A Recoil Resilient Luminal Support

by

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Abstract



Cardiovascular disease (CVD) refers to a class of diseases affecting normal function of cardiovascular system and its momentous role to carry oxygenated blood to the entire body. Taking lives of more than 17 million people in 2008, CVD has yet remained as the primary cause of deaths around the world. Statistics from World Health Organisation in 2002 associated CVD with 10% of the disability-adjusted life years lost in low/middle-income countries and 18% in high-income countries.

Atherosclerosis, as one of the primary causes of CVD, refers to the thickening of vascular walls due to deposition of fatty materials wherein it can lead to impeded or completely occluded blood flow. Obstruction of coronary arteries, referred to as coronary heart disease (CHD), is estimated to become the single leading health problem by 2020. Occurrence and further development of CHD is associated with a number of biological and environmental factors such as an individual's genetic predisposition, lifestyle, climate conditions, exercise habits and emotions to name a few.

Treatment and management of vascular constrictions consists of a combination of nonsurgical and surgical methods. The former includes approaches such as healthy lifestyle changes and pharmacological interventions while the later includes bypass grafting, balloon angioplasty with or without deployment of a stent and atherectomy. Stents are mechanical devices that provide a chronic support against internal walls of occluded vessels to restore their normal luminal patency. In the past decade, stenting has prevailed as the conventional treatment option in management of CVD, exceeding current number of bypass grafting procedures, owing this success to its proven efficacy in short and long-term treatment of occluded vessels. Common stent structures are simply made of a metal mesh, e.g. stainless steel, and deployed in a blood vessel such as an artery during a percutaneous coronary intervention procedure, also known as angioplasty. Several attempts to meet the often self-competing objectives of stents such as high radial strength, low elastic recoil, axial flexibility, trackability in tortuous paths, biocompatibility and radiopacity gave birth to a multitude of different stent design and improvement iterations to date. The acute luminal gain after stenting is often compromised by the two most common post intervention complications, namely in-stent thrombosis (formation of blood clot) and restenosis (re-narrowing of the lesion). Induced trauma during stent deployment is proven to play a key role in the occurrence of these complications. Elastic recoil of stents after deployment due to the intrinsic material properties and the compressive forces from a vessel accounts for both acute and chronic luminal loss after stent deployment. Mitigation measures such as over-expansion in balloon-expandable (BE) stents and use of self-expandable (SE) stents so far have proven to aggravate vascular trauma leading to thrombosis and restenosis. Pharmacological approaches such as systemic administration of blood-thinners or localized drug release in drug-eluting (DE) stents aim to control these complications by inhibition of an accentuated inflammatory response from the body. Despite the promising results in reduction of restenosis after use of DE stents, increased rate of late thrombosis raised concerns about efficacy of these stents in comparison with bare-metal (BM) stents. Moreover, it is important to note that in these approaches the mechanical aspect of the problem still stands. As a result, to meet the oftencompeting aforementioned imperatives of stents, a new design paradigm is called for.

To address the issue of recoil and extend capability of current stents to controlled and incremental expansion steps with alternative expansion mechanisms, in this thesis a novel recoil resilient stent is proposed and developed. The proposed luminal support called a recoil resilient ring (RRR) is an open ring with overlapping ends and asymmetrical sawtooth structures from the two ends that are intermeshed. Utilized as a standalone support or integrated with other stent structures, upon expansion of the RRR, the teeth from opposite ends can slide on top of each other, yet interlock step-by-step in the opposite direction so to keep the final expanded state against compressive forces that normally cause recoil.

Design, fabrication and compatibility of the proposed stent with current state-of-the-art stent deployment procedures and its superior radial strength in comparison with commercial stents are extensively studied in this thesis through finite element modelling (FEM) and experimental studies. The RRR is fabricated from Nitinol sheets with transformation temperatures well above typical body temperature ensuring martensite mode of operation of the device after deployment. Fabrication is carried out by linear patterning of Nitinol sheets of 200- μ m thickness utilizing μ EDM technology. Superior radial strength of the RRR in comparison with a commercial stent composed of the stiffer material, stainless steel, is demonstrated via experimental and numerical studies.

