in the dose calculation process where the inclusion of uncertainty could be placed. In this section, the algorithms are outlined and that ‘natural’ point where dose uncertainty could be placed and accounted for is highlighted.

7.1.3. Correction based techniques

7.2.1.1. Input data

The calculation of dose using the correction-based techniques involves a large amount of input data to characterise the beams from each linear accelerator. This data usually include a depth dose curve and several profile curves stored for a range of field sizes and each available beam energy. The data is measured in a water tank in the conditions specified by the TPS manufacturers.

* referred to as the superposition technique to avoid confusion with the previous convolution techniques described in earlier sections.

A dose distribution for a particular treatment beam and patient configuration is then determined by manipulating these data. Major consideration is given to factors including the position and shape of the patient external contour with respect to the beam and density variations, or inhomogeneities, within the patient.

7.2.1.2. Dose calculation

Dose calculation with correction-based techniques involves correcting the measured dose data according to the CT density and other information. The basic dose calculation model was proposed by Milan and Bentley in the early 1970's (Milan *et al* 1974). The original model was improved through the years to correct for changes in SSD, surface curvature, and basic (effective pathlength) inhomogeneity correction. The dose to a point (x,y) could then be calculated from

$$D(x, y) = G(d_{eff}, FS_s) L(d, y', FS_1) \left(\frac{SSD_1 + d_{max}}{SSD_1 + x} \right)^2 \quad (7.1)$$

where G is the infinite SSD dose (measured), L is the off axis ratio, and the third term is the SSD correction. The infinite SSD dose is calculated for the effective depth, d_{eff} , and field size at the surface, FS_s , with the inverse square law removed. The effective depth is calculated using the densities in the path of the photon beam from the CT density information as the equivalent depth in water. The off-axis ratio at depth, d, off-axis distance, y' (projected to that at the reference SSD) and field size, FS_1 (projected to reference SSD). The last term in equation 7.1 accounts for changes in the SSD from those in the reference conditions, where x is the current SSD.

The Milan/Bentley model calculates dose reasonably accurately in water equivalent media, but density heterogeneities have been shown to be poorly predicted. This is because of the simplistic manner with which the model accounts for heterogeneities, that is, without including the complexities of scattered photons or secondary electrons.

More recent inhomogeneity correction techniques calculate the dose near inhomogeneities more accurately than the effective pathlength method. Some of these include, in increasing sophistication, effective depth method, Batho power law method, equivalent tissue air ratio (ETAR) method, differential scatter air ratio (DSAR) method, the delta volume method, and fast fourier transform (FFT) convolution method. Most of the treatment planning systems in the 1990's used this style of correction based technique for calculating dose corrected for the clinical situation.

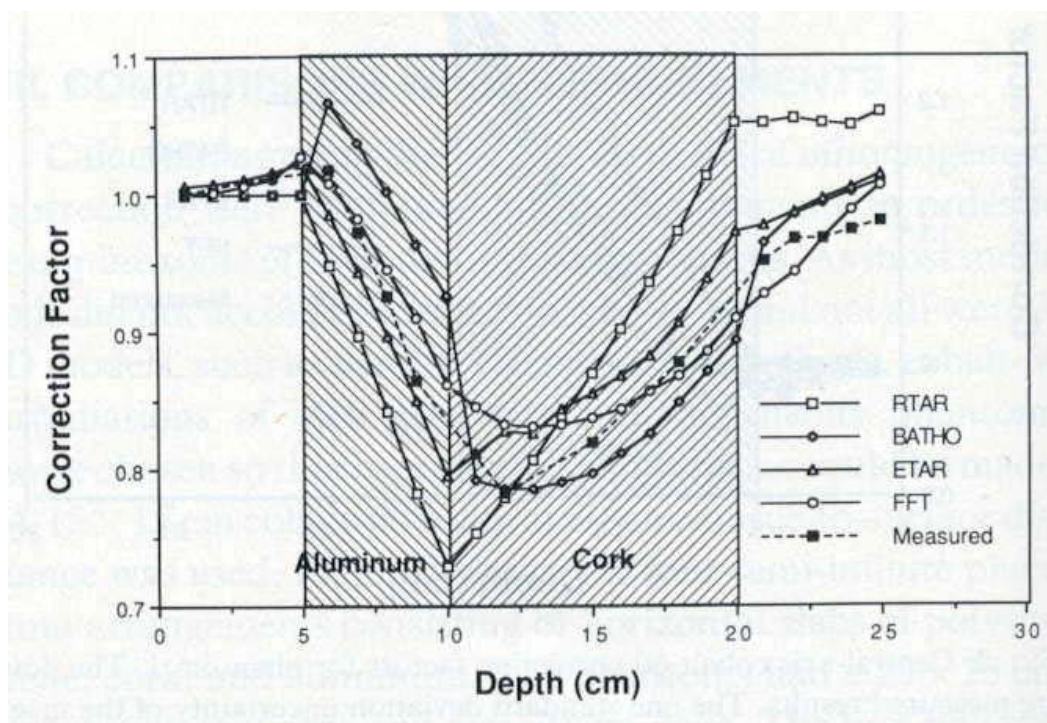


Figure 7.1 Correction factors for various inhomogeneity correction techniques versus depth in different density media. Taken from Wong and Purdy (1990).

As expected, the figure shows that the 3D non scatter ray trace methods (ETAR and FFT) are clearly superior in accuracy to the 1D non scatter ray trace methods (RTAR and BATHO). Furthermore, Wong and Purdy (1990) calculated the mean difference between the calculated and measured doses for each inhomogeneity correction technique. That comparison showed the 1D techniques to vary about their mean with standard deviation of 7.72% and 4.14%, for the RTAR and BATHO techniques, respectively. While the comparison between 3D techniques both showed standard deviations of about 3%. A number of other, less complex, geometries were also tested with similar results.

7.2.1.3. Including estimations of error

The dose data available to manipulate with the correction based dose calculation techniques is limited to a set of measured dose points. To include error in the calculation, a new set of source data will have to be calculated from the original measured data. The calculations are aimed to model the “equal” set of data which would have produced the same dose distribution in a static patient as realistic data set produces in the patient subjected to positioning errors and organ motion. Positioning errors and organ motion can only be accounted for as combined error.

7.1.4. Superposition technique

The superposition technique for calculating dose uses is a model based method. This means that beam data is collected and used to characterise a model for that beam. Each calculation of dose will then be based on that model.

7.2.1.4. Input data

Characterisation of a particular treatment beam will typically include measurements of the depth dose, off axis ratio, and wedge factors for all field sizes. The characterisation involves generating a model of the incident fluence. This may be done by fitting parameters in the software such that the prediction agrees with the measured data.

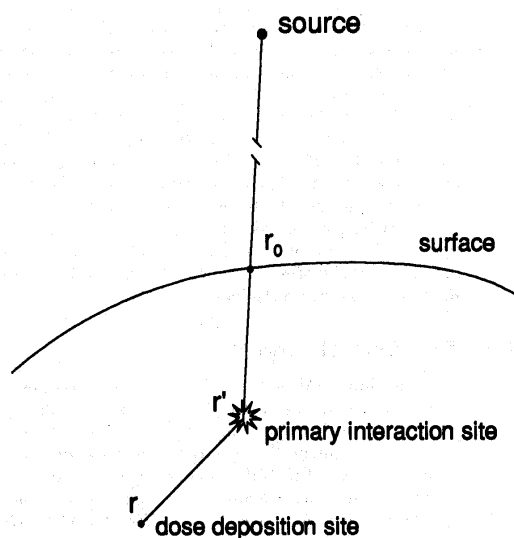
7.2.1.5. Dose calculation

The general form of the superposition dose calculation equation for a polychromatic beam in an inhomogeneous media, is

$$D(r) = \frac{1}{\rho(r)} \int_{r'} T(r') \rho_e^w(r') \cdot [H_p(\rho_{ave}, r - r') + H_s(\rho_{ave}, r - r')] \frac{\rho_e^w(r')}{\rho_{ave}} d^3 r' . \quad (7.2)$$

where the term $\rho(r)$ is the density at vectorial point r in the medium, $T(r')$ is the TERMA calculated at point r' , $\rho_e^w(r')$ is the relative electron density of the media compared to water at point r' , H_p is the primary kernel, H_s is the scatter kernel.

TERMA is the total energy imparted to the medium by the interactions of primary photons, and the kernels represent the energy imparted about a primary photon interaction site, as a fraction of the TERMA at that site. The deposition and interaction sites/voxels are illustrated in figure 7.2. The kernel will equal the sum of primary and scatter kernels. The kernels for each voxel are usually calculated through a MC process. The TERMA for the region of interest (where dose calculation is to take place) will usually be calculated before the actual dose calculation.



*Figure 7.2 The superposition dose calculation technique models primary fluence interactions at r' and the probability of dose deposition in surrounding voxels, including that voxel centred at r . Adapted from Metcalfe *et al.* (1997).*

The literature has shown many examples of complex geometry where the superposition dose calculations are more accurate than those using correction based methods. Regions of sharp change in density are, however, not accurately modelled with the superposition algorithm. Metcalfe *et al* (1997) show an over estimate of dose in an air cavity and under estimation after the air cavity. These results are reproduced in figure 7.3.

7.2.1.6. Including estimations of error

The superposition technique calculates a fluence profile prior to dose calculation. This provides an advantage over the correction based technique, in that the patient positioning errors are more naturally accounted for in the fluence rather than the dose (Lof *et al*

1998). This is because patient positioning errors will affect the location that each beam is incident. In this case patient positioning error can be considered separately from organ motion. This would result in the fluence being convolved with a patient positioning error distribution function, then the incident fluence itself has been ‘corrected’ for uncertainty before it is used for dose calculation. Therefore, the effect of uncertainties near heterogeneities can be more accurately estimated.

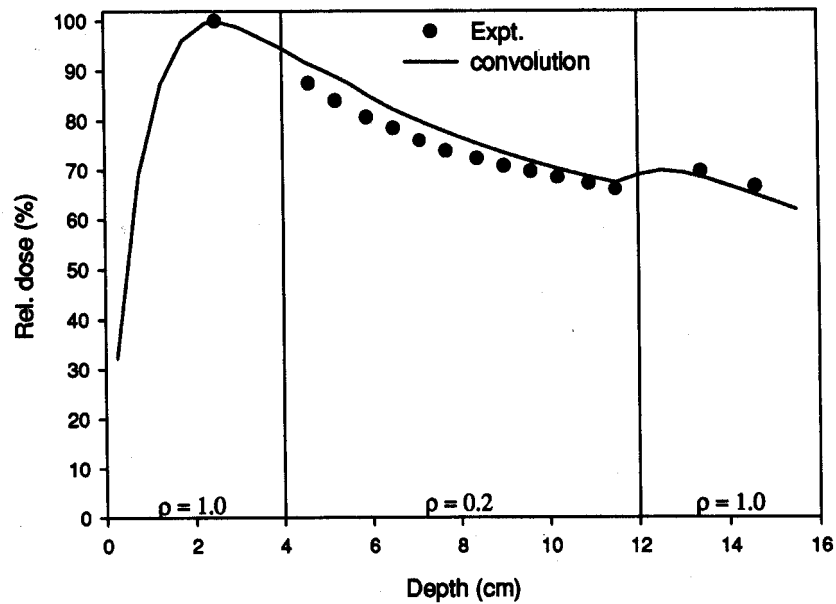


Figure 7.3 The superposition dose calculation overestimates dose in lower density media and underestimates after lower density media. Taken from Metcalfe et al. (1997).

Accounting for organ motion can be done using convolution or MC based techniques. The convolution technique will be faster than the MC, but has important assumptions that should be understood, including the number of treatment fractions, and translation motion only etc.

7.1.5. Monte Carlo technique

The Monte Carlo method calculates the deposited dose from first principles and models the interactions of incident particles along their path length. The most common MC method used in radiotherapy is EGS4 (Electron Gamma Shower[†] version 4) and is used below to exemplify the MC method. Currently, most TPS (treatment planning system) manufacturing companies are in the process of producing MC based TPS, but there are not many systems on the market. The knowledge has been available for many years to be able to do this, but the lack of computing power (and reasonably accurate results with the superposition technique) has slowed the introduction of this technology.

7.2.1.7. Input data

The EGS4 MC code is a computer program containing three main parts: the *user code*, the *EGS4 system code* and *PEGS4* file. Only the third of these is completely an input file. The PEGS4 file specifies the physical properties of each material in the given geometry. These include cross sections, mean free paths, and electron stopping powers.

The user code does contain some precalculation parameters, such as incident beam specifications (fluence, energy spectrum etc), and the output requirements of the simulation (e.g. dose deposited in voxels). The user code also performs functions during the process including recording the parameters of interest, recognizing when a transport step will place a particle in a new region, and outputting results.

The EGS4 system code is generally not accessed by the user and it contains the routines to actually transport each particle through the medium.