Hemodynamic risk assessment of the proposed design as a standalone and integrated support compared with a typical commercial stent is then carried out by transient computational fluid dynamics (CFD). Subject to a realistic pulsatile blood flow, spatial and temporal restenosis risk indicators of three luminal supports are extensively studied utilizing CFD. These luminal supports include a standalone RRR, a nominal BE stent and an RRR-integrated stent. Risk factors including extension of areas subject to low wall shear stress as the primary risk factor of restenosis after deployment, tendency of supports to migrate in response to fluid drag forces as well as flow supply changes to side branches are extensively investigated. Furthermore, sensitivity of the results to the dimensional assumptions of the deployment domain, branching vessels and patency of the supports is studied. Our results indicate superior hemodynamic performance of the performance indicators of RRR-integrated stent and the standalone stent demonstrates minimal hemodynamic footprint of the proposed RRR highlighting its merit as a viable luminal support given its superior radial strength.

Attractive attributes such as shape memory effect of Nitinol, the thermally trained expanded shape of the RRR, its unique incremental slide and lock expansion mechanism and its higher transformation temperature compared to the body temperature, bring new potential for alternative controlled and incremental actuation of the RRR. These alternative expansion methods, by application of direct or electrically-induced heat are further explored through extensive analytical, multi-field numerical and experimental studies. The knowledge and contributions made in the current work, in addition to the design, development, experimental and multi-field numerical results provide a general engineering framework applicable to other biomedical luminal supports in the future. This page is left blank intentionally

Statement of Originality

This work contains no material that has been accepted for the award of any other degree or diploma in any university or other tertiary institution and, to the best of my knowledge and belief, contains no material previously published written by another person, except where due reference has been made in the text.

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Date

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In the end I dedicate this thesis to my grandfathers whose vision for excellence reverberated through generations and beyond.

Arash Mehdizadeh

Conventions



Formatting: For typesetting and image production of this thesis, Microsoft (MS) Office suite 2010 is used. Plots and images were generated using Matlab 10.0 (Mathworks Inc.) and MS Excel 2010.

Spelling: Australian English spelling is adopted, as defined by the Macquarie English Dictionary (Delbridge 2001).

Referencing: IEEE style is used for referencing and citations in this thesis managed by Endnote X6 (Thomson Reuters).

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Publications & Awards

Journal Articles

- **A. Mehdizadeh**, M. S. M. Ali, K. Takahata, S. Al-Sarawi, and D. Abbott, "A recoil resilient lumen support, design, fabrication and mechanical evaluation," *Journal of Micromechanics and Microengineering*, vol. 23, art. no. 065001, 2013.
- M. K. Kopaei, **A. Mehdizadeh**, D. C. Ranasinghe, and S. Al-Sarawi, "A novel hybrid approach for wireless powering of biomedical implants," *IEEE Sensors Journal*, 2013 (Submitted, Under Review).
- A. Mirsepahi, **A. Mehdizadeh**, L. Chen, and B. O'Neill, "A comparative approach between intelligent techniques and conventional methods for inverse heat transfer modelling of an irradiative dryer," *Journal of International Communications in Heat and Mass Transfer*, 2013 (Submitted).

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- **A. Mehdizadeh**, A. Miremadi, S. Al-Sarawi, M. Arjomandi, S. Mehdizadeh, B. Dally, and D. Abbott, "Optimal design of an offset strip fin heat sink using harmony search," in *38th Chemeca 2010: Engineering at the Edge*, Hilton Adelaide, South Australia, 2010, pp. 848-858.
- **A. Miremadi**, A. Mehdizadeh, M. Arjomandi, S. Al-Sarawi, M. Kahrom, B. Dally, and D. Abbott, "Taguchi based performance analysis or an offset strip fin heat sink," in *38th Chemeca 2010: Engineering at the Edge*, Hilton Adelaide, South Australia, 2010, pp. 1-10.