7.2.1.8. Dose calculation

Dose calculation involves following incident particles as they deposit energy in the medium until they fall below a threshold energy. The incident particle is followed in

[†] Website: <http://www.slac.stanford.edu/egs/>

steps, that is, after a pre determined distance the status of that particle is reassessed. At this stage generation of electrons is modelled when the particle under consideration is a photon. If this is an electron, energy deposition to the media is modelled at each step of the trajectory. Inter fraction fluence or variations would not be modelled though. The new status is based on the probability of the particle undergoing certain interactions and will depend on the particle energy and current medium. When the predetermined lower energy cut-off is reached the remaining energy is deposited at that step.

A large number of incident particles are required, due to the stochastic nature of the interactions, to reduce the uncertainty of the result. The uncertainty of the result will also be dependent on the cut-off energies and step size (distance to next interaction) chosen.

The large number of incident photons will create an even larger number of low energy electrons in the medium. Generally the uncertainty will only reduce as the square root of the increased number of incident particles. Therefore, the number of particles must be quadrupled in order to halve the uncertainty. Much effort has been expended to reduce the uncertainty in MC results and improve the efficiency (Keall *et al* 2000). Three of these techniques are geometric interrogation, Zonal discard, and the reciprocity technique (Metcalf *et al* 1997).

7.2.1.9. Including estimations of error

The inclusion of dose uncertainty into an MC technique, such as EGS4, would be relatively straight forward (as compared to other the techniques). For MC based dose calculation techniques the uncertainties can be potentially included in a number of places including within the user code.

The incident beam fluence may be manipulated to better reflect the interfraction or interpatient mean fluence distribution. The geometry of the patient can be manipulated to account for organ motion. This would best be accomplished with detailed data, but again predictive power is limited to population data in most cases. Still, multiple CT image studies could be shown on screen with the dose calculated to accommodate patient positioning errors.

7.3. Requirements for display input data

The visualisation technique will obviously depend on the data available to be displayed. In this section the possible variables that are available to be plotted are discussed.

The most common variables for plotting would be the mean dose and the standard deviation in dose. Such parameters can be extended to calculation of modified DVH's (e.g. CL-DVH), BED calculations with mean treatment dose or variable dose per fraction, and other biological indices including equivalent uniform dose, TCP, or NTCP.

A number of methods have been proposed to calculate the standard deviation in mean fraction dose across a treatment, and mean treatment dose across a patient population. Methods to calculate the standard deviation in dose are briefly outlined below, together with discussion of non-standard deviations in dose. Non standard deviations, perhaps a colloquial term, refers to the characterisation of dose PDFs that are not Gaussian and was used by Goitein (1983).

7.1.6. Standard deviations

For a particular patient the standard deviation in dose can be calculated from (Zavgorodni 1997, Lujan *et al* 1999):

$$\sigma_D(x, y, z) = \sqrt{\left(\iiint D_0^2(x', y', z') dx' dy' dz' - \bar{D}^2(x, y, z) \right) \times g(x' - x, y' - y, z' - z)} \quad (7.3)$$

where D_0^2 is the planned dose to a point x', y', z' ; g is the spatial PDF describing random setup uncertainties, and \bar{D} is the mean dose. The mean dose can be calculated using techniques described in chapter 4 (i.e. MC or convolution).

For a population of patients, the systematic error for each patient will be distributed about the mean systematic error of the population. In chapter 4 the MC method was used to

calculate the standard deviation in dose across a patient population, including systematic uncertainty.

7.1.7. Non standard deviations

In chapter 4 (refer to §4.2) the distribution of dose errors was shown to be Gaussian only in those (very small sections) of dose distribution where the dose changes linearly distance. In all other sections of the dose distribution, the dose PDF will be non-Gaussian. Consequently, the mean will not coincide with the mode, and the standard deviation may not give a clear indication of the spread of dose values (see figure 7.4 below). In this case, the mode and FWHM (Full Width at Half Maximum) may be more useful, but these parameters will be position dependent.

The cause of this non-Gaussian dose PDF is of course the physical limits of maximum and minimum dose. This was discussed in §4.2.2. At doses near the maximum dose, say at 99% of the maximum dose the probability of reducing this dose due to misalignment is the same as an increase, however, the increase is limited to 100%. A larger range of lower dose values exists and the dose PDF will be non-Gaussian.

For the case of non-standard deviations, one way to express them would be to assign a mean value. With estimated standard deviation (Goitein 1983) this would then look like, for example, 99% (+0.5% / -2%). The estimated standard deviation could be calculated from the dose PDF as the definite integral from the mean or mode to the point on the curve where the integral equals 0.66/2 (i.e. 1 SD) of the total integral.

Some of the techniques to display the parameters mentioned above are outlined and illustrated in the next section.

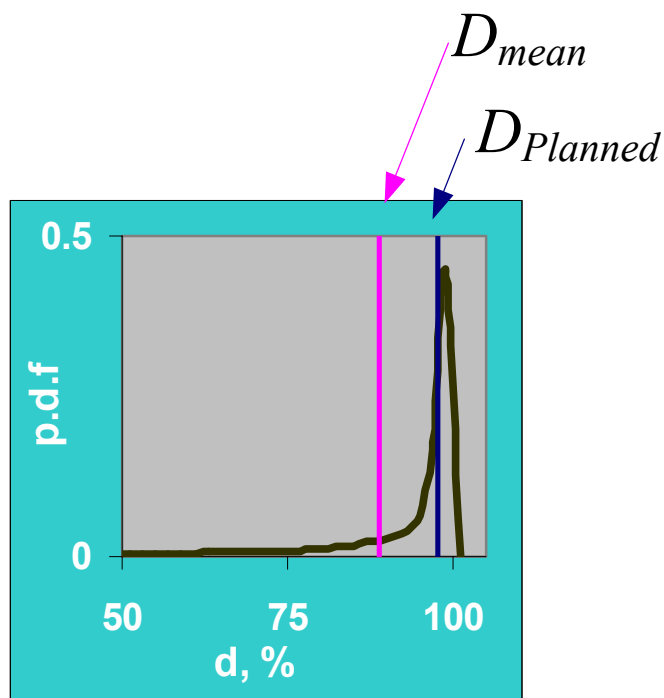


Figure 7.4 Dose PDF at the medial edge of the penumbra.

7.4. Treatment planning displays

The current display tools that are commonly used in practise are isodose plots, and DVHs. The DVH is important to summarise the 3D planning images that are difficult to comprehend alone. Traditionally this was done using the series of 2D isodose plots on transverse CT slices or 3D dose or volume visualisation tools. The DVH is becoming increasingly important as volume constraints on normal tissues are realised.

Four possible types of visualisation tools that extend beyond those conventional tools include displays of mean dose and/or SD, displays relating to the dose PDF, displays of modified DVH's, and difference maps illustrating the 'deviation in dose' between the planned and delivered dose distribution.

7.1.8. Mean dose and/or standard deviation

The mean treatment dose may be calculated for a population of patients or for a particular patient, using convolution or MC based techniques. Typically, the mean treatment dose will show a decreased penumbra slope.

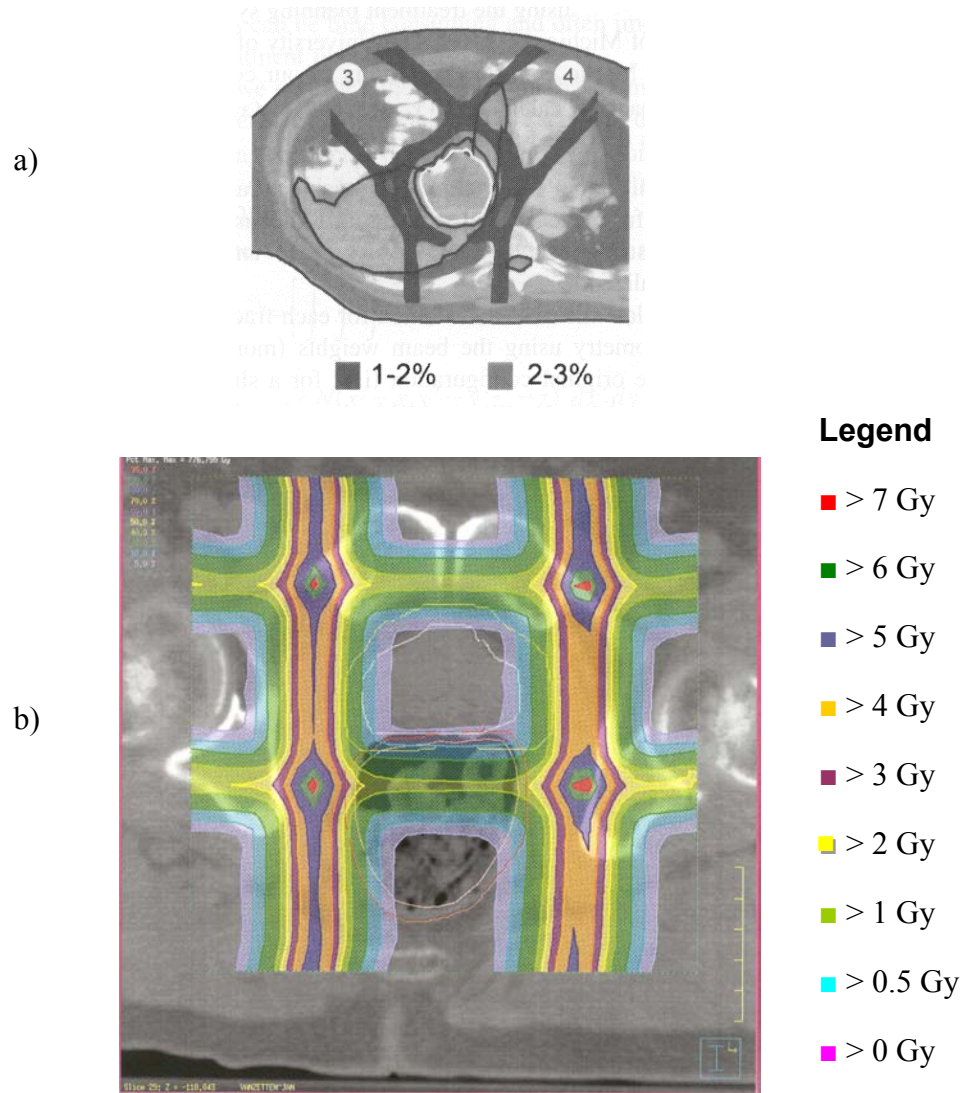


Figure 7.5 Standard deviation isodoses for a) a liver treatment including random patient positioning errors (Taken from Lujan et al. 1999) and b) a 4 field prostate treatment (reproduced from Chapter 4).

The standard deviation in mean treatment dose accounting for the random error is easily calculated (c.f. §7.3.1). An example of the standard deviation in dose is shown in figure 7.5a for the case of random errors in an individual patients' treatment. (The region

illustrating 2-3% dose uncertainty is outlined in black.) This visualisation tool would enable the user to clearly understand where the uncertainty in dose occurs and the expected range of delivered doses. The interpatient standard deviation in treatment dose can also be displayed in the same way, as isocontours or as a colour wash (figure 7.5b).