Awards

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- Research Abroad Scholarship travel grant to visit Microsystems and Nanotechnology (MiNa) research group at the University of British Columbia (UBC), Vancouver, Canada, awarded by University of Adelaide, 2011.
- BUPA Postgraduate Travel Grant and AUGU/RC Heddle Award travel scholarship to visit Microsystems and Nanotechnology (MiNa) research group at the University of British Columbia (UBC), Vancouver, Canada, 2011.
- Selected runner for the 3-Minute thesis competition, Faculty of Engineering Computer Science & Mathematical Sciences, School of Electrical & Electronic Engineering, The University of Adelaide, 2010.
- Postgraduate research Scholarship (ASI) towards doctoral studies, The University of Adelaide, Nov 2008.

List of Symbols

Notation	Description
CSA _{pre}	Luminal cross-sectional area before deflation of balloon
CSA _{post}	Luminal cross-sectional area after deflation of balloon
$ ho_0$	Initial density
V_{0}	Initial volume
V(t)	Current volume
m_0	Initial mass
ρ	Density
t	Time
$\sigma_{_{ij}}$	Stress tensor component <i>ij</i>
<i>x</i>	Acceleration component in the <i>x</i> direction
ÿ	Acceleration component in the y direction
ż	Acceleration component in the z direction
b _i	Body acceleration in the direction of axis <i>i</i> .
${\cal E}_{ij}$	Strain tensor component <i>ij</i>
т	Mass
F	Force
\dot{x}_i	Velocity in the <i>i</i> direction
$\{x\}$	Nodal displacement vector
$\begin{bmatrix} K \end{bmatrix}$	Stiffness matrix
$\{F\}$	Nodal force vector
$D_{\rm effective}$	Effective internal diameter of a scaffold
$D_{ m dilated}$	Average external diameter of a scaffold
D _{lost}	Diameter loss due to strut thickness

Notation	Description
$T_{\rm s}$	Strut thickness
$G_{ m P}$	Patency gain
A _C	Average cross-sectional area patent to fluid
A_{T}	Mean cross-sectional area of a deployed scaffold
$T_{\rm s,avg}$	Average strut thickness
$T_{ m s,flat}$	Fabricated RRR thickness with no sawtooth
t _h	RRR sawtooth height
t_1	RRR sawtooth length
O_1	RRR overlap length
R_1	RRR total length
V	Fluid velocity vector
p	Fluid pressure
μ	Dynamic viscosity
D	Rate of deformation tensor
μ_{∞}	Viscosity at zero shear rate
μ_0	Viscosity at infinite shear rate
γ̈́	Shear rate
U	Velocity component in the direction of <i>x</i> axis
υ	Velocity component in the direction of <i>y</i> axis
w	Velocity component in the direction of z axis
$D_{\mathrm{in,avg}}$	Mean inner diameter of a scaffold
$W_{ m s}$	Strut width
$T_{\rm s}$	Strut thickness
$D_{\rm in_m}$	Main vessel diameter
$D_{\rm in_m}$	Branching vessel diameter
$L_{ m Prox,Stent}$	Boundary layer initial length, proximal end of stent
$L_{\rm Dist,Stent}$	Boundary later initial length, distal end of stent
L _{Prox,RRR-Stent}	Boundary layer initial length, proximal end of RRR-stent
$L_{\rm Dist,RRR-Stent}$	Boundary later initial length, distal end of RRR-stent