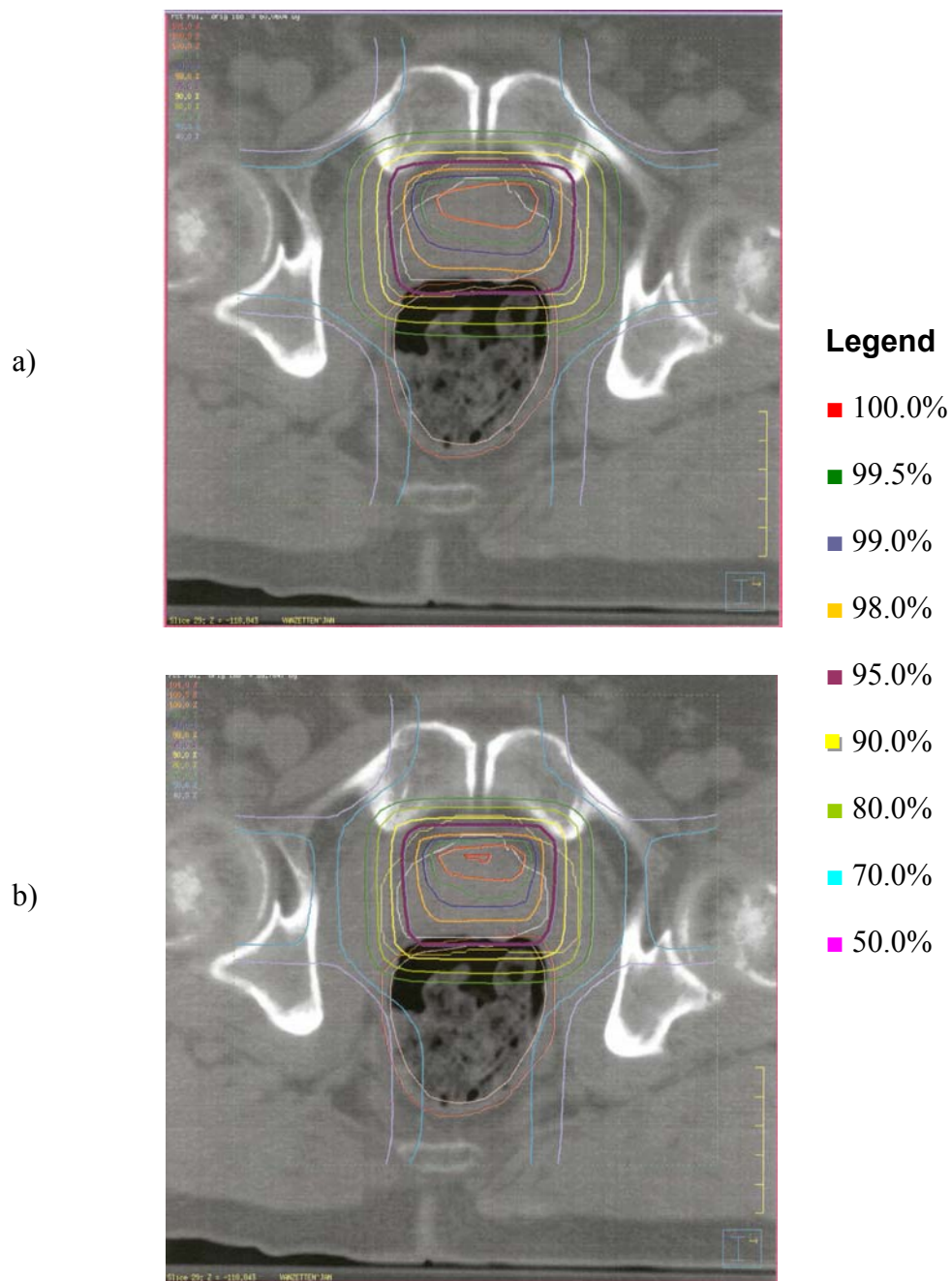


Figure 7.6 a) Mean isodose contours, and b) Confidence limit plot showing the minimum dose received by 90% of the population.

Confidence limit plots featuring, for example, the mean plus or minus a number of standard deviations in dose may also be useful. Figure 7.6 shows a confidence limit plot of mean dose minus 2 standard deviations, which demonstrates the minimum dose received by 90% of the population. The planner would be able to notice that in figure 7.6b the 90% isodose line (purple) indicating the minimum value sampled from 90% of the population is inside the left prostate border.

For a more biologically relevant expression of the effect of dose uncertainty, the biological effective dose could be displayed. Although, displays of BED will have discontinuities at tissue interfaces this reflects tissue/tumour response more explicitly because the BED calculation depends on the tissue properties of the irradiated organ.

7.1.9. Modified dose volume histogram

The DVH is a convenient method to summarise the 3D information from a particular treatment plan. Many authors have used the DVH to highlight the different doses deposited to a volume of interest after each days treatment measured with serial CT studies (Lattanzi *et al* 1999, Zelefsky *et al* 1999).

Through the prediction of volume of interest dose Mageras *et al* (1999) have proposed the confidence limited (CL) DVH (c.f. §2.5). Briefly, the CL-DVH describes a mean dose DVH, according to specified confidence limits (see figure 7.8a). Naturally, the confidence limits will depend on the number of fractions delivered. Lujan *et al* (1999) showed the reduction in uncertainty about the mean as the number of fractions increased using a DVH (see figure 7.8b).

7.1.10. Mean with estimated standard deviation display

To calculate a standard deviation assumes that the dose at that point is normally distributed about the mean. Clearly, from the dose PDFs discussed previously, this is not the case. At positions medial to the penumbra the deposited dose will more likely decrease than increase, and vice versa at points lateral to the penumbra. In this case, the non symmetric estimated standard deviations will need to be displayed.

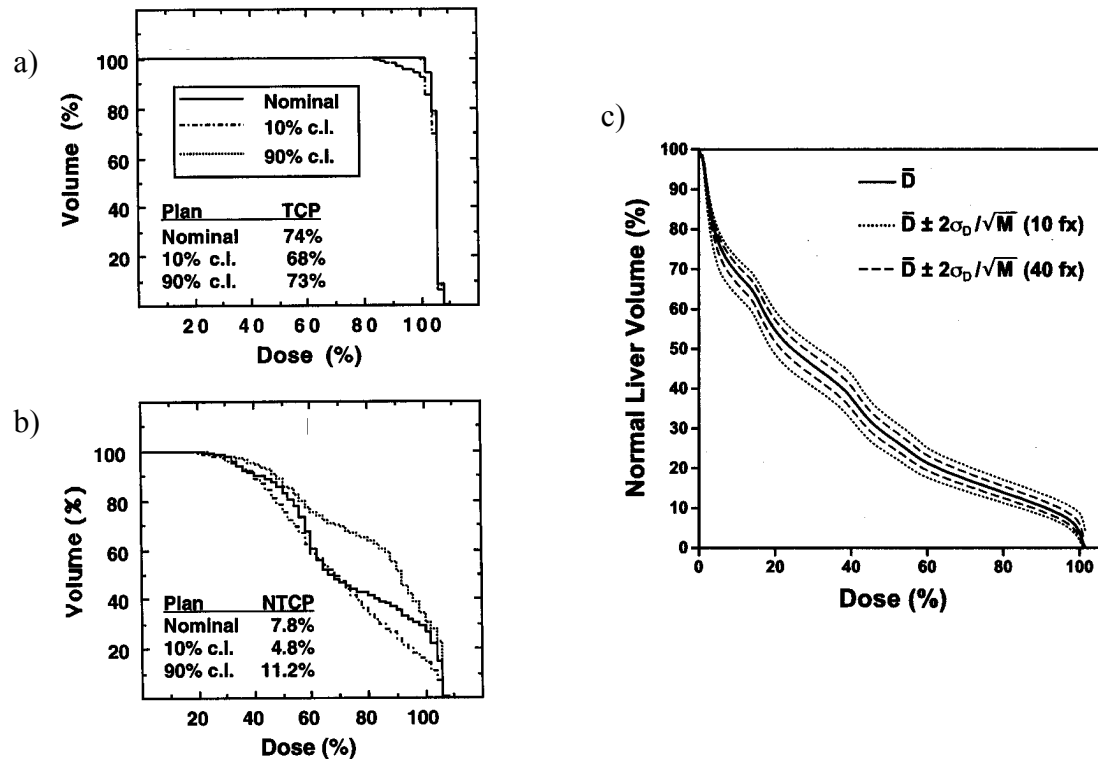


Figure 7.8 The CL-DVH from Mageras et al (1999) a) for prostate and b) rectum, and b) the DVH accuracy increases with the number of fractions (from Lujan et al 1999)

Given the dose PDF of each voxel, a range of parameters can be plotted similarly to the conventional isodose plots. These are the mean dose and modal dose. In analogy with the standard deviation, the FWHM can be calculated and also the distance from the mean value including 95% of responses. This (latter) distance will highlight the tendency of the probability because dose uncertainty in the upper region of the planned penumbra will more likely show decreases in dose than increases and vice versa. Ofcourse, depicting the uncertainty is difficult and displaying more than one isodose with error bars would be confusing for the viewer. Therefore, each isodose should be viewed separately with it's error bars as shown in figure 7.9 below. The MC derived $G(D)$ functions (refer to §4.2.2) may therefore be used to calculate the +% and -% for particular situations.

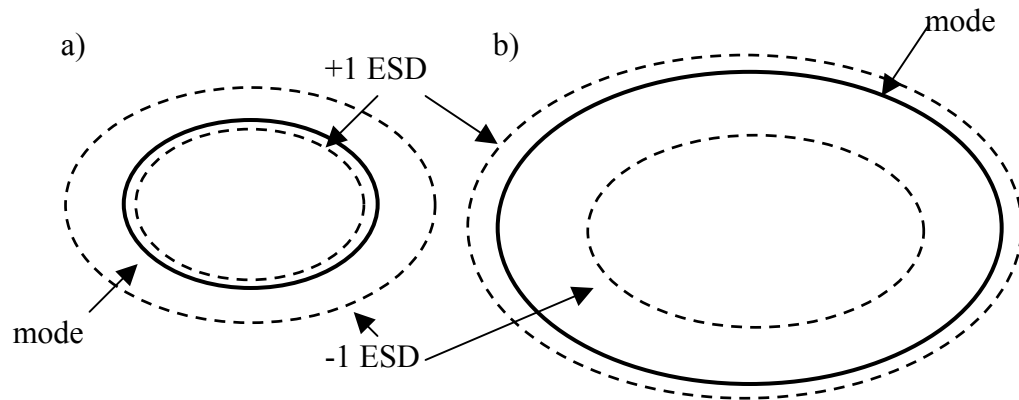


Figure 7.9 Schematic of the a) 95% modal isodose, and b) 30% modal isodose with error bars indicating a 95% chance of depositing given dose.

7.1.11. Difference maps

The difference between planned and delivered dose can be illustrated with difference maps (Lujan *et al* 1999). Lujan *et al* (1999) calculated difference maps for liver dose including the effect of random patient positioning errors, as shown in figure 7.9.

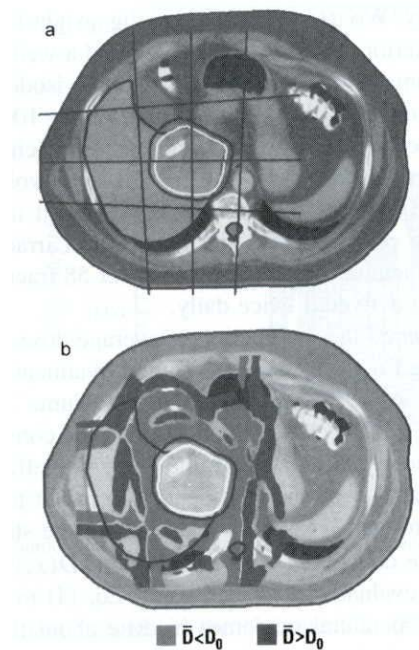


Figure 7.10 Single axial slice showing lateral and AP beam orientation, b) dose difference display:

$\bar{D} - D_0$. Taken from Lujan et al. (1999).

Difference maps have been used for many years in allied fields as a simple way to view gross changes in images or matrices.

7.5. Critical evaluation of uncertainty display tools

There are many factors affecting the success of tools in treatment planning software including; ease of use, value, scientific integrity and marketing of the tool. If a tool was available to display the uncertainty in dose, it is understandable, that for some planners the visualisation of ‘error’ or ‘uncertainty’ in dose could be unsettling. For other planners, this visualisation tool could be reassuring. In this chapter a number of tools have been introduced or discussed and in this section they will critically evaluated for *usefulness*, *ease of implementation* and *value*. The scientific integrity of each tool has already been discussed, and the marketing of any such tool is not relevant to this thesis. The author believes that true value will only be achieved from dose uncertainty display tools if they are used together with current display tools, such as isodose plots, surface maps (of 3D structures and rectal surfaces), dose-volume or -surface histograms etc.

General concerns for each of the dose uncertainty display tools is organising the data to be displayed in such a way as not to crowd the viewing screen. For example, when displaying estimated standard deviations, it would be best to display only one isodose line/surface with the two estimated standard deviations accompanying it on the screen. Otherwise, the planner could easily get confused between the multitude of lines, and their associated meanings.

Another general facility would be to switch between different displays and plans. Thus, the planner could view the difference between the dose fluctuations in the rectal wall with the 6 field technique against the fluctuations with the 4 field technique. The question then is; which plan is better? The answer is to use other tools and make a balanced, educated decision.

Tool 1 mean and/or standard deviation (SD). This tool is relatively simple to implement, using the convolution technique, if the user has access to some dose display components of the treatment planning software (Keall *et al* 1999). As outlined previously, it would be best to use the incident fluence to acknowledge the influence of tissue inhomogeneity on mean dose calculation. The author's intent would be for the planner to be able to switch between mean and SD displays from the current isodose display.

The value of displaying the mean dose is the realisation that the portion of tissue in the upper beam penumbra actually receives less than the planned dose, and vice versa in the lower penumbra. For a particular technique, the mean dose may not differ substantially between patients; however, it would still be useful to confirm the planners' experience. In particular cases, tissue heterogeneities could produce large discrepancies from the standard plan.

The value of displaying the standard deviation in mean dose is the realisation of both the magnitude of inter-fraction dose differences, and the location of these differences with respect to the tumour, organs at risk, and beam penumbra. For a particular technique, the standard deviation in dose will depend on the gradient of the beam penumbra, number of beams, method of beam delivery, tissue heterogeneities, and the amount of patient/organ position variability. The standard deviation in dose may not be as accurate as the estimated standard deviation, which acknowledges the beam penumbra and care should be taken to understand the meaning of the display.

Tool 2 - modified dose volume histogram. The importance of defining the statistical confidence of dose delivery and the volume of tissue receiving each dose level is paramount for both delivering a high quality treatment and building an accurate database on biological effect. The user should understand how the data used to create the display are themselves calculated.