Notation	Description
F _{wh}	Scaffolding withholding force
F _d	Fluid drag force
$f_{\rm i, support}$	Branch <i>i</i> outlet flow rate, main branch scaffolded
$f_{\rm in}$	Inlet flow rate
FR _i	Outlet/Inlet flow rate ratio
$f_{\rm i,healthy}$	Branch <i>i</i> outlet flow rate, main branch unscaffolded
FD _i	Outlet/Inlet flow rate ratio deviation
$A_{\rm RRR-Stent}$	Area subject to low wall shear stress, RRR-stent
A _{Stent}	Area subject to low wall shear stress, stent
$A_{\rm s}$	SMA starting transformation temperature
$A_{ m f}$	SMA finishing transformation temperature
L _{sty,r}	Axial length of Styrofoam rings
L _{sty,c}	Axial length of Styrofoam cap
$L_{\rm rod}$	Axial length of heat transfer rod
<i>r</i> ₁	Radius of heat transfer rod
L _{air,r}	Axial length of air cylinder trapped, Styrofoam rings
$L_{\rm air,d}$	Axial length of air cylinder at the deployment area
<i>r</i> ₂	Mock vessel internal diameter
$T_{ m sty,r}$	Thickness of Styrofoam rings
L _{mock}	Axial length of mock vessel
L _{RRR}	Total length of RRR
t _{RRR}	RRR average thickness
$W_{\rm RRR}$	RRR width
$V_{ m flow}$	Approach velocity
$k_{\rm rod}$	Thermal conductivity of heat transfer rod
$k_{ m sty}$	Thermal conductivity of Styrofoam
$k_{ m air}$	Thermal conductivity of air
V	Kinematic viscosity

Notation	Description
Re	Reynolds number
Pr	Prandtl number
Ż	Heat transfer rate
Т	Temperature
$R_{ m thermal}$	Thermal resistance
R _{cond}	Conduction thermal resistance
R _{conv}	Convective thermal resistance
h	Convective heat transfer coefficient
$R_{\rm rad}$	Radiation thermal resistance
$h_{\rm rad}$	Radiation heat transfer coefficient
$T_{\rm s}$	Surface temperature
$T_{ m surr}$	Surrounding temperature
$R_1 = R_{\text{cond_ins}}$	Conductive thermal resistance of air and Styrofoam rings
$R_2 = R_{\text{cond}_{\text{mock}}}$	Conductive thermal resistance of mock vessel
$R_3 = R_{\rm conv}$	Convective thermal resistance of crossflow
k _{ins}	Thermal conductivity of insulation layer
Nu	Nusselt Number
$\dot{q}_{\rm conv}$	Convective heat flux rate
$\dot{q}_{\rm cond}$	Conductive heat flux rate
$h_{ m flow}$	Effective heat transfer coefficient of crossflow
$L_{\rm chr}$	Characteristic length
Nu _{cyl}	Nusselt number of cylinder in crossflow
T_1	Temperature at internal walls of mock vessel
$T_{\infty 1}$	Constant rod temperature
R _{total}	Total thermal resistance
$\dot{Q}_{\rm in}(x)$	Heat transfer rate into the differential volume at distance x
$\dot{Q}_{\rm out}(x)$	Heat transfer rate out of the diff. volume at distance x
$\dot{Q}_{\rm comb}(x)$	Heat transfer rate out of the diff. volume in radial direction
R _{comb}	Combined thermal resistance of insulation layer

Notation	Description
A _c	Cross-sectional area of heat transfer rod
$L_{ m total}$	Total length of the thermal model of heat transfer rod
$L_{ m added}$	Added length to the thermal mode of heat transfer rod
$\dot{Q}_{\rm out,tip}$	Heat transfer rate from the tip of heat transfer rod
x _{tip}	Axial distance from base to tip of heat transfer rod
$\dot{Q}_{ m added}$	Heat transfer from added length of heat transfer rod
$T_{\rm rod}(x)$	Temperature of rod at axial distance <i>x</i> from the base
$R_{ m total_tip}$	Total thermal resistance at the tip of the rod
$R_{\rm ins}$	Thermal resistance of the insulation at the top section of mock-rod assembly
$A_{\rm c,ins}$	Cross-sectional area of Styrofoam cap
$k_{ m ins,top}$	Thermal conductivity of insulation at the top section of mock-rod assembly
h_{top}	Heat transfer coefficient at the top of mock rod assembly
R_{top}	Thermal resistance at the top of mock-rod assembly
L_{top}	Axial length of the top section of the mock-rod assembly
$P_{ m mock}$	Periphery of the mock vessel
$A_{\rm c,mock}$	Cross-sectional area of mock vessel
<i>p</i>	Heat transfer rate per unit length
R _{mock}	Effective thermal resistance of mock vessel
[<i>K</i>]	Matrix of thermal conductance
$\dot{Q}_{ m electric}$	Electric power consumption
Ι	Electric current
$R_{ m electric, plate}$	Electrical resistance of heating plate
$\dot{Q}_{ m thermal}$	Thermal heat transfer rate
$R_{ m thermal,\ plate}$	Thermal resistance of heating plate
$T_{\rm plate}$	Heating plate temperature
T _{room}	Room temperature