The ideal use of modified dose volume histograms is combined with biological tools (such as TCP and NTCP) to endorse decision making between rival plans. Biological tools are currently used to differentiate overlapping DVH's. For example, Plan 1 has a higher mean dose for the spinal cord, but Plan 2 has a higher maximum dose for the

spinal cord. The structure of the spinal cord and its impact on dose response is assessed through, for example, the seriality variable in the Kallman s-model for NTCP.

Tool 3 estimated standard deviation (ESD). The ESD is potentially a very useful tool to display the effect of patient/organ position uncertainty on the beam penumbra. The ESD is also instructive for the planner to develop a thorough understanding of the spatially non-uniform dose uncertainty by visualising the uncertainty about a number of isodose levels.

Tool 4 Difference maps. The difference between the planned dose calculated for a number of plans could be useful to quickly identify the location of benefits of one plan over another. The difference between a planned dose distribution and a calculation of the actual dose delivered would be more of an educational tool. Similarly, with the difference between the calculated actual dose distributions from a plan with 1 planning CT image and another plan with 5 planning CT images.

Most of the above considerations have regarded forward planning and in some ways the above discussion has moved away from the recommendations of the ICRU. That is, there is little discussion regarding the internal margin or the setup margin, only the clinical target volume. The IM and SM seem to be inflexible measures that feed the incorrect notion that dose uncertainty is not stochastic, or at least the solution cannot be stochastic. The bulk of this thesis has been devoted to deconstructing this notion and, in this chapter, to provide examples on how to provide visualisation on the variability in dose. The clinical impact of such display tools would be farther reaching than simply displaying dose uncertainty, it would educate planners, clinicians and physicists. The simple implementation of a mean dose display or an ESD display would demonstrate repeatedly that the planned dose distribution is not what is delivered to the patient. Of course, to optimise the planned dose should improve the actual delivered dose, but it may not be optimal. These display tools allow the planner to investigate the impact of certain stochastic variables themselves.

In the current climate of continuing technological impact on radiotherapy, it is interesting to suggest 'ideal' uncertainty display tools. The ideal uncertainty display tools should

contain elements of both dose uncertainty and biological uncertainty. Naturally, to cloud current estimates of biological effect with the associated uncertainty in parameter values (with standard deviations around 20% of the mean value) or the models themselves may unsettle some workers. The ideal tools for displaying dose uncertainty, in the author's mind, is a combination of the confidence limited DVH, assessed along side plots of ESD and maps of isoeffect accounting for biological uncertainty.

7.6. Conclusions

Treatment planning might be positively impacted by the availability of visualisation tools for assessing potential 'dose of the day' and likely variations of the dose. The impact of visualisation tool will obviously depend on the quantity and quality of uncertainty data. Each of the three broad types of dose calculation engine has the possibility of using uncertainty data. Four techniques for displaying uncertainty in deposited dose have been outlined. Each of these techniques will offer specialised information that can be used to increase knowledge of potential ramifications of each treatment design.

Chapter 8

Conclusions and further research

Uncertainty exists in every step of the radiotherapy process. The systematic and random components combine to impact on the actual dose delivered to tumour and normal tissue.

The aims of this research, as outlined in Chapter 1, were as follows;

- o to estimate the difference between the planned and deposited doses in the prostate gland and rectal wall
- o to calculate the biological effect of the differences between the planned and deposited dose
- o to investigate tools to visualise the uncertainty in dose delivery.

To achieve the first aim the radiotherapy process was modelled using two models: a Monte Carlo (MC) computer simulation and a novel adaptation of the convolution technique. Both methods accounted for the major sources of systematic and random treatment uncertainty. The major sources of treatment uncertainty include systematic and random organ (prostate and rectum) motion, systematic and random patient positioning errors, and interfraction linear accelerator output variation. The impact of these uncertainties on delivered dose for an

individual patient and also for a population of patients was investigated. The relative importance of these uncertainties with a number of margin sizes was investigated.

To achieve the second aim the radiobiological response of the prostate gland and rectum were modelled using radiobiological models from the literature. The impact on local control of the prostate from the treatment uncertainties was investigated using the linear quadratic model for cell survival. To investigate the impact of treatment uncertainty on rectal complications, the Källman s-model was applied. Interpatient variability in radio sensitivity was modelled across the patient population. The importance of margin size was tested in combination with each of the uncertainties.

Visualisation tools were investigated to display the uncertainty in delivered dose.

8.1. Major conclusions

The relative importance of the components contributing to uncertainty in the dose delivered to the prostate gland and rectum wall has been investigated from calculations of biological indices.

The impact of treatment uncertainties on the delivered dose to the prostate gland and rectum wall was investigated. The planned dose delivery was with a 4-field box technique and three margins between the CTV and PTV were used.

Monte Carlo and convolution models were used model the treatment planning and delivery. Both of the models agreed that random positioning errors will cause a decrease in the penumbra gradient for individual patients over the course of treatment delivery. Considering only random positioning errors for an individual patient, the dose deposited at the edges of the PTV will be decreased from the planned dose. More importantly for the individual patient is systematic positioning error that will shift the entire dose distribution and may lead to significant tumour under dosage.

Across a population of patients the systematic positioning errors were modelled to follow a Gaussian distribution. This effectively increases the standard deviation of the error across the

population and results in further smearing of the penumbra. The standard deviation (SD) in mean treatment dose significantly increases due to systematic error. A three - fold increase in the dose SD is calculated across a patient population by incorporating the systematic error. Previous studies did not include the systematic error; however, this investigation demonstrates it's importance. Both models showed that the estimation of mean organ position in the treatment preparation stage, through averaging organ position in multiple CT image sets, does affect the mean treatment dose delivered. The MC model demonstrated the 3 fold decrease in dose SD that can be achieved by reducing systematic organ motion error across the patient population. The theory of combining uncorrelated standard errors in the mean (Montgomery, 1999) has been applied to extend the statistics/dose based margin size equations (Antolak and Rosen 1999, McKenzie *et al* 2000) to include multiple pre treatment CT scan organ position averaging.

The radio sensitivity of prostate carcinoma was fitted to the clinical data and varies between patients with a standard deviation of 28% as indicated from clinical trials in the literature (Zagars *et al* 1987). This uncertainty has been shown to dominate over the dose/position related errors if the margin is sufficient. Moreover, this variation creates a bi stable distribution of tumour control across the population. This demonstrates that for the treatment dose of ~60 Gy the majority of the patients will fall into one of the two categories: those patients who have high probability of tumour control, and those who have very low TCP. Only a small fraction of patients will have TCPs in the region of 0.1 – 0.9 (figure 6.8). This implies tumour control is less dependent on dose compared to the radio sensitivity of individuals. However, the dose escalation allows a substantial increase in substantially the number of patients with expected high TCP (figure 6.11).

Highly conformal dose distributions characterised by steep penumbra gradients were demonstrated to reduce tumour TCP rapidly (across a patient population) for inadequate margins. In particular, with a 5 mm margin the TCP reduction of 7% with the standard dose distribution increased to a reduction of 10% with the steeper penumbra dose distribution. Furthermore, the dose increase required to retain a mean TCP of 0.8 with the inclusion of dose uncertainty increased from 0.7 Gy with the standard dose distribution to 2.2 Gy with the steeper penumbra dose distribution.

The modelled rectal deformation caused large deviations in deposited dose from the planned dose (up to 25%) due organ motion and patient positioning errors. For an individual patient, the anterior rectal wall will move in and out of the PTV during the treatment delivery if a 5 mm margin is employed. Because the rectum is inevitably in the treatment field, organ motion and patient positioning errors would reduce the volume of rectum irradiated to over 75% dose (or treatment dose). This happens predominantly when the patient has a full rectum during the planning CT scan and consequently during treatment the anterior rectal wall will be posterior to the position in the planning CT image (as shown in figure 5.10). The largest effect will be with a 5 mm margin, where the percentage of rectal wall receiving high dose (i.e. >90% of prescription dose) reduces from 17% to 6%.

Conversely, those individual patients with treatments designed using a CT image set where the rectum is empty may receive larger areas of rectal wall with high dose during treatment delivery (refer to figure 5.9). Again the plan with a 5 mm margin is more sensitive to dose variation than the plans with larger margins. The range of deviation in dose from the plan in that case is ± 15 Gy for a 60 Gy prescription dose. Also, the percentage of high dose volume does not change significantly as shown in the dose surface histogram (refer to figure 5.8). However, to compensate, the percentage of rectal surface receiving less than 50% of the prescription dose reduces from 96% to 75%. This highlights the importance of identifying systematic errors at the planning stage because they do impact strongly on the rectal dose.

Across a population of patients a Gaussian interpatient systematic error will not largely affect the mean rectal dose. However, the interpatient variation in rectal dose will be significant. The standard deviation in rectal wall dose is greater than 6 Gy (i.e. 10% of prescription dose) for some rectal voxels. By averaging CTV position from multiple pretreatment scans the standard deviation in rectal wall dose can be reduced to less than 2 Gy (averaging from 5 CT acquired images). The dose surface maps show that as the margin is increased the uncertainty in dose shifts from the anterior rectal wall to the lateral walls and affects a smaller percentage of the total rectal wall surface area.

The inter patient radio sensitivity of rectal wall tissue was fitted to the clinical data (Sanchez-Neito *et al* 2001b) and it's standard deviation shown to be to 15% of the mean value. Despite the large variation in dose deposited to the rectal wall and the volume of rectal wall receiving

high dose (>90% of prescription) the NTCP was predominantly affected by the inter-patient variation in radio sensitivity. At the prescription dose (64 Gy) the mean NTCP across a population is calculated as 0.08 ± 0.13 . This large standard deviation is primarily due to the inter patient variation in radio sensitivity. The literature presents other studies (Ragazzi *et al* 1997, Lu *et al* 1995, Fenwick *et al* 2001) that concur with the positioning errors having only a relatively small affect on NTCP. It is concluded that the major dose related effect on NTCP is due to the mean rectal dose derived from the margin employed. Due to the volume effect NTCP calculated with the smaller margin was less sensitive to dose variations than NTCP calculated with the other margin sizes.

Deciding on the optimal margin size is obscured when considering the TCP and NTCP separately. The composite index UTCP is calculated combining TCP and NTCP with equal weighting.

This study has highlighted a large difference between the potential doses delivered to individual patients and that averaged over a patient population. In the absence of generalised equations to calculate the margin size for individual patients, visualisation of potential dose discrepancies would be a valued tool. Some of population statistics regarding patient positioning error, organ motion, delineation errors and linear accelerator output uncertainty are recommended to be used in the TPS dose calculation algorithm. Further, statistical methods that adapt the treatment plan to individual patients should be used to shape the geometry and intensity of delivered fields.

8.2. Further research

Further work is suggested to consider the issues that are outside the scope of this thesis, particularly;

- o dose escalation
- o highly conformal dose distributions, such as those created using IMRT, tomotherapy or protons.

- o hypofractionation
- o adaptive radiotherapy

Based on the results in this thesis, these four situations and their potential effect on delivered dose, local control and complications have been discussed. However, a comprehensive modelling study to quantify the benefits or otherwise of each would be useful.

The convolution technique was shown to be a quick and accurate technique to calculate the mean dose and standard deviation, accounting for random translational errors. The MC technique calculated the standard deviation in treatment dose including also systematic errors. This was shown to be a useful quantity to calculate. For application of the convolution technique to account for patient positioning errors, the treatment planning algorithm should include user input parameters (such as population based patient positioning error variance and the number of fractions). These should be used to adjust the outgoing fluence so that the dose computation is more realistic.

With further refinement of the biological models and their parameters, particularly for rectal complications more detailed investigations of the effects on NTCP will follow.

Appendix A

The two most recent published papers derived from this thesis work are included in this Appendix. They include:

Booth JT, Zavgorodni SF. Modelling the dosimetric consequences of organ motion at CT imaging on radiotherapy treatment planning. *Phys.Med.Biol.* **46(5)**:1369-1377.

Booth JT, Zavgorodni SF. The effects of radiotherapy treatment uncertainties on the delivered dose distribution and tumour control probability. *Australas. Phys. Eng. Sci. Med.* **24(2)**:71-79.

Jeremy T Booth and Sergei F Zavgorodni (2001) Modelling the dosimetric consequences of organ motion at CT imaging on radiotherapy treatment planning. *Physics in Medicine and Biology*, v. 46 (5), pp. 1369-1377, May 2001

NOTE: This publication is included in the print copy of the thesis held in the University of Adelaide Library.

It is also available online to authorised users at:

<http://dx.doi.org/10.1088/0031-9155/46/5/303>

Jeremy T Booth and Sergei F Zavgorodni (2001) The effects of radiotherapy treatment uncertainties on the delivered dose distribution and tumour control probability.

Australasian Physical and Engineering Sciences in Medicine, v. 24 (2), pp. 71-78, June 2001

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<http://dx.doi.org/10.1007/BF03178349>

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