Notation	Description
$\delta_{ m linear}$	Coefficient of linear thermal expansion
$L_{ m initial}$	Initial length of a solid
$V_{ m electric}$	Electric potential
$I_{ m electric}$	Electric current
$T_{\rm RRR}$	RRR body temperature
$T_{ m body}$	RRR's surrounding tissue (human body) temperature
$R_{ m thrm,body}$	Thermal resistance tissue surrounding RRR
$R_{ m thrm, blood}$	Effective thermal resistance of blood
$R_{ m elec,RRR}$	Electrical resistance of RRR
$V_{\rm in}$, $V_{\rm out}$	Input and output voltage
$R_{ m cond, parylene}$	Conduction thermal resistance of parylene
$R_{\rm conv, blood}$	Convective thermal resistance of blood
L _{coating}	Thickness of parylene-C layer
$k_{ m parylene}$	Thermal conductivity of parylene
$A_{\rm RRR,conv}$	RRR area subject to blood flow
$h_{ m blood}$	Convective heat transfer coefficient of blood
$ ho_{ m elec,Nitinol}$	Electrical resistance of Nitinol
A _{RRR,cs}	RRR strut cross-sectional area
$V_{ m avg, blood}$	Average blood velocity
$ ho_{ m blood}$	Blood density
$\mu_{ m blood}$	Average blood viscosity
P _{RRR}	Cross-sectional periphery of RRR
f	Fluid body forces

Abbreviations

Notation	Description
μEDM	Micro Electro-Discharge Machining
3D	Three-Dimensional
ACE	Angiotensin-Converting Enzyme
ARB	Angiotensin II Receptor Antagonist
BE	Balloon-Expandable
BM	Bare-Metal
CABG	Coronary Artery Bypass Grafting
CAD	Computer-Assisted Design
CFD	Computational Fluid Dynamics
CHD	Coronary Heart Disease
CNT	Carbon Nanotube
Co-Cr	Cobalt Chromium
CSA	Cross-Sectional Area
CTE	Coefficient of Thermal Expansion
CU	Copper
CVD	Cardiovascular Disease
DE	Drug-eluting
Fe	Iron
FEA	Finite Element Analysis
FEM	Finite Element Modelling
HT	Heat transfer Rod
IR	Infrared
ISR	In-Stent Restenosis
LDL	Low Density Lipoproteins
LWSS	Low Wall Shear Stress
Mg	Magnesium

Notation	Description
MRI	Magnetic Resonance Imaging
Ni-Ti	Nickel-Titanium (Nitinol)
PCI	Percutaneous Coronary Intervention
PCTA	Percutaneous Transluminal Angioplasty
PET	Polyethylene Terephthalate
PEVA	Polyethylene-co-Vinyl Acetate
PGA	Polyglycolid Acid
PLA	Polylactic Acid
PLGA	Poly-l-Glycolic Acid
PMBA	Poly-n-Butyl Methacrylate
Pt-Cr	Platinum Chromium
Pt-Ir	Platinum Iridium
PU	Polyurethane
RF	Radio-Frequency
RRR	Recoil Resilient Ring
SE	Self-Expandable
SIBS	Styrene- <i>b</i> -Isobutylene- <i>b</i> -Styrene
SMA	Shape Memory Alloy
SS 316L	Stainless Steel 316L
SST	Shear Stress Transport
STD	Standard Deviation
Ti	Titanium
TiBN	Titanium-Boron-Nitride
VLSI	Very Large Scale Integration

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